#### Contents

1	formula	1
<b>2</b>	RNN gradients	3
3	Implementation	4
4	Trading	4
5	Direct Learning	4
6	MSE and MLE	5

#### formula 1

First we only consider one play

$$G(P_n, w^1) = \sum_{i=1}^{S} \tilde{\theta_i} \tanh(\theta_i P_n + \theta_{i0}) + \tilde{\theta_0}$$
(1)

Where  $P_n = [p_1, p_2, p_3, ..., p_n], G(P_n, w^1) = [y_1, y_2, y_3, ..., y_n]$  $\forall i \in [1, ..., S], \ \theta_i P_n = (\theta_i p_1, \theta_i p_2, \theta_i p_3, ..., \theta_i p_n),$ 

So  $\tanh(\theta_i P_n + \theta_{i0}) = [\tanh(\theta_i p_1 + \theta_{i0}), \tanh(\theta_i p_2 + \theta_{i0}), \tanh(\theta_i p_3 + \theta_{i0})]$ 

 $\theta_{i0}), \dots, \tanh(\theta_i p_n + \theta_{i0})]$   $\operatorname{So} \sum_{i=1}^{S} \tilde{\theta}_i \tanh(\theta_i P_n + \theta_{i0}) + \tilde{\theta}_0 = \left[\sum_{i=1}^{S} \tilde{\theta}_i \tanh(\theta_i p_1 + \theta_{i0}) + \tilde{\theta}_0, \sum_{i=1}^{S} \tilde{\theta}_i \tanh(\theta_i p_2 + \theta_{i0}) + \tilde{\theta}_0, \dots, \sum_{i=1}^{S} \tilde{\theta}_i \tanh(\theta_i p_1 + \theta_{i0}) + \tilde{\theta}_0\right] = [y_1, y_2, \dots, y_n].$   $\operatorname{Take} y_j, \text{ where } j \in [1, \dots, n] \text{ for example}$ 

Let  $z_j = \theta_i p_j + \theta_{i0}$  and  $f(z_j) = \tanh(\theta_i p_j + \theta_{i0})$ , we obtain

$$y_j = \sum_{i=1}^{S} \tilde{\theta}_i \tanh(\theta_i p_j + \theta_{i0}) + \tilde{\theta}_0$$
 (2)

$$= \sum_{i=1}^{S} \tilde{\theta}_i f(z_j) + \tilde{\theta}_{i0}$$
 (3)

Calculate derivation for  $y_i$ ,

$$\frac{\partial y_j}{\partial p_j} = \sum_{i=1}^{S} \tilde{\theta}_i \theta_i \frac{\partial f(z_j)}{\partial z_j} \tag{4}$$

Now let's consider the mapping between  $p_j$  and  $x_j$ . let  $\sigma_j = w^1 x_j - p_{j-1}$ 

$$p_j = \Phi(\sigma_j) + p_{j-1} \tag{5}$$

and

$$\Phi(x) = \begin{cases} x, x > 0 \\ 0, -1 < x < 0 \\ x - 1, x < -1 \end{cases}$$

(6)

Using chain rule, we obtain

$$\frac{\partial y_j}{\partial x_j} = \frac{\partial y_j}{\partial p_j} \frac{\partial p_j}{\partial x_j} \tag{7}$$

$$= \sum_{i=1}^{S} \tilde{\theta}_{i} \theta_{i} w^{1} \frac{\partial f(z_{j})}{\partial z_{j}} \frac{\partial \Phi(\sigma_{j})}{\partial \sigma_{j}}$$
(8)

To consider **multiple plays** case, we reformulate the derivation as following:

$$\frac{\partial y_j^1}{\partial x_j} = \frac{\partial y_j^1}{\partial p_j^1} \frac{\partial p_j^1}{\partial x_j} \tag{9}$$

$$= \sum_{i=1}^{S} \tilde{\theta_i^1} \theta_i^1 w^1 \frac{\partial f(z_j^1)}{\partial z_j^1} \frac{\partial \Phi(\sigma_j^1)}{\partial \sigma_j^1}$$
 (10)

Now from the architecture, we know that if we have P plays,

$$F = \frac{1}{P} \sum_{k=1}^{P} G^k \tag{11}$$

Where  $F = [f_1, f_2, ..., f_n]$ , and

$$f_j = \frac{1}{P} \sum_{k=1}^{P} y_j^k \tag{12}$$

our derivation is:

$$\frac{\partial f_j}{\partial x_j} = \frac{1}{P} \sum_{k=1}^{P} \frac{\partial y_j^k}{\partial x_j} \tag{13}$$

$$= \frac{1}{P} \sum_{k=1}^{P} \frac{\partial y_j^k}{\partial p_j^k} \frac{\partial p_j^k}{\partial x_j}$$
 (14)

$$= \frac{1}{P} \sum_{k=1}^{P} \sum_{i=1}^{S} \tilde{\theta}_{i}^{k} \theta_{i}^{k} w^{k} \frac{\partial f(z_{j}^{k})}{\partial z_{j}^{k}} \frac{\partial \Phi(\sigma_{j}^{k})}{\partial \sigma_{j}^{k}}$$
(15)

# 2 RNN gradients

$$\frac{\partial p_j}{\partial x_j} = \Phi'(\sigma_j) \frac{\partial \sigma_j}{\partial x_j} \tag{16}$$

$$= \Phi'(\sigma_j)w^1 \tag{17}$$

(18)

$$\frac{\partial p_{j+1}}{\partial x_j} = \frac{\partial (\Phi(\sigma_{j+1}) + p_j)}{\partial x_j} \tag{20}$$

$$= \Phi'(\sigma_{j+1}) \frac{\partial \sigma_{j+1}}{\partial x_j} + \frac{\partial p_j}{\partial x_j}$$
 (21)

$$= \Phi'(\sigma_{j+1}) \frac{\partial (w^1 x_{j+1} - p_j)}{\partial x_j} + \frac{\partial p_j}{\partial x_j}$$
 (22)

$$= (1 - \Phi'(\sigma_{j+1}))\Phi'(\sigma_j)w^1$$
(23)

(24)

$$\frac{\partial p_{j+2}}{\partial x_j} = (1 - \Phi'(\sigma_{j+2}))(1 - \Phi'(\sigma_{j+1}))\Phi'(\sigma_j)w^1$$
 (26)

(27)

(28)

$$\frac{\partial p_{j+i}}{\partial x_i} = (1 - \Phi'(\sigma_{j+i}))...(1 - \Phi'(\sigma_{j+1}))\Phi'(\sigma_j)w^1$$
 (29)

## 3 Implementation

Consider  $\mathcal{P}_n = [p_1, p_2, p_3, ..., p_n], G(\mathcal{P}_n, w^1) = [y_1, y_2, y_3, ..., y_n]$ 

## 4 Trading

Assume, we observe prices  $p_1, p_2, ..., p_N$  for a fixed N > 0. Based on Dima's paper, assume that the price  $p_n$  hysteretically depends on the underlying noise  $b_n$ , with  $b_n$  being a Brownian motion. Using the notation

$$\mathcal{B}_n := (b_1, b_2, ..., b_n), \mathcal{P}_n := (p_1, p_2, ..., p_n)$$

we have

$$b_0 = 0, b_n \sim \mathcal{N}(b_{n-1} + \mu_b, \sigma_b)$$
 (30)

$$p_n = F(\mathcal{B}_n, W_p) \tag{31}$$

Based on Dima's paperr again, the underlying noise  $b_n$  can be expressed as a hysteresis operator depending on the observed prices  $p_n$ , i.e.,

$$b_n = G(\mathcal{P}_n, W_b)$$

\*\*This is very nice as long as F and G are Prandtl-Ishlinskii operators. However, if one explicitly adds N's strategy, G becomes Preisach and F is not Preisach anymore. It is not clear how well it can be approximated by compositions of plays and nonlinear functions\*\*

# 5 Direct Learning

We learn the parameters  $W_b, \mu_b, \sigma_b$  and the initial state  $p_0$  of the network G by maximizing the likelihood of  $\mathcal{P}$ . Since  $\mathcal{P}$  is the determenistic function of a random variable mathcal B, its probability density is given by

$$p(\mathcal{P}) = p(p_1, p_2, ..., p_N)$$
 (32)

$$= p_b(b_1, b_2, ..., b_N) |\det \mathcal{J}(\mathcal{P})| \tag{33}$$

$$= p_b(G(\mathcal{P}_1, W_b), G(\mathcal{P}_2, W_b), ..., G(\mathcal{P}_N, W_b)) |\det \mathcal{J}(\mathcal{P})|$$
 (34)

where

$$p_b(\mathcal{B}) = \prod_{n=1}^N p_b(b_1, b_2, ..., b_N)$$
 (35)

$$= \prod_{n=1}^{N} p_b(b_n|b_{n-1}) \tag{36}$$

$$= \prod_{n=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(b_n - b_{n-1} - \mu_b)^2}{2\sigma^2}\right)$$
(37)

is the probability distribution of  $\mathcal{B}$  and  $\mathcal{J}(\mathcal{P})$  is the Jacobian matrix. Recall that G has the causality property, hence  $\mathcal{J}(\mathcal{P})$  is a triangular matrix. Therefore, yield

$$p(\mathcal{P}) = p_b(G(\mathcal{P}_1, W_b), G(\mathcal{P}_2, W_b), ..., G(\mathcal{P}_N, W_b)) |\det \mathcal{J}(\mathcal{P})|$$
(38)

$$= \prod_{n=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(b_n - b_{n-1} - \mu_b)^2}{2\sigma^2}\right) \prod_{n=1}^{N} \left|\frac{\partial b_n}{\partial p_n}\right|$$
(39)

$$= \prod_{n=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(b_n - b_{n-1} - \mu_b)^2}{2\sigma^2}\right) \left|\frac{\partial b_n}{\partial p_n}\right|$$
(40)

Thus, maximizing the log-likelihood of  $p(\mathcal{P})$  is equivalent to the following:

$$L = \ln p(\mathcal{P}) \sim \sum_{n=1}^{N} \left( -\frac{(b_n - b_{n-1} - \mu_b)^2}{2\sigma_b^2} - \ln \sigma_b + \ln \left| \frac{\partial b_n}{\partial p_n} \right| \right)$$
(41)

$$= -\frac{1}{2} \sum_{n=1}^{N} \left[ \left( \frac{b_n - b_{n-1} - \mu_b}{\sigma_b} \right)^2 + 2 \ln \sigma_b - 2 \ln \left| \frac{\partial b_n}{\partial p_n} \right| \right] (42)$$

It's also equivalent to mimizing the loss function as following:

$$\min L = \min \sum_{n=1}^{N} \left[ \left( \frac{b_n - b_{n-1} - \mu_b}{\sigma_b} \right)^2 - 2 \ln \left| \frac{\partial b_n}{\partial p_n} \right| \right]$$
(43)

$$= \min \sum_{n=1}^{N} \left[ \left( b_n - b_{n-1} - \mu_b \right)^2 - 2\sigma_b^2 \ln \left| \frac{\partial b_n}{\partial p_n} \right| \right]$$
 (44)

#### 6 MSE and MLE

$$y \sim \mathcal{N}\left(y|G(x,w),\sigma^{2}\right) (45)$$

$$p(y) = 1 \frac{1}{\sqrt{2\pi}\sigma \exp\left(-\frac{(y-G(x,w))^{2}}{\sigma^{2}}\right) (46)}$$

$$p(Y) = \prod_{i} p(y_{i}) (47)$$

$$\ln p(\mathcal{Y}) = \sum_{i} \left(-\frac{1}{2} \ln 2\pi - \ln \sigma - \frac{(y_{i}-G(x_{i},w)^{2})}{\sigma^{2}}\right) (48)$$
Assume  $z_{i} = f(y_{i})$ , we obtain
$$p(z_{i}) = p(f(y_{i})) \left(\frac{\partial f}{\partial y_{i}}\right)^{-1} f^{-1}(z_{i})$$
(49)

 $\max(\mu, \sigma, w)$  s.t.  $p(z_i)$  is maximal