

Hochiminh city University of Technology  
Faculty of Computer Science and Engineering



# COMPUTER GRAPHICS

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## CHAPTER 7 :

### Viewing

# OUTLINE

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- ❑ Classical Viewing
- ❑ Orthographic Projection
- ❑ Axonometric Projections
- ❑ Oblique Projection
- ❑ Perspective Projection
- ❑ Computer Viewing
- ❑ View Volume

# Classical Viewing

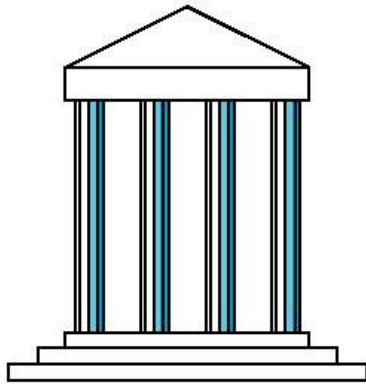


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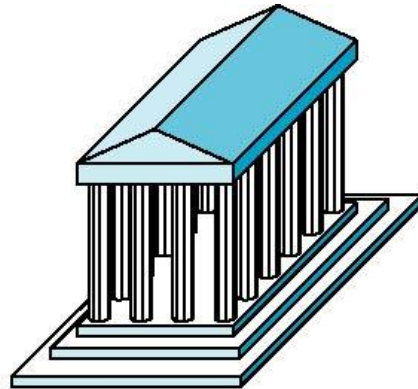
ID 32507419  
Richard Thomas | Dreamstime.com

# Classical Viewing

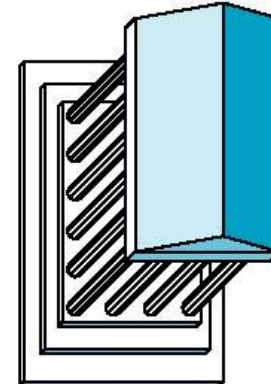
## □ Classical Projections



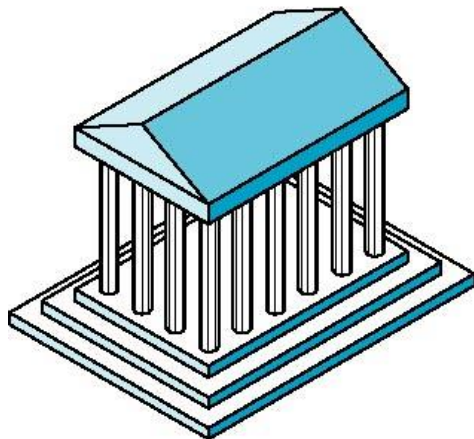
Front elevation



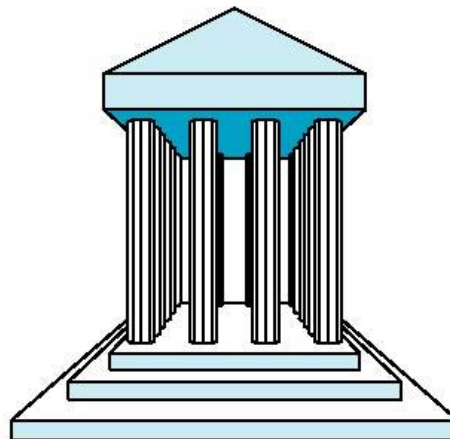
Elevation oblique



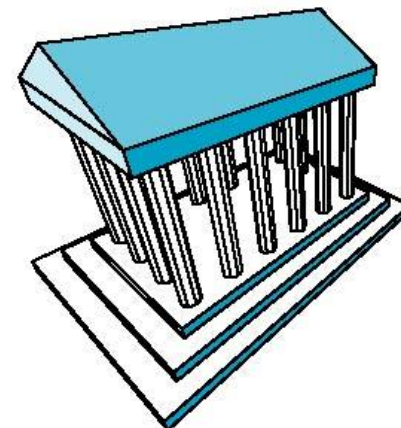
Plan oblique



Isometric



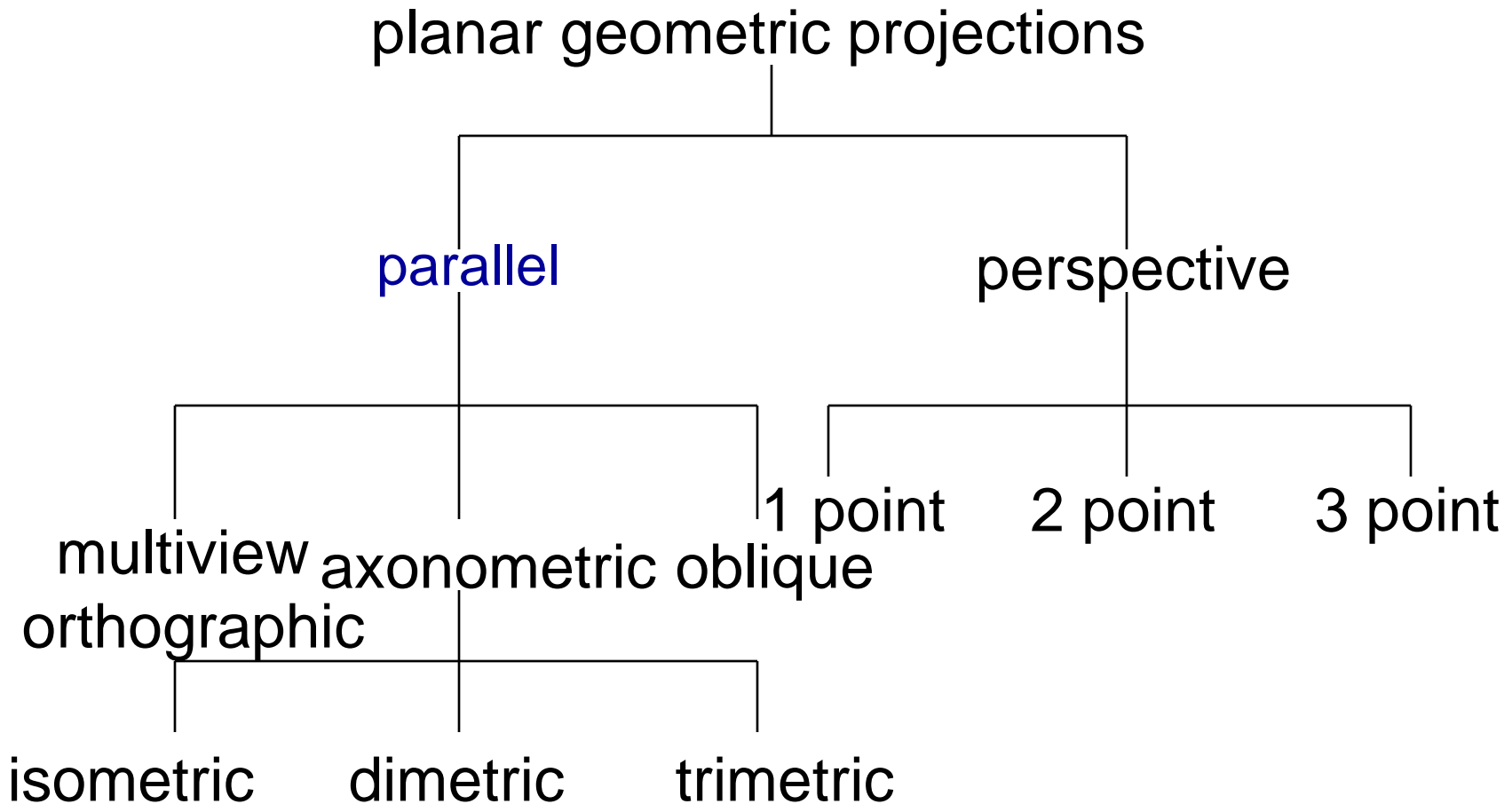
One-point perspective



Three-point perspective

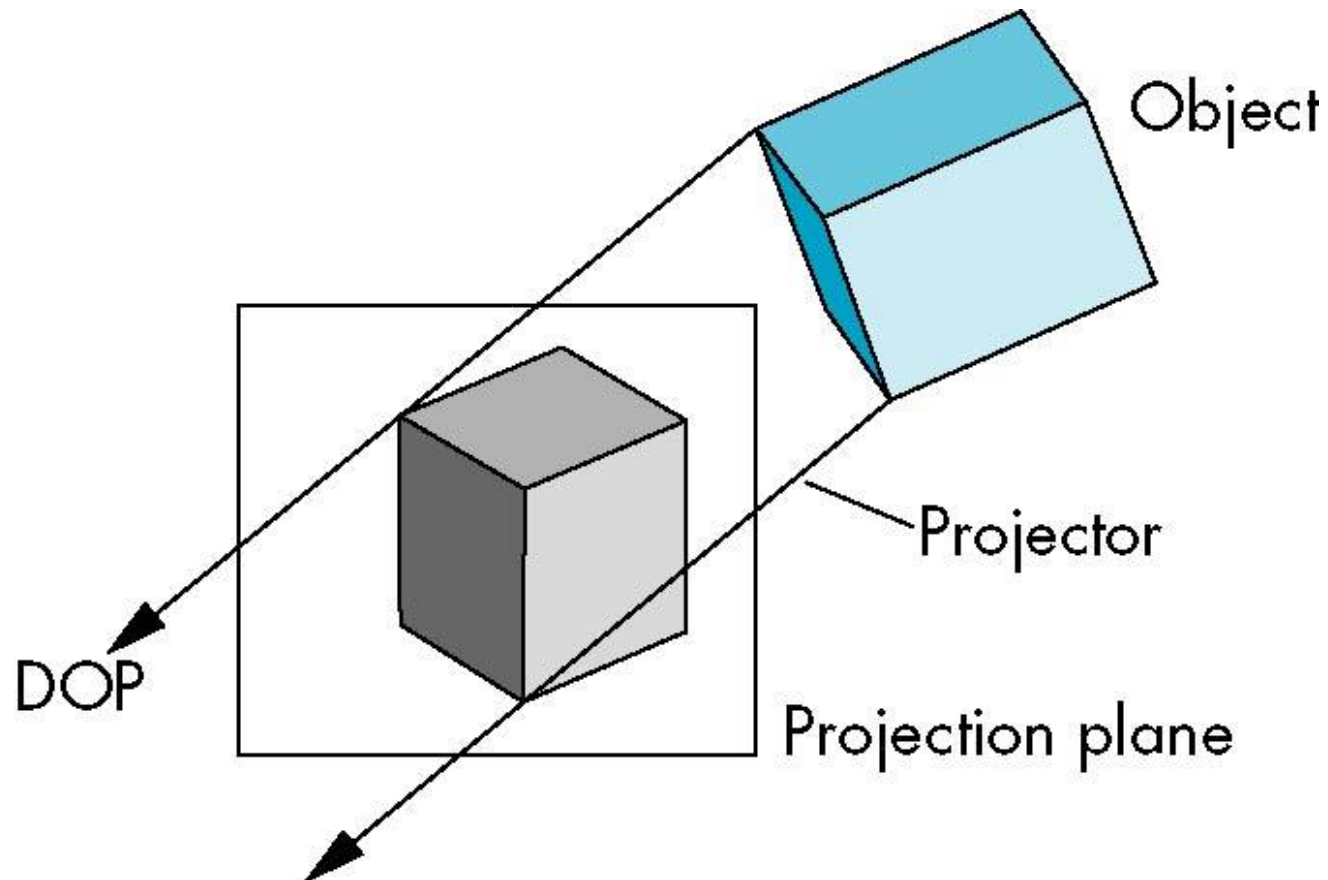
# Classical Viewing

## □ Taxonomy of Planar Geometric Projections



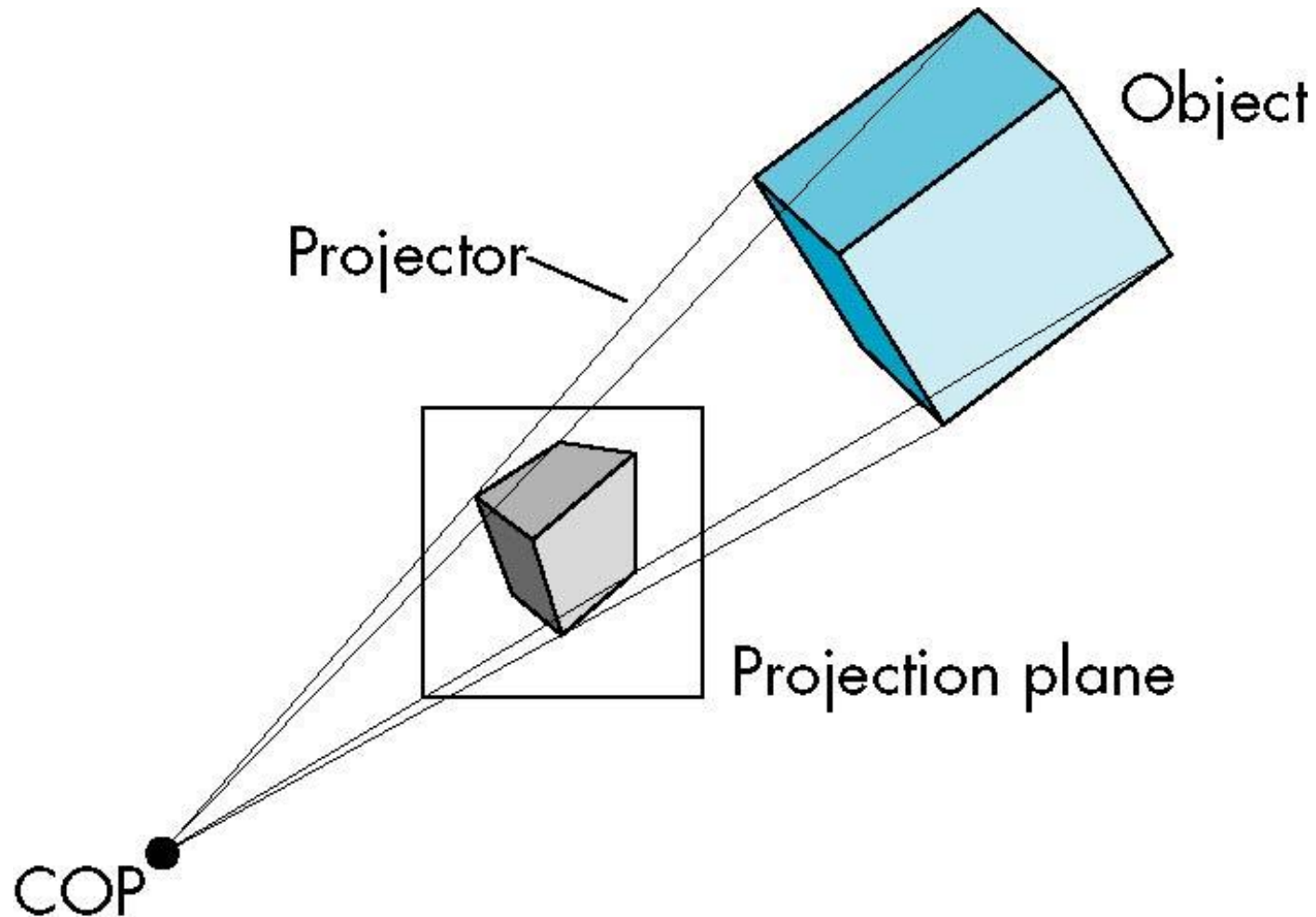
# Classical Viewing

## □ Parallel Projection



# Classical Viewing

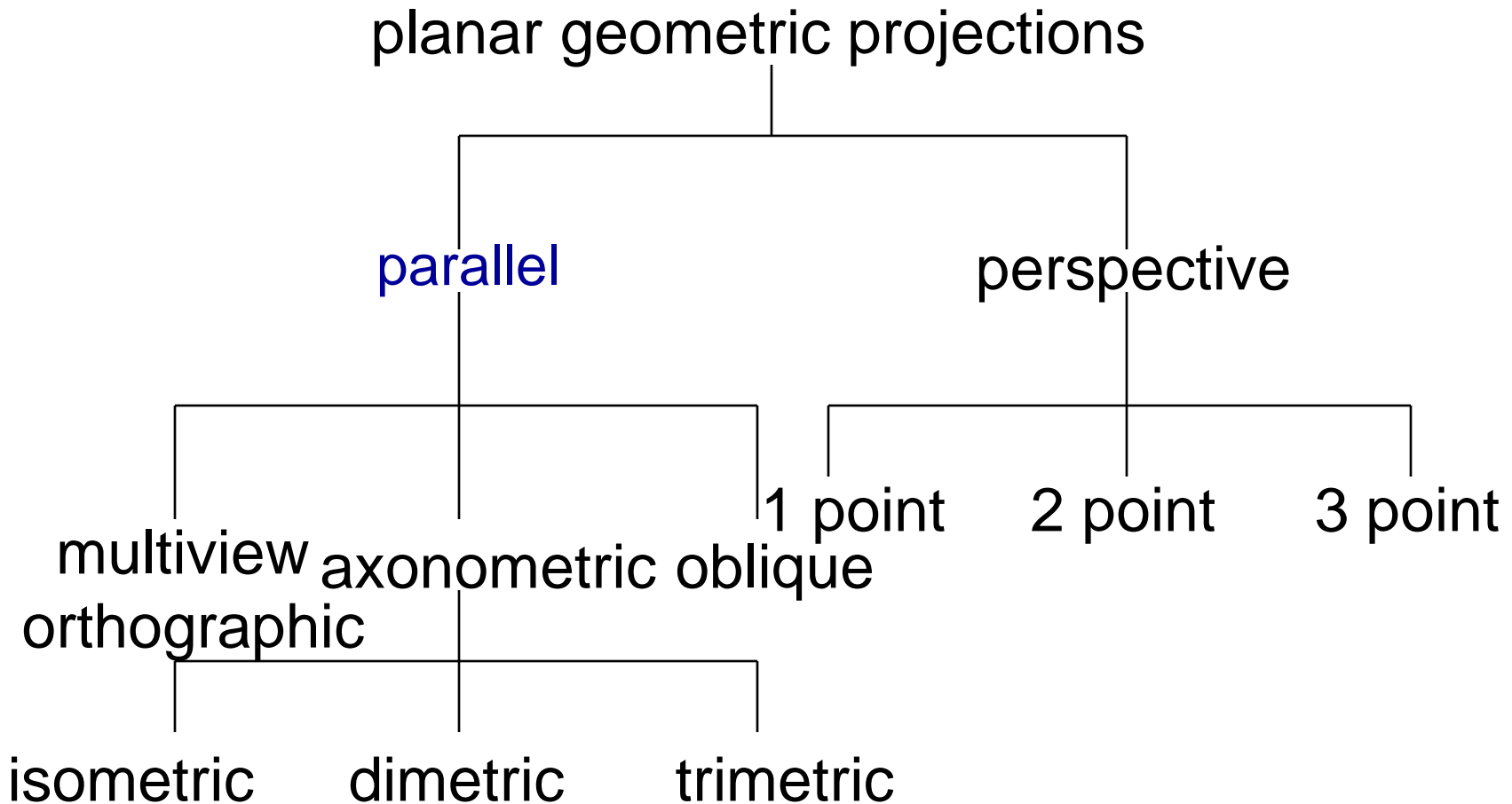
## □ Perspective Projection





# Classical Viewing

## □ Taxonomy of Planar Geometric Projections





# Orthographic Projection

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## ❑ Multiview Orthographic Projection

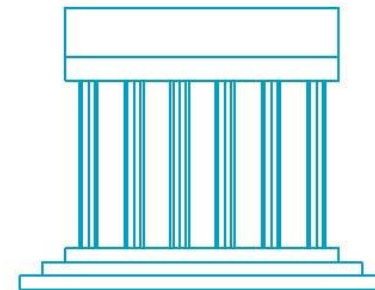
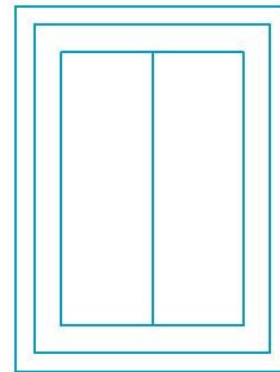
- Projection plane parallel to principal face
- Usually form front, top, side views

isometric (not multiview  
orthographic view)



front

in CAD and architecture,  
we often display three  
multiviews plus isometric  
top



side

# Orthographic Projection

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## ❑ Advantages

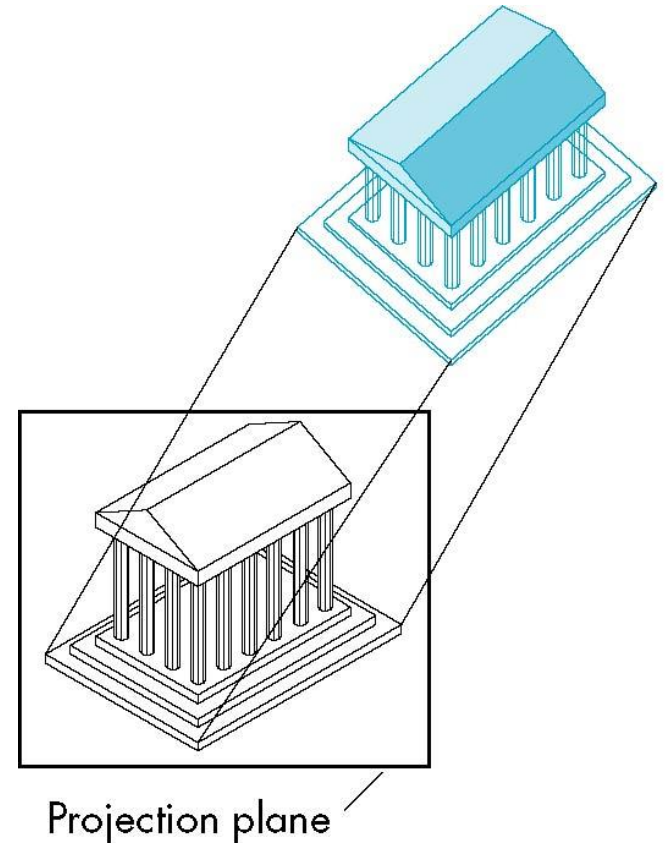
- Preserves both distances and angles
  - Shapes preserved
  - Can be used for measurements
    - Building plans
    - Manuals

## ❑ Disadvantages

- Cannot see what object really looks like because many surfaces hidden from view
  - Often we add the isometric

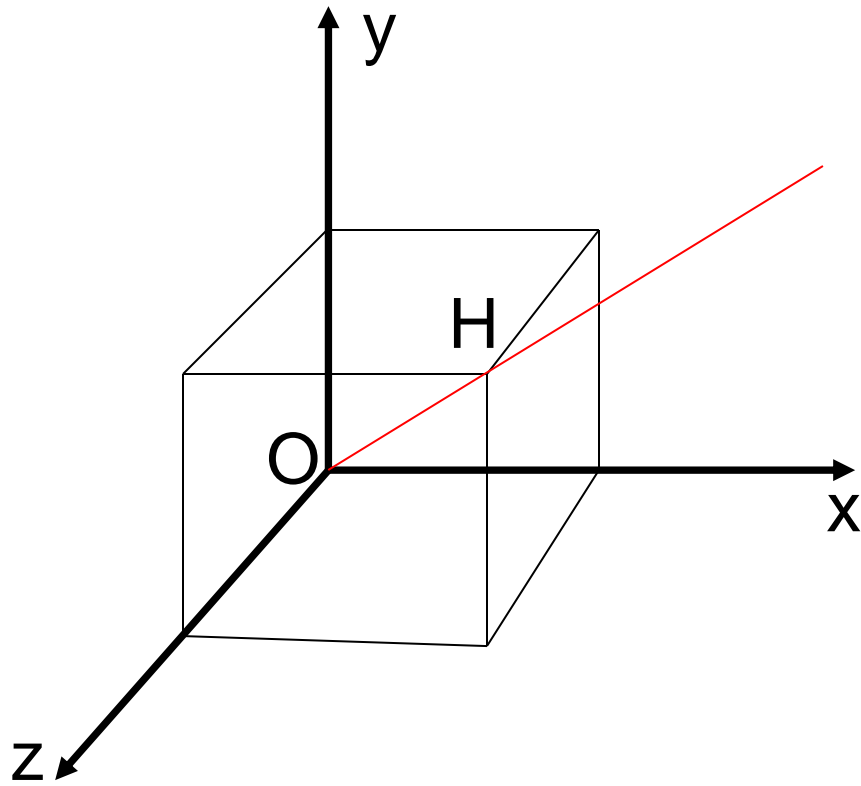
# Axonometric Projections

- Allow projection plane to move relative to object
  - Classify by how many angles of a corner of a projected cube are the same
    - none: trimetric
    - two: dimetric
    - three: isometric(trục đo – đều)

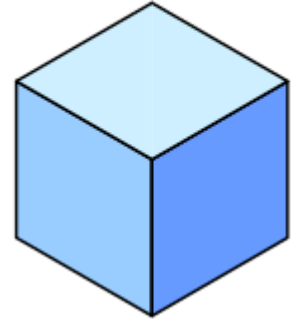


# Axonometric Projections

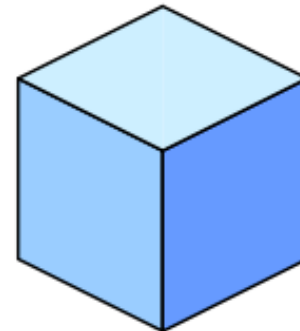
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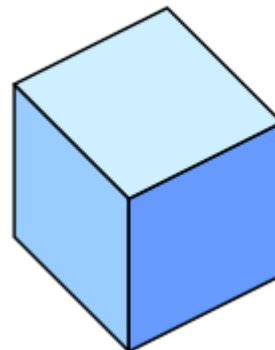
Isometric



Dimetric

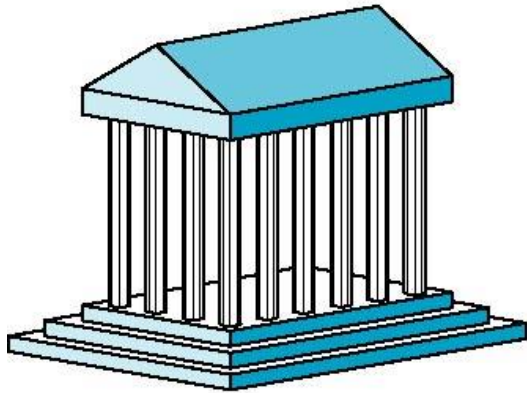


Trimetric

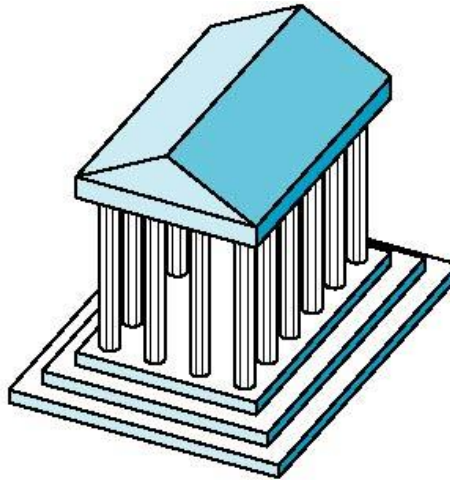


# Axonometric Projections

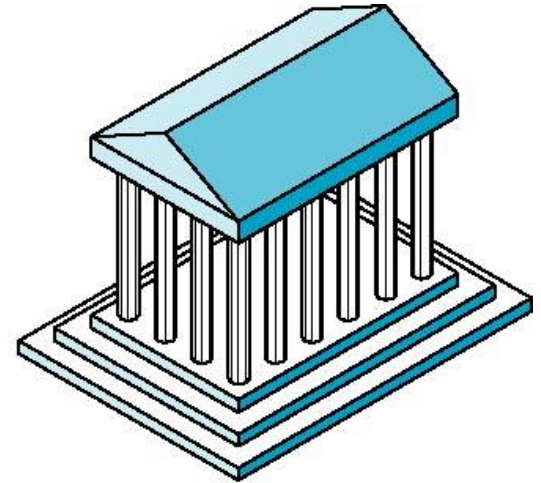
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Dimetric



Trimetric



Isometric

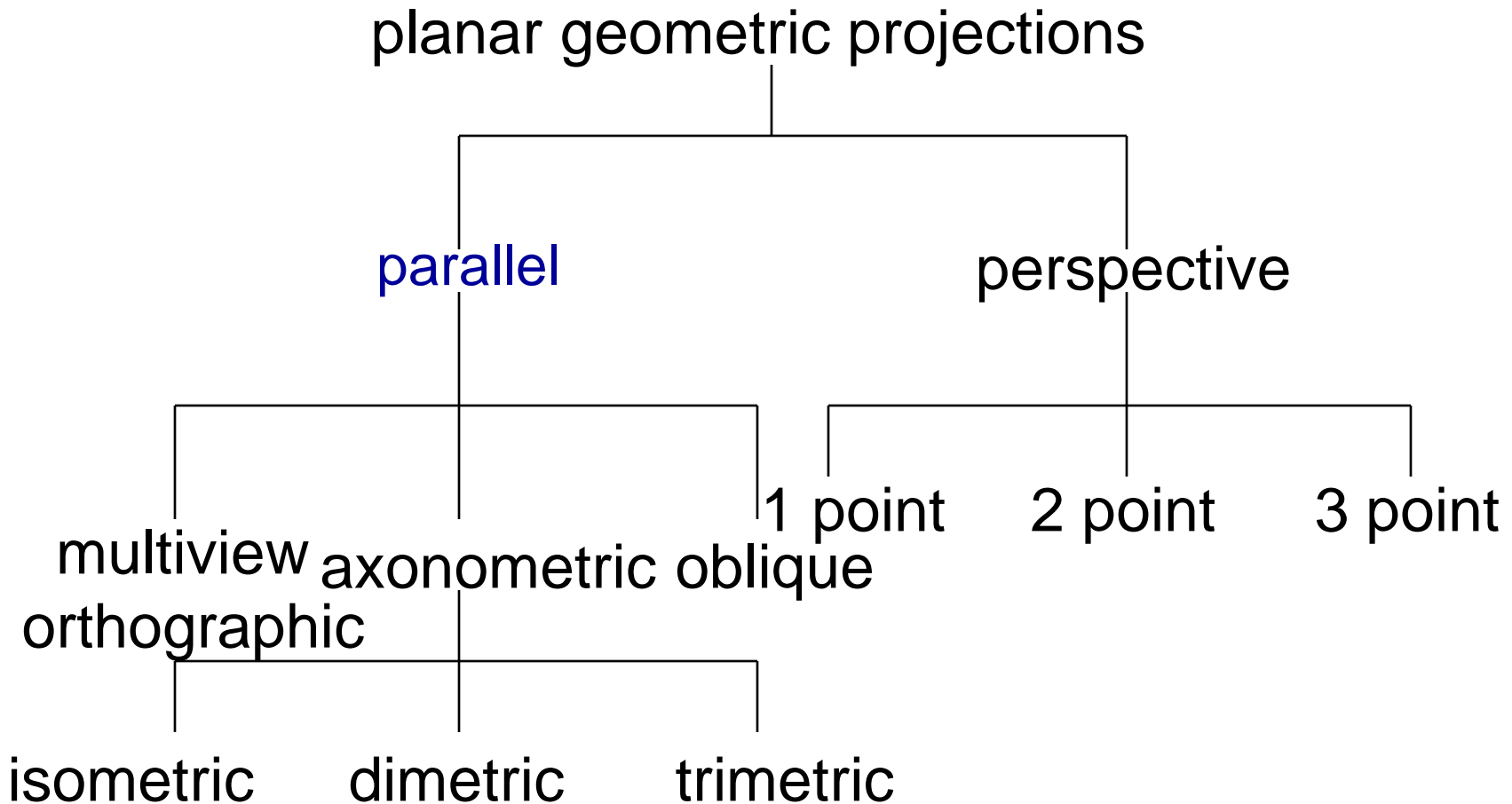
# Axonometric Projections

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- ❑ Lines are scaled (*foreshortened*) but can find scaling factors
- ❑ Lines preserved but angles are not
  - Projection of a circle in a plane not parallel to the projection plane is an ellipse
- ❑ Can see three principal faces of a box-like object
- ❑ Some optical illusions possible
  - Parallel lines appear to diverge
- ❑ Does not look real because far objects are scaled the same as near objects
- ❑ Used in CAD applications

# Classical Viewing

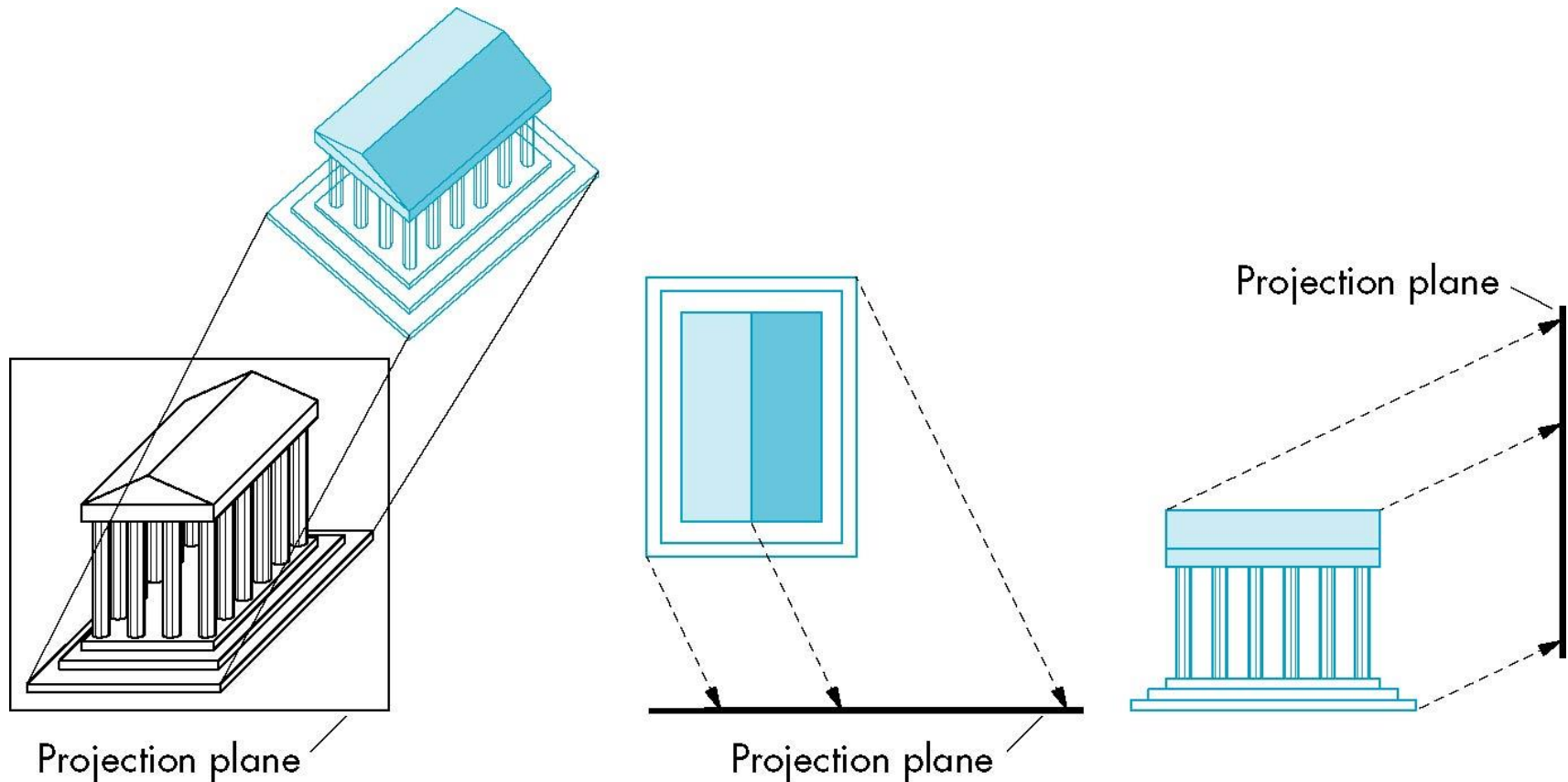
## □ Taxonomy of Planar Geometric Projections





# Oblique Projection

- ❑ Arbitrary relationship between projectors and projection plane



# Oblique Projection

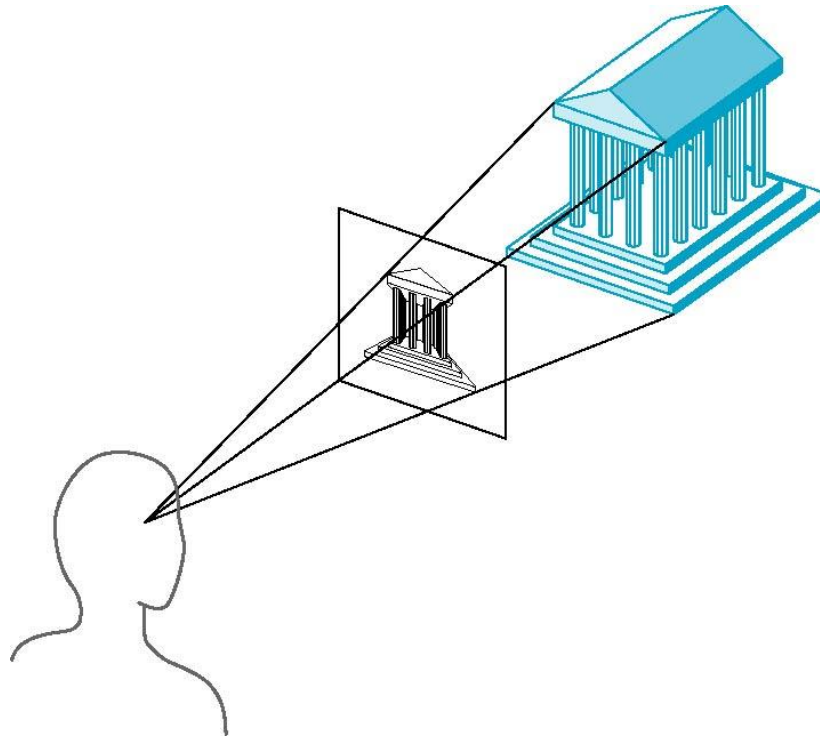
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- ❑ Can pick the angles to emphasize a particular face
  - Architecture: plan oblique, elevation oblique
- ❑ Angles in faces parallel to projection plane are preserved while we can still see “around” side
- ❑ In physical world, cannot create with simple camera; possible with bellows camera or special lens (architectural)

# Perspective Projection

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- ❑ Projectors converge at center of projection

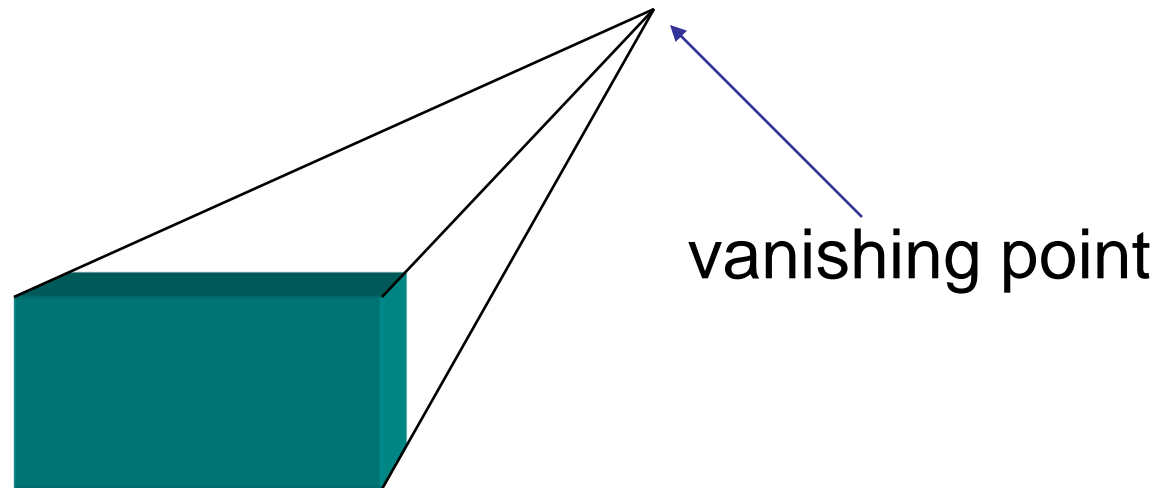


# Perspective Projection

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## ❑ Vanishing Points

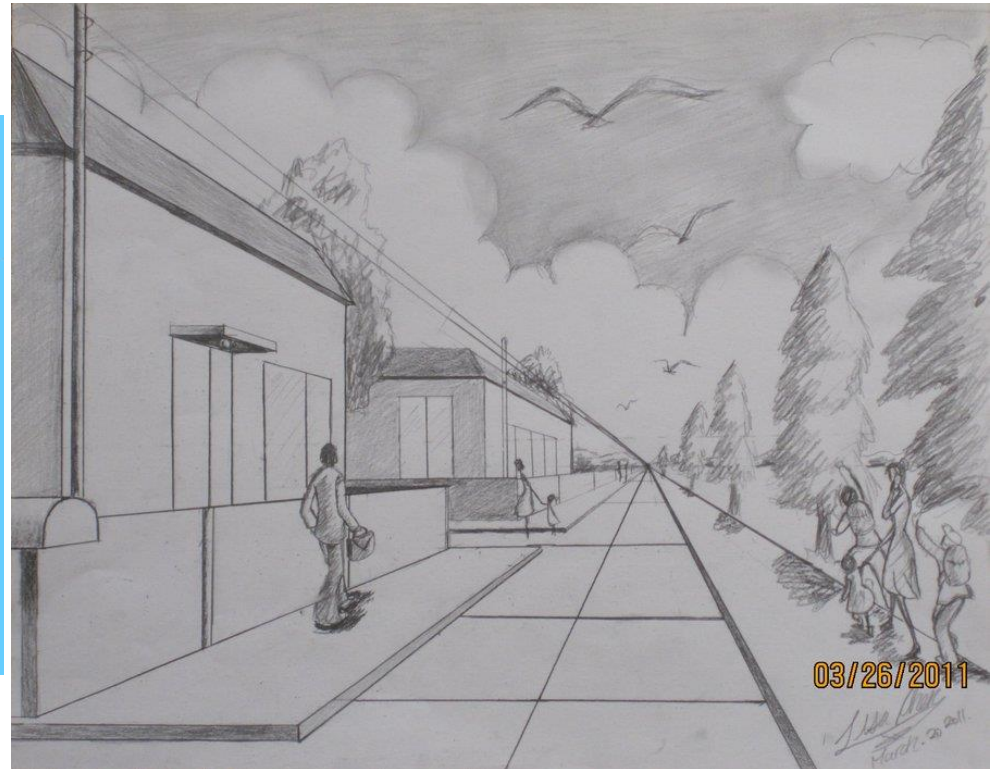
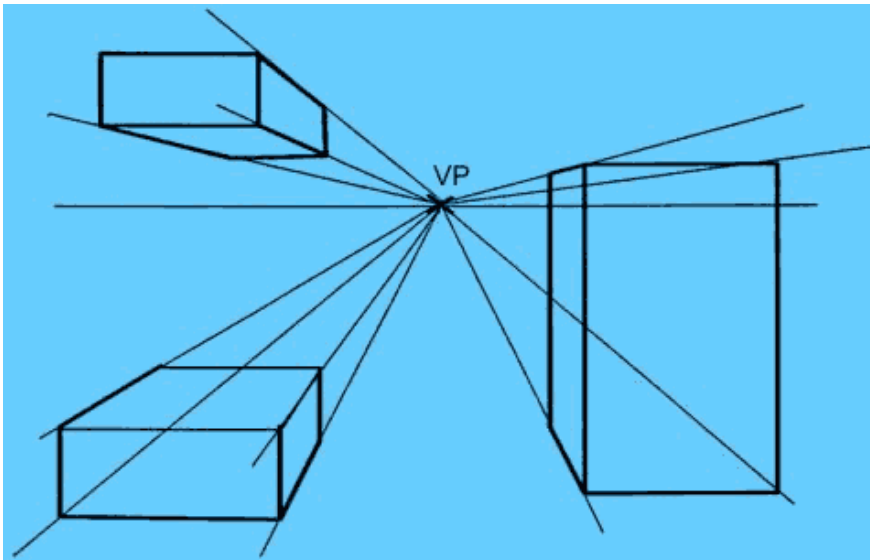
- Parallel lines (not parallel to the projection plan) on the object converge at a single point in the projection (the *vanishing point*)
- Drawing simple perspectives by hand uses these vanishing point(s)



# Perspective Projection

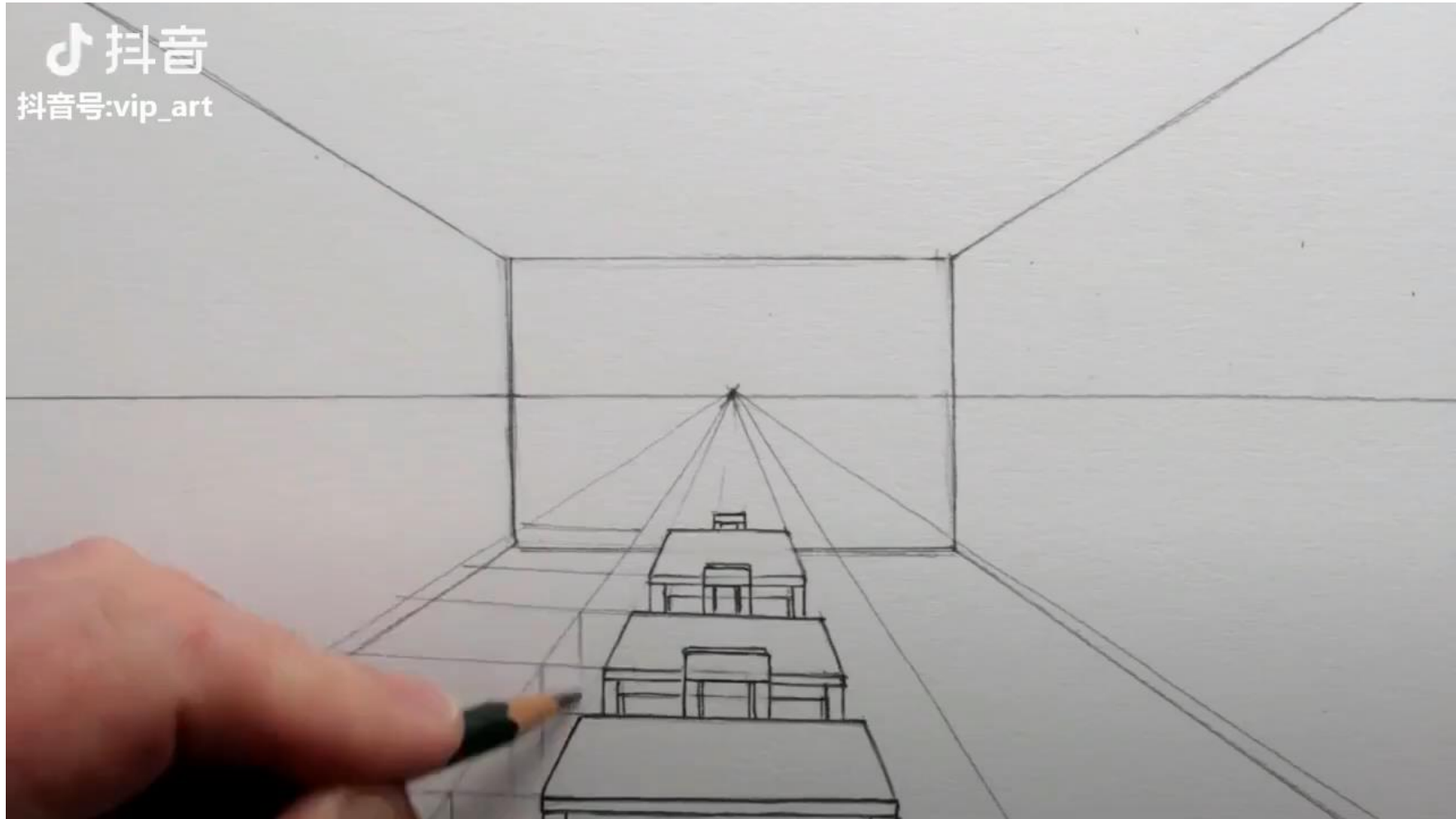
## ❑ One-Point Perspective

- One principal face parallel to projection plane
- One vanishing point for cube



# Perspective Projection

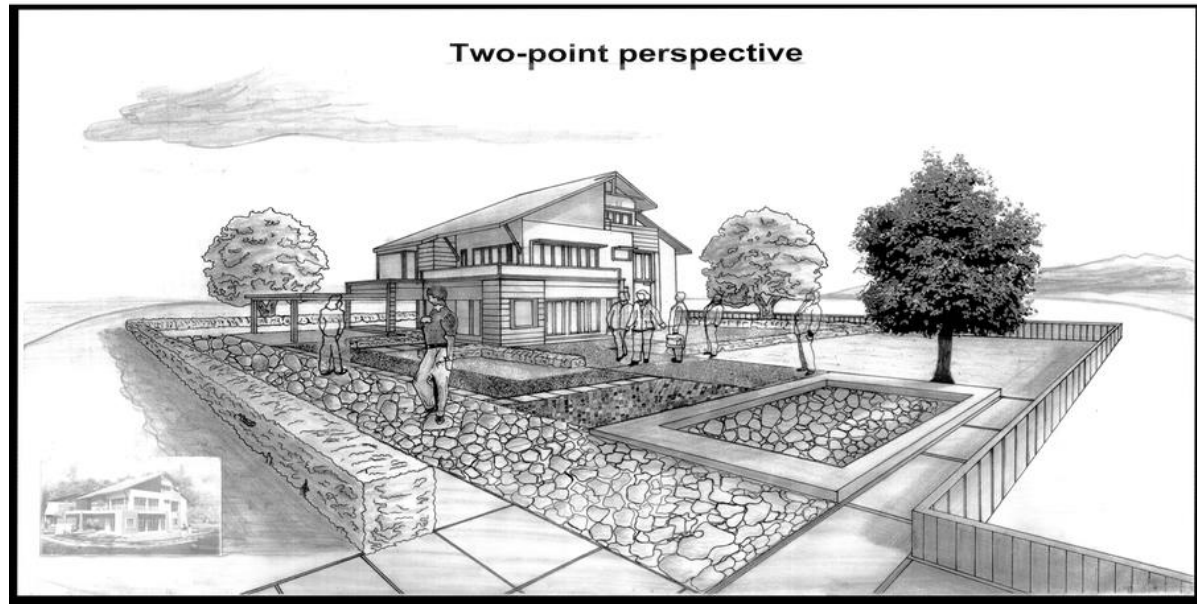
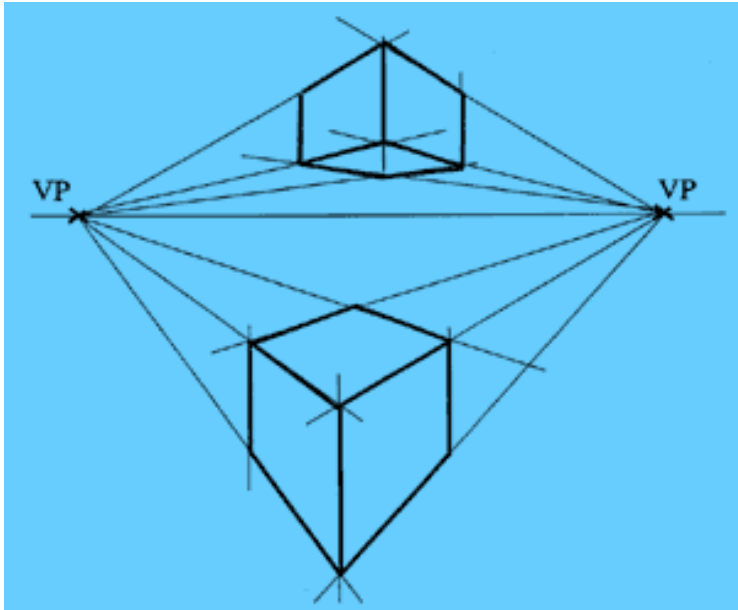
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# Perspective Projection

## ❑ Two-Point Perspective

- On principal direction parallel to projection plane
- Two vanishing points for cube

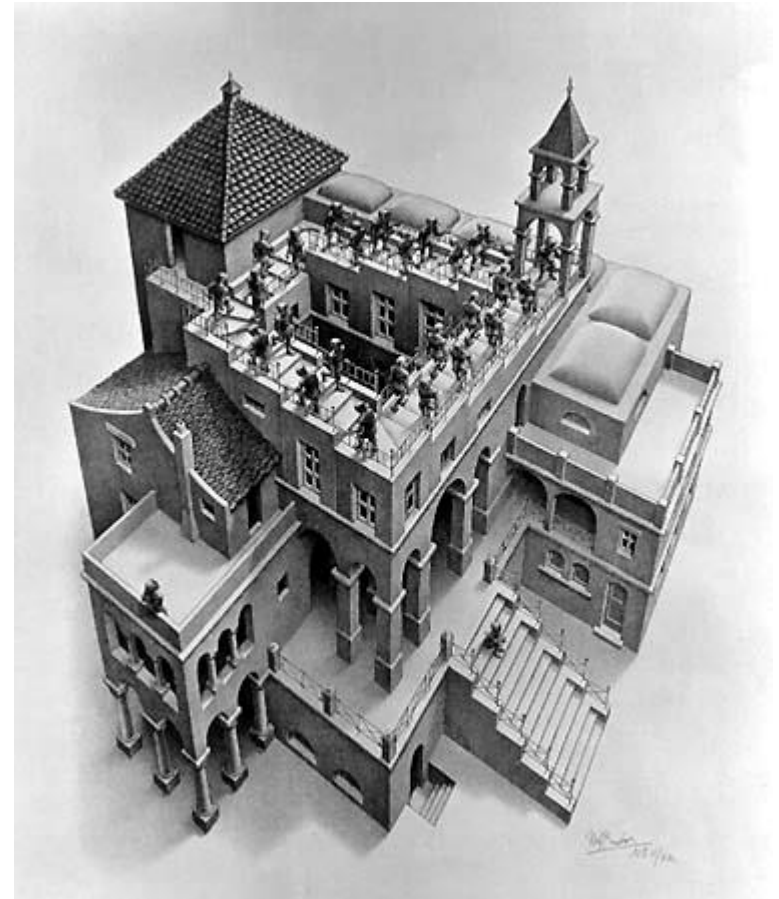
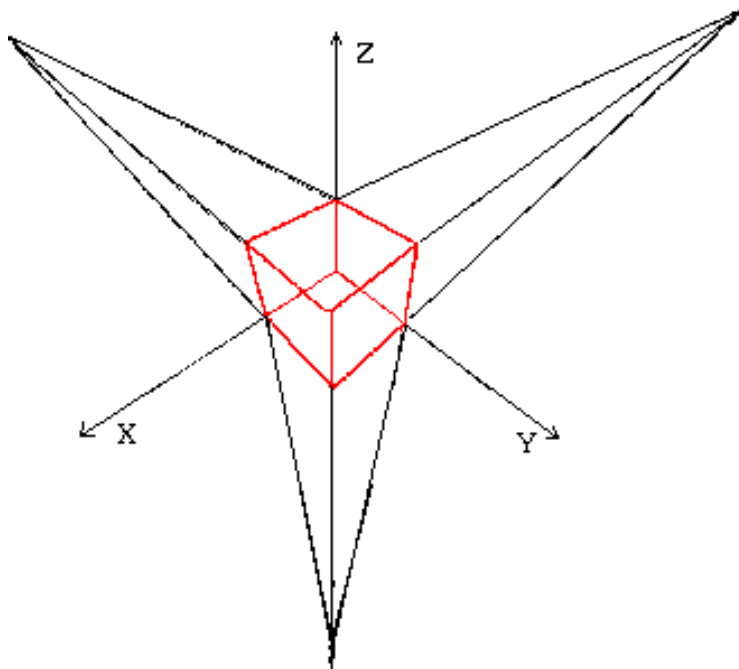




# Perspective Projection

## ❑ Three-Point Perspective

- No principal face parallel to projection plane
- Three vanishing points for cube



# Perspective Projection

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- ❑ Objects further from viewer are projected smaller than the same sized objects closer to the viewer (*diminution*)
  - Looks realistic
- ❑ Equal distances along a line are not projected into equal distances (*nonuniform foreshortening*)
- ❑ Angles preserved only in planes parallel to the projection plane
- ❑ More difficult to construct by hand than parallel projections (but not more difficult by computer)

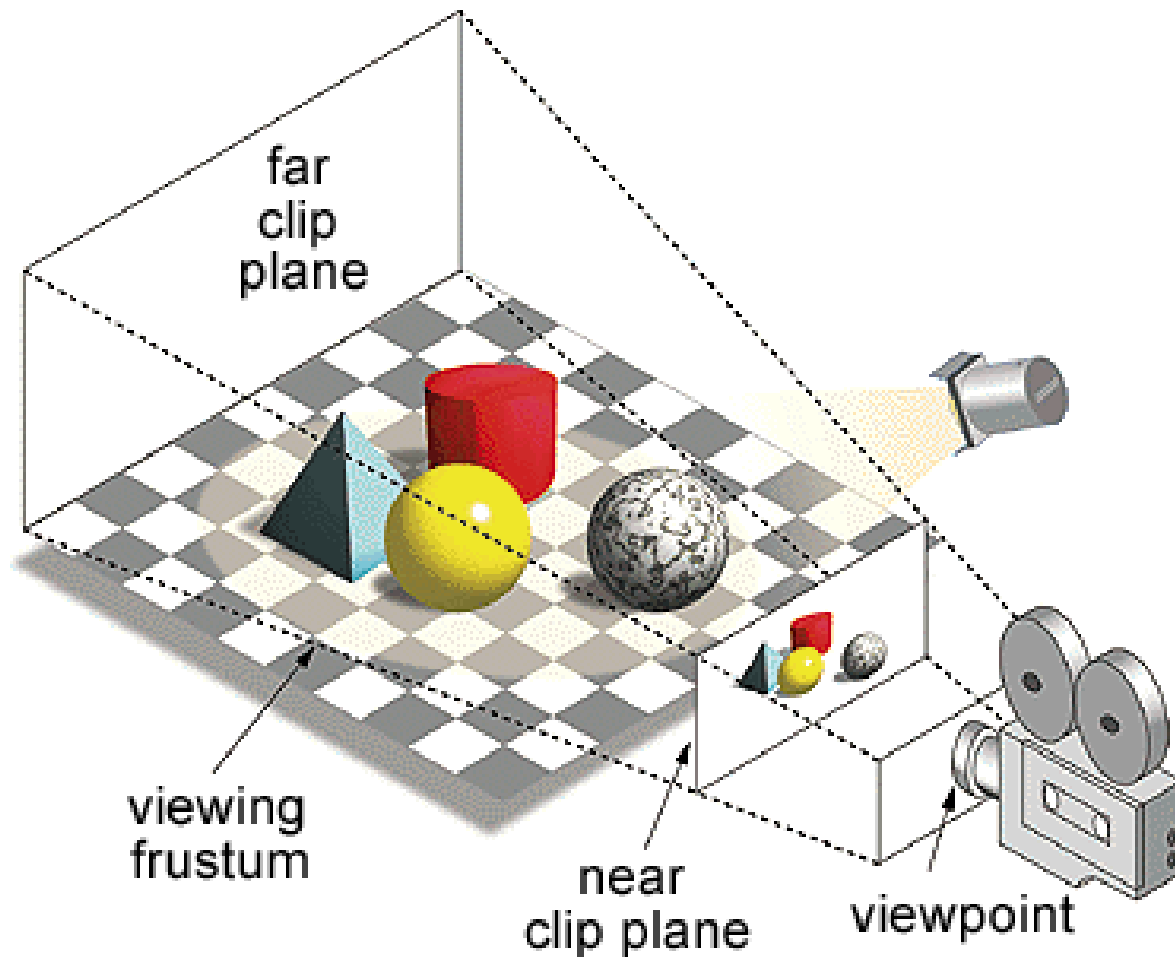
# Computer Viewing

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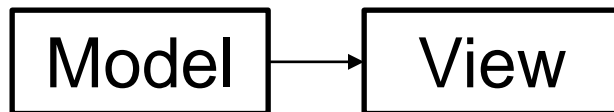
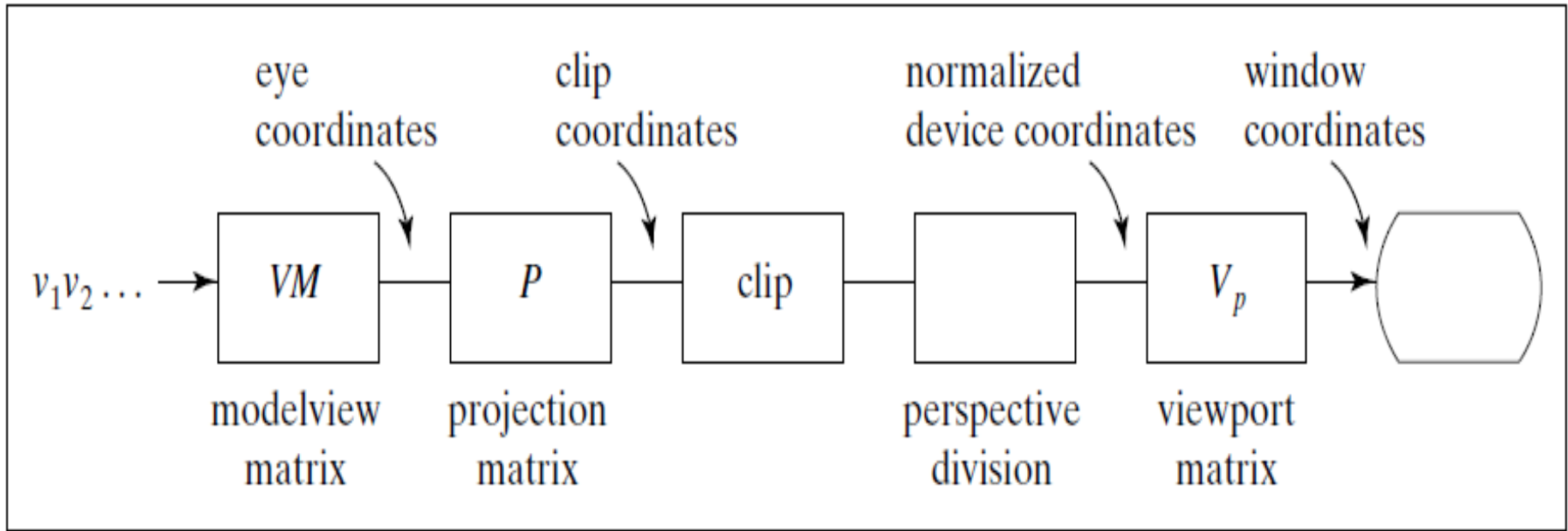
- ❑ There are two aspects of the viewing process, all of which are implemented in the pipeline,
  - Positioning the camera
    - Setting the model-view matrix
  - Selecting the view volume
    - Setting the projection matrix

# Computer Viewing

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# Computer Viewing



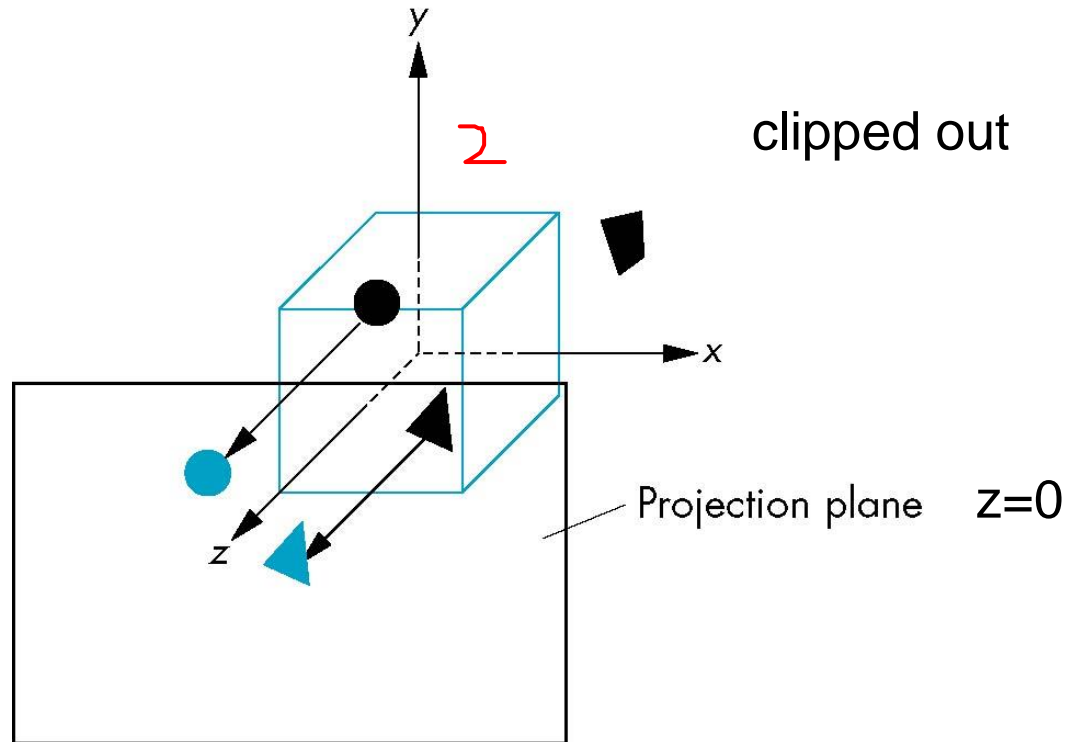
# Computer Viewing

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- ❑ In OpenGL, initially the object and camera frames are the same
  - Default model-view matrix is an identity
- ❑ The camera is located at origin and points in the negative z direction
- ❑ OpenGL also specifies a default view volume that is a cube with sides of length 2 centered at the origin
  - Default projection matrix is an identity

# Computer Viewing

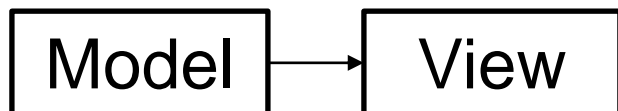
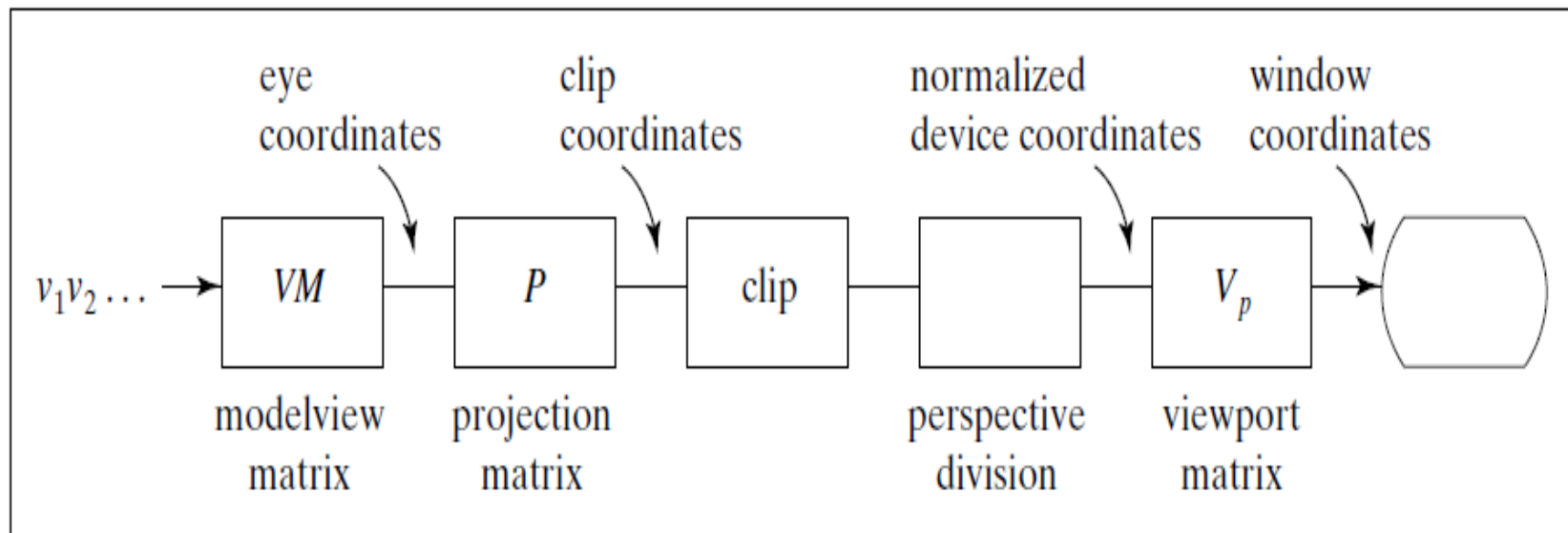
- ❑ Default projection is orthogonal





# Computer Viewing

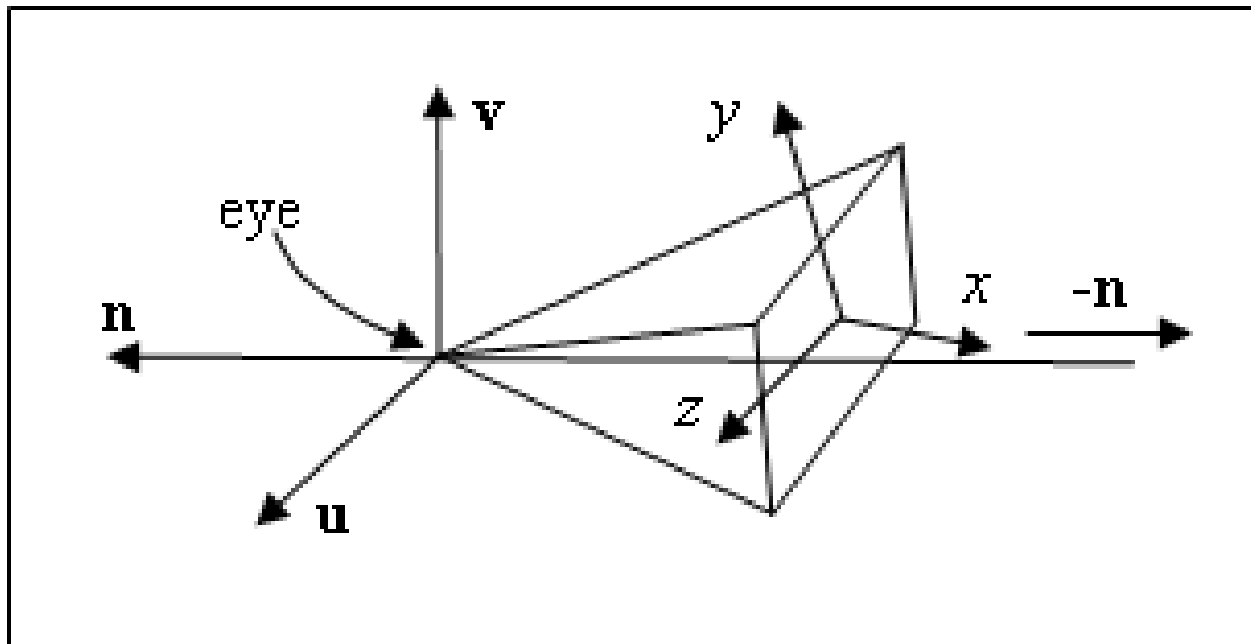
	Orthographic	Oblique	Perspective
Position, direction (V)	<b>gluLookAt</b>		
View Volume (P)	<b>glOrtho</b>		<b>glFrustum or gluPerspective</b>



# Computer Viewing

## ❑ Set up position & direction of camera

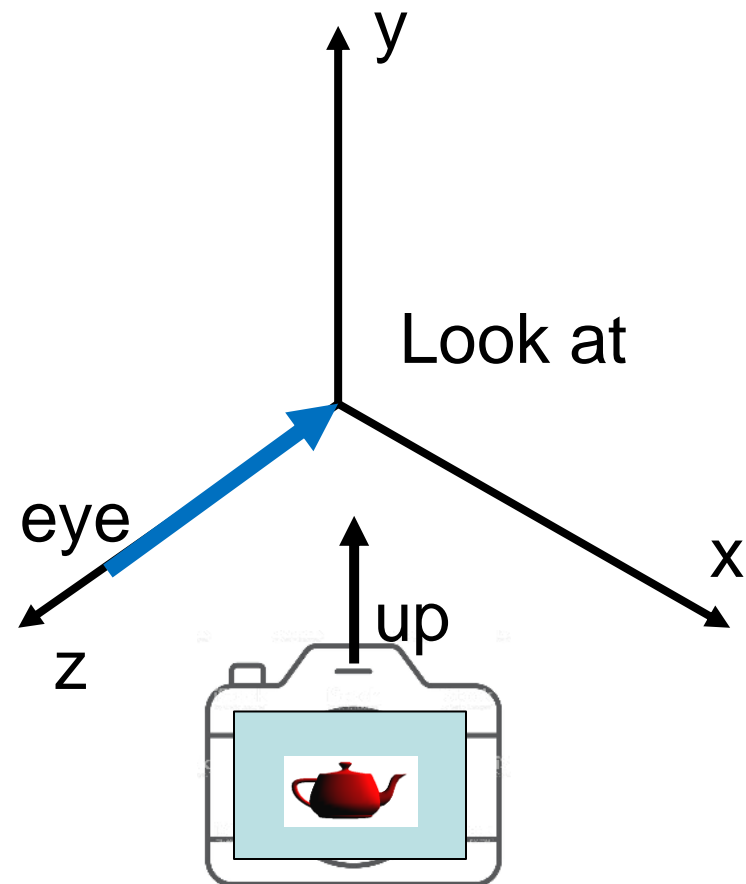
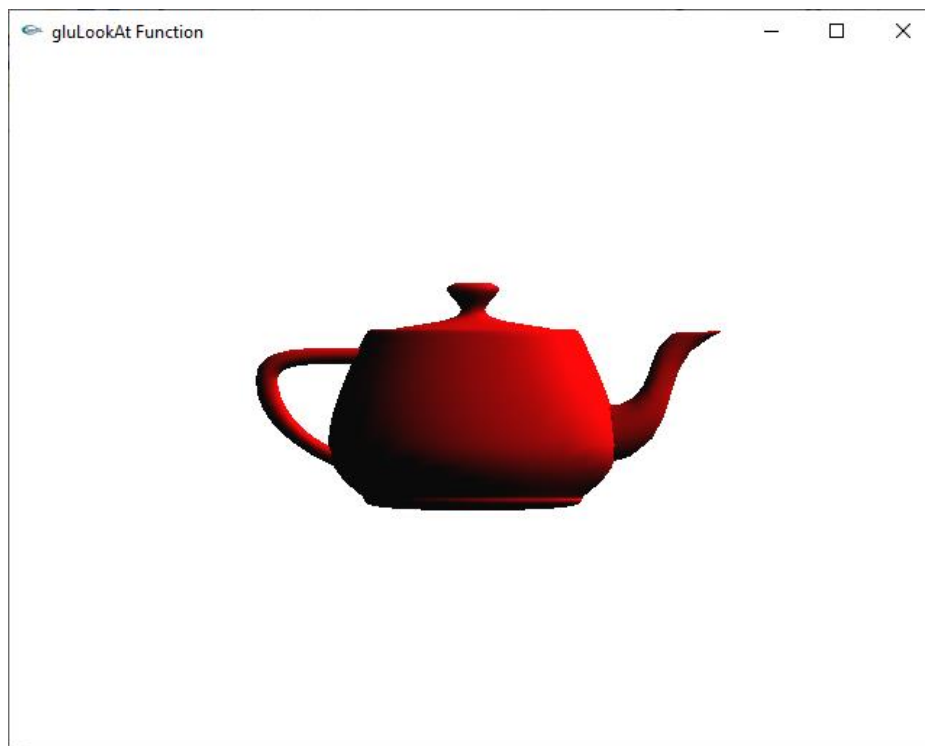
```
glMatrixMode(GL_MODELVIEW);  
glLoadIdentity();  
gluLookAt(eye.x, eye.y, eye.z, look.x, look.y, look.z,  
          up.x, up.y, up.z);
```



# Computer Viewing

- ❑ Set up position & direction of camera

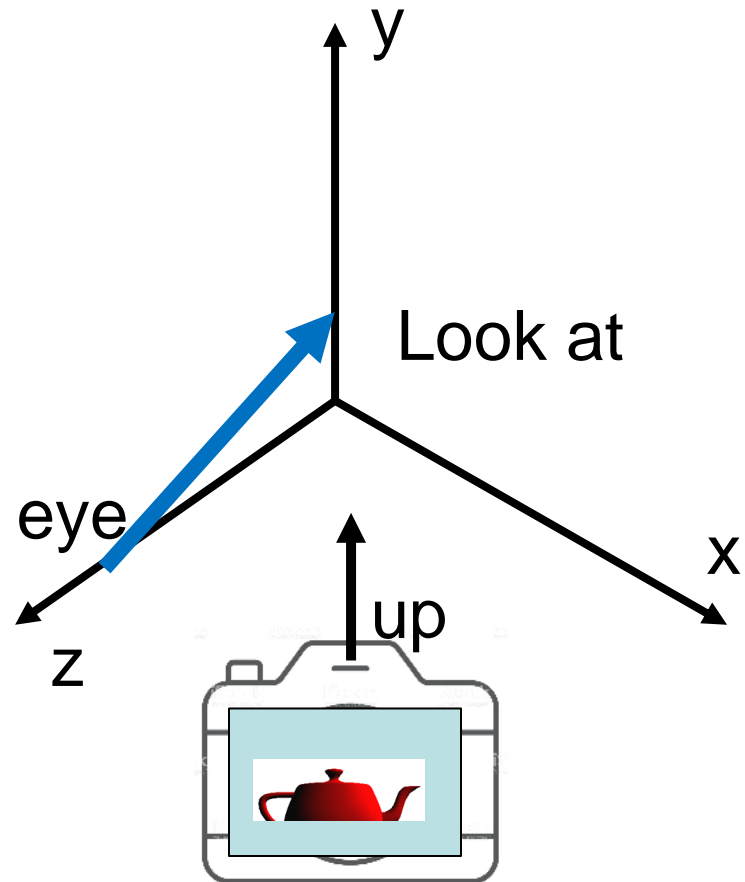
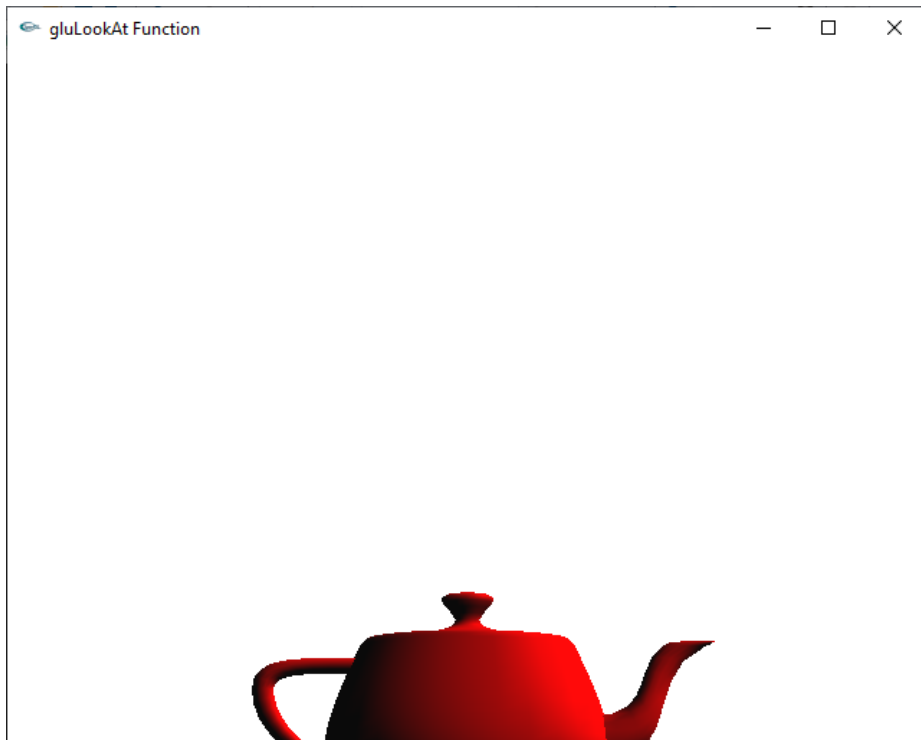
```
gluLookAt(0, 0, 10, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0);
```



# Computer Viewing

- ❑ Set up position & direction of camera

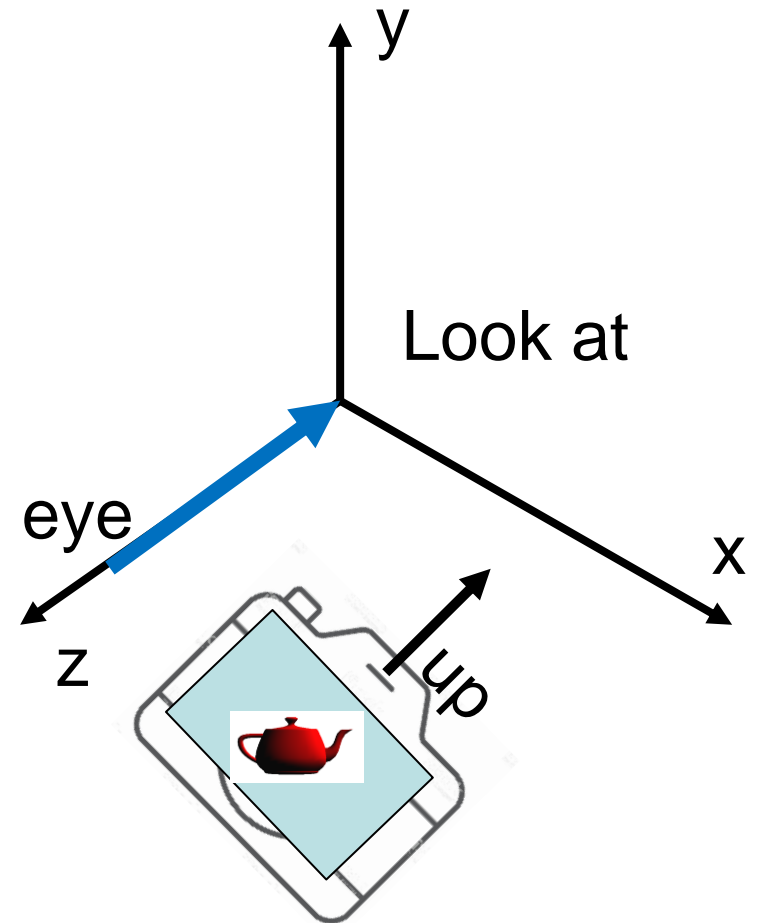
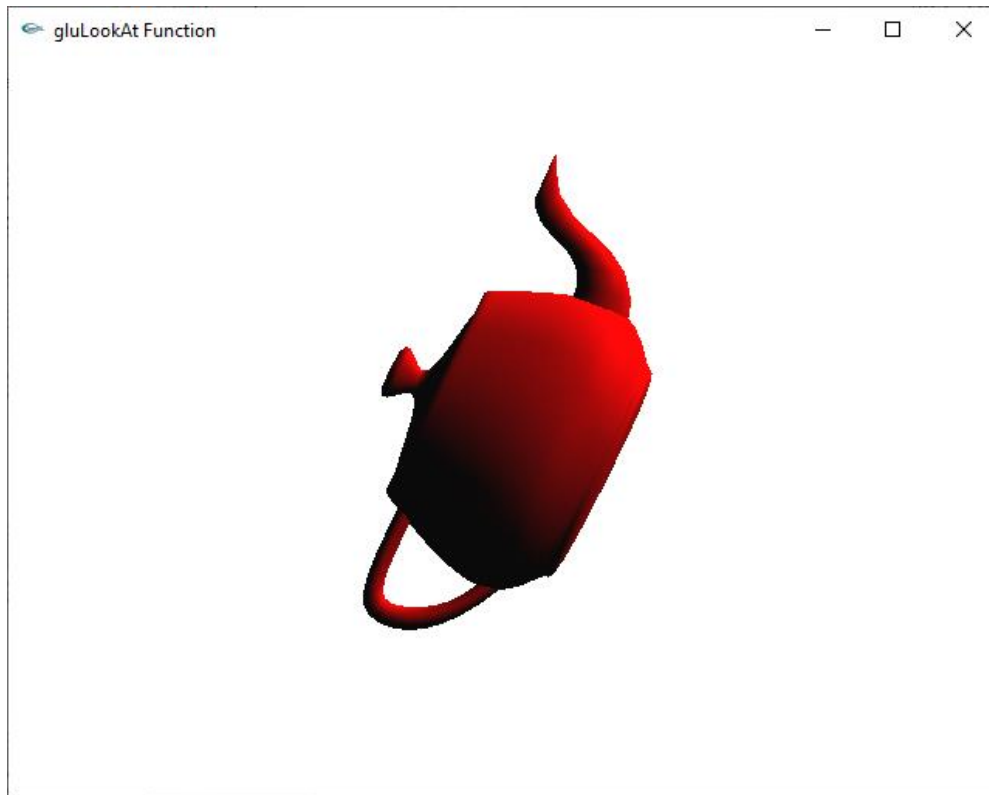
```
gluLookAt(0, 0, 10, 0.0, 1.0, 0.0, 0.0, 1.0, 0.0);
```



# Computer Viewing

- ❑ Set up position & direction of camera

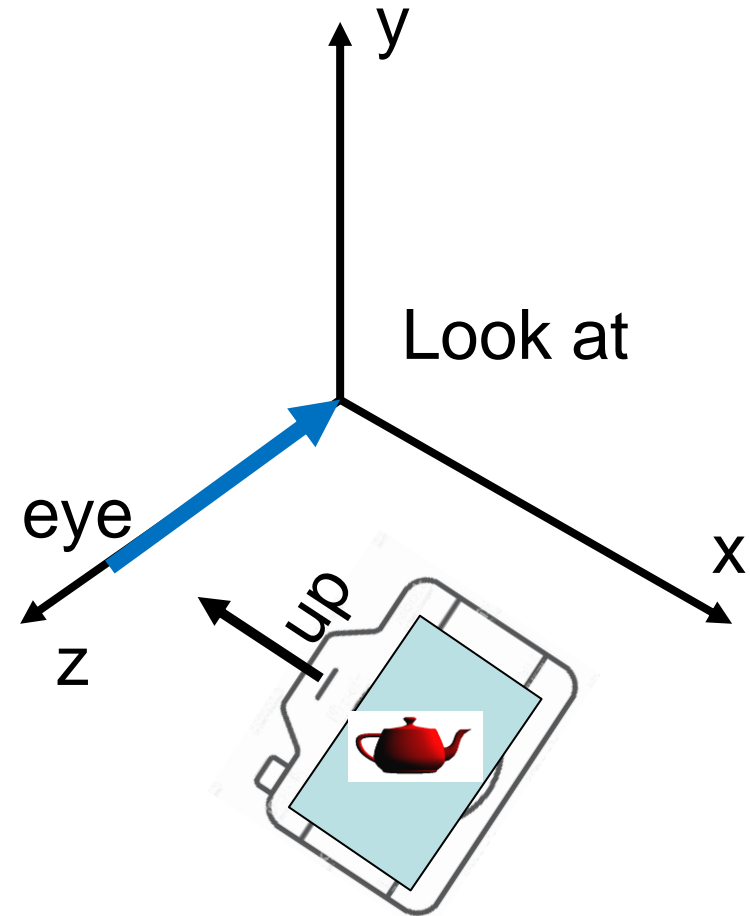
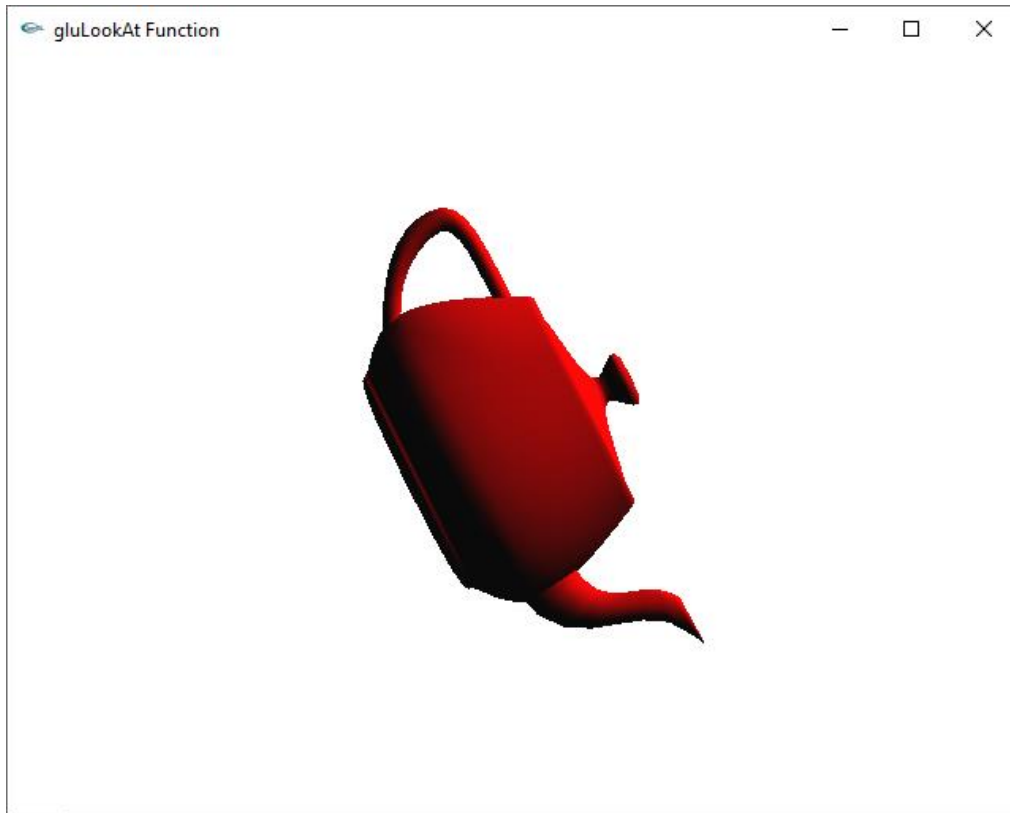
```
gluLookAt(0, 0, 10, 0.0, 0.0, 0.0, 2.0, 1.0, 0.0);
```



# Computer Viewing

- ❑ Set up position & direction of camera

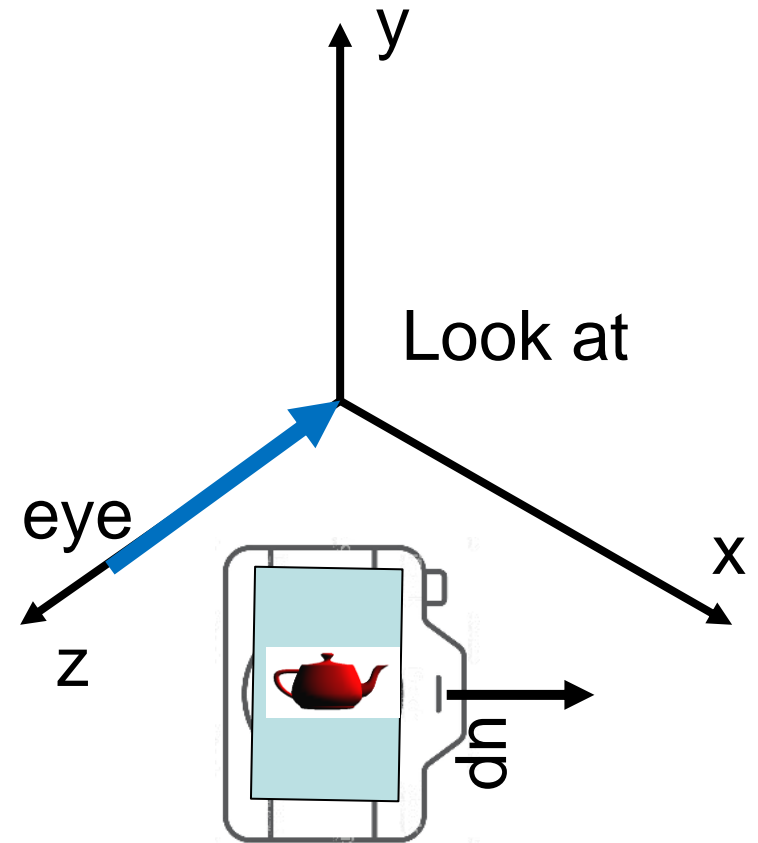
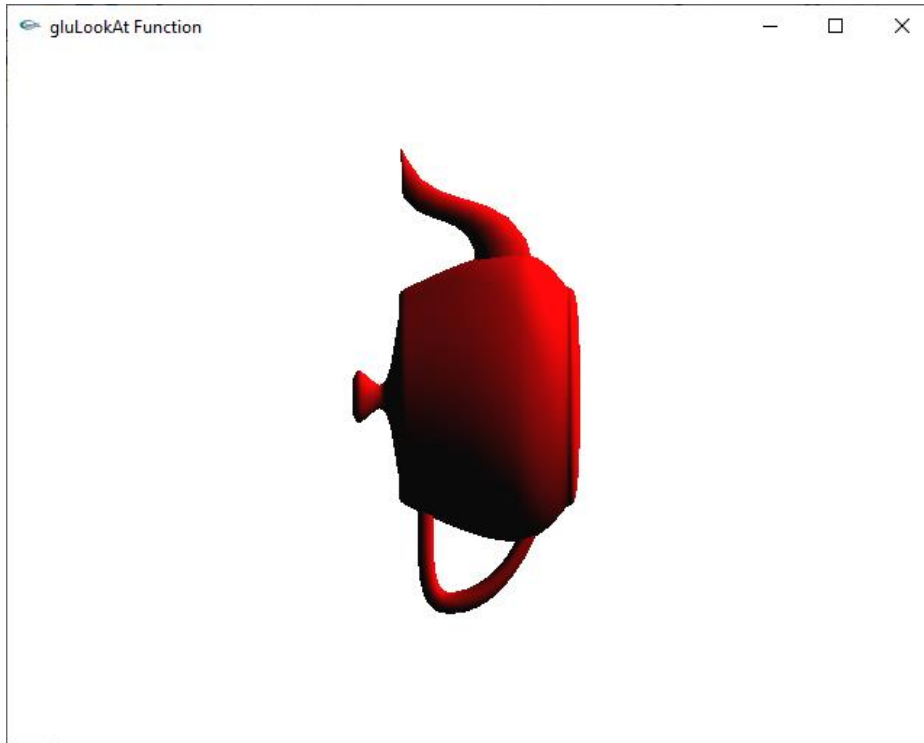
```
gluLookAt(0, 0, 10, 0.0, 0.0, 0.0, -2.0, 1.0, 0.0);
```



# Computer Viewing

- ❑ Set up position & direction of camera

```
gluLookAt(0, 0, 10, 0.0, 0.0, 0.0, 1.0, 0.0, 0.0);
```



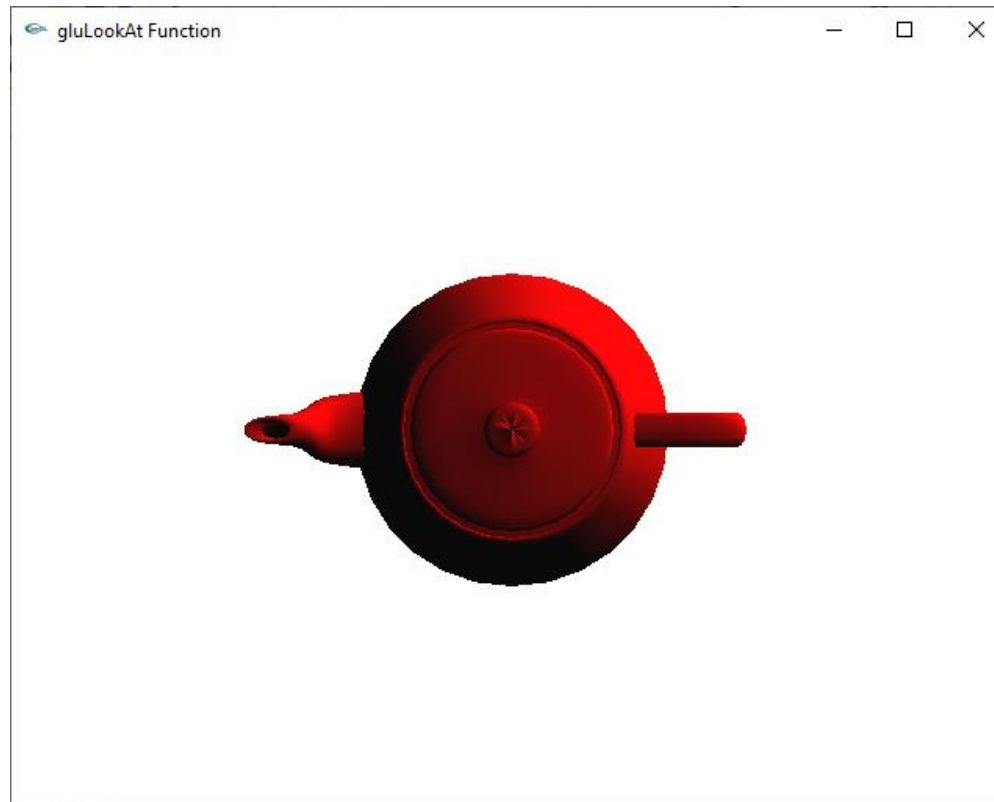


# Computer Viewing

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- ❑ Set up position & direction of camera

`gluLookAt(0, 10, 0, 0.0, 0.0, 0.0, 0, 0, 1);`

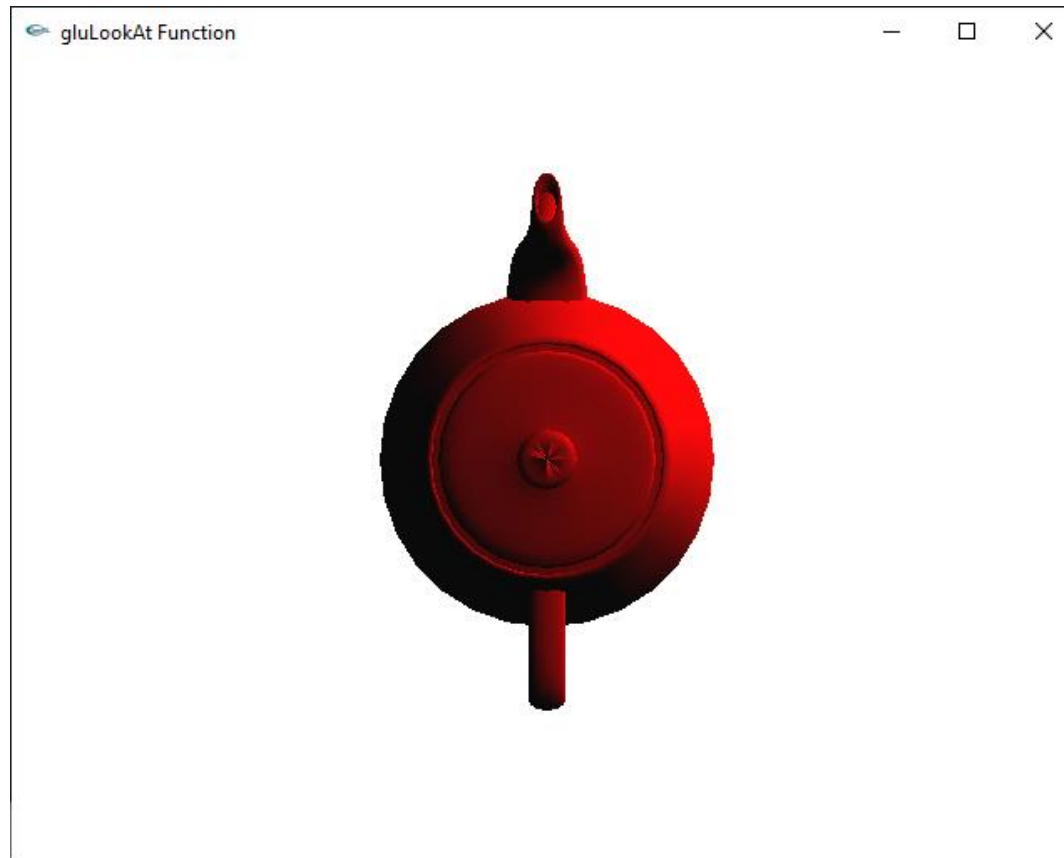


# Computer Viewing

---

- ❑ Set up position & direction of camera

`gluLookAt(0, 10, 0, 0.0, 0.0, 0.0, 1, 0, 0);`

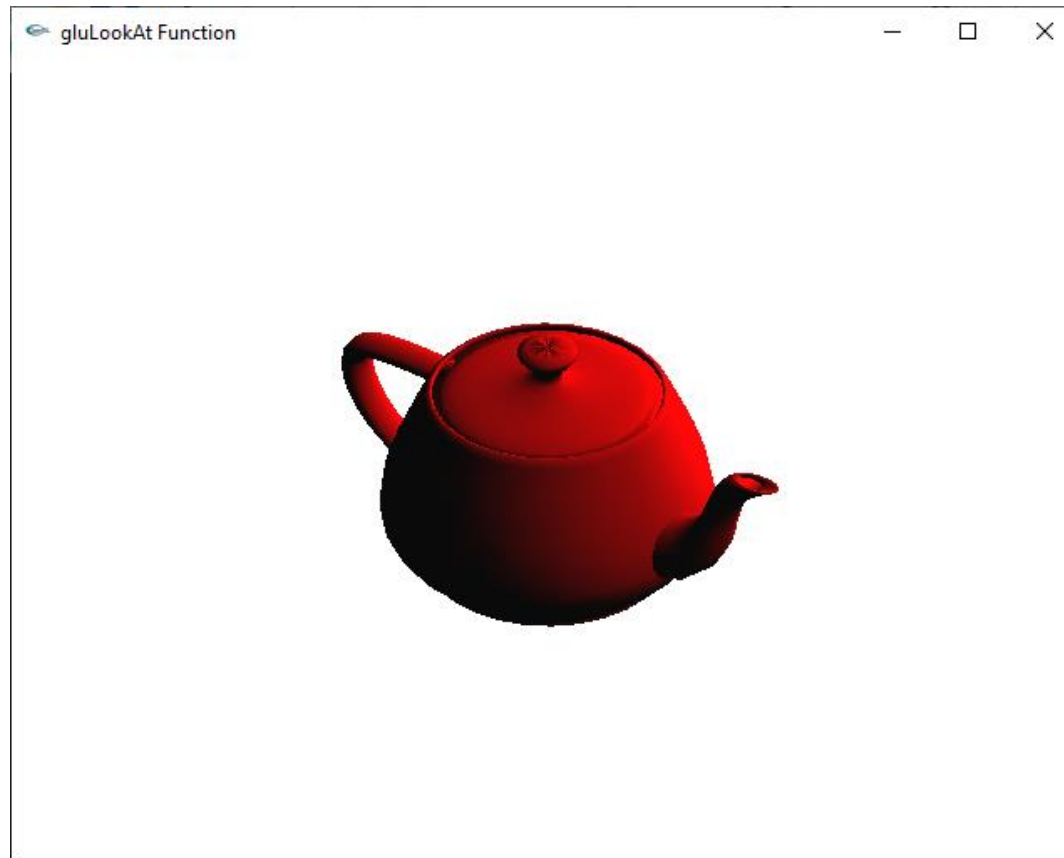


# Computer Viewing

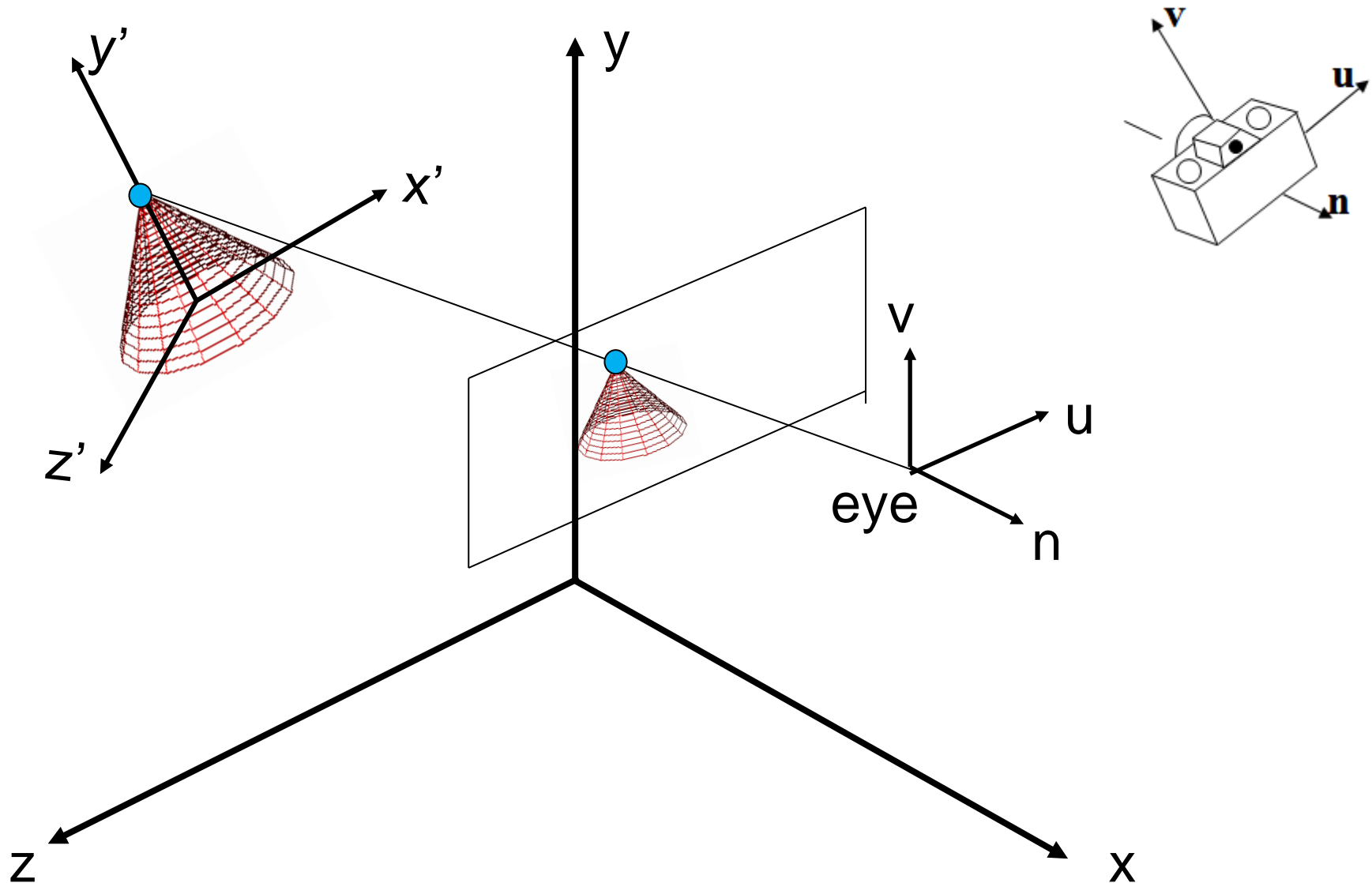
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- ❑ Set up position & direction of camera

```
gluLookAt(6, 7, 8, 0.0, 0.0, 0.0, 0, 1, 0);
```



# Computer Viewing



# Computer Viewing

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## ❑ Orthogonal projection

- The default projection in the eye (camera) frame is orthogonal
- For points within the default view volume

$$x_p = x$$

$$y_p = y$$

$$z_p = 0$$

# Computer Viewing

---

## ❑ Orthogonal projection

default orthographic projection

$$\begin{aligned}x_p &= x \\y_p &= y \\z_p &= 0 \\w_p &= 1\end{aligned}$$

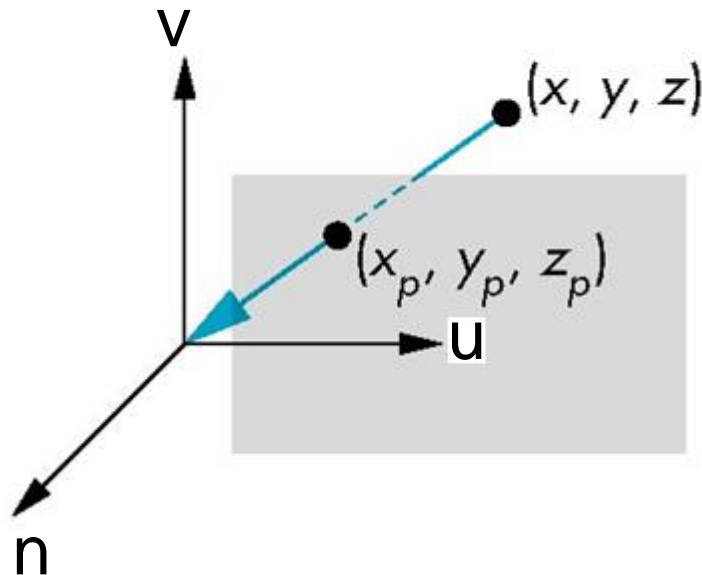
$$\mathbf{p}_p = \mathbf{M}\mathbf{p}$$

$$\mathbf{M} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

# Computer Viewing

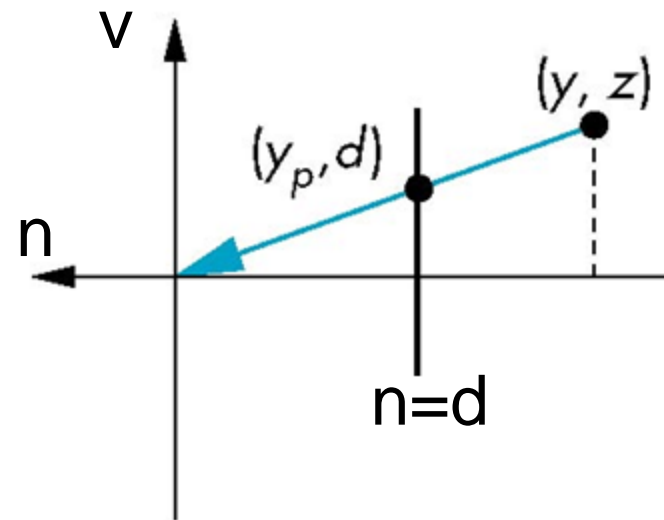
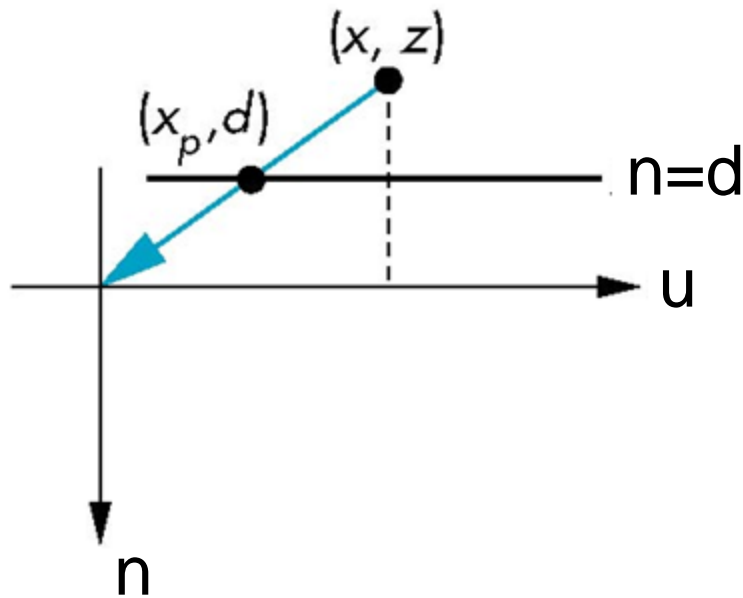
## □ Perspective Projection

- Center of projection at the origin
- Projection plane  $n = d, d < 0$



# Computer Viewing

- ❑ Perspective Projection
  - Consider top and side views



$$x_p = \frac{x}{z/d}$$

$$y_p = \frac{y}{z/d}$$

$$z_p = d$$



# Computer Viewing

## □ Perspective Projection

consider  $\mathbf{q} = \mathbf{M}\mathbf{p}$  where

$$\mathbf{M} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{bmatrix}$$
$$\mathbf{p} = \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \Rightarrow \mathbf{q} = \begin{bmatrix} x \\ y \\ z \\ z/d \end{bmatrix}$$

# Computer Viewing

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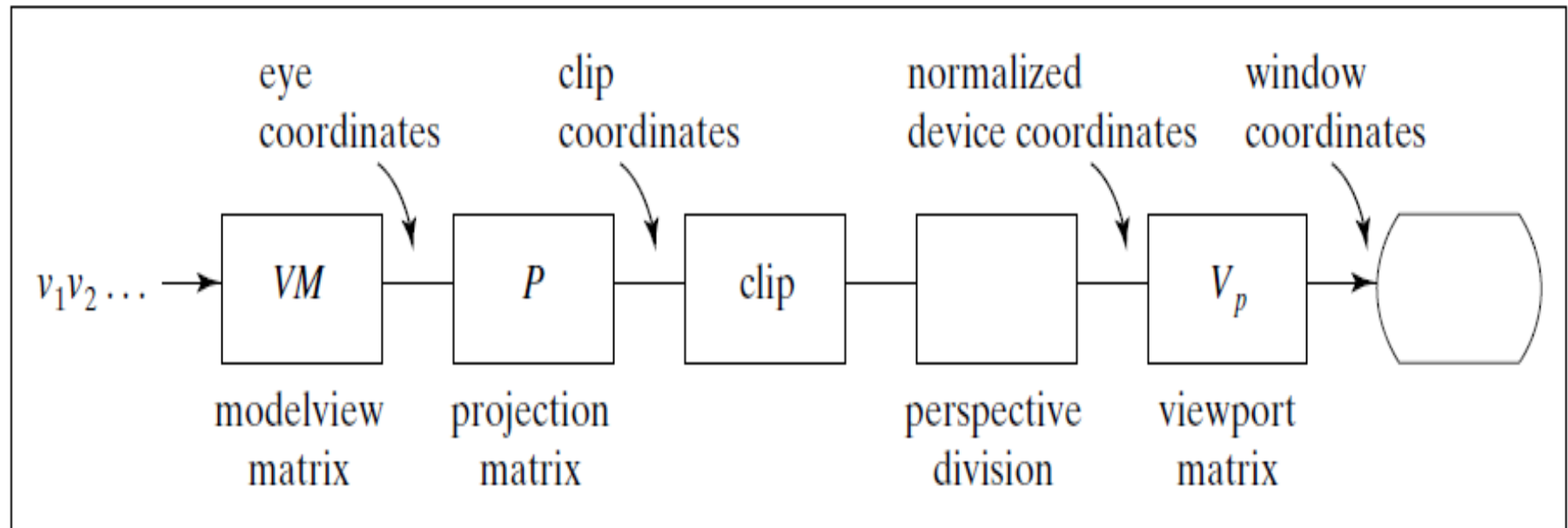
## □ Perspective Projection

- However  $w \neq 1$ , so we must divide by  $w$  to return from homogeneous coordinates
- This *perspective division* yields

$$x_p = \frac{x}{z/d} \quad y_p = \frac{y}{z/d} \quad z_p = d$$

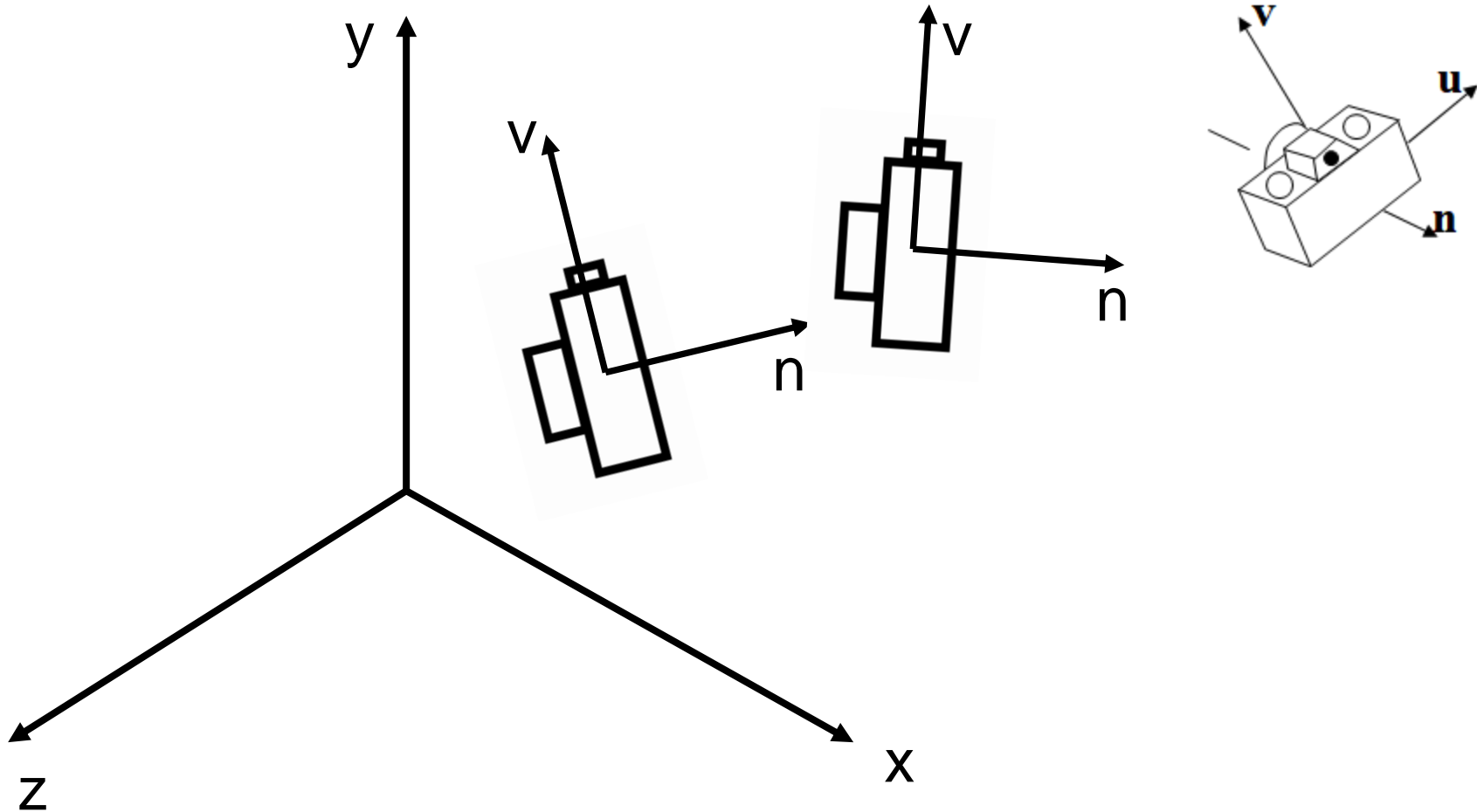
the desired perspective equations

# Computer Viewing



# Computer Viewing

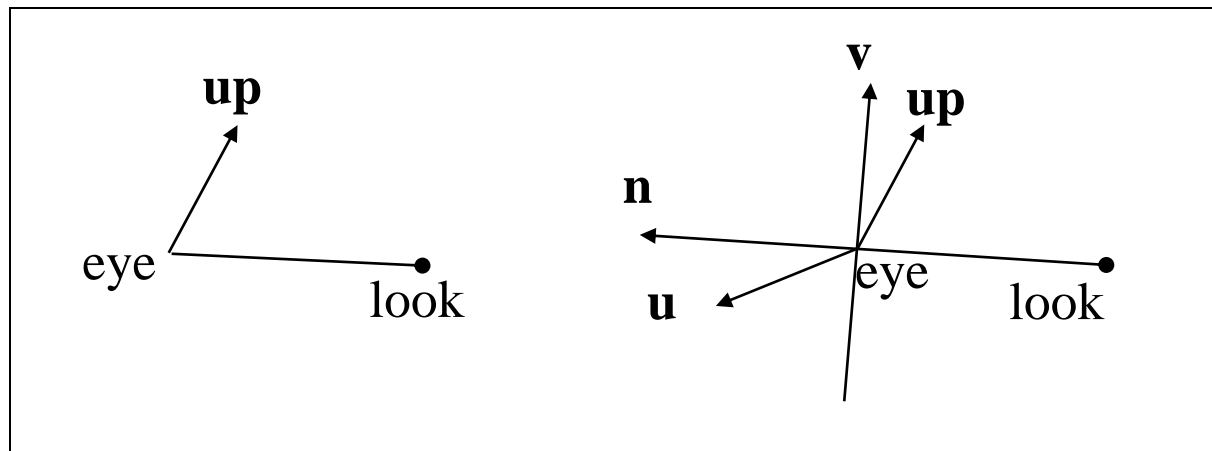
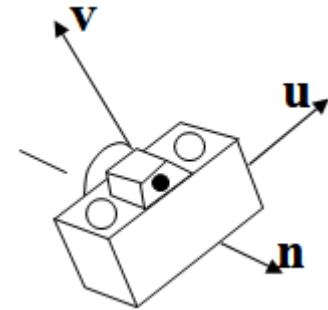
```
gluLookAt (eye.x, eye.y, eye.z, look.x, look.y, look.z,  
          up.x, up.y, up.z);
```



# Computer Viewing

## ❑ Matrix transform from world frame to camera frame

- eye, look at, up  $\rightarrow$  u, v, n
- $\mathbf{n} = \text{eye} - \text{look}$ .
- $\mathbf{u} = \mathbf{up} \times \mathbf{n}$ ,
- $\mathbf{v} = \mathbf{n} \times \mathbf{u}$
- $\mathbf{u}, \mathbf{v}, \mathbf{n}$  : unit vector



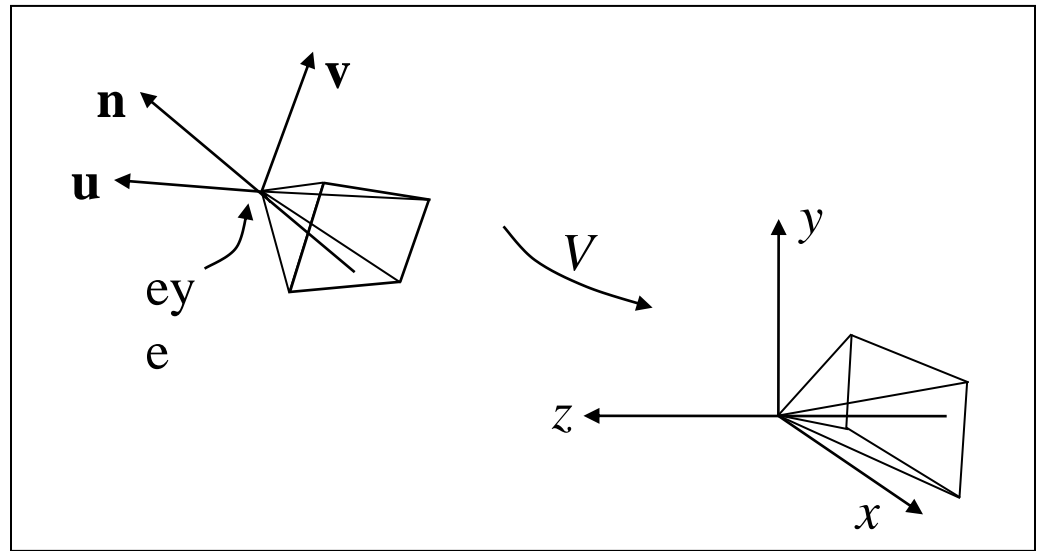
# Computer Viewing

❑ Matrix transform from world frame to camera frame

$$CTM = V.M$$

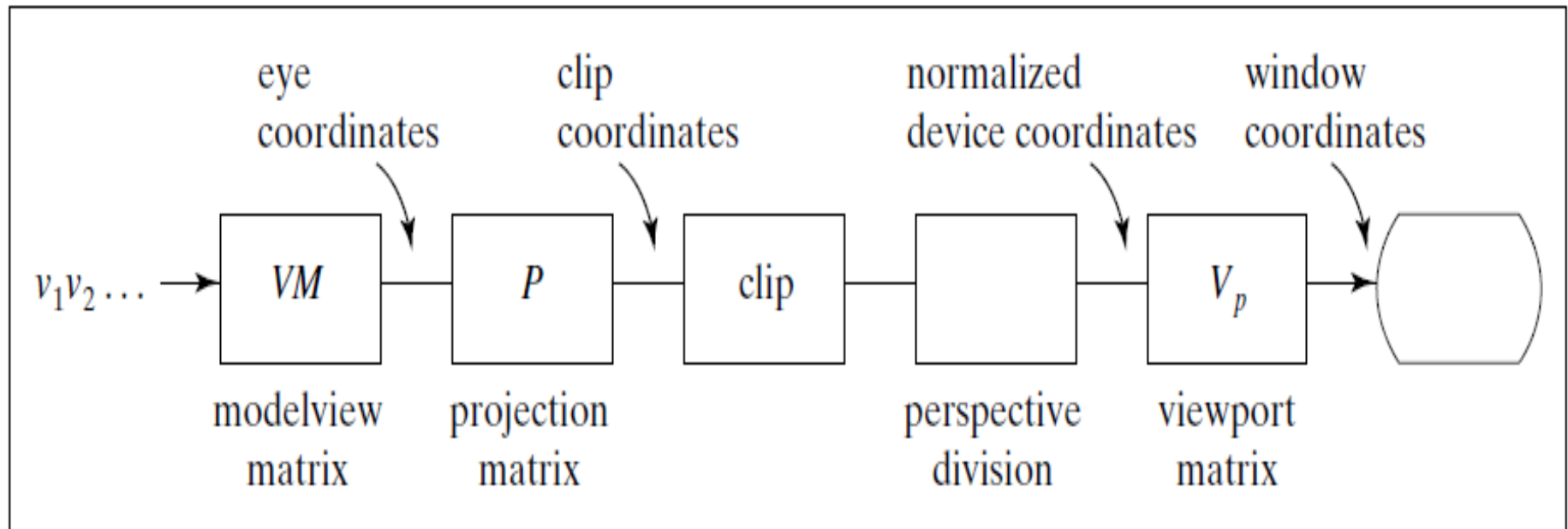
$$V = \begin{pmatrix} u_x & u_y & u_z & d_x \\ v_x & v_y & v_z & d_y \\ n_x & n_y & n_z & d_z \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad (d_x, d_y, d_z) = (-eye \bullet u, -eye \bullet v, -eye \bullet n)$$

$$V \begin{pmatrix} eye_x \\ eye_y \\ eye_z \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \quad V \begin{pmatrix} u_x \\ u_y \\ u_z \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$



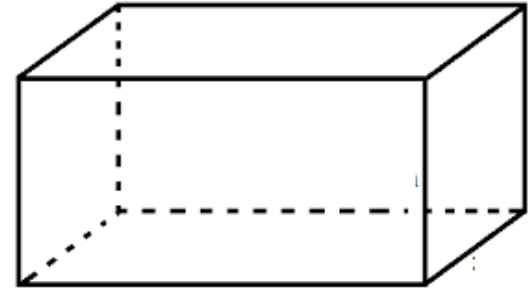
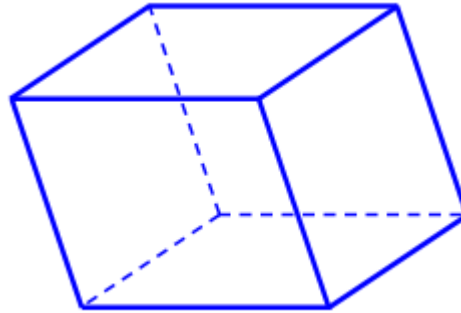
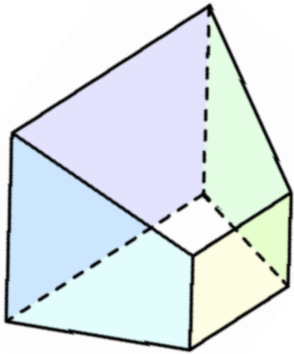
# View Volume

	Orthographic	Oblique	Perspective
Position, direction (V)	<b>gluLookAt</b>		
View Volume (P)	<b>glOrtho</b>		<b>glFrustum or gluPerspective</b>



# View Volume

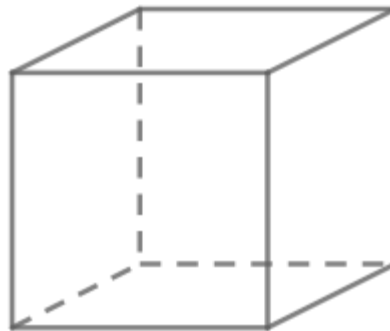
## □ Projection Matrix P



**$\times P$**

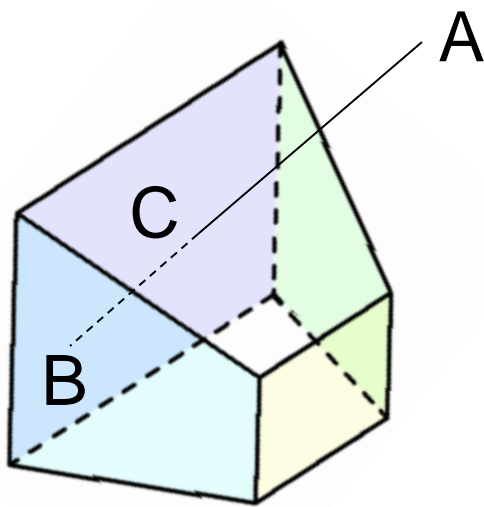
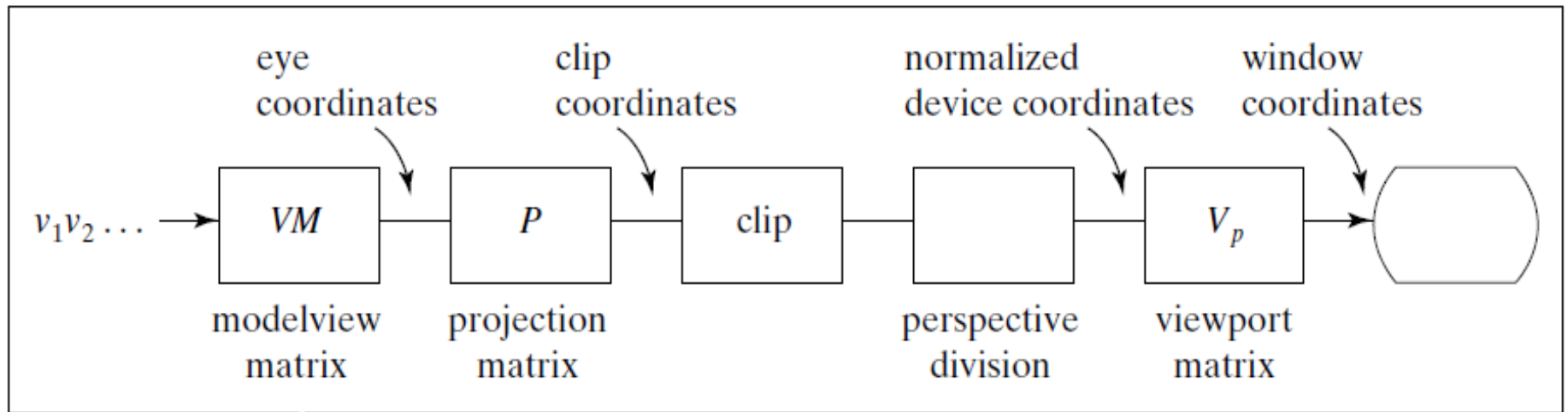
View Volume: CCV

Ortho. Projection

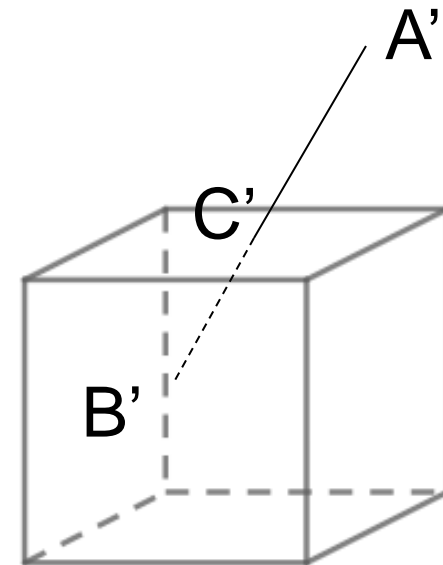




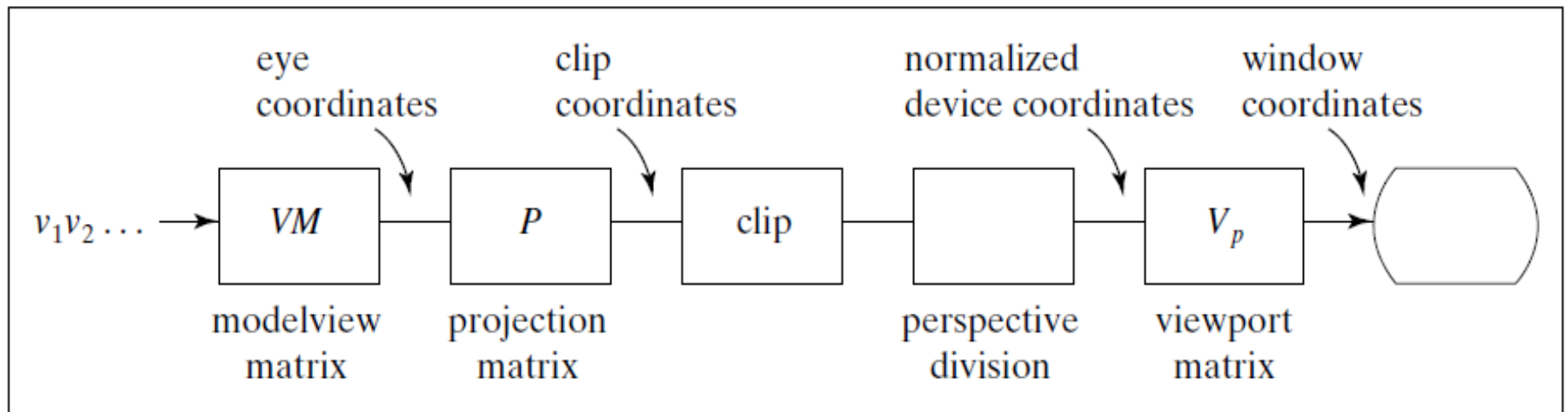
# View Volume



$\times P$



# View Volume



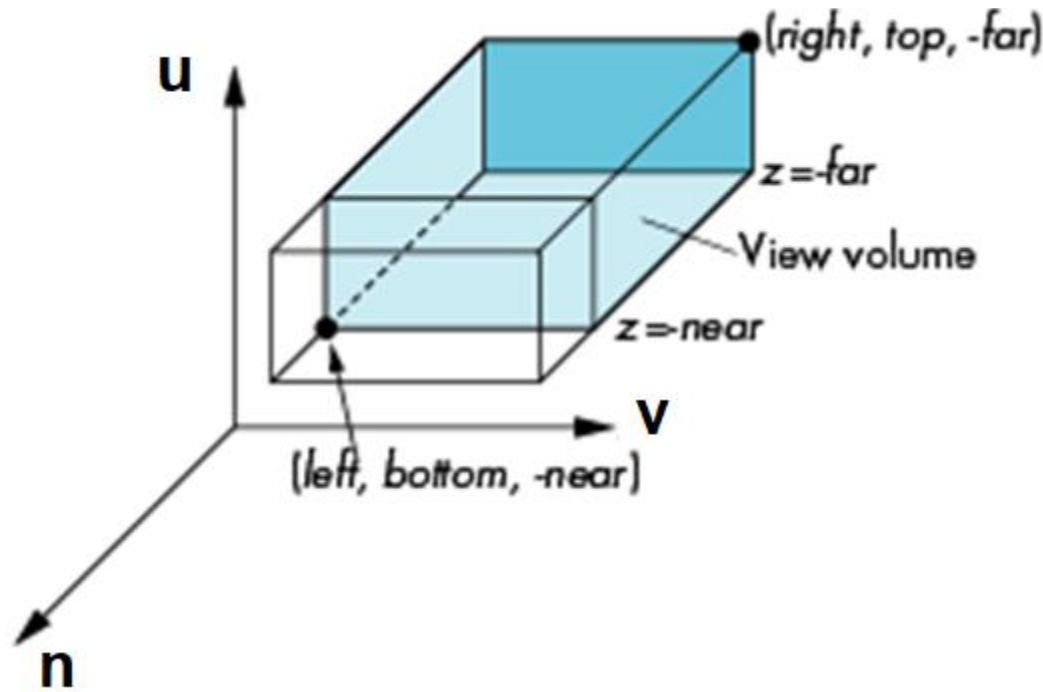
❑ Perspective division: divide by w component

$$(x, y, z, w) \rightarrow (x/w, y/w, z/w, 1)$$

# View volume

## ❑ Orthogonal projection

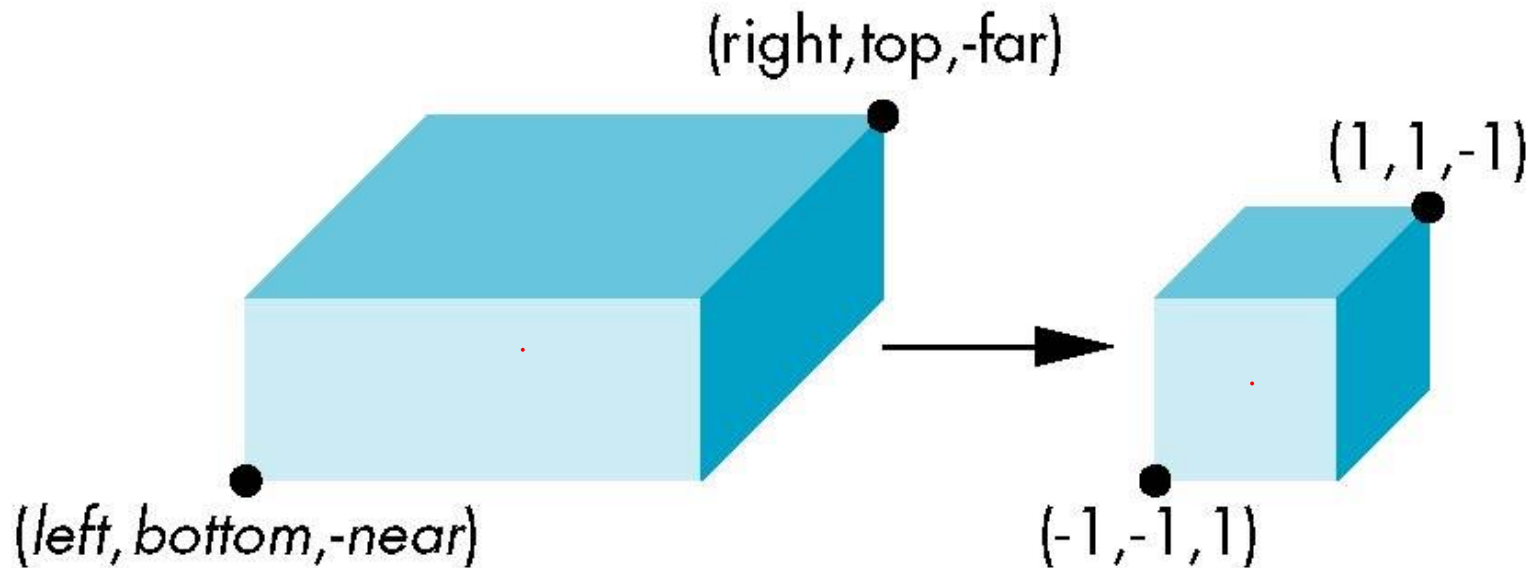
- `glOrtho(left, right, bottom, top, near, far)`
- `near` and `far` measured from camera



# Orthogonal Projection

`glOrtho(left, right, bottom, top, near, far)`

normalization  $\Rightarrow$  find transformation to convert specified clipping volume to default



Flip:  $-far \rightarrow 1$ ;  $-near \rightarrow 1$

$0 < near < far$

# Orthogonal Projection

## □ Two steps

- Move center to origin

$$T(-(left+right)/2, -(bottom+top)/2, (near+far)/2))$$

- Scale to have sides of length 2

$$S(2/(right-left), 2/(top-bottom), 2/(near-far))$$

$$\mathbf{P} = \mathbf{ST} = \begin{bmatrix} \frac{2}{right-left} & 0 & 0 & -\frac{right+left}{right-left} \\ 0 & \frac{2}{top-bottom} & 0 & -\frac{top+bottom}{top-bottom} \\ 0 & 0 & \frac{2}{near-far} & -\frac{far+near}{far-near} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

# Orthogonal Projection

---

- ❑ Set up projection matrix in the pipeline

- Method 1

- `glMatrixMode(GL_PROJECTION);`

- `glLoadIdentity();`

- `glOrtho(-1.2, 1.2, -1.2, 1.2, 0.1, 100);`

# Orthogonal Projection

## ❑ Set up projection matrix in the pipeline

### – Method 2

$$\begin{bmatrix} \frac{2}{right-left} & 0 & 0 & -\frac{right+left}{right-left} \\ 0 & \frac{2}{top-bottom} & 0 & -\frac{top+bottom}{top-bottom} \\ 0 & 0 & \frac{2}{near-far} & -\frac{far+near}{far-near} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

```
float  m[16];
```

```
.....//Calculate m
```

```
glMatrixMode(GL_PROJECTION);
```

```
glLoadMatrixf(m);
```

# Orthogonal Projection

---

## ❑ Set up projection matrix in the pipeline

### – Method 3

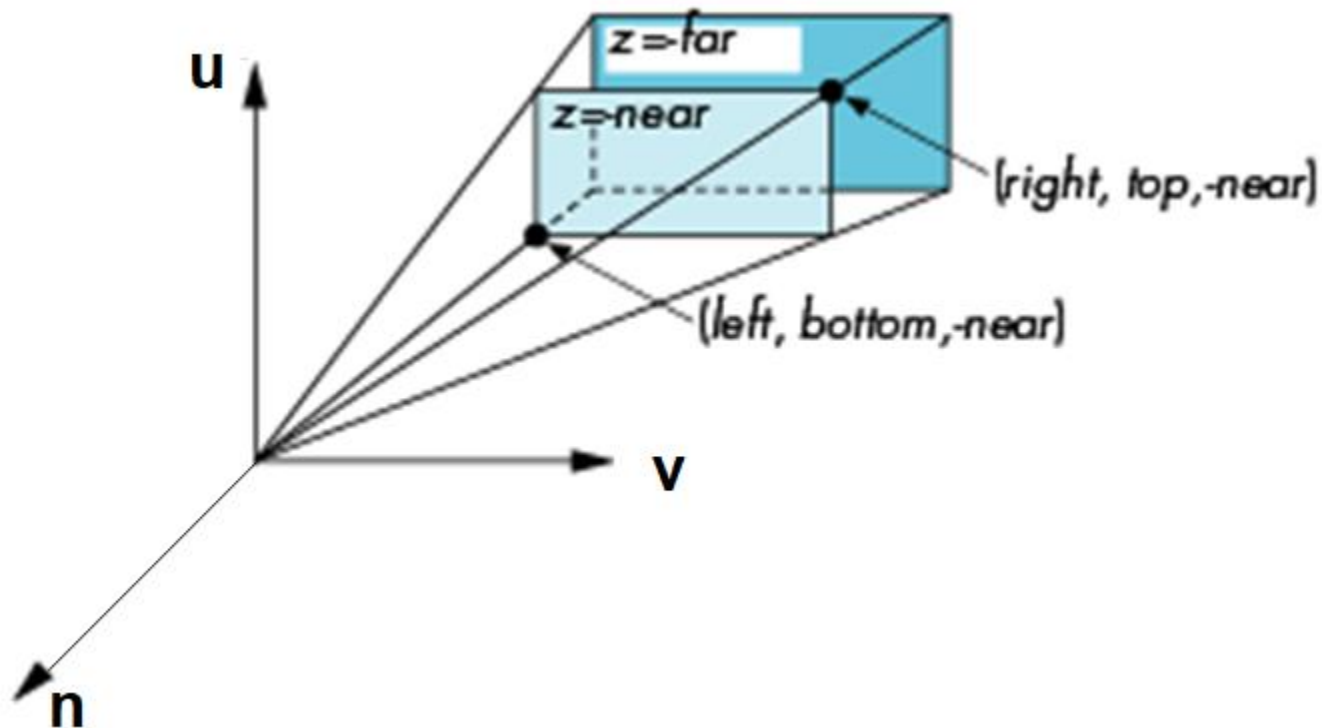
```
glMatrixMode(GL_PROJECTION);  
glLoadIdentity();  
..... //Calculate S matrix  
glMultMatrixf(s);  
..... //Calculate T matrix  
glMultMatrixf(t);
```



# Perspective Projection

## □ Perspective Projection

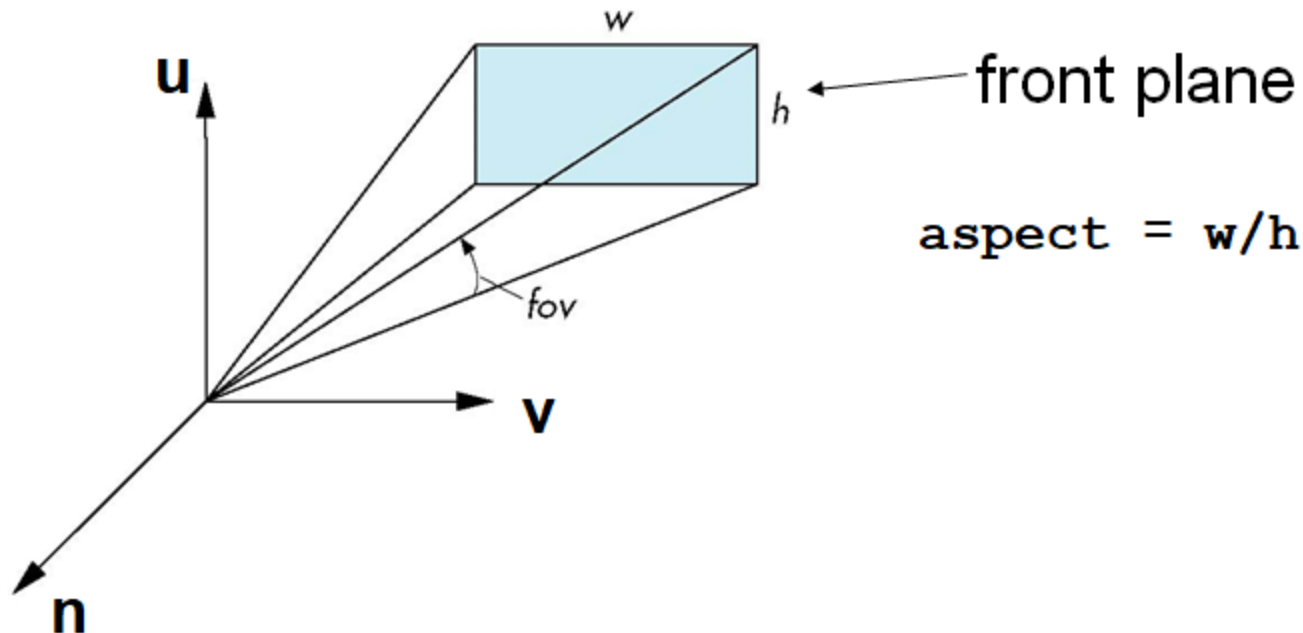
– `glFrustum(left, right, bottom, top, near, far)`



# Perspective Projection

## ❑ Perspective Projection

- With `glFrustum` it is often difficult to get the desired view
- `gluPerspective(fovy, aspect, near, far)` often provides a better interface



# Perspective Projection

---

$$P = \begin{bmatrix} \frac{2 \times \text{near}}{\text{right} - \text{left}} & 0 & \frac{\text{right} + \text{left}}{\text{right} - \text{left}} & 0 \\ 0 & \frac{2 \times \text{near}}{\text{top} - \text{bottom}} & \frac{\text{top} + \text{bottom}}{\text{top} - \text{bottom}} & 0 \\ 0 & 0 & -\frac{\text{far} + \text{near}}{\text{far} - \text{near}} & -\frac{2 \times \text{far} \times \text{near}}{\text{far} - \text{near}} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

$$0 < \text{near} < \text{far}$$

# Oblique Projections

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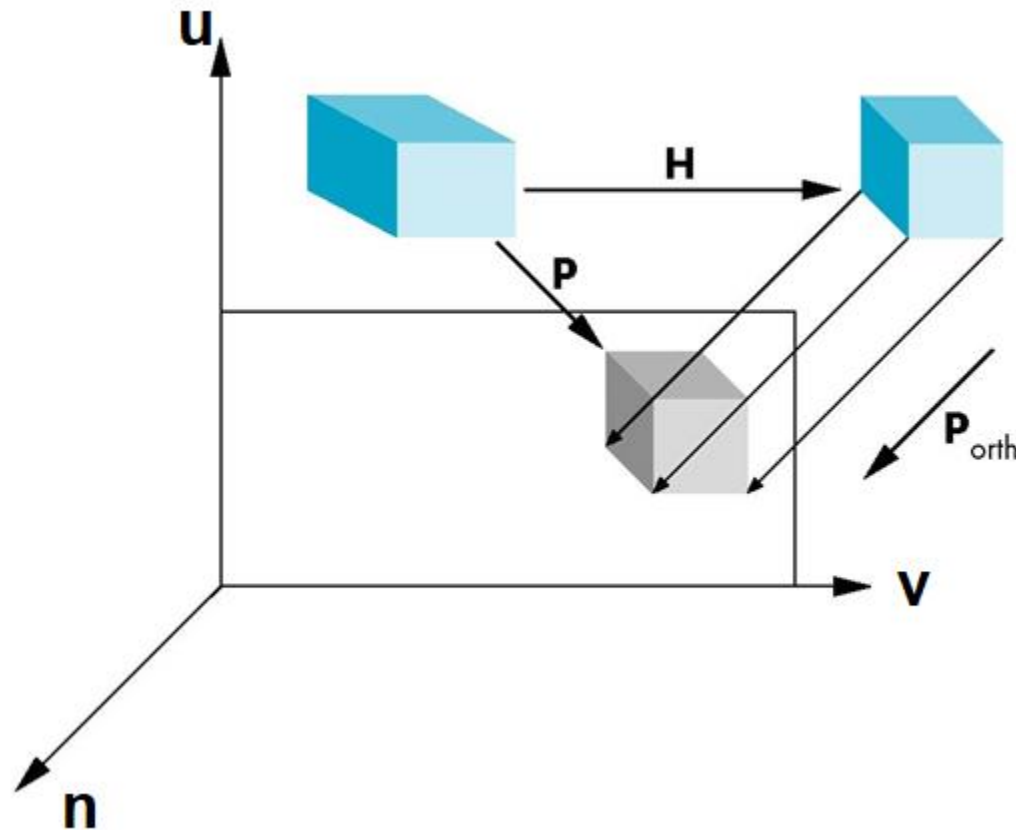
- ❑ The OpenGL projection functions cannot produce general parallel projections such as



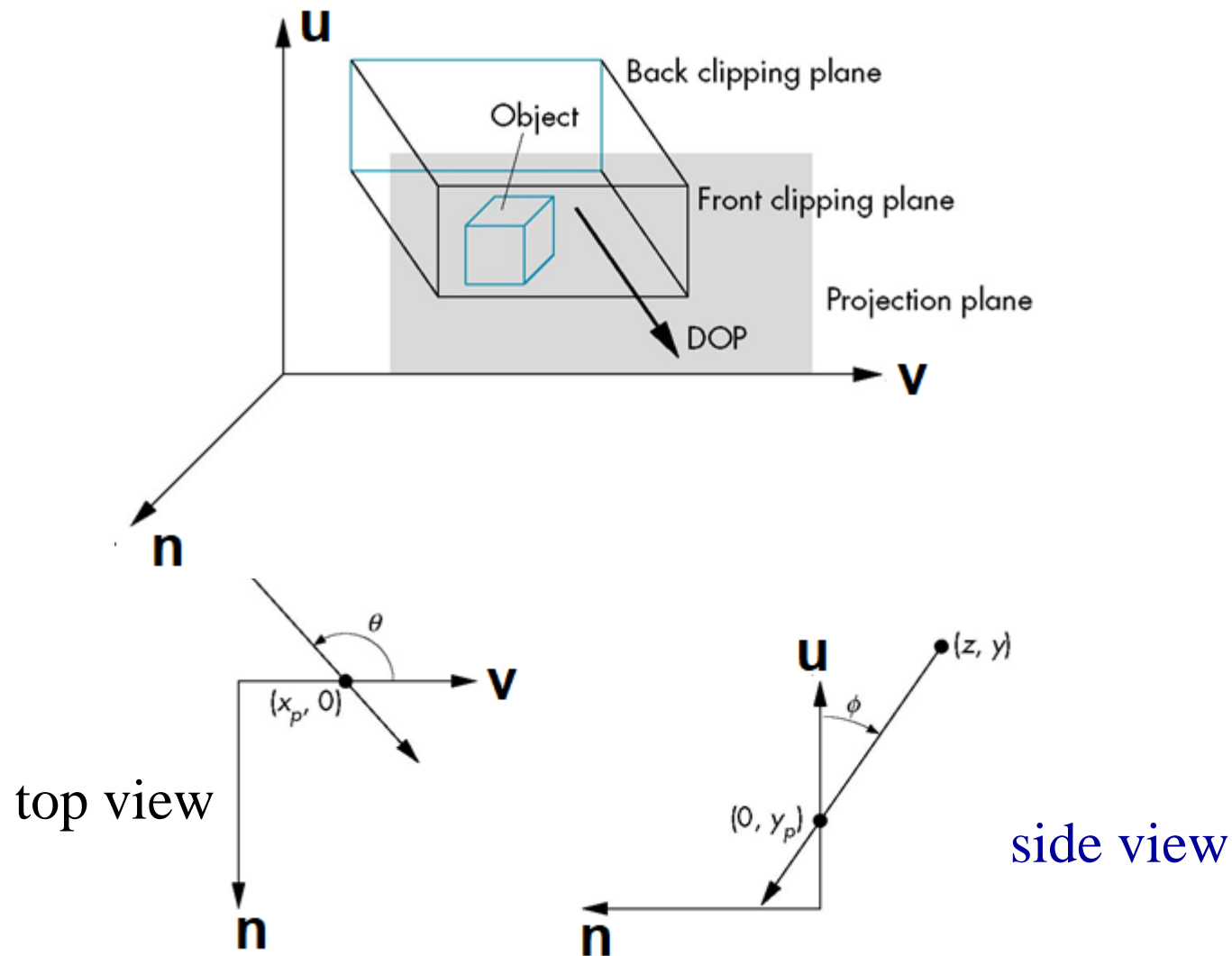
- ❑ However if we look at the example of the cube it appears that the cube has been sheared
- ❑ Oblique Projection = Shear + Orthogonal Projection

# Oblique Projections

---



# Oblique Projections



# Oblique Projections

---

## □ Shear matrix

*xy* shear (*z* values unchanged)

$$\mathbf{H}(\theta, \phi) = \begin{bmatrix} 1 & 0 & \cot \theta & 0 \\ 0 & 1 & \cot \phi & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Projection matrix

$$\mathbf{P} = \mathbf{M}_{\text{orth}} \mathbf{H}(\theta, \phi)$$

# Further Reading

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- ❑ **“Interactive Computer Graphics: A Topdown Approach Using OpenGL”, *Edward Angel***
  - Chapter 5: Viewing
- ❑ **“Đồ họa máy tính trong không gian ba chiều”, Trần Giang Sơn**
  - Phép nhìn trong không gian ba chiều