

# What is Graph Neural Networks (GNN)?

## Exploring the World of GNNs

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## ① CNN & GNN

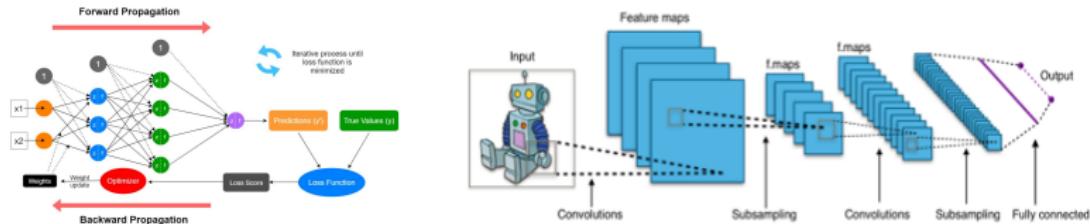
## ② GNN Methods

### ③ Research Directions

## 4 Future Work

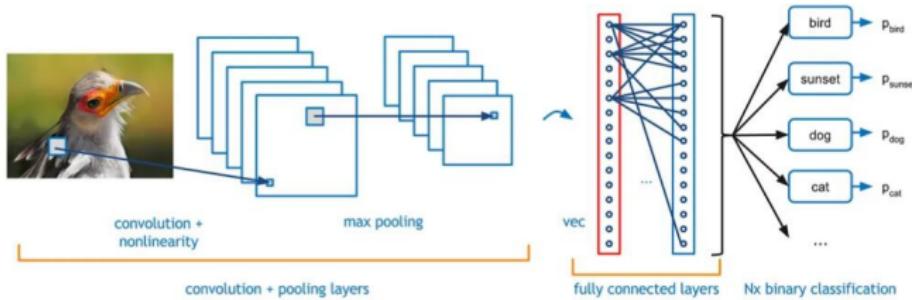
## Convolutional Neural Network

- Neural networks: A neural network is a computational model inspired by the structure of the human brain.
  - Convolutional Neural networks: Convolutional neural network (CNN) gains great success on Euclidean data.
    - Image classification, object detection, machine translation.



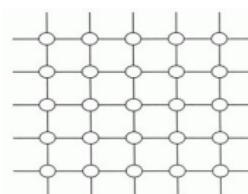
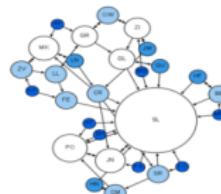
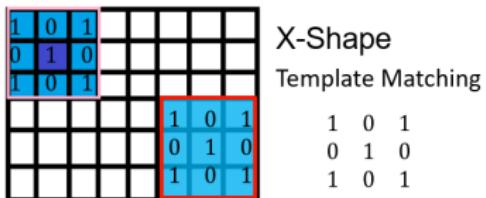
# Convolutional Neural Network

- What is the key strength of CNNs?
  - CNNs excel at learning **local stationary structures** via localized convolution filters and building them into complex, multi-scale hierarchical structures.



## Convolutional Neural Network

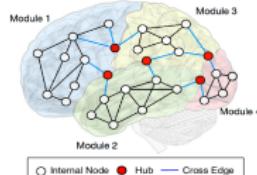
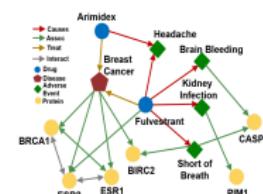
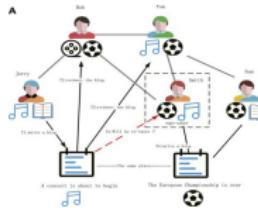
- Localized convolutional filters are **translation/shift-invariant** [1].
    - Which can recognize identical features independently of their spatial locations.
  - One interesting problem is how to generalize convolution to a non-Euclidean domain, e.g., graph?
    - Irregular structure of graph poses challenges for defining convolution.



*Convolution is well defined in Euclidean data, grid-like network.*

# Non-Euclidean Data

- Diverse Applications of Non-Euclidean Data Structures.
  - Transportation Systems:** Urban traffic flow analysis for smart city planning.
  - Social Networks:** Facebook's social graph mapping friendships and interactions.
  - Knowledge Graphs:** Google's Knowledge Graph in search engine algorithms.
  - Brain Topology:** The neurons in the brain and their connections form a non-Euclidean structure.



*In real-world scenarios, there is a plethora of non-Euclidean data, which is why we have introduced Graph Neural Networks.*

## ① CNN & GNN

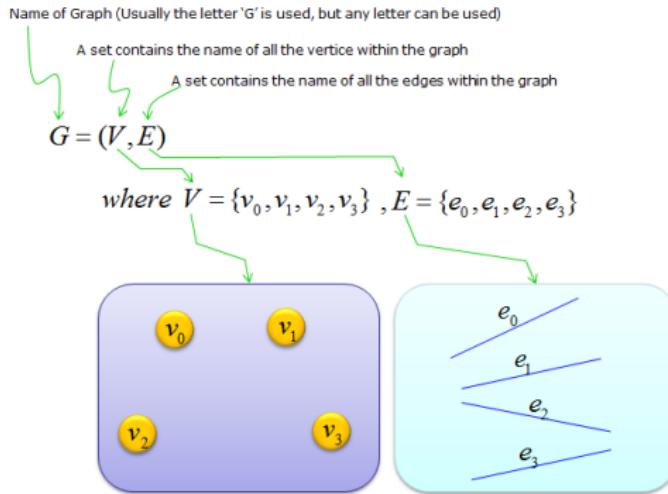
## ② GNN Methods

## ③ Research Directions

## ④ Future Work

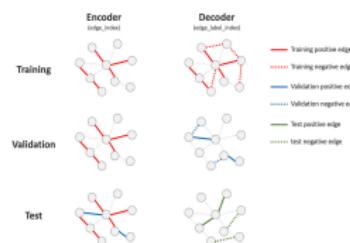
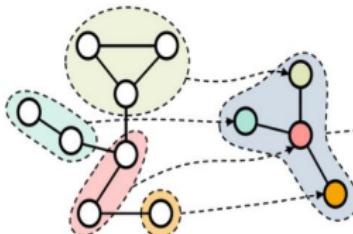
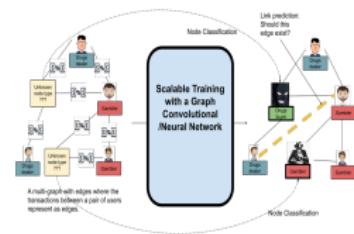
## Preliminaries for GNNs

- The graph notation  $G = (V, E)$ 
    - $V$  is the set of vertices (or nodes).
    - $E$  is the set of edges (or links) between vertices.



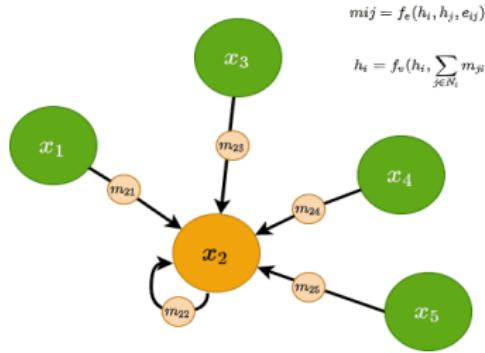
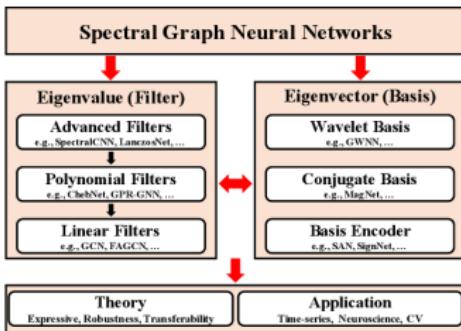
## Typical Tasks for GNN

- Diverse Applications of Non-Euclidean Data Structures.
    - **Node classification:** Assigning labels to nodes based on their features and connections. It's commonly used in social network analysis and bioinformatics.
    - **Graph classification:** In this task, entire graphs (as units) are classified into different categories. This is particularly useful in chemical compound analysis and pattern recognition in various kinds of networks.
    - **Edge classification:** Predicting types or properties of edges in a graph, significant in knowledge graphs and recommender systems.



## Typical Methods for GNN

- Diverse Applications of Non-Euclidean Data Structures.
    - **Spectral GNN methods:** These methods leverage the graph theory, particularly eigenvalues and eigenvectors of the graph Laplacian, to analyze graph structure.
    - **Spatial GNN methods:** Spatial methods directly operate on the graph nodes and their neighbors, focusing on local neighborhood information and making them well-suited for large and dynamic graphs.



# Spectral GCN Methods

- A graph  $G = (V, E, W, X)$ 
  - $V$  is node set with  $n = |V|$ ,  $E$  is edge set, and  $W \in R^{n \times n}$  is the weighted adjacency matrix.
  - Each node is associated with  $d$  features, and  $X \in R^{n \times d}$  is the feature matrix of nodes, each column of  $X$  is a signal defined over nodes.
- Graph Laplacian
  - $L = D - W$ , where  $D$  is a diagonal matrix with  $D_{ij} = \sum_i W_{ij}$ .
  - Graph Laplacian Normalization.

$$L = I - D^{-\frac{1}{2}} WD^{-\frac{1}{2}} \quad (1)$$

where  $I$  is the identity matrix.

Labeled graph	Degree matrix	Adjacency matrix	Laplacian matrix
	$\begin{pmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 2 & -1 & 0 & 0 & -1 & 0 \\ -1 & 3 & -1 & 0 & -1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 3 & -1 & -1 \\ -1 & -1 & 0 & -1 & 3 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{pmatrix}$

# Graph Fourier Transform

- Fourier basis of graph  $G$ 
    - The complete set of orthonormal eigenvectors  $\{u_l\}_{l=0}^{n-1}$  of  $L$ , ordered by its non-negative eigenvalues  $\{\lambda_l\}_{l=0}^{n-1}$ .
    - Graph Laplacian could be diagonalized as

$$L = U\Lambda U^T \quad (2)$$

where  $U = [u_0, \dots, u_{n-1}]$  and  $\Lambda = \text{diag}([\lambda_0, \dots, \lambda_{n-1}])$

- Graph Fourier transform
    - Graph Fourier transform of a signal  $x \in R^n$  is defined as

$$\hat{x} = U^T x \quad (3)$$

- Graph Fourier inverse transform is

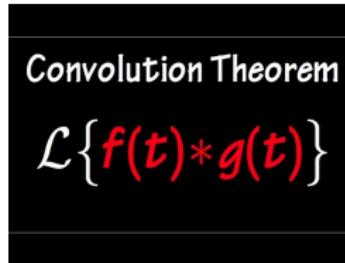
$$x = U\hat{x} \quad (4)$$

## Convolution in spectral domain

- Convolution theorem
    - The Fourier transform of a convolution of two signals is the point-wise product of their Fourier transforms
  - According to the convolution theorem, given a signal  $x$  as input and the other signal  $y$  as filter, graph convolution  $*_G$  can be written as:

$$x *_G y = U \left( (U^T x) \cdot (U^T y) \right) \quad (5)$$

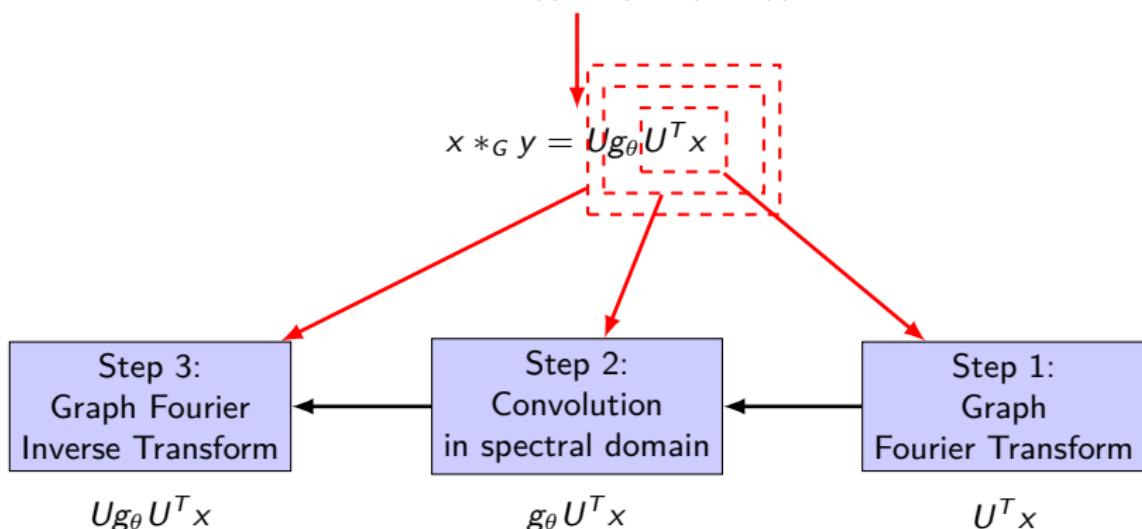
Here, the convolution filter in the spectral domain is  $U^T y$ .



# Convolution in spectral domain

- Let  $\mathbf{U}^T \mathbf{y} = [\theta_0, \dots, \theta_{n-1}]^T$  and  $\mathbf{g}_\theta = \text{diag}([\theta_0, \dots, \theta_{n-1}])$ , we have
  - The Fourier transform of a convolution of two signals is the point-wise product of their Fourier transforms

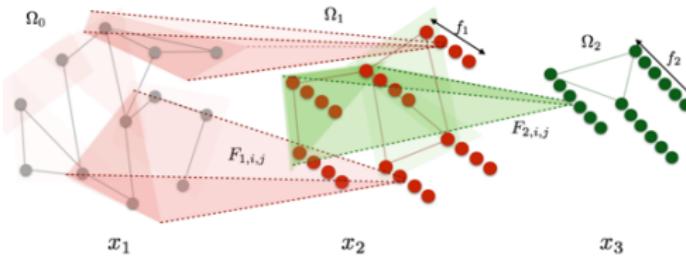
$$\mathbf{x} *_G \mathbf{y} = \mathbf{U} ((\mathbf{U}^T \mathbf{x}) \odot (\mathbf{U}^T \mathbf{y}))$$



# Spectral Graph CNN

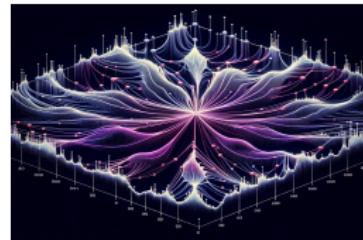
- Spectral Graph CNN

$$x_{k+1,j} = h \left( \sum_{i=1}^{f_k} U F_{k,i,j} U^T x_{k,i} \right), \quad j = 1, \dots, f_{k+1} \quad (6)$$



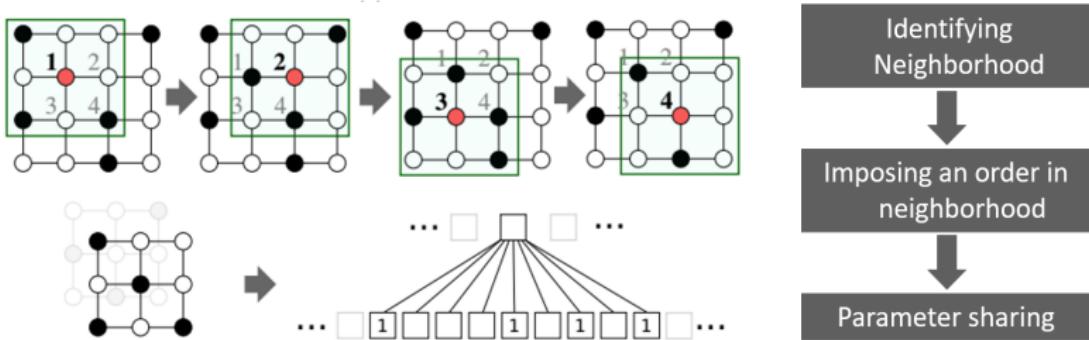
# Limitation of Spectral Graph CNN

- The limitations of spectral GCNs are summarized as follows:
  - Eigen-decomposition:** Spectral GCNs require the eigen-decomposition of the Laplacian matrix, which is a computationally intensive task.
  - High Computational Costs:** The operations involved in spectral GCNs, particularly eigen-decomposition, are resource-intensive, leading to high computational costs.
  - Non-localization in Vertex Domain:** Spectral GCNs lack localization, meaning that the filters applied are global and not restricted to the immediate neighborhood of a vertex, which can lead to inefficiencies in capturing localized patterns in the data.



# Spatial Graph CNN

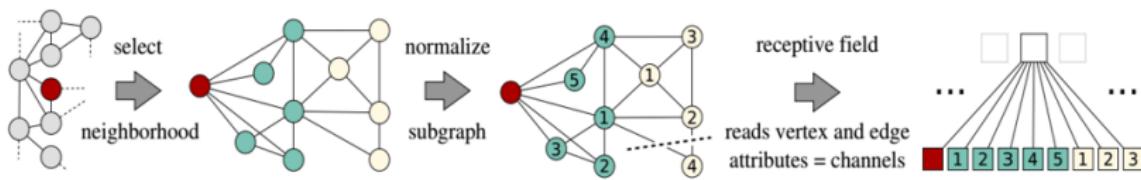
- Analogy[2]
  - What can we learn from the architecture of a standard convolutional neural network?



# Spatial Graph CNN

- Analogy

- Select a fixed number of nodes as neighbors for each node, based on a specific proximity metric.
- Establish an order for the nodes using the proximity metric as a basis.
- Implement parameter sharing across the nodes.



Step 1:  
Identifying  
Neighborhood

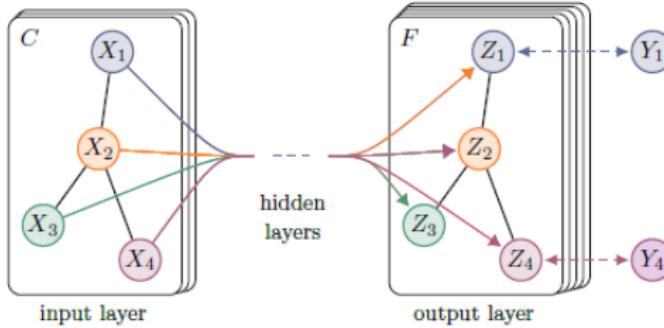
Step 2:  
Imposing an order  
in Neighborhood

Step 3:  
Parameter  
Sharing

# Spatial Graph CNN

- GCN: Graph Convolution Network
  - Aggregating information from neighborhood via a normalized Laplacian matrix.
  - Parameters sharing is from feature transformation.

$$Z = f(X, A) = \text{softmax} \left( \hat{A} \text{ReLU} \left( \hat{A} X W^{(0)} \right) W^{(1)} \right) \quad (7)$$



# Framework of Graph Neural Network

- GNNs offer us a **flexible and effective** framework for both node classification and graph classification tasks
  - Leveraging graph structure and node feature to learn a representation vector of each node  $h_v$ , or the entire graph  $h_G$ .
  - Neighborhood aggregation strategy: iteratively updates a node's representation by aggregating its neighbors' representations.
- GNN framework: **Aggregate + Combine**

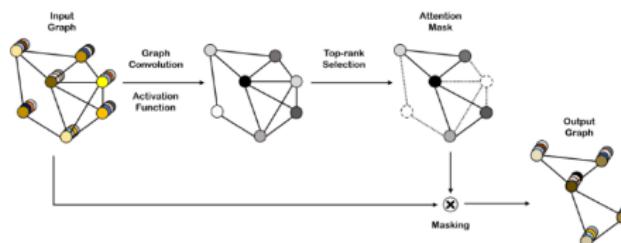
$$a_v^{(k)} = \text{AGGREGATE}^{(k)} \left( \left\{ h_u^{(k-1)} : u \in \mathcal{N}(v) \right\} \right) \quad (8)$$

$$h_v^{(k)} = \text{COMBINE}^{(k)} \left( h_v^{(k-1)}, a_v^{(k)} \right) \quad (9)$$

$h_v^{(k)}$  is the feature vector of node at the  $k$ -th layer/iteration of GNN, and  $h_v^{(0)} = X_v$ .  $\mathcal{N}(v)$  is a set of nodes adjacent to  $v$ .

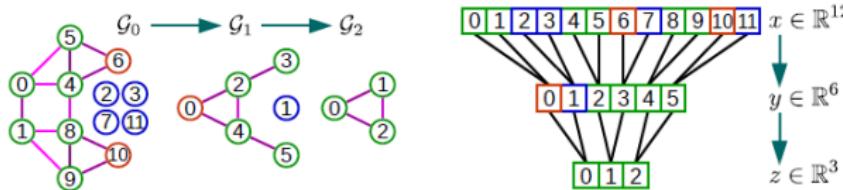
## Graph pooling via node selection[3]

- Graph coarsening: Graph coarsening aims to reduce the size of a graph by merging similar nodes or edges, resulting in a coarser, simpler graph.
  - **Node Selection Strategies:** Nodes can be selected based on various criteria like node importance, feature similarity, or structural roles in the graph.
  - **Preserving Graph Structure:** An important aspect of node selection is to preserve the essential structural and feature-related information of the original graph.
  - **Hierarchical Graph Representations:** Graph pooling layers can be stacked to produce hierarchical representations of graphs, capturing features at different scales.



## Graph Pooling via graph coarsening [4]

- Graph coarsening: Graph coarsening aims to reduce the size of a graph by merging similar nodes or edges, resulting in a coarser, simpler graph.
  - **Node Merging:** Nodes are often merged based on **similarity, connectivity, or other criteria**, forming super-nodes in the coarser graph.
  - **Edge Reduction:** Alongside node merging, edges may also be reduced or reweighted to reflect the new structure of the coarser graph.
  - **Application in GNNs:** In graph neural networks, coarsening is used to reduce the graph size.
  - **Impact on Performance:** Proper graph coarsening must be taken to ensure that the coarsening process does not lead to a significant loss of information.



## ① CNN & GNN

## ② GNN Methods

## ③ Research Directions

## ④ Future Work

# Graph Neural Networks

- Graph neural networks (GNNs) gained remarkable success
  - Achieving state-of-the-art empirical performance in node classification, link prediction, and graph classification.
- The design of new GNNs is mostly based on empirical intuition, heuristics and experimental trial-and-error.
- We lack theoretical understanding of the properties and limitations of GNNs.
  - One fundamental problem is the expressive power of GNNs.

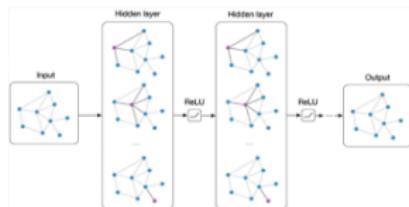


Figure 1: Node classification task

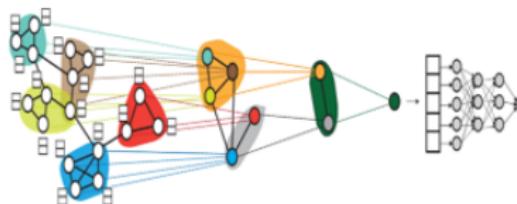
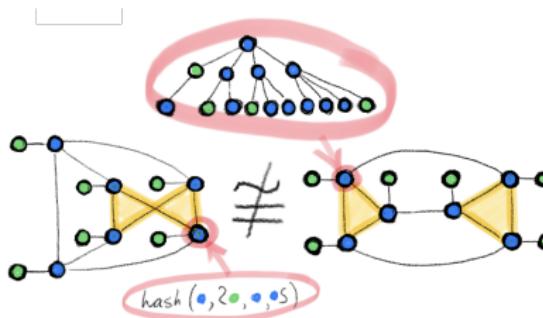


Figure 2: Graph classification task

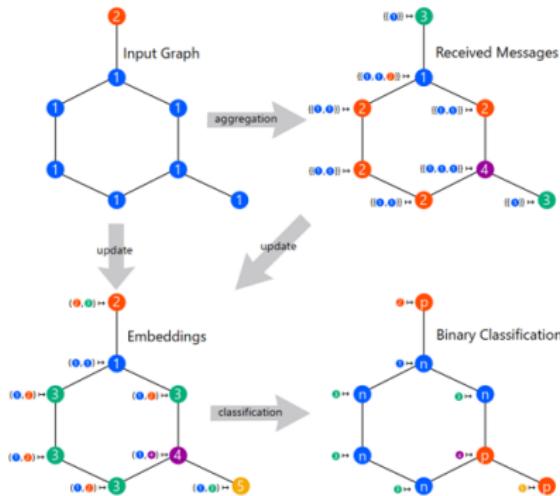
# Expressive Power

- Number of possible distinct occurrences
  - Expressive power of  $n$  bits is  $2^n$ .
    - ✓ For example, 5 bits can distinguish 32 distinct states.
    - ✓ Given no more than 32 bottles of water and one of them is poisonous, at most 5 mice are required to identify which bottle is poisonous.
- Approximation capability
  - Expressive power of 1-layer perception.
  - Multi-layer perceptron offers us a universal approximator.



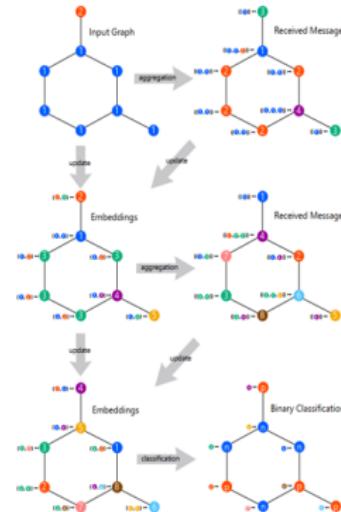
## GNNs for node classification

- 1-layer GCN
    - Limited expressive power of 1-layer GCN: it cannot fully distinguish all nodes



# GNNs for node classification

- 2-layer GCN
  - 2-layer GCN can fully distinguish all nodes in this toy example.
  - Depth of GNNs matters.
- Can the expressive power of GNNs be improved infinitely via improving their depth? Is there a bound?



## Over-smooth issue

- Effect on Model Performance
  - As a result of over-smoothing, the performance of GCNs on tasks like node classification, graph classification, and others can significantly degrade.
  - The model might end up producing similar outputs for all nodes, reducing its ability to make accurate predictions.

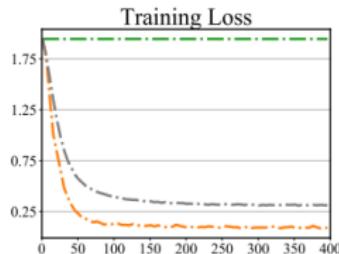


Figure 3: Node classification task

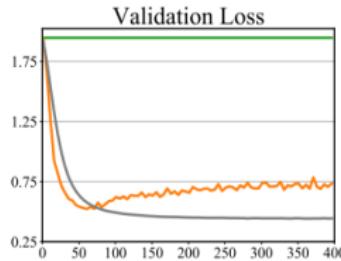


Figure 4: Graph classification task

Why deeper GNNs perform worse than their shallow counterparts?

## ① CNN & GNN

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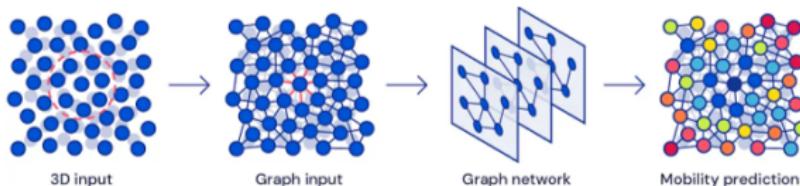
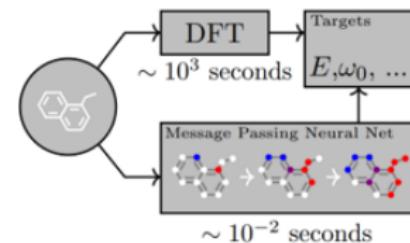
## ④ Future Work

# Expressive Power

- Three major scenarios
    - Node-level
      - ✓ Node classification: predict the label of nodes according to several labeled nodes and graph structure.
      - ✓ Link prediction: predict the existence or occurrence of links among pairs of nodes.
  - Graph-level
    - Graph classification: predict the label of graphs via learning a graph representation using graph CNN.
  - Signal-level
    - Signal classification, similar to image classification which is signal-level scenario on a grid-like network

# Applications in other fields

- GNNs for quantum chemistry
  - Predict the quantum properties of molecules using GNNs.
  - Traditional methods, i.e., DFT (Density Functional Theory), is computationally expensive .
- GNNs for quantum chemistry
  - Predict the quantum properties of molecules using GNNs.
  - Traditional methods, i.e., DFT (Density Functional Theory), is computationally expensive.
- Modeling dynamics of glassy systems using GNNs



- [1] Y. LeCun, Y. Bengio, and G. Hinton, "Deep learning," *nature*, vol. 521, no. 7553, pp. 436–444, 2015.
- [2] M. Niepert, M. Ahmed, and K. Kutzkov, "Learning convolutional neural networks for graphs," in *Proceedings of The 33rd International Conference on Machine Learning*, ser. Proceedings of Machine Learning Research, vol. 48, New York, New York, USA, 2016, pp. 2014–2023.
- [3] J. Lee, I. Lee, and J. Kang, "Self-attention graph pooling," in *Proceedings of the 36th International Conference on Machine Learning*, ser. Proceedings of Machine Learning Research, K. Chaudhuri and R. Salakhutdinov, Eds., vol. 97, 2019, pp. 3734–3743.
- [4] Z. Ying, J. You, C. Morris, X. Ren, W. Hamilton, and J. Leskovec, "Hierarchical graph representation learning with differentiable pooling," in *Advances in Neural Information Processing Systems*, S. Bengio, H. Wallach, H. Larochelle, K. Grauman, N. Cesa-Bianchi, and R. Garnett, Eds., vol. 31, 2018.

# Thank you for your attentions!