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# Integral decomposition of polyhedra and some applications in mixed integer programming

Received: May 22, 2000 / Accepted: March 19, 2002

Published online: December 19, 2002 - © Springer-Verlag 2002

**Abstract.** This paper addresses the question of decomposing an infinite family of rational polyhedra in an integer fashion. It is shown that there is a finite subset of this family that generates the entire family. Moreover, an integer analogue of Carathéodory's theorem carries over to this general setting. The integer decomposition of a family of polyhedra has some applications in integer and mixed integer programming, including a test set approach to mixed integer programming.

**Key words.** mixed integer programming – test sets – indecomposable polyhedra – Hilbert bases – rational polyhedral cones

#### 1. Introduction

This paper deals with the question of decomposing an infinite family of rational polyhedra that one associates with a fixed matrix and varying right hand side vectors into *irreducible* ones. This problem has been studied in various fields of geometry when the right hand side vectors are arbitrary vectors. Our object of investigation is in fact the *integral decomposition* of polyhedra. More precisely, given a fixed matrix and an infinite family of integral right hand side vectors, we are interested in a finite subset of this family of integral right hand sides that generate the entire family of polyhedra.

This extends naturally the result about the existence of a Hilbert basis for rational polyhedral cones. Here the family of polyhedra that one considers is just a family of points, i.e., a family of 0-dimensional polyhedra. Recall that the Hilbert basis of a rational polyhedral cone  $\mathcal{C}$  is a minimal finite generating set of the integral points in  $\mathcal{C}$  with respect to non-negative integral combinations. In other words, the Hilbert basis  $\mathcal{H}(\mathcal{C})$  consists of a minimal number of vectors  $h^1, \ldots, h^l \in \mathcal{C} \cap \mathbb{Z}^d \setminus \{0\}$  such that

$$C \cap \mathbb{Z}^d = \left\{ \lambda_1 h^1 + \lambda_2 h^2 + \dots + \lambda_l h^l : \lambda_i \in \mathbb{Z}_+, \ 1 \le i \le l \right\}.$$

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This work was supported partially by the DFG through grant WE1462, by the Kultusministerium of Sachsen Anhalt through the grants FKZ37KD0099 and FKZ 2945A/0028G and by the EU Donet project ERB FMRX-CT98-0202. The first named author acknowledges the hospitality of the International Erwin Schrödinger Institute for Mathematical Physics in Vienna, where a main part of his contribution to this work has been completed.

Mathematics Subject Classification (1991): 52C17, 11H31

The existence of a Hilbert basis follows from the classical lemma of Gordan [Go1873], and it was shown by van der Corput [Cor1931] that the Hilbert basis of a pointed cone  $\mathcal{C}$  is uniquely determined by the following characterization.

**Lemma 1.1.** (van der Corput). The Hilbert basis of a rational polyhedral pointed cone  $C \subset \mathbb{R}^n$  consists of all elements  $h \in C \cap \mathbb{Z}^n \setminus \{0\}$  which can not be written as  $h = z^1 + z^2$  for some  $z^i \in C \cap \mathbb{Z}^n \setminus \{0\}$ .

For further geometric and algorithmic properties of Hilbert bases we refer to [AWW00].

In the same vein it is shown in this paper that an integer analogue of Carathéodory's theorem that is known to hold for the integral points in a rational polyhedral cone carries over to the more general setting when one deals with families of polyhedra with integral right hand sides.

The question of decomposing such a family of polyhedra with integral right hand sides in an integer fashion has different applications in integer and mixed integer programming. In the sequel we will illuminate three such settings that we consider relevant. To this end, let  $A \in \mathbb{Z}^{m \times n}$  be an arbitrary, but fixed matrix, and for  $b \in \mathbb{Z}^m$  let

$$P_b = \{ x \in \mathbb{R}^n : Ax < b \}.$$

Furthermore, let  $\mathcal{L}$  denote a lattice in  $\mathbb{Z}^m$ .

**Application 1** addresses the question of whether there exists a finite certificate for testing that an infinite family of polyhedra with integral right hand sides is integral. Note that a rational polyhedron is called *integral* if each of its faces contains an integral point. Here we have the following result.

**Theorem 1.1.** There exists a finite subset  $\mathcal{F} \subseteq \mathcal{L}$  such that  $P_b$  is integral for all  $b \in \mathcal{L}$  if and only if  $P_b$  is integral for all  $b \in \mathcal{F}$ .

Theorem 1.1 follows immediately from the theory of integral decomposition of polyhedra that we will introduce in section 3.

**Application 2** extends the first application by considering totally dual integral systems of inequalities instead of integer polyhedra.

**Definition 1.1.** Let  $A \in \mathbb{Z}^{m \times n}$ ,  $b \in \mathbb{Z}^m$ . The system  $Ax \leq b$  of linear inequalities is called totally dual integral (TDI) if for every  $c \in \mathbb{Z}^m$  the minimum  $\min\{b^{\mathsf{T}}y : A^{\mathsf{T}}y = c, y \geq 0\}$  is attained at an integral vector, provided the minimum exists.

**Theorem 1.2.** There exists a finite subset  $\mathcal{F} \subseteq \mathcal{L}$  such that  $Ax \leq b$  is TDI for all  $b \in \mathcal{L}$  if and only if  $Ax \leq b$  is TDI for all  $b \in \mathcal{F}$ .

In this sense, Theorem 1.2 shows the existence of a a finite certificate for testing that an infinite family of systems of inequalities with integral right hand sides is TDI.

**Application 3** is directed towards the design of a primal approach for mixed integer programming. For integral matrices  $A \in \mathbb{Z}^{m \times d}$ ,  $B \in \mathbb{Z}^{m \times n}$  and integral vectors  $b \in \mathbb{Z}^m$ ,

 $\alpha \in \mathbb{Z}^d$  and  $\beta \in \mathbb{Z}^n$  the mixed integer linear programming problem (MIP) is the task to determine

$$\max \left\{ \alpha^{\mathsf{T}} x + \beta^{\mathsf{T}} y : A x + B y \le b, \ x \in \mathbb{Z}^d, \ y \in \mathbb{R}^n \right\}. \tag{1.1}$$

By a primal approach we mean an augmentation algorithm that, starting from any feasible point of the mixed integer program, moves through an improving direction to a new feasible point of the program as long as possible. In other words, such an algorithm repeatedly solves the following problem:

**Problem 1.1** (Augmentation Problem, AUG) Given vectors  $\alpha \in \mathbb{Z}^d$ ,  $\beta \in \mathbb{Z}^n$  and a feasible point  $(x, y) \in \mathbb{Z}^d \times \mathbb{R}^n$  for the mixed-integer program (1.1), find a vector  $(\tilde{x}, \tilde{y}) \in \mathbb{Z}^d \times \mathbb{R}^n$  such that  $\alpha^T \tilde{x} + \beta^T \tilde{y} > 0$  and  $(x + \tilde{x}, y + \tilde{y})$  is feasible, i.e.,  $(\tilde{x}, \tilde{y})$  is an *improving direction*, or assert that (x, y) is optimal.

One approach for solving (AUG) is to compute the family of improving directions for all feasible points beforehand. Of course, this set may not be finite, even for pure integer programs (i.e., in the case n=0). However, in the pure integer case, one can resort to a finite generating set for the family of all improving directions for an integer program. Such a finite set is commonly called a *test set*, since it serves as a *finite certificate* for testing optimality of a feasible point.

A particularly nice geometric way of defining a test set has been presented by Graver [Gra75].

**Definition 1.2.** For the family of integer programs of the form (1.1) with n = 0 associated with a fixed matrix A but varying data  $b \in \mathbb{Z}^m$ ,  $\alpha \in \mathbb{R}^d$ , the Graver test set  $\mathcal{G}(A)$  is defined as

$$\mathcal{G}(A) = \bigcup_{\varepsilon \in \{-1,1\}^m} \mathcal{H}(\left\{x \in \mathbb{R}^d : A_\varepsilon x \le 0\right\}),\tag{1.2}$$

where  $A_{\varepsilon} = Diag(\varepsilon)A$  arises from A by multiplying the i-th row with  $\varepsilon_i$ .

One purpose of this note is to present an analogous test set approach for mixed integer linear programming problems. Here, the situation is however more complicated, because a test set minimal with respect to inclusion may not be finite as the following trivial example demonstrates.

Example 1.1. We consider the mixed integer program

$$\begin{array}{llll} \max & x \\ \mathrm{s.\,t.} & x & + & y & \leq 1, \\ & -x & & \leq 0, \\ & & -y & \leq 0, \\ & x \in \mathbb{Z}, & y \in \mathbb{R}, \end{array}$$

whose feasible set consists of the points of the unit triangle with integral x coordinate, i.e., a single point  $(1,0)^T$  with objective value 1 and the points  $(0,y)^T$  for  $y \in [0,1]$  with objective value 0; see Figure 1. Every test set for (1.3) must contain all the vectors  $(1,-y)^T$  for  $y \in [0,1]$ .

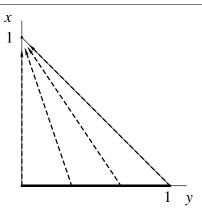


Fig. 1. A mixed integer linear program with an infinite minimal test set.

According to the survey [Hem00], there is an unpublished manuscript by Foroudi and Graver, where the notion of the Graver test set is extended to the case of mixed-integer programs. However, the resulting optimality certificate is no longer finite.

In this paper, we present a way to overcome the difficulty of dealing with infinite test sets by resorting to a *finite representation*. This can indeed be done by applying the methods that we introduce in the context of integral decompositions of rational polyhedra. We obtain the following result.

**Theorem 1.3.** There exists a finite set  $\mathcal{G}(A, B) \subset \{(x, \varepsilon, u)^{\mathsf{T}} : x \in \mathbb{Z}^d, \varepsilon \in \{-1, 1\}^m, u \in \mathbb{Z}^m \}$ , depending only on A and B, such that for each non optimal point  $(\overline{x}, \overline{y})^{\mathsf{T}} \in \{(x, y)^{\mathsf{T}} \in \mathbb{Z}^d \times \mathbb{R}^n : Ax + By \le b\}$  of (1.1) there exists a  $(\widetilde{x}, \varepsilon, u)^{\mathsf{T}} \in \mathcal{G}(A, B)$  and a vector  $\widetilde{y} \in P^{\varepsilon}_u$  satisfying

$$A(\overline{x} + \widetilde{x}) + B(\overline{y} + \widetilde{y}) \le b, \tag{1.4a}$$

$$\alpha^\intercal(\overline{x}+\widetilde{x})+\beta^\intercal(\overline{y}+\widetilde{y})>\alpha^\intercal\overline{x}+\beta^\intercal\overline{y}, \tag{1.4b}$$

where  $P_u^{\varepsilon} = \{ y \in \mathbb{R}^n : B_{\varepsilon} y \leq u \}$  and  $B_{\varepsilon} = Diag(\varepsilon)B$  is the matrix obtained from B by multiplying the i-th row with  $\varepsilon_i$ .

When the finite set  $\mathcal{G}(A, B)$  is computed, we can solve the augmentation problem simply by solving a number of linear-programming problems. This is formulated as Algorithm 1.1. For the sake of simplicity, we assume that the mixed integer program (1.1) has a finite optimal solution.

## Algorithm 1.1 (MIP Augmentation Algorithm)

- 1: *input* MIP (1.1),  $\mathcal{G}(A, B)$ , feasible point  $(\overline{x}, \overline{y})$ ;
- 2: **output** a vector  $(\widetilde{x}, \widetilde{y}) \in \mathbb{Z}^d \times \mathbb{R}^n$  such that  $(\overline{x} + \widetilde{x}, \overline{y} + \widetilde{y})$  is feasible and  $\alpha^{\mathsf{T}}(\overline{x} + \widetilde{x}) + \beta^{\mathsf{T}}(\overline{y} + \widetilde{y}) > \alpha^{\mathsf{T}}\overline{x} + \beta^{\mathsf{T}}\overline{y}$ , or assert that  $(\overline{x}, \overline{y})$  is an optimal solution to (1.1);
- 3: **for all**  $(\widetilde{x}, \varepsilon, u) \in \mathcal{G}(A, B)$  **do**
- *4: Solve the linear program*

$$\max \beta^{\mathsf{T}} \widetilde{y}$$
s. t.  $B \widetilde{y} \leq b - A (\overline{x} + \widetilde{x}) - B \overline{y},$  (1.5)
$$\widetilde{y} \in \mathbb{R}^{n};$$

- 5: **if** program (1.5) has an optimal solution  $\tilde{y}$  **then**
- 6: **if**  $\alpha^{\mathsf{T}}\widetilde{x} + \beta^{\mathsf{T}}\widetilde{y} > 0$  **then**
- 7: **return** the vector  $(\widetilde{x}, \widetilde{y})$ ;
- 8: return "optimal."

### **Lemma 1.2.** Algorithm 1.1 is correct.

*Proof.* Let  $(\overline{x}, \overline{y})$  be a feasible, non optimal point of the mixed integer program (1.1). By Theorem (1.3), there exists a  $(\widetilde{x}, \varepsilon, u)^{\mathsf{T}} \in \mathcal{G}(A, B)$  and a vector  $y' \in P_u^{\varepsilon}$  satisfying (1.4). Clearly y' is a feasible solution to the linear program (1.5). Let  $\widetilde{y}$  be an optimal solution to (1.5). Then  $(\overline{x} + \widetilde{x}, \overline{y} + \widetilde{y})$  is a feasible solution to (1.1), and we have

$$\alpha^{\mathsf{T}}\widetilde{x} + \beta^{\mathsf{T}}\widetilde{y} \ge \alpha^{\mathsf{T}}\widetilde{x} + \beta^{\mathsf{T}}y' > 0.$$

Therefore, Algorithm 1.1 returns a vector  $(\widetilde{x}, \widetilde{y})$  with the required properties.

On the other hand, if  $(\overline{x}, \overline{y})$  is optimal, none of the linear programs (1.5) solved during the course of the algorithm has an optimal solution  $(\widetilde{x}, \widetilde{y})$  such that  $\alpha^{\mathsf{T}}\widetilde{x} + \beta^{\mathsf{T}}\widetilde{y} > 0$ , and hence Algorithm 1.1 reports the optimality of  $(\overline{x}, \overline{y})$ .

Via Algorithm 1.1, the set  $\mathcal{G}(A, B)$  serves as a finite optimality certificate for feasible points of mixed-integer programs (1.1) with fixed matrices A and B and varying data  $\alpha$ ,  $\beta$ , and B.

In this paper, we first study the geometric concept of linear decomposability of polytopes (section 2). In section 3, we introduce an integral analogon of this concept. The results obtained there are applied to the three applications; proofs of the respective theorems are given in section 4.

## 2. Linear decomposition of polytopes

In the following let  $W \in \mathbb{Z}^{m \times n}$  be a fixed but arbitrary integral matrix with row vectors  $w^i \in \mathbb{Z}^n$ , 1 < i < m. We assume that

$$pos\{w^1,\ldots,w^m\} = \mathbb{R}^n,$$

where pos denotes the positive hull. Thus for every  $u \in \mathbb{R}^m$  the set  $P_u = \{ y \in \mathbb{R}^n : Wy \le u \}$  is a polytope. Now we are interested in the family of all non empty polytopes arising in this way and therefore we set

$$\mathcal{U}(W) = \left\{ u \in \mathbb{R}^m : P_u \neq \emptyset \right\}.$$

This set has been investigated by various authors in different contexts (cf. [Grü67, p. 316], [KLS90], [McM73], [Mey74], [Smi87] and the references within). It is not hard to see that the dual set

$$\mathcal{U}^*(W) = \{ s \in \mathbb{R}^m : s^{\mathsf{T}}u \ge 0, \text{ for all } u \in \mathcal{U}(W) \}$$

is given by

$$\mathcal{U}^*(W) = \{ s \in \mathbb{R}^m : W^{\mathsf{T}} s = 0 \text{ and } s \ge 0 \}.$$

This shows, in particular, that  $\mathcal{U}(W)$  is a rational polyhedral m-dimensional cone. Since we do not want to distinguish between a polytope  $P_u$  and its translate  $t + P_u = P_{u+Wt}$  for  $t \in \mathbb{R}^n$ , we choose as a representative of each equivalence class  $P_{u+Wt}$ ,  $t \in \mathbb{R}^n$ , the right hand side  $\tilde{u}$  satisfying  $W^T\tilde{u} = 0$ . In other words,  $\tilde{u}$  is the orthogonal projection of u onto the orthogonal complement of the space  $W\mathbb{R}^n$ . Hence

$$\widetilde{\mathcal{U}}(W) = \left\{ u \in \mathbb{R}^m : P_u \neq \emptyset \text{ and } W^\mathsf{T} u = 0 \right\}$$

is a rational polyhedral (m-n)-dimensional cone and we have that  $\mathcal{U}W$  is the orthogonal sum

$$\mathcal{U}(W) = \widetilde{\mathcal{U}}(W) \oplus W\mathbb{R}^n.$$

Since the maximal linear subspace of  $\mathcal{U}(W)$  consists of the space  $W\mathbb{R}^n$  the cone  $\widetilde{\mathcal{U}}(W)$  is even pointed. Moreover, the dual cone  $\widetilde{\mathcal{U}}^*(W)$  of  $\widetilde{\mathcal{U}}(W)$  w.r.t. the subspace  $\{s\in\mathbb{R}^m:W^\intercal s=0\}$  reads

$$\widetilde{\mathcal{U}}^*(W) = \left\{ s \in \mathbb{R}^m : s^{\mathsf{T}} u \ge 0 \text{ for all } u \in \widetilde{\mathcal{U}}(W), \ W^{\mathsf{T}} s = 0 \right\}.$$

This shows that  $\widetilde{\mathcal{U}}^*(W)$  coincides with  $\mathcal{U}^*(W)$ . By the primal-dual relationship we obtain the following characterization of the facets of  $\widetilde{\mathcal{U}}(W)$ .

Remark 2.1. For  $s \in \widetilde{\mathcal{U}}^*(W)$  let  $W_s$  be the matrix consisting of all rows  $w^i$  with  $s_i > 0$  and let  $r_s$  be the number of rows of  $W_s$ . Then the outer normal vector of the facets of  $\widetilde{\mathcal{U}}(W)$  are given by  $\{s \in \widetilde{\mathcal{U}}^*(W) : \operatorname{rank}(W_s) = r_s - 1\}$ .

As a side note, let us mention that there is also a nice geometrical meaning of the outer normal vectors of the facets of  $\widetilde{\mathcal{U}}(W)$ :

Remark 2.2. Via the so called Minkowski's existence theorem of polytopes [Mi1897] one can assign to each outer normal vector s a ( $\#W_s-1$ )-dimensional unique (up to dilations) simplex such that each polytope  $P_u$  for  $u \in \widetilde{\mathcal{U}}(W)$  can be written as the Blaschke sum of at most m-n of those simplices; see [Grü67, p. 331].

In this paper, however, we deal with another interesting aspect of  $\widetilde{\mathcal{U}}(W)$ , which arises from the study of *homothetically (in)decomposable* polytopes. In the following, we denote by  $P_1 + P_2$  the usual Minkowski sum of two sets  $P_1$ ,  $P_2$ .

**Definition 2.1.** (a) Two polytopes  $P_1$ ,  $P_2 \subset \mathbb{R}^n$  are called homothetic if  $P_1 = \rho P_2 + t$  for some  $t \in \mathbb{R}^n$  and  $\rho > 0$ .

- (b) A polytope  $P \subset \mathbb{R}^n$  is called (homothetically) decomposable if two polytopes  $P_1$  and  $P_2$  exist with  $P = P_1 + P_2$ , where  $P_i$  is not homothetic to P for  $i \in \{1, 2\}$ . Otherwise P is (homothetically) indecomposable.
- (c) A polytope  $P_1$  is called a summand of a polytope P (denoted as  $P_1 \prec P$ ) if there exist a scalar  $\rho > 0$  and a polytope  $P_2$  such that  $P = \rho P_1 + P_2$ .

Observe that, in this general setting, every point is indecomposable.

Example 2.1. Let us consider the polytope  $P_u = \{x \in \mathbb{R}^2 : Wx \leq u\}$ , where

$$W = \begin{pmatrix} 2 & 1 \\ 1 & 2 \\ 1 & 1 \\ -1 & 0 \\ 0 & -1 \end{pmatrix} \quad \text{and} \quad u = \begin{pmatrix} 4 \\ 4 \\ 5 \\ 0 \\ 0 \end{pmatrix}.$$

The polytope  $P_u$  and the constraints corresponding to the rows of W are shown in Figure 2(a).  $P_u$  is the Minkowski sum of the polytopes  $P_1$  and  $P_2$ , which are clearly not homothetic to  $P_u$ ; see Figure 2(c, d). Note that we have a representation  $P_i = P_{u^i}$  for  $i \in \{1, 2\}$ , where  $u^1 = (\frac{4}{3}, \frac{8}{3}, \frac{2}{3}, 0, 0)^{\mathsf{T}}$  and  $u^2 = (\frac{8}{3}, \frac{4}{3}, \frac{2}{3}, 0, 0)^{\mathsf{T}}$ .

In fact, this holds in general: For a polytope  $P_u, u \in \mathcal{U}(W)$ , each summand admits a representation as  $P_v$  for a certain  $v \in \mathcal{U}(W)$ . Again, since we may neglect translations, the polytope  $P_u, u \in \widetilde{\mathcal{U}}(W)$ , is decomposable if and only if there exist  $u^1, u^2 \in \widetilde{\mathcal{U}}(W)$  such that  $P_u = P_{u^1} + P_{u^2}$  and  $P_{u^i}, i = 1, 2$ , are not homothetic to  $P_u$ . In fact, one can even establish a stronger relation to the cone  $\widetilde{\mathcal{U}}(W)$ . To this end we denote for  $u \in \mathcal{U}(W)$  by  $\eta(u) \in \mathcal{U}(W)$  the *support vector* of the polytope  $P_u$ , i.e.,

$$\eta(u)_i = \max\left\{ (w^i)^\mathsf{T} y : y \in P_u \right\}, \quad 1 \le i \le m.$$

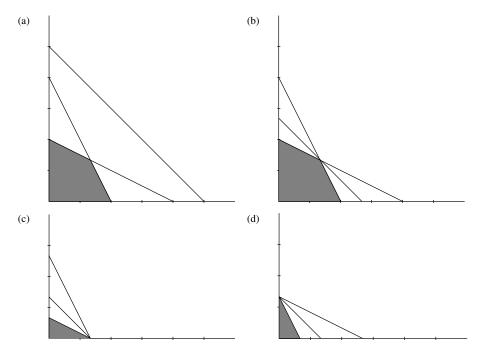


Fig. 2. A decomposable polytope and its summands. (a) The polytope  $P_u$  from Example 2.1 and the constraints  $Wx \le u$ ; (b) the constraints  $Wx \le \eta(u)$  corresponding to the support vector of  $P_u$ ; (c, d) two summands  $P_1$ ,  $P_2$  of  $P_u$  with  $P_u = P_1 + P_2$ .

In other words,  $\eta(u)$  is the componentwise least right hand side which yields the same polytope,  $P_u = P_{\eta(u)}$ . Figure 2 (a, b) illustrates the move from u to the support vector  $\eta(u) = (4, 4, \frac{4}{3}, 0, 0)^{\mathsf{T}}$ . One can show that (cf. e.g. [Grü67])

$$P_u = P_{u^1} + P_{u^2} \Leftrightarrow \eta(u) = \eta(u^1) + \eta(u^2) \text{ and } P_{u^1}, P_{u^2} \prec P_u.$$
 (2.1)

Note that in Example 2.1, the vectors  $u^1$  and  $u^2$  have been chosen such that  $u^i = \eta(u^i)$  for  $i \in \{1, 2\}$ ; see Figure 2 (c, d). Indeed, one can verify that  $\eta(u^1) + \eta(u^2) = \eta(u)$  holds.

Furthermore, it follows from works of McMullen [McM73] and Meyer [Mey74] that  $\widetilde{\mathcal{U}}(W)_u = \{ \eta(v) : v \in \widetilde{\mathcal{U}}(W) \text{ with } P_v \prec P_u \}$  is a rational polyhedral subcone of  $\widetilde{\mathcal{U}}(W)$ , where the extreme rays of  $\widetilde{\mathcal{U}}(W)_u$  correspond to indecomposable polytopes. As a nice consequence of this construction we get by Carathéodory's theorem and (2.1)

**Theorem 2.1** (McMullen, Meyer). Every polytope  $P_u$ ,  $u \in \widetilde{\mathcal{U}}(W)$ , can be written as the Minkowski sum of at most m-n indecomposable polytopes.

*Remark 2.3.* Depending on certain affine dependencies of the rows of the matrix *W* one can give stronger bounds; cf. [Mey74], [McM73], [Smi87].

The relative interior of this cone  $\widetilde{\mathcal{U}}(W)_u$  consists of all polytopes  $P_v$  which are strongly combinatorially equivalent to  $P_u$ . Recall that two polytopes  $P, Q \subset \mathbb{R}^n$  are called *strongly combinatorially equivalent* if for all  $v \in \mathbb{R}^n$  holds:

$$\begin{split} \dim\left(\left\{\,y\in P:v^{\mathsf{T}}y=\max\{\,v^{\mathsf{T}}y:y\in P\,\}\,\right\}\right)\\ &=\dim\left(\left\{\,y\in Q:v^{\mathsf{T}}y=\max\{\,v^{\mathsf{T}}y:y\in Q\,\}\,\right\}\right). \end{split}$$

Since the cone  $\widetilde{\mathcal{U}}(W)$  possesses only finitely many strongly combinatorially non equivalent polytopes we can extend Theorem 2.1 to the cone  $\mathcal{U}(W)$ .

**Corollary 2.1.** There exist finitely many vectors  $u^1, \ldots, u^k \in \mathcal{U}(W)$ , corresponding to indecomposable polytopes, such that each polytope  $P_u$ ,  $u \in \mathcal{U}(W)$ , can be written as a non-negative linear combination of at most m of the polytopes  $P_{u^i}$ .

*Proof.* By the foregoing remarks and Theorem 2.1 we know that there exist finitely many  $u^1,\ldots,u^l\in\widetilde{\mathcal{U}}(W)$ , corresponding to indecomposable polytopes, such that for each  $\tilde{u}\in\widetilde{\mathcal{U}}(W)$  the polytope  $P_{\tilde{u}}$  can be written as a non-negative linear combination of at most (m-n) polytopes  $P_{u^i}, i\in\{1,\ldots,l\}$ . Let us select  $u^{l+1},\ldots,u^{l+n+1}\in W\mathbb{R}^n$  such that  $\operatorname{pos}\{u^{l+1},\ldots,u^{l+n+1}\}=W\mathbb{R}^n$ . Obviously,  $P_{u^{l+i}}$  is indecomposable. Let  $u\in\mathcal{U}(W)$  and let  $\tilde{u}\in\widetilde{\mathcal{U}}(W)$  be its orthogonal projection onto the orthogonal complement of  $W\mathbb{R}^n$ . Then there exist non-negative scalars  $\lambda_i$  such that  $u-\tilde{u}=\lambda_1u^{l+1}+\cdots+\lambda_{n+1}u^{l+n+1}$ , where at least one  $\lambda_i$  vanishes. We have  $P_u=P_{\tilde{u}}+\lambda_1P_{u^{l+1}}+\cdots+\lambda_{n+1}P_{u^{l+n+1}}$  and hence the vectors  $u^1,\ldots,u^{l+n+1}$  have the desired property.

In this sense one may regard the vectors  $u^i$  from the corollary above as a *minimal* generating system of  $\mathcal{U}(W)$  (or of all polytopes  $P_u$ ,  $u \in \mathcal{U}(W)$ ).

## 3. Integral decomposition of polytopes

Here we want to study an analogous relation for polytopes  $P_u$  with an integral right hand side, i.e.,  $u \in \mathcal{U}(W) \cap \mathbb{Z}^m$ , and with respect to non-negative integral combinations. To this end we need one more result on Hilbert bases of rational polyhedral pointed cones that we will refer to as the *weak integer Carathéodory property*.

**Theorem 3.1** (Sebö, [Seb90]). Each integral vector of a rational polyhedral pointed cone  $C \subset \mathbb{R}^n$  can be written as a non-negative integral combination of at most 2n-2 elements of its Hilbert basis  $\mathcal{H}(C)$ .

Moreover, it was also shown by Sebö that in the 3-dimensional case 3 elements of the Hilbert basis are sufficient. However, there does not exist a strong integral counterpart to Carathéodory's theorem since, in general, one needs more elements of the Hilbert basis than the dimension of the cone [B-W99]. In order to establish an analogous statement to Corollary 2.1 we need to express precisely what we mean by the integral decomposition of a polytope  $P_z$ ,  $z \in \mathcal{U}(W) \cap \mathbb{Z}^m$ .

First we note that the literature provides a notion of "integral decomposability," which deals with *integral polyhedra* only, cf. [GL01]. In our application to test sets, however, also non integral polyhedra will arise (like  $P_u$  in Example 2.1), so a more general notion is required. We define:

**Definition 3.1.** A polytope  $P_z$ ,  $z \in \mathcal{U}(W) \cap \mathbb{Z}^m$ , is called integrally decomposable if there exist  $P_{z^1}$ ,  $P_{z^2}$  not homothetic to  $P_z$  such that  $P_z = P_{z^1} + P_{z^2}$  and  $z = z^1 + z^2$ ,  $z^i \in \mathcal{U}(W) \cap \mathbb{Z}^m$ . Otherwise  $P_z$  is called integrally indecomposable.

Observe that this definition does not depend on the polytope only but also on the right hand side, i.e., on the *representation* of the polytope. It may indeed happen that for some  $z, z' \in \mathcal{U}(W) \cap \mathbb{Z}^m$  the polytopes  $P_z$  and  $P_{z'}$  coincide, although  $P_z$  is decomposable, whereas  $P_{z'}$  is indecomposable.

Example 3.1. We consider the same polytope as in Example 2.1, represented as both  $P_z$  and  $P_{z'}$ , where

$$W = \begin{pmatrix} 6 & 3 \\ 3 & 6 \\ 1 & 2 \\ -1 & 0 \\ 0 & -1 \end{pmatrix} \quad \text{and} \quad z = \begin{pmatrix} 12 \\ 12 \\ 5 \\ 0 \\ 0 \end{pmatrix} \quad \text{and} \quad z' = \begin{pmatrix} 12 \\ 12 \\ 4 \\ 0 \\ 0 \end{pmatrix}.$$

Then  $P_z$  is integrally decomposable into summands  $P_{z^1}$  and  $P_{z^2}$ , where  $z^1 = (4, 8, 3, 0, 0)^T$  and  $z^2 = (8, 4, 2, 0, 0)^T$ , whereas  $P_{z'}$  is integrally indecomposable.

Of course, the reason lies in the representation of redundant facets. These do not play any role in the non integral case, since we may always fix the representation of the polytope via the support vector. If we restrict our attention to polytopes  $P_z$ ,  $z \in \mathcal{U}(W) \cap \mathbb{Z}^m$ , with integral support vectors, then we have the following

**Theorem 3.2.** There exist finitely many vectors  $h^i \in \mathcal{U}(W) \cap \mathbb{Z}^m$ , corresponding to integrally indecomposable polytopes, such that for each polytope  $P_z$ ,  $z \in \mathcal{U}(W) \cap \mathbb{Z}^m$ , with  $\eta(z) = z$  there exist  $h^{j_1}, \ldots, h^{j_{2m-2-n}}$  and non-negative integers  $\lambda_{j_1}, \ldots, \lambda_{j_{2m-2-n}}$  with

$$P_z = \sum_{i=1}^{2m-2-n} \lambda_{j_i} P_{h^{j_i}}$$
 and  $z = \sum_{i=1}^{2m-2-n} \lambda_{j_i} h^{j_i}$ .

Before giving the proof we fix some notation. Let  $\overline{w}^1, \ldots, \overline{w}^m$  be a basis of the lattice  $\mathbb{Z}^m$  such that  $\overline{w}^1, \ldots, \overline{w}^n$  build a basis of the sublattice  $W\mathbb{Z}^n \cap \mathbb{Z}^m$ . Then for each  $u \in \mathcal{U}$ ,  $u = \sum_{i=1}^m \lambda_i \overline{w}^i$ , let  $\overline{u}$  be the vector given by  $\overline{u} = \sum_{i=n+1}^m \lambda_i \overline{w}^i$  and let  $\overline{W} \in \mathbb{Z}^{m \times n}$  be the matrix with column vectors  $\overline{w}^i$ ,  $1 \le i \le n$ . We define

$$\overline{\mathcal{U}}(W) = \{ \overline{u} : u \in \mathcal{U}(W) \}. \tag{3.1}$$

 $\overline{\mathcal{U}}(W)$  is a rational polyhedral pointed (m-n)-dimensional cone. In particular, we have

$$(\overline{\mathcal{U}}(W) \cap \mathbb{Z}^m) + \overline{W}\mathbb{Z}^n = \mathcal{U}(W) \cap \mathbb{Z}^m,$$

and  $P_u = P_{\overline{u}} + t$ , for some rational vector t. We are now ready for the proof of Theorem 3.2.

*Proof of Theorem 3.2.* Let  $z \in \mathcal{U}(W) \cap \mathbb{Z}^m$  with  $\eta(z) = z$  and thus  $\overline{z} = \eta(\overline{z}) \in \mathbb{Z}^m$ . As in the general case we consider the cone

$$\overline{\mathcal{U}}(W)_z = \{\overline{\eta(v)} : v \in \mathcal{U}(W) \text{ and } P_v \prec P_z \}.$$

 $\overline{\mathcal{U}}(W)_z$  is a rational polyhedral pointed cone. Therefore, it possesses a unique Hilbert basis that we denote by  $h^1,\ldots,h^k$ . First we claim, that the polytopes  $P_{h^i}$  are integrally indecomposable. For if not, then there exist  $z^1, z^2 \in \mathcal{U}(W) \cap \mathbb{Z}^m \setminus \{0\}$  such that  $P_{h^i} = P_{z^1} + P_{z^2}$  and  $h^i = z^1 + z^2$ . This yields (see (2.1))

$$z^{1} + z^{2} = h^{i} = \eta(h^{i}) = \eta(z^{1}) + \eta(z^{2}) \le z^{1} + z^{2}.$$

In other words,  $\eta(z^1)=z^1$  and  $\eta(z^2)=z^2$ . Thus  $z^1,z^2$  belong to the cone  $\overline{\mathcal{U}}(W)_z$ . This contradicts the definition of a Hilbert basis, cf. Theorem 1.1. On account of (2.1) and Theorem 3.1, there exist  $h^{ji}$  and non-negative integers  $\lambda_{ji}$ ,  $1 \le i \le 2(m-n)-2$ , such that

$$P_{\overline{z}} = \sum_{i=1}^{2m-2-2n} \lambda_{j_i} P_{h^{j_i}}$$
 and  $\overline{z} = \sum_{i=1}^{2m-2-2n} \lambda_{j_i} h^{j_i}$ .

Finally, we note that  $z-\overline{z}$  can be written as a non-negative integral combination of at most n vectors from the set  $\overline{w}^1,\ldots,\overline{w}^n,-(\overline{w}^1+\cdots+\overline{w}^n)$ . As mentioned before, the relative interior points of the cone  $\overline{\mathcal{U}}(W)_z$  correspond to polytopes which are strongly combinatorially equivalent to  $P_z$  and since there are only finitely many strongly combinatorially non equivalent polytopes  $P_u,u\in\mathcal{U}(W)$ , we are done.

In the general case we are not aware of a nice geometric description of a family of indecomposable polytopes such that each polytope can be written as a non negative integral combination of a *fixed number* of polytopes. However, a finite *generating system* for all  $P_z$ ,  $z \in \mathcal{U}(W) \cap \mathbb{Z}^m$ , with the weak integer Carathéodory property can always be constructed.

**Theorem 3.3.** There exist finitely many vectors  $h^1, \ldots, h^k \in \mathcal{U}(W) \cap \mathbb{Z}^m$  such that for each polytope  $P_z$ ,  $z \in \mathcal{U}(W) \cap \mathbb{Z}^m$ , there exist  $h^{j_1}, \ldots, h^{j_{2m-2-n}}$  and non-negative integers  $\lambda_{j_1}, \ldots, \lambda_{j_{2m-2-n}}$  such that

$$P_z = \sum_{i=1}^{2m-2-n} \lambda_{j_i} P_{h^{j_i}}$$
 and  $z = \sum_{i=1}^{2m-2-n} \lambda_{j_i} h^{j_i}$ .

*Proof.* For an index set  $I = \{i_1, \ldots, i_n\}$  corresponding to linearly independent row vectors  $w^{i_1}, \ldots, w^{i_n}$  of the matrix W, let  $W_I$  be the regular submatrix consisting of these rows and let  $\Pi_I$  be the matrix representing the projection of an m-dimensional vector b onto its coordinates  $b_{i_1}, \ldots, b_{i_n}$ . Let  $I_1, \ldots, I_k$  be all possible index sets of this type and let

$$M = \left( W (W_{I_1})^{-1} \Pi_{I_1} - E_m, \dots, W (W_{I_k})^{-1} \Pi_{I_k} - E_m \right)^{\mathsf{T}} \in \mathbb{R}^{k \, m \times m},$$

where  $E_m$  is the  $m \times m$  identity matrix. Let  $\overline{\mathcal{U}}(W)$  be the cone constructed in (3.1) and for a given orthant  $\mathcal{O}$  in  $\mathbb{R}^{k\,m}$  let

$$\overline{\mathcal{U}}(W)_{\mathcal{O}} = \{ \overline{z} \in \overline{\mathcal{U}}(W) : M\overline{z} \in \mathcal{O} \}.$$

 $\overline{\mathcal{U}}(W)_{\mathcal{O}}$  is a rational polyhedral pointed cone of dimension at most m-n. Next we claim,

$$P_{\overline{z}^1} + P_{\overline{z}^2} = P_{\overline{z}^1 + \overline{z}^2}, \quad \text{for } z^1, z^2 \in \overline{\mathcal{U}}(W)_{\mathcal{O}}. \tag{3.2}$$

To this end let  $\mathcal{I}_i$  be the set of all index sets I satisfying

$$W(W_I)^{-1}\Pi_I\overline{z}^i-\overline{z}^i\leq 0,$$

and for an arbitrary index set let  $v_i^I = (W_I)^{-1} \Pi_I \overline{z}^i$ , i = 1, 2. In particular we have

$$P_{\overline{z}^i} = \operatorname{conv}\left\{v_i^I : I \in \mathcal{I}_i\right\}.$$

Let I be an index set such that  $v^I=(W_I)^{-1}\Pi_I(\overline{z}^1+\overline{z}^2)$  is a vertex of the polytope  $P_{\overline{z}^1+\overline{z}^2}$ . Of course, we have  $v^I=v^I_1+v^I_2$  and since the vectors  $W(v^I_1),\,W(v^I_2)$  lie in the same orthant  $\mathcal O$  we get  $I\in\mathcal I_1\cap\mathcal I_2$ . Thus

$$P_{\overline{z}^1 + \overline{z}^2} = \text{conv}\{v_1^I + v_2^I : I \in \mathcal{I}_1 \cap \mathcal{I}_2\} \subset P_{\overline{z}^1} + P_{\overline{z}^2} \subset P_{\overline{z}^1 + \overline{z}^2},$$

which shows (3.2).

Now let  $h^1, \ldots, h^l$  be the Hilbert basis of the cone  $\overline{\mathcal{U}}(W)_{\mathcal{O}}$ . Then by Theorem 3.1 and (3.2) we know that each  $P_{\overline{z}}$  for  $\overline{z} \in \overline{\mathcal{U}}(W)_{\mathcal{O}}$  can be written as a non negative integral

combination of at most 2(m-n)-2 polytopes of the form  $P_{h^i}$  and the corresponding right hand sides sum up. Finally, let  $h^1,\ldots,h^k$  be the union of all Hilbert bases with respect to all orthants. Then these vectors form a generating system satisfying the requirements of the theorem for all  $z\in \overline{\mathcal{U}}(W)\cap \mathbb{Z}^m$ . Finally, as in the proof of Corollary 3.2, we may conclude that  $h^1,\ldots,h^k,\overline{w}^1,\ldots,\overline{w}^n,-(\overline{w}^1+\cdots+\overline{w}^n)$  have the desired property for all  $z\in \mathcal{U}(W)\cap \mathbb{Z}^m$ .

Next we want to consider a slight variant of the above problem. To this end let  $W \in \mathbb{Z}^{m \times n}$  as above and let  $\mathcal{L} \subset \mathbb{Z}^m$  be a lattice. Then we are interested in the set

$$\mathcal{U}(\mathcal{L}, W) = \{ l \in \mathcal{L} : P_l \neq \emptyset \}. \tag{3.3}$$

In other words we restrict the class of all possible right hand sides to a sublattice. It is not hard to see that also in this case we can easily find via the methods described in the proof of Theorem 3.3 a finite generating system. More precisely we have

Remark 3.1. There exists a finite set of lattice points  $\mathcal{H}(\mathcal{L}, W) \subset \mathcal{U}(\mathcal{L}, W)$  such that for each  $l \in \mathcal{U}(\mathcal{L}, W)$  there exist at most 2m - 2 - n elements  $h^1, \ldots, h^k \in \mathcal{H}(\mathcal{L}, W)$  and positive integers  $\lambda_1, \ldots, \lambda_k$  such that

$$P_l = \lambda_1 P_{h^1} + \dots + \lambda_k P_{h^k}$$
 and  $l = \lambda_1 h^1 + \dots + \lambda_k h^k$ .

#### 4. Proofs of the Theorems

The proof of Theorem 1.1 is an immediate consequence of the previous section.

*Proof of Theorem 1.1.* Let  $\mathcal{H}(\mathcal{L}, W)$  as in Remark 3.1. Then we obviously have that  $P_l$  is integral for all  $l \in \mathcal{L}$  if and only if  $P_h$  is integral for all  $h \in \mathcal{H}(\mathcal{L}, W)$ .

For the proof of Theorem 1.2 we need a well-known characterization of TDI-systems due to Giles and Pulleyblank [GP79].

**Theorem 4.1.** Let  $A \in \mathbb{Z}^{m \times n}$  and  $b \in \mathbb{Z}^m$ . The system  $Ax \leq b$  is TDI if and only if for every minimal face of  $P_b$  the set of row vectors that are tight at this face determine a Hilbert basis of the cone that they generate.

*Proof of Theorem 1.2.* Theorem 4.1 implies that for two strongly combinatorially equivalent polytopes  $P_{l^1}$  and  $P_{l^2}$ ,  $l^i \in \mathbb{Z}^m \cap \mathcal{L}$ , it holds, that  $P_{l^1}$  is TDI if and only if  $P_{l^2}$  is TDI. Since there are only finitely many strongly combinatorially non equivalent polytopes of the type  $P_l$ ,  $l \in \mathcal{L}$ , we have a finite certificate to test whether all polytopes  $P_l$ ,  $l \in \mathcal{L}$ , are TDI.

Now we come to the proof of the main theorem. We consider the mixed integer linear program as described in (1.1). Let  $a^1, \ldots, a^m$  and  $b^1, \ldots, b^m$  be the row vectors of the matrix A and B. For  $\varepsilon \in \{-1, 1\}^m$  let  $A_{\varepsilon}$  and  $B_{\varepsilon}$  be the matrices with row vectors  $\varepsilon_1 a^1, \ldots, \varepsilon_m a^m$  and  $\varepsilon_1 b^1, \ldots, \varepsilon_m b^m$ , respectively. We may assume that  $\operatorname{rank}(A) = d$  by replacing the columns of A with a basis for the lattice  $A\mathbb{Z}^d$ .

*Proof of Theorem 1.3.* For each  $\varepsilon \in \{-1, 1\}^m$  let

$$\bar{A}_{-\varepsilon} = \begin{pmatrix} A_{-\varepsilon} \\ -E_n \\ E_n \end{pmatrix} \quad \text{and} \quad \bar{B}_{\varepsilon} = \begin{pmatrix} B_{\varepsilon} \\ -E_n \\ E_n \end{pmatrix},$$

where  $E_n$  is the  $n \times n$  identity matrix, and let  $\mathcal{H}(\bar{A}_{-\varepsilon}, \bar{B}_{\varepsilon}) \subset \mathbb{Z}^d$  be a finite generating set of all non empty polytopes of the form

$$P_{\bar{A}_{-\varepsilon}(x,\mathfrak{l},\mathfrak{u})^{\mathsf{T}}}^{\varepsilon} = \{ y \in \mathbb{R}^{n} : \bar{B}_{\varepsilon}y \leq \bar{A}_{-\varepsilon}(x,\mathfrak{l},\mathfrak{u})^{\mathsf{T}} \}$$
$$= \{ y \in \mathbb{R}^{n} : B_{\varepsilon}y \leq A_{-\varepsilon}x, \, \mathfrak{l} \leq y \leq \mathfrak{u} \}$$

for arbitrary  $x \in \mathbb{Z}^d$  and lower and upper bounds  $\mathfrak{l}$ ,  $\mathfrak{u} \in \mathbb{Z}^n$  as defined in Remark 3.1. Note that  $P^{\varepsilon}_{\bar{A}_{-\varepsilon}(x,\mathfrak{l},\mathfrak{u})^{\mathsf{T}}} \subset P^{\varepsilon}_{A_{-\varepsilon}x}$  for all  $\mathfrak{l}$ ,  $\mathfrak{u} \in \mathbb{Z}^n$ , where  $P^{\varepsilon}_{A_{-\varepsilon}x}$  is the polyhedron defined in Theorem 1.3. Finally we set

$$\mathcal{G}(A,B) = \bigcup_{\varepsilon \in \{-1,1\}^m} \left\{ (x,\varepsilon,u) : x \in \mathcal{H}(\bar{A}_{-\varepsilon},\bar{B}_{\varepsilon}), u = A_{-\varepsilon}x \right\}$$

and claim that this set has the properties required in the theorem. To this end, let  $(\bar{x}, \bar{y})^T$  be a feasible but non-optimal solution of the mixed-integer program (1.1) and let  $(x^*, y^*)^T$  be an optimal solution of the problem. Now let  $I_1, I_2$  be a partition of the indices  $\{1, \ldots, m\}$  such that

$$(a^{i})^{\mathsf{T}}\bar{x} + (b^{i})^{\mathsf{T}}\bar{y} \le (a^{i})^{\mathsf{T}}x^{*} + (b^{i})^{\mathsf{T}}y^{*}, \quad i \in I_{1},$$
  
 $(a^{i})^{\mathsf{T}}\bar{x} + (b^{i})^{\mathsf{T}}\bar{y} \ge (a^{i})^{\mathsf{T}}x^{*} + (b^{i})^{\mathsf{T}}y^{*}, \quad i \in I_{2}.$ 

Define  $\varepsilon \in \{-1, 1\}^m$  according to  $\varepsilon_i = -1$  for  $i \in I_1$  and  $\varepsilon_i = 1$  for  $i \in I_2$ . Then we have

$$B_{\varepsilon}(y^* - \bar{y}) \le A_{-\varepsilon}(x^* - \bar{x})$$

and thus  $(x^* - \bar{x}, \ell, \mathfrak{u})^{\mathsf{T}} \in \mathcal{U}(\bar{A}_{-\varepsilon}, \bar{B}_{\varepsilon})$  for some  $\ell, \mathfrak{u} \in \mathbb{Z}^n$ . Hence there exist some  $(g^1, \ell^1, \mathfrak{u}^1)^{\mathsf{T}}, \dots, (g^k, \ell^k, \mathfrak{u}^k) \in \mathcal{H}(\bar{A}_{-\varepsilon}, \bar{B}_{\varepsilon})$  and positive integers  $\lambda_1, \dots, \lambda_k$  such that

$$\begin{pmatrix} x^* - \bar{x} \\ \mathfrak{l} \\ \mathfrak{u} \end{pmatrix} = \sum_{j=1}^k \lambda_i \begin{pmatrix} g^j \\ \mathfrak{l}^j \\ \mathfrak{u}^j \end{pmatrix} \quad \text{and} \quad P^{\varepsilon}_{\bar{A}_{-\varepsilon}(x^* - \bar{x}, \mathfrak{l}, \mathfrak{u})^{\mathsf{T}}} = \sum_{j=1}^k \lambda_j P^{\varepsilon}_{\bar{A}_{-\varepsilon}(g^j, \mathfrak{l}^j, \mathfrak{u}^j)^{\mathsf{T}}}.$$

Thus there exist  $y^j \in P_{A-\varepsilon g^j}^{\varepsilon}$  such that

$$\begin{pmatrix} x^* - \bar{x} \\ y^* - \bar{y} \end{pmatrix} = \sum_{j=1}^k \lambda_j \begin{pmatrix} g^j \\ y^j \end{pmatrix}.$$

Now we show that for each  $j \in \{1, ..., k\}$  the vector  $(\bar{x} + g^j, \bar{y} + y^j)$  is feasible. For  $i \in \{1, ..., m\}$  we have

$$b_i \ge (a^i, b^i) \begin{pmatrix} x^* \\ y^* \end{pmatrix} = (a^i, b^i) \begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} + \sum_{i=1}^k \lambda_j (a^i, b^i) \begin{pmatrix} g^j \\ y^j \end{pmatrix}. \tag{4.1}$$

By definition we have

$$(a^i, b^i) \begin{pmatrix} g^j \\ y^j \end{pmatrix} \ge 0$$
 for  $i \in I_1$  and  $(a^i, b^i) \begin{pmatrix} g^j \\ y^j \end{pmatrix} \le 0$  for  $i \in I_2$ .

Since all the scalars in (4.1) are positive, every vector  $(\bar{x}+g^j, \bar{y}+y^j)$  for  $j \in \{1, \ldots, k\}$  is feasible. Finally we observe that  $\alpha^{\mathsf{T}} x^* + \beta^{\mathsf{T}} y^* > \alpha^{\mathsf{T}} \bar{x} + \beta^{\mathsf{T}} \bar{y}$ . Thus there exists at least one index j such that

$$\alpha^{\mathsf{T}} g^j + \beta^{\mathsf{T}} y^j > 0.$$

This finally shows that the vector  $(g^j, y^j)^T$  is both applicable at  $(\bar{x}, \bar{y})^T$  and improving.  $\Box$ 

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