# CS189/289A – Spring 2017 — Homework 2

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## 1. Conditional Probability

- (a) i) P(Wind and hits) =  $0.3 \times 0.4 = 0.12$ 
  - ii) P(hits with first shot) =  $0.3 \times 0.4 + (1 0.3) \times 0.7 = 0.61$
  - iii) P(hits once in two shots) =  $0.61 \times (1 0.61) \times 2 = 0.4758$
  - iv) P(no wind when missed) =  $\frac{0.7*0.3}{0.7*0.3+0.3*0.6} = \frac{21}{39} = \frac{3}{13}$
- (b) We know that

$$P(ABC) + P(ABC^C) = P(AB) = P(AB)P(C|B) + P(AB)P(C^C|B)$$

Because

$$P(A|B,C) > P(A|B)$$
  
$$P(ABC) > P(AB)P(BC)/P(B) = P(AB)P(C|B)$$

Therefore

$$P(ABC^C) < P(AB)P(C^C|B)$$

Which is equivalent to

$$\frac{P(ABC^C)}{P(BC^C)} < \frac{P(AB)}{P(B)}$$

Or,

$$P(A|B, C^C) < P(A|B)$$

### 2. Positive Definiteness

- (a) (i) $\rightarrow$ (ii): if  $A \succeq 0$ , then  $\forall x \in \mathbb{R}^n \{0\}$ ,  $x^\top B^\top A B x = (Bx)^\top A (Bx) \geq 0$ . Therefore  $B^\top A B \succeq 0$ .
  - (ii) $\rightarrow$ (i): if  $B^{\top}AB \succeq 0$ , because B is invertible, then  $\forall x \in \mathbb{R}^n \{0\}$ , there is a y that x = By. Then  $x^{\top}Ax = (By)^{\top}A(By) \geq 0$ . Hence  $A \succeq 0$ .
  - (i) $\rightarrow$ (iii): Suppose there exist an eigenvalue  $\lambda_i$  that is negative, then let x be the eigen vector corresponding to that  $lambda_i$ , then  $x^{\top}Ax < 0$ . This contradicts the assumption that  $A \succeq 0$ . Therefore all the eigenvalues or A are nonnegative.
  - (iii) $\rightarrow$ (iv): According to the spectral theorem,  $A = QBQ^{\top}$ , where B is a diagonal matrix with entries being the eigenvalues of A. If all the eigenvalues of A are nonegative, then there exists C that  $B = C^{\top}C$ . Therefore  $A = QC^{\top}CQ^{\top}$ . Let  $U = QC^{\top}$ , so  $A = UU^{\top}$ .
  - (iv) $\rightarrow$ (i): If there is a matrix U such that  $A = UU^{\top}$ , then  $\forall x \in \mathbb{R}^n \{0\}$ ,  $x^{\top}Ax = x^{\top}UU^{\top}x = ||(U^{\top}x)||^2 \geq 0$ , so  $A \succeq 0$ .
- (b) i) Obviously,  $\forall x \in \mathbb{R}^n \{0\}, \ x^\top (A_\lambda I) x = x^\top A x + \lambda ||x||^2 > 0$ , therefore  $A + \lambda I \succeq 0$ .
  - ii) Using the spectral theorem,  $A = QBQ^{\top}$ , where B is diagonal matrix with all the diagonal entries greater than 0. Then  $A \gamma I = QBQ^{\top} \gamma I = Q(B \gamma I)Q^{\top}$ . Suppose the smallest eigenvalue of A is a, let  $\gamma < a$ , then  $B' = B \gamma I$  is still a all-possitive diagonal matrix. Therefore  $A' = QB'Q^{\top}$  is also positive definite.
  - iii) Suppose  $A_{jj} \le 0$ , then let  $x = (0, 0, ...1, ..., 0)^{\top}$  be a vector with the jth entry be 1. Then  $x^{\top}Ax = A_{jj} \le 0$ , which contradicts to the assumption that  $A \succ 0$ . Therefore  $A_{jj} > 0$  for all j.
  - iv) Similar to (iii), let  $x = (1, 1, 1, ..., 1)^{\top}$  be a all-one vector, then this requires that  $\sum_{i} \sum_{j} A_{ij} > 0$ .

### 3. Derivatives and Norms

(a)  $\nabla_x(a^{\top}x) = \nabla_x(a_1x_1 + a_2x_2 + \dots + a_nx_n) = (a_1, a_2, \dots, a_n)^{\top} = a$ 

(b) If A is 2-by-2 matrix, we can get the following result:

$$\nabla_x(x^{\top}Ax) = (2A_{11}x_1 + (A_{12} + A_{21})x_2, 2A_{22}x_2 + (A_{12} + A_{21})x_1)$$

This is equivalent to the matrix form  $\nabla_x(x^\top Ax) = (A + A^\top)x$ . If the matrix A is symmetric, then  $\nabla_x(x^\top Ax) = 2Ax$ .

(c)  $\nabla_X(\operatorname{trace}(A^\top X)) = \nabla_X(\sum_i \sum_j A_{ij} X_{ij}) = A$ 

- (d) Let x = (1,1), y = (-1,-1), then  $\delta(x,y) = f(x,y) = (\sqrt{1+1} + \sqrt{1+1})^2 = 8$ . But f(x) = f(y) = 2. This does not satisfy the triangle inequality that  $\delta(x,y) \leq f(x) + f(y)$ , so this function f(x) is not a norm.
- (e) Let  $||x||_{\infty} = \max x_i = x_M$ , then

$$||x||_2 = \sqrt{\sum_i x_i^2} \ge \sqrt{x_M^2} = ||x||_{\infty}$$

And

$$||x||_2 = \sqrt{\sum_i x_i^2} \le \sqrt{nx_M^2} = \sqrt{n}||x||_{\infty}$$

(f) 
$$||x||_2^2 = \sum x_i^2 \le (|x_1| + |x_2| + \dots + |x_n|)^2 = ||x||_1^2$$

Therefore

$$||x||_2 \le ||x||_1$$

Using the Cauchy-Schwarz inequality  $|\langle a, b \rangle| \le ||a||_2 ||b||_2$ ,

$$|\langle x, \vec{1} \rangle| = ||x||_1 \le ||x||_2 ||\vec{1}||_2 = \sqrt{n} ||x||_2$$

## 4. Eigenvalues

(a) According to the spectral theorem,  $A = Q^{\top} \Lambda Q$ , where  $\Lambda$  is a diagonal matrix whose diagonal entries are eigenvalues of A. Let y = Qx, because Q is an orthogonal matrix,  $||y||_2 = 1$ . then

$$\max_{||x||_2=1} x^{\top} A x = \max_{||y||_2=1} y^{\top} \Lambda y = \max_{||y||_2=1} \sum_{i=1}^{n} \lambda_i y_i^2 = \lambda_{max}(A)$$

(b) Similar to (a),

$$\min_{||x||_2=1} x^\top A x = \min_{||y||_2=1} y^\top \Lambda y = \min_{||y||_2=1} \sum \lambda_i y_i^2 = \lambda_{min}(A)$$

(c) The optimization problem in (a) is equivalent to:

$$\max_{z_1, z_2, \dots z_n} \sum_i \lambda_i z_i$$

s.t. 
$$\sum_{i} z_{i} = 1$$

Which is a linear program, so it is convex. The problem in (b) is similar to (a), except that it is minimization problem instead of maximization.

(d) If  $Ax = \lambda x$ , then

$$A^2x = A(Ax) = A(\lambda x) = \lambda Ax = \lambda \times \lambda x = \lambda^2 x$$

Therefore  $\lambda^2$  is an eigenvalue of  $A^2$ .

Because  $A \succeq 0$ , all  $\lambda > 0$ . Therefore for all eigenvalues  $\lambda$  of A,  $\lambda^2$  are eigenvalues of  $A^2$ . Among them, the largest one is  $\lambda^2_{max}$  and the smallest one is  $\lambda^2_{min}$ , therefore

$$\lambda_{max}(A^2) = \lambda_{max}(A)^2$$

$$\lambda_{min}(A^2) = \lambda_{min}(A)^2$$

(e) 
$$\lambda_{min}(A) = \sqrt{\lambda_{min}(A^2)} \le \sqrt{x^{\top}A^{\top}Ax} = ||Ax||_2 \le \sqrt{\lambda_{max}(A^2)} = \lambda_{max}(A)$$

(f) For any vector x, there is a vector  $y = \frac{x}{||x||_2}$  which satisfies  $||y||_2 = 1$ . Then according to (e), there is

$$\lambda_{min}(A) \le ||Ay||_2 \le \lambda_{max}(A)$$

Therefore,

$$\lambda_{min}(A) \le ||Ax/||x||_2||_2 \le \lambda_{max}(A)$$

$$\lambda_{min}(A)||x||_2 \le ||Ax||_2 \le \lambda_{max}(A)||x||_2$$

## 5. Gradient Descent

(a) The first-order optimality condition is:

$$Ax^* = b$$

Therefore the closed-form solution is:

$$x^* = A^{-1}b$$

- (b)  $x^{(k+1)} = x^{(k)} \nabla f(x^{(k)})$
- (c)  $x^{(k)} x^* = x^{(k-1)} \nabla f(x^{(k-1)}) x^* = x^{(k-1)} x^* (Ax^{(k-1)} Ax^*) = (I A)(x^{(k-1)} x^*)$
- (d) Because the eigenvalues of A are all between 0 and 1, then the eigenvalues of matrix B = I A is also between 0 and 1. From (c), we got  $x^{(k)} x^* = (I A)(x^{(k-1)} x^*)$ , so

$$||x^{(k)} - x^*||_2 = ||(I - A)(x^{(k-1)} - x^*)||_2 \le \lambda_{max}(B)||x^{(k-1)} - x^*||_2$$

. Let  $\rho = \lambda_{max}(B)$  then there is

$$||x^{(k)} - x^*||_2 \le \rho ||x^{(k-1)} - x^*||_2$$

.

(e) From (d), there is:

$$||x^{(k)} - x^*||_2 \le \rho^k ||x^{(0)} - x^*||_2$$

To achieve  $||x^{(k)} - x^*||_2 \le \epsilon$ , there should be

$$\rho^k ||x^{(0)} - x^*||_2 \le \epsilon$$

Therefore,

$$k \geq \frac{\log \frac{\epsilon}{||x^{(0)} - x^*||_2}}{\log \rho}$$

(f) The running time of each iteration is  $O(n^2)$ , and there are  $\frac{\log \frac{\epsilon}{||x^{(0)}-x^*||_2}}{\log \rho}$  iteration. So the total running time is  $O(\frac{\log \frac{\epsilon}{||x^{(0)}-x^*||_2}}{\log \rho}n^2)$ .

#### 6. Classification

- (a) According to the definition of the loss function, if we choose c+1,  $R(f(x)=i|x)=\lambda_r$ . If we don't choose doubt, then  $R(f(x)=i|x)=\lambda_s(1-P(Y=k|x))$ . To minimize the risk, obviously when  $\lambda_r < \lambda_s(1-P(Y=k|x))$  for all k, we should choose c+1. Otherwise when  $\lambda_r \geq \lambda_s(1-P(Y=k|x))$  for some k, we should choose the k such that P(Y=k|x) is maximized. Therefore we got the policy to obtain the minimum risk.
- (b) If  $\lambda_r = 0$ , then we always classify the input as "doubt", because this will have zero risk. If  $\lambda_r > \lambda_s$ , the first policy is always adopted, so we never choose "doubt". This is consistent with our intuitive because when  $\lambda_r > \lambda_s$ , no matter which class we decide, we will have a lower risk than "doubt", so we never "doubt".

## 7. Gaussian Classification

- (a) According to the Bayes optimal decision theory, the boundary is the point where the two Gaussian distribution intersects, which is  $\frac{\mu_1 + \mu_2}{2}$ . And the desicion rule is that when  $x \leq \frac{\mu_1 + \mu_2}{2}$ ,  $f(x) = \omega_1$ , otherwise  $f(x) = \omega_2$ .
- (b) Because the two distributions are symmetric with respect to the decision boundary, so

$$P_e = 2 \times 0.5 \times \int_{\frac{\mu_1 + \mu_2}{2}}^{\infty} \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x - \mu_1)^2}{2\sigma^2}} dx$$

Let 
$$z = \frac{x - \mu_1}{\sigma}$$
, then

$$P_e = \frac{1}{\sqrt{2\pi}} \int_{\frac{\mu_2 - \mu_1}{2\sigma}}^{\infty} e^{-z^2/2} dz$$

### 8. Maximum Likelihood Estimation

The likelihood function is:

$$L(\vec{p}) = P(X_1 = x_1, X_2 = x_2, ..., ..., X_n = x_n) = p_1^{k_1} p_2^{k_2} p_3^{k_3}$$

Where  $k_j = \sum_{i=1}^n \mathbb{I}(x_i = j)$ . To maximize the likelihood, take the logarithm of the likelihood and then the derivative of the log likelihood should be zero:

$$L'(\vec{p}) = k_1 \log p_1 + k_2 \log p_2 + k_3 \log(1 - p_1 - p_2)$$

$$\frac{\partial L'(\vec{p})}{\partial p_1} = \frac{k_1}{p_1} - \frac{n - k_1 - k_2}{1 - p_1 - p_2} = 0$$

$$\frac{\partial L'(\vec{p})}{\partial p_2} = \frac{k_1}{p_2} - \frac{n - k_1 - k_2}{1 - p_1 - p_2} = 0$$

Solve the above two equation,

$$p_1 = \frac{k_1}{n}, p_2 = \frac{k_2}{n}, p_3 = \frac{k_3}{n}$$