

### 3 Homework 3 (Image Registration, sections 9-10)

Inexact landmark matching: Image matching with translation

- a.) We consider aligning a 2D template image  $I$  to a 2D target image  $I'$  using translation only. We want to find the vector  $b$  that minimizes the cost

$$C(b) = \frac{1}{2} \int |I(x - b) - I'(x)|^2 dx$$

Consider the perturbation  $b \rightarrow b + \epsilon h$  and write

$$J(\epsilon) = C(b + \epsilon h)$$

Work out

$$\left. \frac{d}{d\epsilon} J(\epsilon) \right|_{\epsilon=0}$$

- b.) Write down the gradient of the cost with respect to  $b$ . Recall that  $\nabla C(b) \cdot h = \left. \frac{d}{d\epsilon} J(\epsilon) \right|_{\epsilon=0}$ .  
 c.) Write down a gradient descent algorithm that can be used to minimize this cost for a given  $I$  and  $I'$ . It should take the form of

$$b_{new} = b_{old} - \epsilon(\text{gradient term})$$

for  $\epsilon$  for a small step.

- d.) Write a program in matlab that will implement this algorithm. The inputs should be the template image  $I$ , the target image  $I'$  (both 2D arrays), the gradient descent step size  $\epsilon$ , and the number of iterations of gradient descent.

The program should output the optimal vector  $b$ , and the transformed image  $I(x-b)$ .

Note that you can use MATLAB's built in function `gradient` to compute the gradient of the image. One method that you can use to apply the translation to  $I$  is:

```
[X, Y] = meshgrid(1:size(I,2),1:size(I,1));
I_translated_by_b = interp2(I, X-b(1),Y-b(2), 'linear',0);
```

You should print the cost  $C$  at each iteration of gradient descent to make sure it is decreasing. If it is not decreasing, choose a smaller step size.

You may use the given code `splineImage.m` as a model for your program. You will notice a lot of similarities, but your program will be simpler. For example, you will not need the function `applyPowerOfA` or input arguments `alpha` or `sigma`. Remember that your gradient will be a vector with 2 components. It will not be a function at each point in space like in `splineImage.m`



- e.) Use your code to match the corpus callosum 0001\_CC\_Con.png to 0003\_CC\_Alz.png with translation. You can view the whole MRI these structures are segmented from the files 0001\_MRI\_Con.png and 0003\_CC\_Alz.png if you wish.

You can load them like this:

```
I = double(imread('0001_CC_Con.png') > 0);
IPrime = double(imread('0001_CC_Alz.png') > 0);
```

This image should now take two values only: 0 and 1, and be represented in double precision, not with an 8-bit integer. You can see what these images look like in Fig. 1.

Make a figure showing the template image, the translated image, and the target image. Make a figure showing the template image minus the target image, and the translated template image minus the target image. Include a colorbar.

- f.) **Image matching with splines.** Use the given code `splineimage.m` to match your translated corpus callosum to your target. If you were unable to complete the previous part of the homework then just use the original (untranslated) corpus callosum.

- Use the value  $\sigma = 0.01$ . This parameter controls how important matching accuracy is relative to the size of the deformation.

- Use the value  $\alpha = 20$ . This parameter controls how smooth the deformation is.

Report the step size you used and the number of iterations. Report the **initial cost**, and the **final cost** after your algorithm is finished. Again, if the cost is not decreasing, choose a smaller gradient descent step size.

Make a figure showing the deformed image. Make a figure showing the deformed image minus the target image. Include a colorbar.

- g.) **Jacobian calculations.** Calculate the determinant of the Jacobian of the transformation  $\phi(x) = x + v(x)$  at each point in space. Show this in a figure with a colorbar.



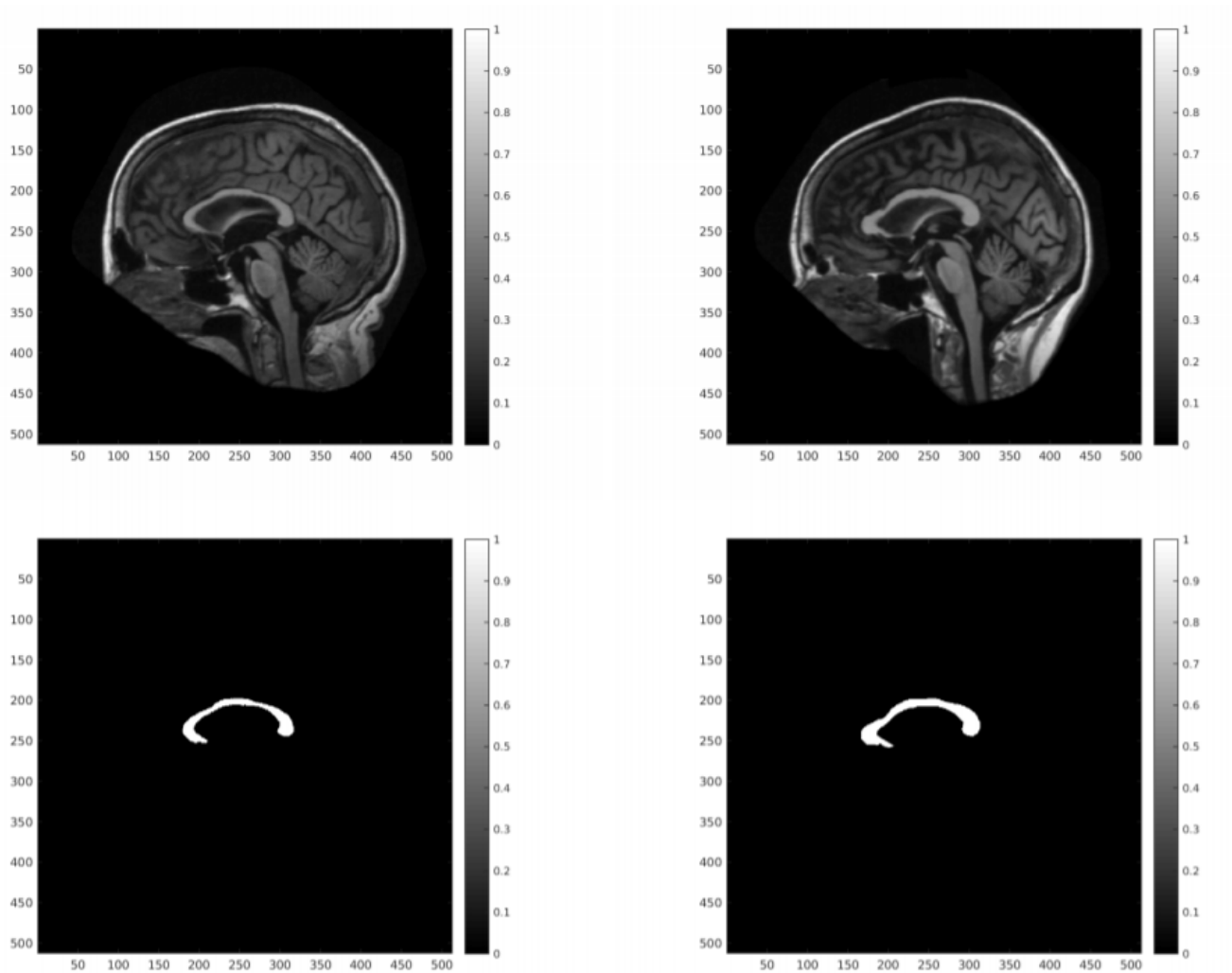


Figure 1: Corpus callosum for control (left) and Alzheimer's (right) subjects used for this exercise, shown with colorbar.