Supplementary Reading for Module 4, Lesson 1: Kinematic Modeling in 2D

Read more about 2D plan motion and coordinate frames in the PDF below:

Chapter 2, "Models of Mobile Robots in the Plane" B.A. Francis and M. Maggiore, *Flocking and Rendezvous in Distributed Robotics*, SpringerBriefs in Control, Automation and Robotics (2016), https://www.springer.com/cda/content/document/cda_downloaddocument/9783319247274-c2.pdf?SGWID=0-0-45-1532785-p177708750.

Models of Mobile Robots in the Plane.pdf

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