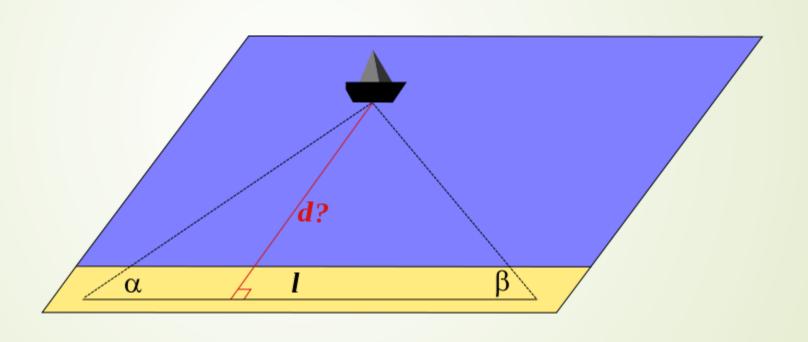
MV4D Survey

Henry Chen 2015/05/27

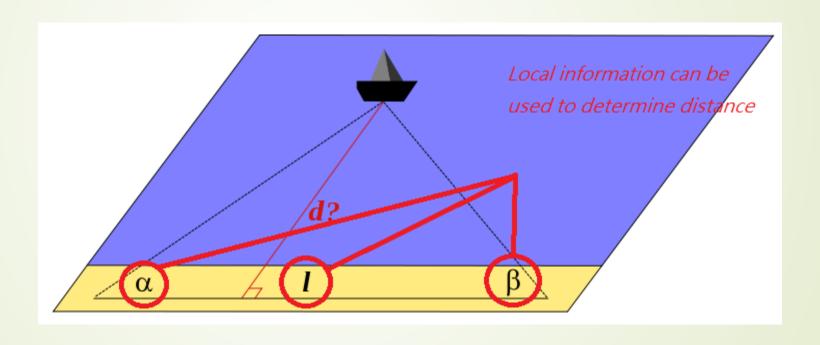
Agenda

- Basic Depth Map Technique Triangulation
- Common Depth Measurement Techniques
- What is MV4D (Project Tango Tablet)
- Patents and Major Players
- Analysis Matrix
- Future Application

Basic Depth Map Technique – Triangulation

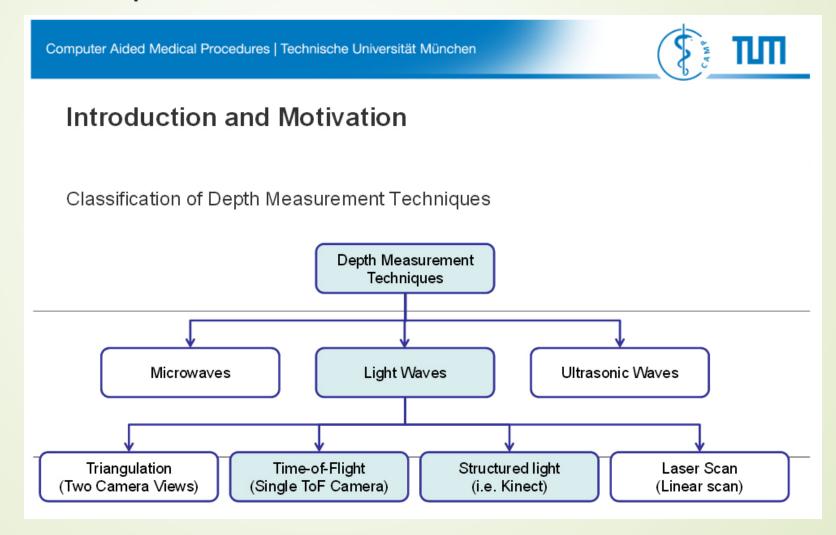


Basic Depth Map Technique – Triangulation



Basic Depth Map Technique – Triangulation

- Correspondence Problem
- The correspondence problem refers to the problem of ascertaining which parts of one image correspond to which parts of another image, where differences are due to movement of the camera, the elapse of time, and/or movement of objects in the photos -- Wikipedia

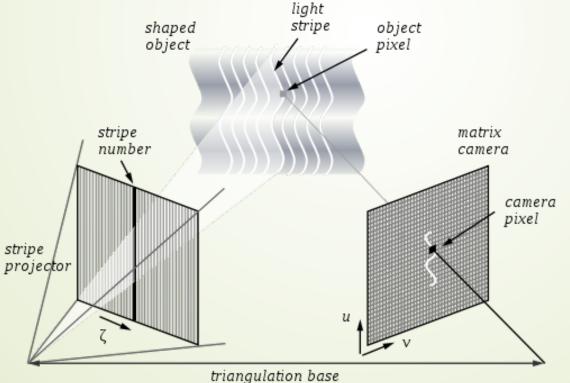


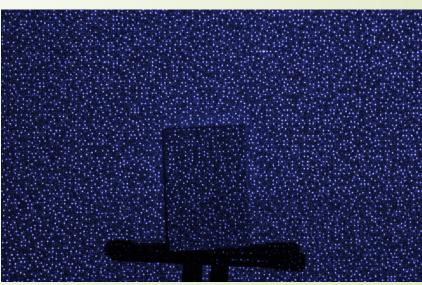
- Triangulation Two Camera Views
 - Human Eyes
 - HTC Dual Camera



- Triangulation Two Camera Views
- Pros:
 - 1. Passive
 - 2. No interference on objects
 - 3. Low dependency on objects' texture/material
 - 4. Relatively low hardware cost
- Cons:
 - 1. Need image processing algorithm to solve Correspondence Problem
 - 2. Relatively high software cost (algorithm, computing power, ...)
 - 3. High dependency on lighting condition
 - 4. Hard to get real-time information (computing)
 - 5. Medium accuracy

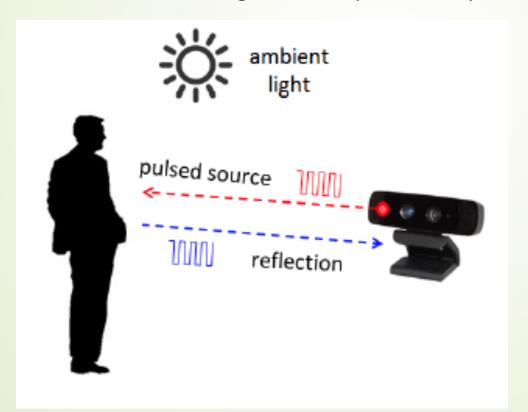
- Structured Light
 - Microsoft 1st gen Kinect (XBOX 360)





- Structured Light
- Pros:
 - 1. Active
 - 2. Correspondence Problem is easily solved
 - 3. Low software cost
 - 4. Low dependency on lighting condition
 - 5. Can get real-time information
 - 6. High accuracy
- Cons:
 - 1. Interference on objects (use IR to avoid this)
 - 2. High dependency on objects' texture (strong reflective, strong absorption)
 - 3. Relatively high hardware cost.

- Time-of-Flight
 - Microsoft 2nd gen Kinect (XBOX One)



Pros:

- 1. Real-time
- 2. High accuracy
- 3. Single camera (theoretically)

Cons:

1. Super expensive in money, size, and power

From MV4D website: http://www.mv4d.com/

1. CORE TECHNOLOGY

All MV4D solutions begin here, with our proprietary Structured Light Pattern. This patented "motion-capable" 3D range-imaging technology was developed to allow accurate capture of 3D data in dynamic scenes.

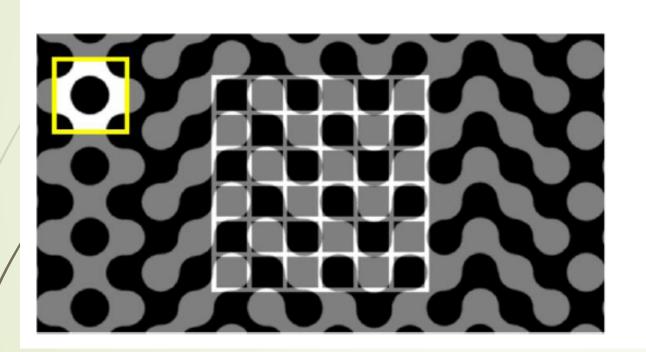
This pattern, which is projected upon physical objects and environments, is captured by a synced camera, and processed by our structured light algorithms to produce an accurate, detailed depth map of the captured scene.

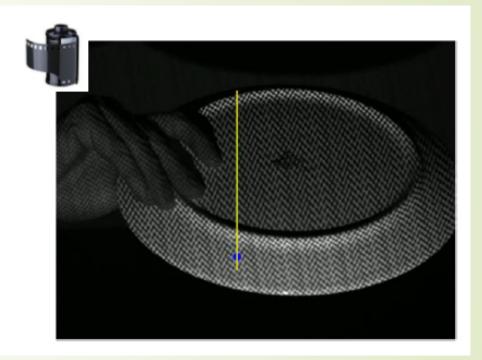


Core Technology:

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This patented "motion-capable" 3D range-imaging technology was developed to allow accurate capture of 3D data in dynamic scenes





3D geometric modeling and motion capture using both single and dual imaging

US 8090194 B2

摘要

A method and apparatus for obtaining an image to determine a three dimensional shape of a stationary or moving object using a bi dimensional coded light pattern having a plurality of distinct identifiable feature types. The coded light pattern is projected on the object such that each of the identifiable feature types appears at most once on predefined sections of distinguishable epipolar lines. An image of the object is captured and the reflected feature types are extracted along with their location on known epipolar lines in the captured image. Displacements of the reflected feature types along their epipolar lines from reference coordinates thereupon determine corresponding three dimensional coordinates in space and thus a 3D mapping or model of the shape of the object at any point in time.

公開號 US8090194 B2

出版類型 授權

申請書編號US 11/837,553發佈日期2012年1月3日申請日期2007年8月13日優先權日期 ②2006年11月21日

其他公開專利號 US8208719, US20080118143,

US20120063672

發明人 Eyal Golrdon, Gur Arie Bittan

原專利權人 Mantis Vision Ltd.

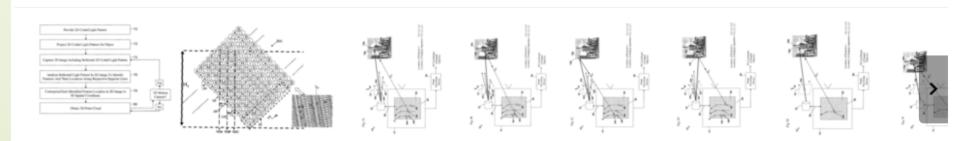
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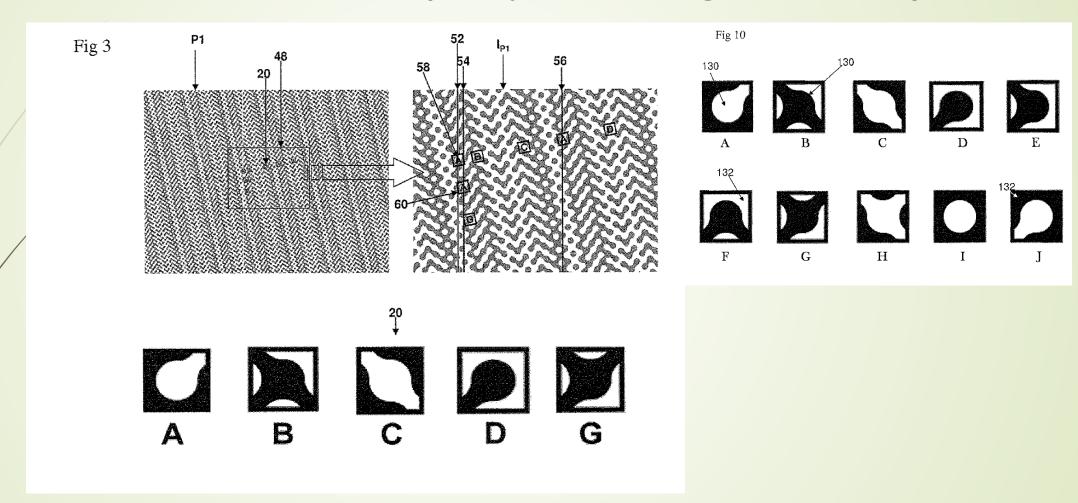
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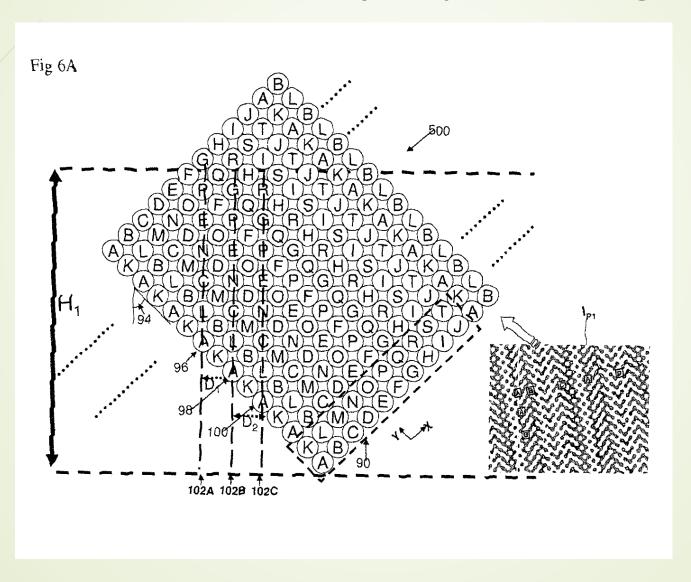
法律事件(2)

外部連結: 美國專利商標局, 美國專利商標局專利轉讓訊息, 歐洲專利局

圖片 (35)



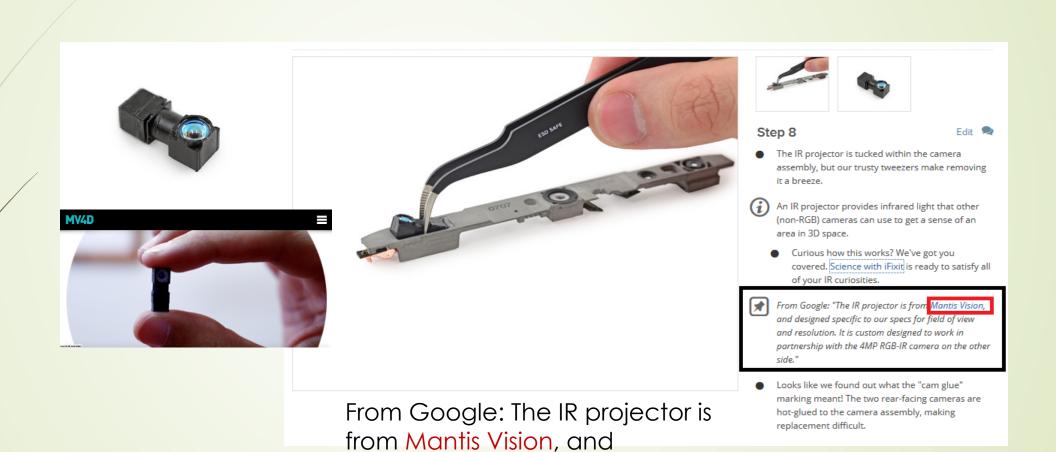




- From iFixit: Project Tango Tablet Teardown
- https://www.ifixit.com/Teardown/Project+Tango+Tablet+Teardown/28148







designed specific to our specs

.

2. CORE COMPONENTS

1. DRIVER

The patent-pending, Flash Projector
Driver maximizes the power-efficiency of
our flash projector and is customizable
per device.

4. SOFTWARE PROCESSING

Our Structured Light Algorithms process the camera's captured images in real-time to create an accurate point-cloud depth map. All SW is ported to off-the-shelf SOCs and application processors.

2. FLASH

The Structured Light Flash Projector is where MV4D formatted 3D begins. This component projects Mantis Vision's patented Structured Light Pattern onto the captured scene or object for depth capture, via invisible, infrared light.

3. CAMERA



The MV Camera Module depth sensors and optical elements work with off-the-shelf or custom camera modules to capture the encoded objects for 3D content creation. Available as single or dual modules (IR and/or color).

1. Driver:

The patent-pending, Flash
Projector Driver maximizes the
power-efficiency of our flash
projector and is customizable
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2. Flash:

The Structured Light Flash Projector is where MV4D formatted 3D begins

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Project Tango Tablet has those 3 parts

2. FLASH



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Project Tango Tablet has a customized 4mp RGB-IR camera

3. CAMERA



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3. INTEGRATED SOLUTIONS

AQUILA 3D TABLET

3D for Developers, Creators and Makers. An OEM-ready 3D tablet, specifically designed for dynamic 3D content creation, and featuring Mantis Vision's MV4D core 3D engine and depth sensing platform.



AQUILA PAGE

3D POCKET CAMERA

3D for Everyone. A handheld, mobile 3D scanner for real-time modeling of physical objects and environments. Quick, easy user-generated 3D content for design, printing, virtual planning, and more. Available as a fully manufactured solution or for integration with third-party solutions.



POCKETSCAN 3D PAGE

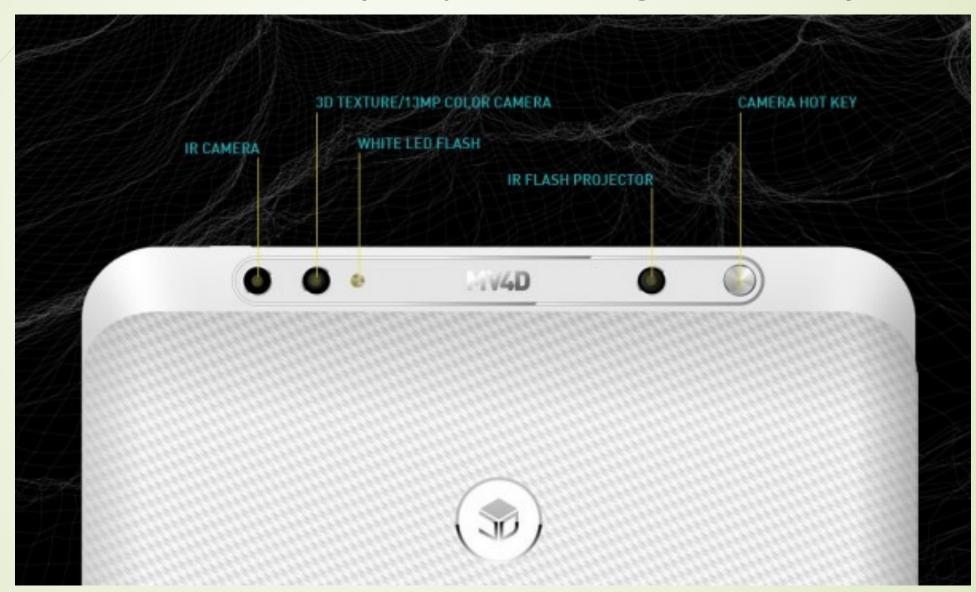
HANDHELD 3D SCANNERS

3D for Professional Applications. Our F5 Series of handheld 3D imagers was the first Mantis Vision solution built on our core technology to enter the market, and to this day is the only professional-grade mobile scanning solution specifically designed for field-use.

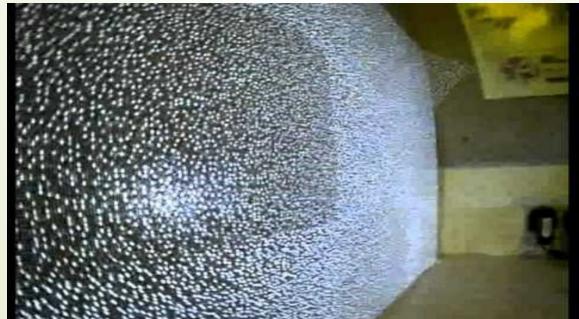


PRODUCT PAGE

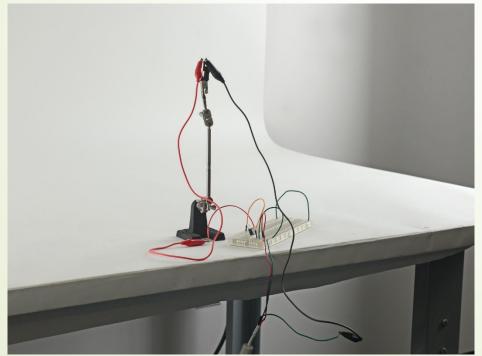




- Microsoft 1st gen Kinect (XBOX 360)
- Light code technology and patent from PrimeSense
- PrimeSense was bought by Apple on November 24, 2013
- https://www.youtube.com/watch?v=Tpa1JP1AtCo



- → 1st gen Project Tango Phone (Tablet is 2nd gen)
- Light code looks like 1st gen Kinect





- Microsoft 2nd gen Kinect (XBOX One)
- Time-of-Flight technology
- ToF technology and patent from Canesta (M\$ purchased this company)
- M\$ also purchased 3DV Systems, another low-cost ToF tech company, for patent concern



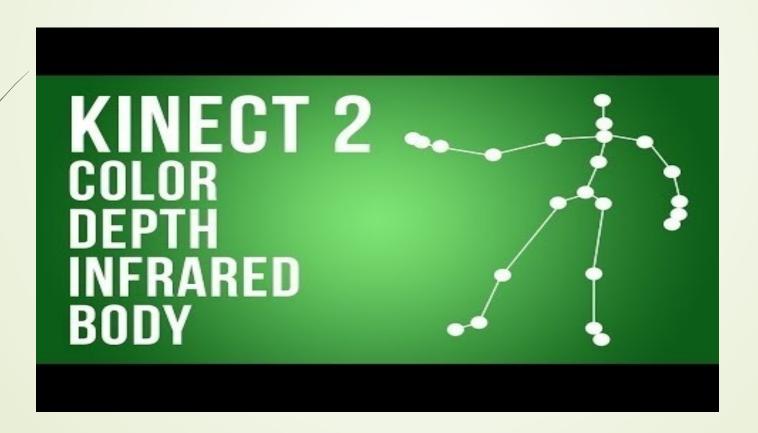




- Kinect's depth map
- Depth stream is at 30fps for Kinect 2 (XBOX One)

	Version 1	Version 2
Depth range	$0.4m \rightarrow 4.0m$	$0.4\text{m} \rightarrow 4.5\text{m}$
Color stream	640×480	1920×1080
Depth stream	320×240	512×424
Infrared stream	None	512×424
Audio stream	4-mic array	4-mic array
USB	2.0	3.0

https://www.youtube.com/watch?v=GZ3eYyBPv44



Analysis Matrix

Analysis Matrix

	Accuracy	Real-Time Feasible	Battery
Two-Camera (Passive)	Medium	Possible (correspondence problem)	Friendly
Projector-Camera (Active)	High (depends on good pattern)	Yes	Un-friendly
Time-of-Flight (Active)	High	Yes	Very Un-friendly

Analysis Matrix

Analysis Matrix

	Environment Lighting	Object Texture Dependency	Price
Two-Camera (Passive)	High	Low	Low
Projector-Camera (Active)	Low (IR-projector)	Medium	Medium
Time-of-Flight (Active)	Low (IR-projector)	Low?	High ? (Microsoft)

Analysis Matrix

Analysis Matrix

	Size
Two-Camera (Passive)	Small
Projector-Camera (Active)	Small
Time-of-Flight (Active)	Large

- Depth Map
 - Gesture Recognition Control
 - Apple wins the patent (M\$: what the)
 - http://technews.tw/2015/01/14/apple-patent-minority-report-style-gesture-controls/
 - http://www.appshot.net/op/news?nid=2804



- Depth Map
 - Robotics / Al

- 3D modeling (Real-time)
 - Google's search engine could advanced to 3D
 - Text → Image → Video(stream of images) → 3D → Stream of 3Ds
 - On-line store
 - Fitting
 - Advertising
 - Recommendation (Avatar)

- 3D modeling (Real-time)
 - AR / VR
 - Gaming
 - Interaction with designed 3D object → with real 3D object

http://www.mv4d.com/