Group

March 28, 2019

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1 Semigroups, Monoids And Groups

1.1 Exercise 7 (P29)

it is easy to see that $(\forall \bar{a}, \bar{b} \in Z_p - \bar{0}) \to \bar{a}\bar{b} \in Z_p - \bar{0}$. And $(\forall \bar{a} \neq 0) \to (a, p) = 1$. so $(\exists x, y \in Z) \land xa + yp = 1$, i.e. xa = y'p + 1. which means that $a^{-1} = x$ exists.

1.2 Exercise 11 (P30)

if $(ab)^n = a^n b^n$ for three consequtive integers n. then, $(ab)^{n-1} = a^{n-1}b^{n-1}$, $(ab)^n = a^n b^n$, $(ab)^{n+1} = a^{n+1}b^{n+1}$. split $(ab)^{n+1}$, we get:

$$(ab)^{n+1} = a^{n+1}b^{n+1} (1)$$

$$=(ab)(ab)^n = (ab)a^nb^b (2)$$

$$=(ab)^n(ab) = a^n b^n(ab) \tag{3}$$

$$=(ab)(ab)^{n-1}(ab) = (ab)a^{n-1}b^{n-1}(ab)$$
(4)

$$=(ab)^{2}(ab)^{n-1} = (ab)^{2}a^{n-1}b^{n-1}$$
(5)

$$=(ab)^{n-1}(ab)^2 = a^{n-1}b^{n-1}(ab)^2$$
(6)

from (1) and (3) we could get:

$$a^n b^n (ab) = a^{n+1} b^{n+1} (7)$$

$$b^n a b = a b^{n+1} \tag{8}$$

$$b^n a = ab^n \tag{9}$$

from (1) and (2) we could get:

$$(ab)a^n b^n = a^{n+1}b^{n+1} (10)$$

$$ba^n = a^n b \tag{11}$$

from (1) and (4) we could get:

$$(ab)(ab)^{n-1}(ab) = a^{n+1}b^{n+1}$$
(12)

$$(ab)a^{n-1}b^{n-1}(ab) = a^{n+1}b^{n+1}$$
(13)

$$ba^{n-1}b^{n-1}a = a^n b^n (14)$$

$$ba^n a^{-1} b^{-1} b^n a = a^n b^b (15)$$

from (9), (11) and (15) we could get:

$$a^n b a^{-1} b^{-1} a b^n = a^n b^n (16)$$

$$ba^{-1}b^{-1}a = e (17)$$

$$a^{-1}b^{-1} = b^{-1}a^{-1} (18)$$

1.3 Exercise 15 (P30)

for all $a \in G$, we could define $G' = \{ab | \forall b \in G\}$. because $(\forall a, b, c \in G)ab = ac \rightarrow b = c$, we could define a injection function $f: G \rightarrow G'$ by leting

f(x)=ax. It is easy to verify that Img f=G'. so f is a bijection and G=G'. we could look the f(x) as an edge from x to f(x). then we could get a graph, such that all the verteces in the graph are in a cycle. so we could get a circle like this: $aa=f, af=c, ac=\cdots ax=a$. and we could get $a^k=a$ from this circle. so $(\forall b\in G)a^kb=ab\to a^{k-1}b=b$. so we could let $a^{k-1}=e$ to be the left unit of G. and by knowing that $(\forall x\in G)(\exists y\in G)\land xy=e$. we've proved that all the elements in G has a inverse.

2 Homomorphism And Subgroups

2.1 Exercise 1 (P33)

construct a monoid G as follow:

it is easy to find that G is a monoid. And we construct a homomorphism $f: G \to G$ as follow: f(a) = a, f(b) = a, f(e) = a.

2.2 Exercise 2 (P33)

$$f(x)f(y) = x^{-1}y^{-1} = (yx)^{-1} \neq (xy)^{-1} = f(xy)$$

2.3 Exercise 3 (P33)

2.3.1 non-abelian

$$AB = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$$

$$BA = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} \text{ so, } Q_8 \text{ is not abelian.}$$

2.3.2 it is a group

And we know that $A^4 = B^4 = I$. Because $jBB(\forall i, j \in Z)A^iB^jB^{4-j}A^{4-i} = I \Rightarrow (A^iB^j)^{-1} = B^{4-j}A^{4-i}$, we claim that all the elements in this set have a inverse.

2.3.3 why order 8

you could write a program to check this.

```
template <class Type>
struct Matrix {
#define FOR(i, 1, r) for (int (i) = (1); (i) <= (r); (i)++)
    int row, col;
    complex<Type> w[maxn] [maxn];
    Matrix (int row, int col):row(row), col(col) {
        FOR(i, 1, row) FOR(j, 1, col) w[i][j] = 0; // initalize
    }
    Matrix (const Matrix &other) {
        row = other.row, col = other.col;
        FOR(i, 1, row) FOR(j, 1, col) w[i][j] = other.w[i][j];
    }
    friend Matrix operator * (const Matrix &a, const Matrix &b) {
        assert(a.col == b.row);
        Matrix c(a.row, b.col);
        FOR(i, 1, a.row) FOR(j, 1, b.col) {
            c.w[i][j] = 0;
            FOR(k, 1, a.col) c.w[i][j] += a.w[i][k] * b.w[k][j];
        }
        return c;
    friend bool operator < (const Matrix &a, const Matrix &b) {
        assert(a.row == b.row);
        assert(a.col == b.col);
        FOR(i, 1, a.row) FOR(j, 1, a.col) {
            if (a.w[i][j] != b.w[i][j]) {
                if (a.w[i][j].real() == b.w[i][j].real())
                    return a.w[i][j].imag() < b.w[i][j].imag();
                return a.w[i][j].real() < b.w[i][j].real();
            }
        }
        return false;
    friend bool operator == (const Matrix &a, const Matrix &b) {
        if (a.row != b.row || a.col != b.col) return false;
        FOR(i, 1, a.row) FOR(j, 1, a.col) {
            if (a.w[i][j] != b.w[i][j]) return false;
```

```
}
        return true;
    }
    void Log() {
        FOR(i, 1, row) {
            FOR(j, 1, col) {
                printf("%d + %di ", w[i][j].real(), w[i][j].imag());
            } printf("\n");
        }
#undef FOR
};
void search() {
    initI(); initA(); initB();
    set<Matrix<int> > st; st.clear();
    queue<Matrix<int> > q;
    q.push(I);
    st.insert(I);
    while(!q.empty()) {
        Matrix<int> tt = q.front(); q.pop();
        tt.Log(); puts("");
        Matrix<int> ta = tt * A;
        Matrix<int> tb = tt * B;
        Matrix<int> at = A * tt;
        Matrix<int> bt = B * tt;
        if (!st.count(ta)) {
            st.insert(ta);
            q.push(ta);
        }
        if (!st.count(tb)) {
            st.insert(tb);
            q.push(tb);
        }
        if (!st.count(at)) {
            st.insert(at);
            q.push(at);
        }
        if (!st.count(bt)) {
            st.insert(bt);
```

```
q.push(bt);
        }
    }
    cout << st.size() << endl;</pre>
}
#include <iostream>
#include <cstring>
#include <cstdio>
#include <complex>
#include <map>
#include <set>
#include <queue>
using namespace std;
const int maxn = 10;
// load the Matrix Class
template <class Type>
struct Matrix {
#define FOR(i, 1, r) for (int (i) = (1); (i) \leq (r); (i)++)
    int row, col;
    complex<Type> w[maxn][maxn];
    Matrix (int row, int col):row(row), col(col) {
        FOR(i, 1, row) FOR(j, 1, col) w[i][j] = 0; // initalize
    }
    Matrix (const Matrix &other) {
        row = other.row, col = other.col;
        FOR(i, 1, row) FOR(j, 1, col) w[i][j] = other.w[i][j];
    }
    friend Matrix operator * (const Matrix &a, const Matrix &b) {
        assert(a.col == b.row);
        Matrix c(a.row, b.col);
        FOR(i, 1, a.row) FOR(j, 1, b.col) {
            c.w[i][j] = 0;
            FOR(k, 1, a.col) c.w[i][j] += a.w[i][k] * b.w[k][j];
        }
        return c;
    friend bool operator < (const Matrix &a, const Matrix &b) {
```

```
assert(a.row == b.row);
        assert(a.col == b.col);
        FOR(i, 1, a.row) FOR(j, 1, a.col) {
            if (a.w[i][j] != b.w[i][j]) {
                if (a.w[i][j].real() == b.w[i][j].real())
                    return a.w[i][j].imag() < b.w[i][j].imag();
                return a.w[i][j].real() < b.w[i][j].real();</pre>
            }
        }
        return false;
    }
    friend bool operator == (const Matrix &a, const Matrix &b) {
        if (a.row != b.row || a.col != b.col) return false;
        FOR(i, 1, a.row) FOR(j, 1, a.col) {
            if (a.w[i][j] != b.w[i][j]) return false;
        }
        return true;
    }
    void Log() {
        FOR(i, 1, row) {
            FOR(j, 1, col) {
                printf("%d + %di ", w[i][j].real(), w[i][j].imag());
            } printf("\n");
        }
    }
#undef FOR
};
Matrix<int> I(2, 2), A(2, 2), B(2, 2);
void initI() {
    I.w[1][1] = 1;
    I.w[2][2] = 1;
}
void initA() {
    A.w[1][2] = 1;
    A.w[2][1] = -1;
void initB() {
    B.w[1][2] = complex < int > (0, 1);
    B.w[2][1] = complex < int > (0, 1);
```

```
}
void search() {
    initI(); initA(); initB();
    set<Matrix<int> > st; st.clear();
    queue<Matrix<int> > q;
    q.push(I);
    st.insert(I);
    while(!q.empty()) {
        Matrix<int> tt = q.front(); q.pop();
        tt.Log(); puts("");
        Matrix<int> ta = tt * A;
        Matrix<int> tb = tt * B;
        Matrix<int> at = A * tt;
        Matrix<int> bt = B * tt;
        if (!st.count(ta)) {
            st.insert(ta);
            q.push(ta);
        }
        if (!st.count(tb)) {
            st.insert(tb);
            q.push(tb);
        }
        if (!st.count(at)) {
            st.insert(at);
            q.push(at);
        }
        if (!st.count(bt)) {
            st.insert(bt);
            q.push(bt);
        }
    }
    cout << st.size() << endl;</pre>
}
int main() {
    search();
    return 0;
}
```

2.4 Exercise 4 (P33)

```
#include <iostream>
#include <cstring>
#include <cstdio>
#include <complex>
#include <map>
#include <set>
#include <queue>
using namespace std;
const int maxn = 10;
// load the Matrix Class
template <class Type>
struct Matrix {
#define FOR(i, 1, r) for (int (i) = (1); (i) <= (r); (i)++)
    int row, col;
    complex<Type> w[maxn][maxn];
    Matrix (int row, int col):row(row), col(col) {
        FOR(i, 1, row) FOR(j, 1, col) w[i][j] = 0; // initalize
    }
    Matrix (const Matrix &other) {
        row = other.row, col = other.col;
        FOR(i, 1, row) FOR(j, 1, col) w[i][j] = other.w[i][j];
    friend Matrix operator * (const Matrix &a, const Matrix &b) {
        assert(a.col == b.row);
        Matrix c(a.row, b.col);
        FOR(i, 1, a.row) FOR(j, 1, b.col) {
            c.w[i][j] = 0;
            FOR(k, 1, a.col) c.w[i][j] += a.w[i][k] * b.w[k][j];
        return c;
    }
    friend bool operator < (const Matrix &a, const Matrix &b) {</pre>
        assert(a.row == b.row);
        assert(a.col == b.col);
        FOR(i, 1, a.row) FOR(j, 1, a.col) {
            if (a.w[i][j] != b.w[i][j]) {
```

```
if (a.w[i][j].real() == b.w[i][j].real())
                     return a.w[i][j].imag() < b.w[i][j].imag();
                return a.w[i][j].real() < b.w[i][j].real();</pre>
            }
        }
        return false;
    }
    friend bool operator == (const Matrix &a, const Matrix &b) {
        if (a.row != b.row || a.col != b.col) return false;
        FOR(i, 1, a.row) FOR(j, 1, a.col) {
            if (a.w[i][j] != b.w[i][j]) return false;
        }
        return true;
    void Log() {
        FOR(i, 1, row) {
            FOR(j, 1, col) {
                printf("%d + %di ", w[i][j].real(), w[i][j].imag());
            } printf("\n");
        }
    }
#undef FOR
};
Matrix<int> I(2, 2), A(2, 2), B(2, 2);
void initI() {
    I.w[1][1] = 1;
    I.w[2][2] = 1;
}
void initA() {
    A.w[1][2] = 1;
    A.w[2][1] = -1;
}
void initB() {
    B.w[1][2] = complex < int > (1, 0);
    B.w[2][1] = complex < int > (1, 0);
}
void search() {
    initI(); initA(); initB();
```

```
set<Matrix<int> > st; st.clear();
    queue<Matrix<int> > q;
    q.push(I);
    st.insert(I);
    while(!q.empty()) {
        Matrix<int> tt = q.front(); q.pop();
        tt.Log(); puts("");
        Matrix<int> ta = tt * A;
        Matrix<int> tb = tt * B;
        Matrix<int> at = A * tt;
        Matrix<int> bt = B * tt;
        if (!st.count(ta)) {
            st.insert(ta);
            q.push(ta);
        }
        if (!st.count(tb)) {
            st.insert(tb);
            q.push(tb);
        }
        if (!st.count(at)) {
            st.insert(at);
            q.push(at);
        if (!st.count(bt)) {
            st.insert(bt);
            q.push(bt);
        }
    cout << st.size() << endl;</pre>
}
int main() {
    search();
    return 0;
}
```

2.5 Exercise 5 (P33)

Reflexivity: $aa^{-1} \in S \Leftrightarrow e \in S$. Symmetry: $ab^{-1} \in S \to ba^{-1} \in S \Leftrightarrow \text{every}$ elements in S has an inverse. Transitivity: $ab^{-1} \in S \wedge bc^{-1} \in S \to ac^{-1} \in S$

 $S \Leftrightarrow \text{operation on } S \text{ is close.}$

2.6 Exercise 6 (P34)

name the subset as S. $\forall a \in S$, let $S_a = \{a^n | n \in Z\} \subset S$. then we could find that $(\exists n, m \in Z)a^n = a^m$ (because of finite). we could use this infomation to construct e and the inverse.

2.7 Exercise 7 (P34)

let $S=\{kn|k\in Z\}$. construct a homomorphism $f:S\to Z$ by letting f(x)=x/n. $f(xnyn)=\frac{xn}{n}\frac{yn}{n}=f(xn)f(yn)$.

1. f is a surjection.

2. $f(x) = f(y) \Rightarrow x/n = y/n \Rightarrow x = y$, so f is a injectoin.

so f is a bijection. so $S \cong Z$.