Contents

1	formula	1
2	RNN gradients	4
3	Implementation	4
4	Trading	4
5	Direct Learning	5
6	MSE and MLE	6
7	How to determine undetermined direction of random walk	7

1 formula

First we only consider one play

$$G(P_n, w^1) = \sum_{i=1}^{S} \tilde{\theta}_i \tanh(\theta_i P_n + \theta_{i0}) + \tilde{\theta_0}$$
(1)

Where $P_n = [p_1, p_2, p_3, ..., p_n], G(P_n, w^1) = [y_1, y_2, y_3, ..., y_n]$ $\forall i \in [1, ..., S], \theta_i P_n = (\theta_i p_1, \theta_i p_2, \theta_i p_3, ..., \theta_i p_n),$ So $\tanh(\theta_i P_n + \theta_{i0}) = [\tanh(\theta_i p_1 + \theta_{i0}), \tanh(\theta_i p_2 + \theta_{i0}), \tanh(\theta_i p_3 + \theta$

So $\tanh(\theta_i P_1 + \theta_{i0}) = [\tanh(\theta_i p_1 + \theta_{i0}), \tanh(\theta_i p_2 + \theta_{i0}), \tanh(\theta_i p_1 + \theta_{i0})]$ $+ \theta_{i0} + \sinh(\theta_i p_1 + \theta_{i0}) = [\sum_{i=1}^{S} \hat{\theta}_i \tanh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i \tanh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i \tanh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i \tanh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i \tanh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \sum_{i=1}^{S} \hat{\theta}_i + \sinh(\theta_i p_1 + \theta_{i0}) + \hat{\theta}_0 + \hat{\theta}_$

So $\sum_{i=1}^{S} \tilde{\theta}_{i} \tanh(\theta_{i} p_{n} + \theta_{i0}) + \tilde{\theta}_{0} = \left[\sum_{i=1}^{S} \tilde{\theta}_{i} \tanh(\theta_{i} p_{1} + \theta_{i0}) + \tilde{\theta}_{0}, \sum_{i=1}^{S} \tilde{\theta}_{i} \tanh(\theta_{i} p_{1} + \theta_{i0}) + \tilde{\theta}_{0}, \sum_{i=1}^{S} \tilde{\theta}_{i} \tanh(\theta_{i} p_{1} + \theta_{i0}) + \tilde{\theta}_{0}\right] = [y_{1}, y_{2}, ..., y_{n}].$

Take y_j , where $j \in [1, ..., n]$ for example

Let $z_j = \theta_i p_j + \theta_{i0}$ and $f(z_j) = \tanh(\theta_i p_j + \theta_{i0})$, we obtain

$$y_j = \sum_{i=1}^{S} \tilde{\theta}_i \tanh(\theta_i p_j + \theta_{i0}) + \tilde{\theta}_0$$
 (2)

$$= \sum_{i=1}^{S} \tilde{\theta_i} f(z_j) + \tilde{\theta_{i0}}$$
(3)

Calculate derivation for y_i ,

$$\frac{\partial y_j}{\partial p_j} = \sum_{i=1}^S \tilde{\theta}_i \theta_i \frac{\partial f(z_j)}{\partial z_j} \tag{4}$$

Now let's consider the mapping between p_j and x_j . let $\sigma_j = w^1 x_j - p_{j-1}$

$$p_j = \Phi(\sigma_j) + p_{j-1} \tag{5}$$

and

$$\Phi(x) = \begin{cases}
 x - 1/2, & x > 1/2 \\
 0, & -1/2 < x < -1/2 \\
 x + 1/2, & x < -1/2
\end{cases}$$
(6)

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 x + 1/2, & x > 1/2 \\
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 x - 1/2, & x < -1/2
 \end{cases}$$
(7)

Using chain rule, we obtain

$$\frac{\partial y_j}{\partial x_j} = \frac{\partial y_j}{\partial p_j} \frac{\partial p_j}{\partial x_j} \tag{8}$$

$$= \sum_{i=1}^{S} \tilde{\theta}_{i} \theta_{i} w^{1} \frac{\partial f(z_{j})}{\partial z_{j}} \frac{\partial \Phi(\sigma_{j})}{\partial \sigma_{j}}$$

$$\tag{9}$$

To consider **multiple plays** case, we reformulate the derivation as following:

$$\frac{\partial y_j^1}{\partial x_j} = \frac{\partial y_j^1}{\partial p_i^1} \frac{\partial p_j^1}{\partial x_j} \tag{10}$$

$$= \sum_{i=1}^{S} \tilde{\theta_i^1} \theta_i^1 w^1 \frac{\partial f(z_j^1)}{\partial z_j^1} \frac{\partial \Phi(\sigma_j^1)}{\partial \sigma_j^1}$$
(11)

Now from the architecture, we know that if we have P plays,

$$F = \frac{1}{P} \sum_{k=1}^{P} G^k \tag{12}$$

Where $F = [f_1, f_2, ..., f_n]$, and

$$f_j = \frac{1}{P} \sum_{k=1}^{P} y_j^k \tag{13}$$

our derivation is:

$$\frac{\partial f_j}{\partial x_j} = \frac{1}{P} \sum_{k=1}^{P} \frac{\partial y_j^k}{\partial x_j} \tag{14}$$

$$= \frac{1}{P} \sum_{k=1}^{P} \frac{\partial y_j^k}{\partial p_j^k} \frac{\partial p_j^k}{\partial x_j}$$
 (15)

$$= \frac{1}{P} \sum_{k=1}^{P} \sum_{i=1}^{S} \tilde{\theta}_{i}^{k} \theta_{i}^{k} w^{k} \frac{\partial f(z_{j}^{k})}{\partial z_{j}^{k}} \frac{\partial \Phi(\sigma_{j}^{k})}{\partial \sigma_{j}^{k}}$$
(16)

2 RNN gradients

$$\frac{\partial p_j}{\partial x_j} = \Phi'(\sigma_j) \frac{\partial \sigma_j}{\partial x_j} \tag{17}$$

$$= \Phi'(\sigma_j)w^1 \tag{18}$$

(19)(20)

$$\frac{\partial p_{j+1}}{\partial x_j} = \frac{\partial (\Phi(\sigma_{j+1}) + p_j)}{\partial x_j}$$

$$= \Phi'(\sigma_{j+1}) \frac{\partial \sigma_{j+1}}{\partial x_j} + \frac{\partial p_j}{\partial x_j}$$
(21)

$$= \Phi'(\sigma_{j+1}) \frac{\partial \sigma_{j+1}}{\partial x_j} + \frac{\partial p_j}{\partial x_j}$$
 (22)

$$= \Phi'(\sigma_{j+1}) \frac{\partial (w^1 x_{j+1} - p_j)}{\partial x_j} + \frac{\partial p_j}{\partial x_j}$$
 (23)

$$= (1 - \Phi'(\sigma_{j+1}))\Phi'(\sigma_j)w^1 \tag{24}$$

(25)

(26)

$$\frac{\partial p_{j+2}}{\partial x_i} = (1 - \Phi'(\sigma_{j+2}))(1 - \Phi'(\sigma_{j+1}))\Phi'(\sigma_j)w^1$$
 (27)

(28)

(29)

$$\frac{\partial p_{j+i}}{\partial x_j} = (1 - \Phi'(\sigma_{j+i}))...(1 - \Phi'(\sigma_{j+1}))\Phi'(\sigma_j)w^1$$
 (30)

3 Implementation

Consider
$$\mathcal{P}_n = [p_1, p_2, p_3, ..., p_n], G(\mathcal{P}_n, w^1) = [y_1, y_2, y_3, ..., y_n]$$

4 Trading

Assume, we observe prices $p_1, p_2, ..., p_N$ for a fixed N > 0. Based on Dima's paper, assume that the price p_n hysteretically depends on the underlying noise b_n , with b_n being a Brownian motion. Using the notation

$$\mathcal{B}_n := (b_1, b_2, ..., b_n), \mathcal{P}_n := (p_1, p_2, ..., p_n)$$

we have

$$b_0 = 0, b_n \sim \mathcal{N}(b_{n-1} + \mu_b, \sigma_b)$$
 (31)

$$p_n = F(\mathcal{B}_n, W_p) \tag{32}$$

Based on Dima's paperr again, the underlying noise b_n can be expressed as a hysteresis operator depending on the observed prices p_n , i.e.,

$$b_n = G(\mathcal{P}_n, W_b)$$

This is very nice as long as F and G are Prandtl-Ishlinskii operators. However, if one explicitly adds N's strategy, G becomes Preisach and F is not Preisach anymore. It is not clear how well it can be approximated by compositions of plays and nonlinear functions

5 Direct Learning

We learn the parameters W_b, μ_b, σ_b and the initial state p_0 of the network G by maximizing the likelihood of \mathcal{P} . Since \mathcal{P} is the determenistic function of a random variable mathcal B, its probability density is given by

$$p(\mathcal{P}) = p(p_1, p_2, ..., p_N)$$
 (33)

$$= p_b(b_1, b_2, ..., b_N) |\det \mathcal{J}(\mathcal{P})| \tag{34}$$

$$= p_b(G(\mathcal{P}_1, W_b), G(\mathcal{P}_2, W_b), ..., G(\mathcal{P}_N, W_b)) |\det \mathcal{J}(\mathcal{P})|$$
 (35)

where

$$p_b(\mathcal{B}) = \prod_{n=1}^{N} p_b(b_1, b_2, ..., b_N)$$
(36)

$$= \prod_{n=1}^{N} p_b(b_n|b_{n-1}) \tag{37}$$

$$= \prod_{n=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(b_n - b_{n-1} - \mu_b)^2}{2\sigma^2}\right)$$
 (38)

is the probability distribution of \mathcal{B} and $\mathcal{J}(\mathcal{P})$ is the Jacobian matrix. Recall that G has the causality property, hence $\mathcal{J}(\mathcal{P})$ is a triangular matrix.

Therefore, yield

$$p(\mathcal{P}) = p_b(G(\mathcal{P}_1, W_b), G(\mathcal{P}_2, W_b), ..., G(\mathcal{P}_N, W_b)) |\det \mathcal{J}(\mathcal{P})|$$
(39)

$$= \prod_{n=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(b_n - b_{n-1} - \mu_b)^2}{2\sigma^2}\right) \prod_{n=1}^{N} \left|\frac{\partial b_n}{\partial p_n}\right|$$
(40)

$$= \prod_{n=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(b_n - b_{n-1} - \mu_b)^2}{2\sigma^2}\right) \left|\frac{\partial b_n}{\partial p_n}\right|$$
(41)

Thus, maximizing the log-likelihood of $p(\mathcal{P})$ is equivalent to the following:

$$L = \ln p(\mathcal{P}) \sim \sum_{n=1}^{N} \left(-\frac{(b_n - b_{n-1} - \mu_b)^2}{2\sigma_b^2} - \ln \sigma_b + \ln \left| \frac{\partial b_n}{\partial p_n} \right| \right)$$
(42)

$$= -\frac{1}{2} \sum_{n=1}^{N} \left[\left(\frac{b_n - b_{n-1} - \mu_b}{\sigma_b} \right)^2 + 2 \ln \sigma_b - 2 \ln \left| \frac{\partial b_n}{\partial p_n} \right| \right] (43)$$

It's also equivalent to minimize the loss function as following:

$$\min_{W_b, p_0} L = \min_{W_b, p_0} \sum_{n=1}^{N} \left[\left(\frac{b_n - b_{n-1} - \mu_b}{\sigma_b} \right)^2 - 2 \ln \left| \frac{\partial b_n}{\partial p_n} \right| \right]$$
(44)

$$= \min_{W_b, p_0} \sum_{n=1}^{N} \left[(b_n - b_{n-1} - \mu_b)^2 - 2\sigma_b^2 \ln \left| \frac{\partial b_n}{\partial p_n} \right| \right]$$
(45)

From the target loss function, the only parameters we need to known is μ_b .

6 MSE and MLE

$$y \sim \mathcal{N}(y|G(x,w),\sigma^2)$$
 (46)

$$p(y) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(y - G(x, w))^2}{\sigma^2}\right)$$
 (47)

$$p(\mathcal{Y}) = p(y_1, y_2, ..., y_N)$$
 (48)

$$= \prod_{i=1}^{N} p(y_i) \tag{49}$$

(50)

$$\ln p(\mathcal{Y}) = \sum_{i} \left(-\frac{1}{2} \ln 2\pi - \ln \sigma - \frac{(y_i - G(x_i, w)^2)}{\sigma^2} \right)$$
 (51)

Assume $z_i = f(y_i)$, we obtain

$$p(z_i) = p(f(y_i)) \left(\frac{\partial f}{\partial y_i}\right)^{-1} f^{-1}(z_i)$$
(52)

 $\max(\mu, \sigma, w)$ s.t. $p(z_i)$ is maximal

7 How to determine undetermined direction of random walk?

If external agents buy stocks from the market, then the total number of stocks in market descreases, leading to increasing the prices.

In other words, the amount of stocks in market descreases if price rises. And the amount of stocks increases if prices go down.

The root cause of amount chaging in our assumption is the behavior of external agents. We model the behavior of external agents as markov chain(random walk).

Since we observe a series of prices in advance, we can determine the direction of random walk.