

Strong One-Way Functions: A function $M: N \rightarrow R$ is called negligible if for every positive polynomial $p(\cdot)$ and all sufficiently large n 's, it holds that $M(n) < \frac{1}{p(n)}$.

A function $f: \{0,1\}^* \rightarrow \{0,1\}^*$ is called strongly one-way if the following two conditions hold:

- (1) Easy to compute: There exists a deterministic polynomial-time algorithm A such that on input x algorithm A outputs $f(x)$: $A(x) = f(x)$.
- (2) Hard to invert: For every probabilistic polynomial-time algorithm A' , every positive polynomial $p(\cdot)$, and all sufficiently large n 's,

$$\Pr[A'(f(u_n), 1^n) \in f^{-1}(f(u_n))] < \frac{1}{p(n)},$$

Here u_n denotes a random variable uniformly distributed over $\{0,1\}^n$. The probability in (2) is taken over all possible values assigned to u_n and all possible internal coin tosses of A' , with uniform probability distribution. A' is not required to output a specific pre-image of $f(x)$; any pre-image (element in the set $f^{-1}(f(x))$) will do. In case f is 1-1, the string x is the only pre-image of $f(x)$ under f ; but in general there may be other pre-images.

The Auxiliary Input 1^n : In addition to an input in the range of f , the inverting algorithm A' is also given the length of the desired output (in unary notation). The main reason for this convention is to rule out the possibility that a function will be considered one-way merely because it drastically shrinks its input, and so the inverting algorithm just does not have enough time to print the desired output (the corresponding pre-image). Consider, for example, the function f_{len} defined by $f_{\text{len}}(x) = y$ such that y is the binary representation of the length of x ($f_{\text{len}}(x) = |x|$). Since $|f_{\text{len}}(x)| = \log_2 |x|$, no algorithm can invert f_{len} on y in time polynomial in $|y|$; yet there exists an obvious algorithm that inverts f_{len} on $y = f_{\text{len}}(x)$ in time polynomial in $|x|$ ($|x| \rightarrow 0^{|x|}$). In general, the auxiliary input $|x|$, provided in conjunction with the input $f(x)$, allows the inverting algorithm to run in time polynomial in the total length of the main input and the desired output.

Weak One-Way Functions: A function $f: \{0,1\}^* \rightarrow \{0,1\}^*$ is called weakly one-way if the following two conditions hold:

- ① Easy to compute: There exists a deterministic polynomial-time algorithm A such that on input x algorithm A outputs $f(x)$: $A(x) = f(x)$.
- ② Slightly hard to invert: There exists a polynomial $p(\cdot)$ such that for every probabilistic polynomial-time algorithm A' and all sufficiently large n 's,

$$\Pr [A'(f(U_n), 1^n) \notin f^{-1}(f(U_n))] > \frac{1}{p(n)}$$

Non-Uniformly Strong One-Way Functions: A function $f: \{0,1\}^* \rightarrow \{0,1\}^*$ is called non-uniformly strong one-way if the following two conditions hold:

- ① Easy to compute: There exists a polynomial-time algorithm A such that on input x algorithm A outputs $f(x)$.
- ② Hard to invert: For every family of polynomial-size circuits $\{C_n\}_{n \in \mathbb{N}}$, every polynomial $p(\cdot)$, and all sufficiently large n 's,

$$\Pr [C_n(f(U_n)) \in f^{-1}(f(U_n))] < \frac{1}{p(n)},$$

Here the probability is taken over all possible values of U_n .