

# On second-order conditions in unconstrained optimization

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**Abstract** The main purpose of this paper is to establish the second-order nonsmooth sufficient unconstrained optimality condition for so called  $\ell$ -stable at some point functions and in this way to generalize some previous results in this direction. We provide the comparisons with other results by examples.

**Keywords** Locally Lipschitz function · Regular function ·  $C^{1,1}$  function · Peano derivative · Stable function · Isolated minimizer of order  $k$  · Dini derivative

**Mathematics Subject Classification (2000)** 49K10 · 26B05

## 1 Introduction and preliminaries

Second-order optimality conditions play a crucial role in optimization theory. In particular, they are very useful for the study of sensitivity analysis of optimal solutions and convergence analysis of optimal algorithms. For more details

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concerning wide range of applications, see e.g. [5, 7, 11, 12, 14, 18–21, 25–27, 29–31] and references therein.

Various generalized second-order derivatives have been introduced to obtain optimization results. In this paper, we will focus on the Peano type of directional derivatives (deeply studied e.g. in [6, 13–17, 24, 29]) and the Dini type of directional derivatives [3, 4, 29]. The previous two types of derivatives are compared (and their advantages are shown) with some other types of generalized derivatives for instance in [3, 4, 22, 23, 29–31]. At this point we should say that the terminology and notations of the previous types of derivatives are not unified, maybe because it has been made a big development since 1980s of twentieth century.

The main aim of this paper is to generalize early obtained sufficient second-order optimality conditions which were introduced in terms of the previous types of derivatives for the class of  $C^{1,1}$  functions or for the class of stable functions. We will introduce a new optimality condition expressed by means of a certain directional derivative of the Peano type which suits the purpose (see Theorem 6).

$\mathbb{R}^N$  means  $N$  dimensional arithmetical space equipped with the Euclidean norm  $\|\cdot\|$ . A symbol  $\langle \cdot, \cdot \rangle$  stands for the scalar product in  $\mathbb{R}^N$ . We also always identify the space  $\mathbb{R}^N$  with its dual space.  $S$  denotes the unit sphere  $\{x \in \mathbb{R}^N : \|x\| = 1\}$ , and  $B(x, r) = \{y \in \mathbb{R}^N : \|y - x\| \leq r\}$  for  $x \in \mathbb{R}^N$  and  $r > 0$ . The symbols  $[a, b]$ ,  $(a, b]$ ,  $[a, b)$  and  $(a, b)$  are reserved for intervals in  $\mathbb{R}^N$  with endpoints  $a$  and  $b$  (e.g.,  $[a, b] = \{ta + (1-t)b : 0 < t \leq 1\}$ ). In the case of  $N = 1$ , we assume  $a < b$ .

We say that  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  is *Fréchet differentiable* at  $x \in \mathbb{R}^N$  if there is  $f'(x) \in \mathbb{R}^N$  such that

$$\lim_{t \rightarrow 0} \frac{f(x + th) - f(x)}{t} = \langle f'(x), h \rangle, \quad \forall h \in S,$$

and, moreover, this limit is uniform for  $h \in S$ . By the *strict differentiability* at  $x$  we mean that for some  $L \in \mathbb{R}^N$  it holds

$$\langle L, h \rangle = \lim_{y \rightarrow x, t \downarrow 0} \frac{f(y + th) - f(y)}{t}, \quad \forall h \in \mathbb{R}^N,$$

and the limit is uniform with respect to  $h \in S$ . It is easy to show that the strict differentiability implies the Fréchet differentiability and  $L = f'(x)$ .

For a function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$ , we define the first-order directional derivative of  $f$  at  $x \in \mathbb{R}^N$  in the direction  $h \in \mathbb{R}^N$  by

$$f'(x; h) = \lim_{t \downarrow 0} \frac{f(x + th) - f(x)}{t},$$

and the lower and upper first-order directional derivative of  $f$  at  $x$  in the direction  $h$  by, respectively,

$$f^\ell(x; h) = \liminf_{t \downarrow 0} \frac{f(x + th) - f(x)}{t},$$

$$f^u(x; h) = \limsup_{t \downarrow 0} \frac{f(x + th) - f(x)}{t}.$$

If  $f$  is a function of a one real variable, we will use  $f'(x)$ ,  $f^\ell(x)$  and  $f^u(x)$  instead of  $f'(x; 1)$ ,  $f^\ell(x; 1)$  and  $f^u(x; 1)$ , respectively. In this case, it will be clear from the context whether by  $f'(x)$  we mean directional derivative  $f'(x; 1)$  or an element of the dual of  $\mathbb{R}$ .

Let us recall that a locally Lipschitz function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  is said to be *regular* at  $x \in \mathbb{R}^N$  provided that  $f'(x; h) = f^\circ(x; h)$  for every  $h \in \mathbb{R}^N$ , where  $f^\circ(x; h)$  denotes the upper Clarke directional derivative of  $f$  at  $x$  in the direction  $h$  defined in [10] as

$$f^\circ(x; h) = \limsup_{y \rightarrow x, t \downarrow 0} \frac{f(y + th) - f(y)}{t}.$$

The Clarke subdifferential of a locally Lipschitz function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  at  $x \in \mathbb{R}^N$  is defined by

$$\partial_c f(x) = \{x^* \in \mathbb{R}^N : \langle x^*, h \rangle \leq f^\circ(x; h) \quad \forall h \in \mathbb{R}^N\}.$$

We say that  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  is a  $C^{1,1}$  function near  $x \in \mathbb{R}^N$  if it is Fréchet differentiable on some neighbourhood of  $x$  and its derivative  $f'(\cdot)$  is Lipschitz there.

Analogously, we will say that a function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  satisfies a  $p$ -property near  $x \in \mathbb{R}^N$  if that  $p$ -property holds on some neighbourhood of  $x$ .

A function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$ , for which there exist a neighbourhood  $U$  of  $x \in \mathbb{R}^N$  and  $K > 0$  such that for all  $y \in U$  there exists the Fréchet derivative  $f'(y)$  and

$$\|f'(y) - f'(x)\| \leq K\|y - x\|, \quad \forall y \in U,$$

is called *stable* at  $x$ . Notice that if  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  is a  $C^{1,1}$  function near  $x \in \mathbb{R}^N$ , then  $f$  is stable at  $x$ .

The rest of this section is devoted to the generalized second-order directional derivatives.

Peano's second-order directional derivative of  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  at  $x \in \mathbb{R}^N$  in the direction  $h \in \mathbb{R}^N$  is given as

$$f_P''(x; h) = \lim_{t \downarrow 0} \frac{f(x + th) - f(x) - tf'(x; h)}{t^2/2}.$$

We note that  $f''_P(x; h)$  coincides with a classical second-order directional derivative for functions which are twice Fréchet differentiable at  $x$ .

In this paper, we also use the following second-order directional derivatives of the Peano type of  $f$  at  $x$  in the direction  $h$ :

$$f''_P(x; h) = \liminf_{t \downarrow 0} \frac{f(x + th) - f(x) - tf'(x; h)}{t^2/2},$$

$$\underline{f}''_P(x; h) = \liminf_{t \downarrow 0} \frac{f(x + th) - f(x) - tf''(x; h)}{t^2/2},$$

For the following theorem, see [6, Theorem 3.2].

**Theorem 1** *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be Fréchet differentiable near  $x \in \mathbb{R}^N$  and let  $f$  be stable at  $x$ . If  $f'(x) = 0$  and*

$$f''_P(x; h) > 0, \quad \forall h \in S,$$

*then  $x$  is a strict local minimizer for  $f$ .*

Recall that  $x \in \mathbb{R}^N$  is an *isolated minimizer of order  $k$*  ( $k \in \mathbb{N}$ ) for a function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  if there are a neighbourhood  $U$  of  $x$  and  $A > 0$  satisfying  $f(y) \geq f(x) + A\|y - x\|^k$  for every  $y \in U$ . It is easy to verify that each isolated minimizer is a strict local minimizer. The notion of an isolated minimizer was studied e.g. by Auslender [1].

Ginchev et al. [13] presented the problem for what class  $\mathcal{F}$  of functions  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  the following theorem holds:

**Theorem P** (problem what  $\mathcal{F}$ ) *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be of class  $\mathcal{F}$ , and let  $x \in \mathbb{R}^N$ . If for each  $h \in S$  one of the following conditions holds:*

- (i)  $f''(x; h) > 0$ ,
- (ii)  $f''(x; h) = 0$  and  $\underline{f}''_P(x; h) > 0$ ,

*then  $x$  is a strict local minimizer for  $f$ . Conversely, if  $x$  is an isolated minimizer of order 2, then the previous conditions hold.*

*They showed that the class of  $C^{1,1}$  functions solves this problem:*

**Theorem 2** ([13, Theorem 2]). *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a  $C^{1,1}$  function near  $x \in \mathbb{R}^N$ . If  $f'(x) = 0$  and*

$$\underline{f}''_P(x; h) > 0, \quad \forall h \in S,$$

*then  $x$  is an isolated minimizer of order 2 for  $f$ . Conversely, each isolated minimizer of order 2 satisfies these sufficient conditions.*

We turn now to some definitions and notations which are mostly taken from Chaney's papers [8, 9].

**Definition 1** Let  $u$  be a nonzero vector in  $\mathbb{R}^N$ . Suppose that the sequence  $\{x_k\}_{k=1}^{+\infty}$  in  $\mathbb{R}^N$  converges to  $x$ . We say that  $\{x_k\}_{k=1}^{+\infty}$  converges to  $x$  in the direction  $u$ , denoted by  $x_k \rightarrow_u x$ , if  $x_k \neq x$  for every  $k \in \mathbb{N}$  and the sequence  $\{(x_k - x)/\|x_k - x\|\}_{k=1}^{+\infty}$  converges to  $u/\|u\|$ .

**Definition 2** Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a locally Lipschitz function,  $x \in \mathbb{R}^N$ , and let  $u$  be a nonzero vector in  $\mathbb{R}^N$ . We define the subset  $\partial_u f(x)$  of  $\mathbb{R}^N$  by

$$\partial_u f(x) := \{x^* \in \mathbb{R}^N; \text{ there exist sequences } \{x_k\}_{k=1}^{+\infty} \text{ and } \{x_k^*\}_{k=1}^{+\infty} \text{ such that } x_k^* \in \partial_c f(x_k), x_k \rightarrow_u x, \text{ and } x_k^* \rightarrow x^* \text{ in norm}\}.$$

**Definition 3** Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a locally Lipschitz function,  $x \in \mathbb{R}^N$ , and let  $u$  be a nonzero vector in  $\mathbb{R}^N$ . Suppose that  $x^* \in \partial_u f(x)$ . Then  $f''_-(x, x^*, u)$  is defined to be the infimum of all numbers

$$\liminf_{k \rightarrow +\infty} \frac{f(x_k) - f(x) - \langle x^*, x_k - x \rangle}{t_k^2/2},$$

taken over all triples of sequences  $\{x_k\}_{k=1}^{+\infty}$ ,  $\{x_k^*\}_{k=1}^{+\infty}$  and  $\{t_k\}_{k=1}^{+\infty}$  for which

- (a)  $t_k > 0$  for each  $k \in \mathbb{N}$  and  $x_k \rightarrow x$ ,
- (b)  $t_k \downarrow 0$  and  $\{(x_k - x)/t_k\}_{k=1}^{+\infty}$  converges to  $u$ ,
- (c)  $x_k^* \in \partial_c f(x_k)$  and  $x_k^* \rightarrow x^*$ .

L.R. Huang and K.F. Ng introduced the second-order sufficient condition by means of  $f''_-(x, 0, u)$ .

**Theorem 3** ([16, Theorem 2.9]) Suppose that  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  is a locally Lipschitz function and  $x \in \mathbb{R}^N$ . Suppose that  $f^\ell(x; h) \geq 0$  for every  $h \in S$ . If  $f''_-(x, 0, h) > 0$  for all  $h \in S$  for which  $f^\ell(x; h) = 0$ , then  $x$  is a strict local minimizer for  $f$ .

Theorem 4 uses a certain directional derivative of the Dini type.

**Theorem 4** ([4, Theorem 3.2]) Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a  $C^{1,1}$  function near  $x \in \mathbb{R}^N$ . If  $f'(x) = 0$  and

$$f_D^\ell(x; h) := \liminf_{t \downarrow 0} \frac{f'(x + th; h) - f'(x; h)}{t} > 0, \quad \forall h \in S,$$

then  $x$  is a strict local minimizer for  $f$ .

Theorem 4 covers also the following result due to Cominetti and Correa (see [11] and also [7, Proposition 6.2], [30, Theorem 5.1(ii)], [31, Theorem 4.2(ii)]):

**Theorem 5** ([11, Proposition 5.2]) Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a  $C^{1,1}$  function near  $x \in \mathbb{R}^N$ . If  $f'(x) = 0$ , and

$$f_\infty^\ell(x; h) := \liminf_{y \rightarrow x, t \downarrow 0} \frac{\langle \nabla f(y + th) - \nabla f(y), h \rangle}{t} > 0, \quad \forall h \in S,$$

then  $x$  is a strict local minimizer for  $f$ .

The main purpose of this paper is to establish the generalization of Theorems 1, 2, 4 and 5.

## 2 Main result

A stability property reminded in Sect. 1 can be weakened by the following way.

**Definition 4** We say that a function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  is  $\ell$ -stable at  $x \in \mathbb{R}^N$  if there exist a neighbourhood  $U$  of  $x$  and  $K > 0$  such that

$$|f^\ell(y; h) - f^\ell(x; h)| \leq K\|y - x\|, \quad \forall y \in U, \quad \forall h \in S.$$

Since  $C^{1,1}$  functions appear in, e.g. the augmented Lagrange method, the penalty function method and the proximal point method, and since the property to be  $C^{1,1}$  function near some point requires stronger assumptions than the property to be  $\ell$ -stable function at considered point, it seems to be useful to study the class of  $\ell$ -stable functions. We will show in this section, among the others, some properties of the functions which are  $\ell$ -stable at some point.

In order to generalize Theorems 1, 2, 4 and 5, we first derive the generalization of Lagrange's mean value theorem (see Lemma 4). The following lemma is an easy consequence of [28, p. 135].

**Lemma 1** *Let  $a, b \in \mathbb{R}$ , and let  $f : [a, b] \rightarrow \mathbb{R}$  be a continuous function. If  $f'(x) > 0$  for every  $x \in (a, b)$ , then  $f$  is increasing.*

Next lemma is the generalization of classical Cauchy's theorem.

**Lemma 2** *Let  $a, b \in \mathbb{R}$ , let  $f : [a, b] \rightarrow \mathbb{R}$  and  $g : [a, b] \rightarrow \mathbb{R}$  be continuous functions, and let  $g'(x) > 0$  for every  $x \in (a, b)$ . Then there are  $\xi_1, \xi_2 \in (a, b)$  satisfying*

$$\frac{f^\ell(\xi_1)}{g'(\xi_1)} \leq \frac{f(b) - f(a)}{g(b) - g(a)} \leq \frac{f^\ell(\xi_2)}{g'(\xi_2)}.$$

*Proof* We consider the function  $F : [a, b] \rightarrow \mathbb{R}$  such that

$$F(x) = (f(b) - f(a))(g(x) - g(a)) - (f(x) - f(a))(g(b) - g(a)), \quad \forall x \in [a, b].$$

Since  $F$  is continuous and  $F(a) = F(b)$ , by Lemma 1 there is  $\xi_2 \in (a, b)$  with the property

$$F'(\xi_2) = (f(b) - f(a))g'(\xi_2) - f'(\xi_2)(g(b) - g(a)) \leq 0.$$

Indeed, supposing  $F'(\xi) > 0$  for every  $\xi \in (a, b)$ , we obtain by Lemma 1 that  $F(b) > F(a)$ , a contradiction. Note that due to Lemma 1, it holds  $g(b) > g(a)$ .

Therefore

$$\frac{f(b) - f(a)}{g(b) - g(a)} \leq \frac{f^\ell(\xi_2)}{g'(\xi_2)},$$

which is the second inequality. The first inequality will be obtained by transition to the function  $-f$  and by using the obvious inequality  $f^\ell \leq f^u$ .  $\square$

Setting  $g(x) = x$  in Lemma 2, we obtain the following lemma immediately.

**Lemma 3** *Let  $a, b \in \mathbb{R}$  and let  $f : [a, b] \rightarrow \mathbb{R}$  be a continuous function. Then there exists  $\xi_1, \xi_2 \in (a, b)$  such that*

$$(b - a)f^\ell(\xi_1) \leq f(b) - f(a) \leq (b - a)f^\ell(\xi_2).$$

**Lemma 4** *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a continuous function, and let  $a, b \in \mathbb{R}^N$ . Then there exist  $\xi_1, \xi_2 \in (a, b)$  such that*

$$f^\ell(\xi_1; b - a) \leq f(b) - f(a) \leq f^\ell(\xi_2; b - a). \quad (1)$$

*Proof* Considering the function  $g : [0, 1] \rightarrow \mathbb{R}$ ,  $g(t) = f(a + t(b - a))$ , due to Lemma 3 we can find  $t_1, t_2 \in (0, 1)$  satisfying

$$g^\ell(t_1) \leq g(1) - g(0) \leq g^\ell(t_2). \quad (2)$$

For every  $t \in (0, 1)$ , we have

$$\begin{aligned} g^\ell(t) &= \liminf_{s \downarrow 0} \frac{g(t+s) - g(t)}{s} \\ &= \liminf_{s \downarrow 0} \frac{f(a + (t+s)(b-a)) - f(a + t(b-a))}{s} \\ &= f^\ell(a + t(b-a); b-a). \end{aligned} \quad (3)$$

Setting  $\xi_i = a + t_i(b-a)$  for  $i = 1, 2$ , formulas (2) and (3) imply formula (1).  $\square$

It follows immediately from Definition 4 that if  $f$  is  $\ell$ -stable, then  $f^\ell(y; h)$  is finite for every  $y$  sufficiently near  $x$  and for every  $h \in \mathbb{R}^N$ . In fact, we can say more.

**Lemma 5** *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a continuous function near  $x \in \mathbb{R}^N$  and let  $f$  be  $\ell$ -stable at  $x$ . Then there exists a neighbourhood  $V$  of  $x$  such that*

$$\sup_{h \in S, y \in V} |f^\ell(y; h)| < +\infty. \quad (4)$$

*Proof* Suppose for a contradiction that there are sequences  $\{y_n\}_{n=1}^\infty \subset \mathbb{R}^N$ ,  $\{h_n\}_{n=1}^\infty \subset S$  such that  $y_n \rightarrow x$  as  $n \rightarrow +\infty$  and

$$\lim_{n \rightarrow \infty} |f^\ell(y_n; h_n)| = +\infty.$$

Without any loss of generality we can assume that either

$$\lim_{n \rightarrow +\infty} f^\ell(y_n, h_n) = -\infty$$

or

$$\lim_{n \rightarrow +\infty} f^\ell(y_n, h_n) = +\infty.$$

We suppose that the first case occurs (the second case can be treated by an analogous way).

Next we can assume that for certain  $\gamma > 0$  the condition in Definition 4 of  $\ell$ -stability is fulfilled on  $B(x, \gamma)$ , and moreover  $f$  is continuous and bounded on  $B(x, \gamma)$ . Let  $\delta > 0$  denotes a constant such that for each sufficiently large  $n \in \mathbb{N}$  we have  $y_n + \delta h_n \in B(x, \gamma)$ .

Now, if we combine  $\ell$ -stability and Lemma 4, for each sufficiently large  $n \in \mathbb{N}$  we get  $\xi_n \in (y_n, y_n + \delta h_n)$  such that the following holds :

$$\begin{aligned} f(y_n + \delta h_n) &\leq f(y_n) + \delta f^\ell(\xi_n; h_n) \\ &= f(y_n) + \delta [f^\ell(\xi_n; h_n) - f^\ell(x; h_n) + f^\ell(x; h_n) \\ &\quad - f^\ell(y_n; h_n) + f^\ell(y_n; h_n)] \\ &\leq f(y_n) + 2K\delta\gamma + \delta f^\ell(y_n; h_n). \end{aligned}$$

Since  $f$  is bounded on  $B(x, \gamma)$  and  $f^\ell(y_n; h_n) \rightarrow -\infty$ , the previous inequality does not hold for every  $n \in \mathbb{N}$ , a contradiction.  $\square$

**Proposition 1** *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a continuous function near  $x \in \mathbb{R}^N$  and let  $f$  be  $\ell$ -stable at  $x$ . Then  $f$  is Lipschitz near  $x$ .*

*Proof* Thanks to Lemma 5 there is some ball  $B(x, \delta)$  on which  $f$  is continuous and

$$L := \sup_{y \in B(x, \delta), h \in S} |f^\ell(y; h)| < +\infty.$$

Next by Lemma 4, for any pair of points  $a, b \in B(x, \delta)$  there exists  $\xi \in (a, b) \subset B(x, \delta)$  such that

$$\begin{aligned} |f(b) - f(a)| &\leq |f^\ell(\xi; (b - a)/\|b - a\|)| \|b - a\| \\ &\leq L \|b - a\|. \end{aligned} \quad \square$$



**Proposition 2** *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a continuous function near  $x \in \mathbb{R}^N$  and let  $f$  be  $\ell$ -stable at  $x$ . Then  $f$  is strictly differentiable at  $x$ .*

*Proof* By Proposition 1 there is a neighbourhood  $U$  of  $x$  on which  $f$  is Lipschitz. Now, due to the Rademacher theorem, we can find a sequence  $\{x_n\}_{n=1}^\infty \subset U$  such that  $f'(x_n)$  exists for each  $n \in \mathbb{N}$ , and  $x_n \rightarrow x$  as  $n \rightarrow +\infty$ . We claim that for any fixed  $h \in \mathbb{R}^N$ , the sequence  $\{f'(x_n)h\}_{n=1}^\infty$  is Cauchy and hence converges. Indeed, using  $\ell$ -stability at  $x$ , we get for any  $m, n \in \mathbb{N}$ :

$$\begin{aligned} 0 &\leq |f'(x_n)h - f'(x_m)h| \\ &= |f'(x_n)h - f^\ell(x; h) + f^\ell(x; h) - f'(x_m)h| \\ &\leq |f'(x_n)h - f^\ell(x; h)| + |f^\ell(x; h) - f'(x_m)h| \\ &\leq K(\|x_n - x\| + \|x - x_m\|)\|h\|. \end{aligned}$$

If we here pass to the limit where  $m, n \rightarrow +\infty$ , we see that

$$|f'(x_n)h - f^\ell(x; h)| \rightarrow 0, \quad \text{as } m, n \rightarrow +\infty.$$

Thus, for any  $h \in \mathbb{R}^N$ , we can put  $L(h) := \lim_{n \rightarrow \infty} f'(x_n)h$ . Clearly  $L \in \mathbb{R}^N$ . We claim that for any  $h \in \mathbb{R}^N$ ,  $L(h) = f^\ell(x; h)$ . Indeed, for fixed  $h \in \mathbb{R}^N$ , it holds

$$\begin{aligned} 0 &\leq |L(h) - f^\ell(x; h)| = |L(h) - f'(x_n)h + f'(x_n)h - f^\ell(x; h)| \\ &\leq |L(h) - f'(x_n)h| + |f'(x_n)h - f^\ell(x; h)| \\ &\leq |L(h) - f'(x_n)h| + K\|x_n - x\|\|h\|. \end{aligned}$$

In view of definition of  $L(h)$  and the fact that  $x_n \rightarrow x$ , we infer  $|L(h) - f^\ell(x; h)| \leq 0$ , i.e.  $L(h) = f^\ell(x; h)$  for each  $h \in \mathbb{R}^N$ . This equality, Lemma 4, and  $\ell$ -stability now imply that for all  $y$  sufficiently close to  $x$ , all  $t > 0$  sufficiently small, and all  $h \in S$ , there is  $\xi \in (y, y + th)$  such that it holds

$$|[f(y + th) - f(y)]/t - L(h)| \leq |f^\ell(\xi; h) - f^\ell(x; h)| \leq K\|\xi - x\|$$

This immediately yields that  $[f(y + th) - f(y)]/t \rightarrow L(h)$  as  $y \rightarrow x, t \downarrow 0$  uniformly with respect to  $h \in S$ .  $\square$

Now, we are able to show that the class of the functions which are  $\ell$ -stable at some point and continuous near this point solves the problem given before Theorem P.

**Theorem 6** *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be continuous near  $x \in \mathbb{R}^N$  and let  $f$  be  $\ell$ -stable at  $x$ . If  $f^\ell(x; h) = 0$  for every  $h \in S$ , and*

$$f_P^{\ell}(x; h) > 0, \quad \forall h \in S, \quad (5)$$

then  $x$  is an isolated minimizer of order 2 for  $f$ . Conversely, each isolated minimizer of order 2 satisfies these sufficient conditions.

*Proof* We can assume, without any loss of generality, that  $x = 0$  and  $f(0) = 0$ .

Suppose for a contradiction that 0 is not an isolated minimizer of order 2 for  $f$ . Then there exists a sequence  $\{x_n\}_{n=1}^{+\infty} \subset \mathbb{R}^N \setminus \{0\}$  satisfying  $\lim_{n \rightarrow +\infty} x_n = 0$  and

$$f(x_n) < \frac{1}{n} \|x_n\|^2, \quad \forall n \in \mathbb{N}. \quad (6)$$

Setting

$$h_n = \frac{x_n}{\|x_n\|}, \quad t_n = \|x_n\|, \quad \forall n \in \mathbb{N},$$

we have  $h_n \in S$  for every  $n \in \mathbb{N}$ . Because of the compactness of  $S$ , we can find, without any loss of generality,  $\tilde{h} \in S$  with the property

$$\lim_{n \rightarrow +\infty} h_n = \tilde{h}. \quad (7)$$

Formula (5) and  $f^\ell(0; \tilde{h}) = 0$  imply the existence of  $c > 0$  and  $\delta > 0$  such that

$$\frac{f(t\tilde{h})}{t^2} > c, \quad \forall 0 < t \leq \delta. \quad (8)$$

Since  $f$  is  $\ell$ -stable at 0, there are an open neighbourhood  $U$  of 0 and  $K > 0$  satisfying

$$|f^\ell(y; h)| \leq K \|y\| \|h\|, \quad \forall y \in U, \quad \forall h \in \mathbb{R}^N. \quad (9)$$

Using the formula (6) and Lemma 4, respectively, it holds for every sufficiently large  $n \in \mathbb{N}$  that

$$\frac{f(t_n \tilde{h}) - \frac{1}{n} \|x_n\|^2}{t_n^2} < \frac{f(t_n \tilde{h}) - f(t_n h_n)}{t_n^2} \leq \frac{f^\ell(a_n; t_n(\tilde{h} - h_n))}{t_n^2}, \quad (10)$$

where  $a_n \in (x_n, t_n \tilde{h})$ .

Due to the inequalities (8), (9) and (10), we obtain for every sufficiently large  $n \in \mathbb{N}$  that

$$\begin{aligned} 0 &< \frac{c}{2} \leq \frac{f(t_n \tilde{h}) - \frac{1}{n} \|x_n\|^2}{t_n^2} \leq \frac{f^\ell(a_n; t_n(\tilde{h} - h_n))}{t_n^2} \\ &\leq \frac{K \|a_n\| t_n \|\tilde{h} - h_n\|}{t_n^2}. \end{aligned}$$

Because of  $\|a_n\| \leq t_n$  for every  $n \in \mathbb{N}$  considered before, it follows from the previous inequality that

$$\frac{c}{2K} \leq \lim_{n \rightarrow +\infty} \|\tilde{h} - h_n\|,$$

what is a contradiction with (7).

Conversely, if  $x$  is an isolated minimizer of order 2 for a function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  which is continuous near  $x \in \mathbb{R}^N$  and  $\ell$ -stable at  $x$ , then  $f$  is differentiable at  $x$  by Proposition 2,  $f'(x) = 0$  and  $f_P^\ell(x; h) > 0$  for every  $h \in S$ .  $\square$

### 3 Comparisons and examples

For a function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  which satisfies the  $C^{1,1}$  property near  $x \in \mathbb{R}^N$ , and  $h \in \mathbb{R}^N$ , we can easily derive from [29, Theorem 4], the relation

$$f_D^\ell(x; h) \leq f_P^\ell(x; h).$$

Theorem 6 generalizes Theorems 1, 2, 4 and 5 now, as one can see immediately from the definitions and from the previous relation.

*Example 1* Let us consider a function

$$f(x) = \begin{cases} \int_0^{|x|} t \left( \frac{19}{20} + \sin \ln t \right) dt & \text{if } x \neq 0, \\ 0 & \text{if } x = 0. \end{cases}$$

$f$  is  $C^{1,1}$  function since  $f'(x)h = x((19/20) + \sin(\ln |x|))h$  for  $x \neq 0$ ,  $h \in \mathbb{R}$ , and  $f'(0) = 0$ . Integration per partes gives

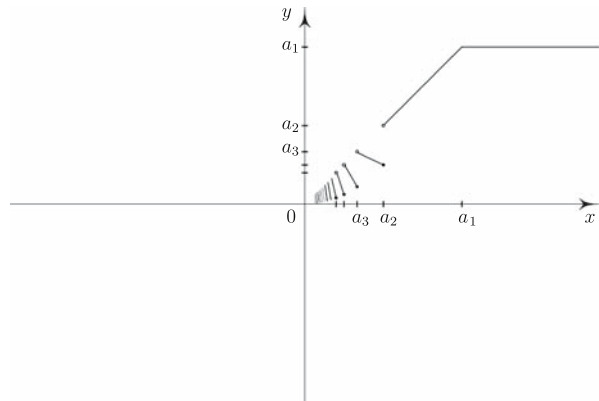
$$\int t \sin(\ln t) dt = (1/5)t^2(2 \sin(\ln t) - \cos(\ln t)).$$

As a consequence, we have :

$$\int_0^{|x|} t \sin(\ln t) dt = \frac{1}{5}x^2(2 \sin(\ln |x|) - \cos(\ln |x|)).$$

Then

$$\begin{aligned} f_P^\ell(0; 1) &= f_P^\ell(0; -1) = \liminf_{x \downarrow 0} \frac{\frac{19}{20} \frac{x^2}{2} + \frac{1}{5}x^2(2 \sin(\ln x) - \cos(\ln x))}{x^2/2} \\ &= \frac{19}{20} + \frac{2}{5} \liminf_{x \downarrow 0} (2 \sin(\ln x) - \cos(\ln x)) = \frac{19}{20} + \frac{2}{5}(-\sqrt{5}) > 0. \end{aligned}$$

**Fig. 1** Function  $\varphi$ 

Consequently, according to Theorem 6  $x = 0$  is a strict local minimizer for  $f$ . Further calculation shows :  $f_D^\ell(0; 1) = (19/20) - 1 < 0$ ,  $f_\infty^\ell(0; 1) = (19/20) - \sqrt{2} < 0$  (for this calculation, see [2]), and  $f_P''(0; 1)$  does not exist. In contrast to Theorems 2 and 6, we can see that Theorems 1, 4 and 5 are not applicable in this context.

The following example illustrates that Theorem 6 also overcomes Theorem 2.

*Example 2* Consider a sequence  $a_n = 1/n, n = 1, 2, \dots$ . Then

$$\lim_{n \rightarrow \infty} \frac{a_{n+1} + a_n^2}{a_{n+1} + a_n} = \frac{1}{2} > 0.$$

Let us define a function  $\varphi : [0, \infty) \rightarrow \mathbb{R}$  as follows (see Fig. 1 for the construction of  $\varphi$ ).

$$\varphi(u) = \begin{cases} a_1 & \text{if } u > a_1, \\ \frac{a_n^2 - a_{n+1}}{a_n - a_{n+1}}(u - a_{n+1}) + a_{n+1} & \text{if } u \in (a_{n+1}, a_n], \\ 0 & \text{if } u = 0. \end{cases}$$

Next, we will define a function  $f : \mathbb{R} \rightarrow \mathbb{R}$  via the Riemann integral :

$$f(x) := \int_0^{|x|} \varphi(u) du, \quad x \in \mathbb{R}.$$

Since  $\varphi$  is a piecewise affine function, the integral exists. Because of  $f'(a_n; 1) = a_n$  and  $f'(a_n; -1) = a_n^2$  for every  $n > 1$ , the function  $f$  is not differentiable on any neighbourhood of 0. Thus, we cannot use Theorems 1, 2, 4 and 5.

On the other hand,  $f$  is Lipschitz on  $\mathbb{R}$  with Lipschitz constant equal to  $a_1$ . Let  $x, y \in \mathbb{R}$  be arbitrary points such that  $|x| \leq |y|$ . We have:

$$\begin{aligned} |f(x) - f(y)| &= \left| \int_0^{|x|} \varphi(u) du - \int_0^{|y|} \varphi(u) du \right| = \left| \int_{|x|}^{|y|} \varphi(u) du \right| \\ &\leq \int_{|x|}^{|y|} |\varphi(u)| du \leq a_1(|y| - |x|) \leq a_1|x - y|. \end{aligned}$$

It is easy to show that  $f'(0) = 0$  and that  $f$  is  $\ell$ -stable at  $x = 0$ . Now we claim that  $f_P^{\ell}(0; \pm 1) > 0$ . So it suffices to show that

$$\liminf_{t \downarrow 0} \frac{f(t)}{t^2/2} > 0.$$

Note that there is  $\epsilon > 0$  such that for each  $n \in \mathbb{N}$  it holds:

$$\frac{a_{n+1} + a_n^2}{a_{n+1} + a_n} \geq \epsilon > 0. \quad (11)$$

Now consider  $t \in [a_{j+1}, a_j]$  for some  $j \in \mathbb{N}$  and fix  $k \in \mathbb{N}, k \geq j + 2$ . Let  $S_n$  denotes an area of a trapezoid over the interval  $(a_{n+1}, a_n), n = j + 1, \dots, k$ , bounded by a graph of  $\varphi$ . Let  $R$  denotes an area of a trapezoid over the interval  $(a_{j+1}, t)$  bounded by the graph of  $\varphi$ . Now we can write down the formula for the integral:

$$\int_{a_k}^t \varphi(u) du = \left( \sum_{n=j+1}^k S_n \right) + R. \quad (12)$$

Further  $\tilde{S}_n$  stands for an area of a trapezoid over the interval  $(a_{n+1}, a_n), n = j + 1, \dots, k$  bounded by the linear function  $y = x$ , and  $\tilde{R}$  stands for an area of a trapezoid over the interval  $(a_{j+1}, t)$  bounded also by the function  $y = x$ . Now it can be shown that

$$\begin{aligned} \int_{a_k}^t \varphi(u) du &= \left( \sum_{n=j+1}^k S_n \right) + R \geq \epsilon \sum_{n=j+1}^k \tilde{S}_n + \epsilon \tilde{R} \\ &= \epsilon \left( \sum_{n=j+1}^k \tilde{S}_n + \tilde{R} \right). \end{aligned}$$

Letting  $k \rightarrow +\infty$ , we will get:

$$\begin{aligned} f(t) &= \int_0^t \varphi(u) du \geq \epsilon \left( \sum_{n=j+1}^{\infty} \tilde{S}_n + \tilde{R} \right) \\ &= \epsilon \frac{t^2}{2}. \end{aligned}$$

Hence  $2f(t)/t^2 \geq \epsilon > 0$ , where  $t \in [a_{j+1}, a_j]$ . Since this holds for almost any  $j \in \mathbb{N}$  and for all  $t \in [a_{j+1}, a_j]$ , we have for any  $\delta > 0$  sufficiently small,

$$\inf \left\{ 2 \frac{f(t)}{t^2} : t \in (0, \delta) \right\} \geq \epsilon > 0.$$

Hence  $\liminf_{t \downarrow 0} 2f(t)/t^2 \geq \epsilon > 0$ . Now, we can conclude that  $f$  satisfies the assumptions of Theorem 6 and therefore  $x = 0$  is a strict local minimizer for  $f$ .

Finishing this section, we compare Theorems 6 and 3. We will need the following proposition which can be obtained as a special case of [16, Theorem 4.1].

**Proposition 3** *Let  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  be a locally Lipschitz function, and  $x, u \in \mathbb{R}^N$  with  $\partial_u f(x) = \{0\}$ . Then*

$$f''_-(x, 0, h) \leq f'^{\ell}_P(x; h).$$

Let us consider the function  $f : \mathbb{R} \rightarrow \mathbb{R}$  defined by  $f(x) = |x|$ . Since  $f$  is not differentiable at 0,  $f$  is not  $\ell$ -stable at 0 by Proposition 2 and we cannot use Theorem 6 to verify that 0 is a strict local minimizer for  $f$  in contrast to Theorem 3.

Moreover, it is not possible to find an example of function  $f$  which satisfies the assumptions of Theorem 6 but doesn't satisfy the assumptions of Theorem 3. Indeed, if  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  is  $\ell$ -stable at  $x \in \mathbb{R}^N$ , continuous near  $x$ ,  $f^{\ell}(x; h) = 0$  and  $f'^{\ell}_P(x; h) > 0$  for every  $h \in S$ , then from Proposition 2 and the well known fact that the Clarke subdifferential of strictly differentiable function  $f$  at  $x$  is  $\{f'(x)\}$ , we have that  $\partial_u f(x) = \{0\}$  for every  $h \in S$ . Because  $x$  is a local minimizer of order 2 for  $f$  by Theorem 6, it follows from the definition that  $f''_-(x, 0, h) > 0$  for every  $h \in S$ .

On the other hand, for this special situation (i.e.  $f$  is continuous near  $x$  and  $\ell$ -stable at  $x$ ) Theorem 6 offers a sharper conclusion ( $x$  is a strict local minimizer of order 2) and it seems that the calculus with  $f'^{\ell}_P(x; h)$  is more comfortable than with  $f''_-(x, 0, h)$ . Notice also that  $f'(x) = 0$  implies by Propositions 2 and 3 that  $f''_-(x, 0, h) \leq f'^{\ell}_P(x; h)$ .

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