

Supplementary Reading: Environment Representation

This paper discusses a highly detailed map used for autonomous driving:

- P. Bender, J. Ziegler and C. Stiller, "[Lanelets: Efficient map representation for autonomous driving](#)," 2014 IEEE Intelligent Vehicles Symposium Proceedings, Dearborn, MI, 2014, pp. 420-425. doi: 10.1109/IVS.2014.6856487 (Lanelet)

✓ Complete

