## k-center Clustering

**TOP: Data Clustering 076/091** 

Instructor: Sayan Bandyapadhyay
Portland State University

#### Outline

1 Discrete *k*-center

- 2 The First Algorithm
- 3 The Second Algorithm
- 4 Drawbacks

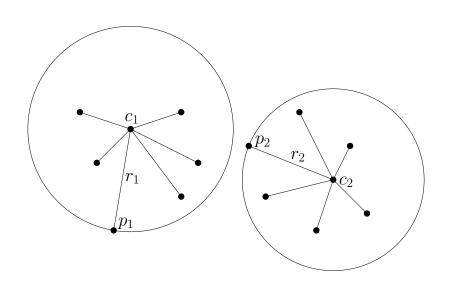
## Discrete *k*-center Clustering

#### Given a set X of n points in the metric space (X, d)

■ Find a set *C* of *k* points (cluster centers) in *X* that minimizes,

$$cost(C) = \max_{p \in X} d(p, NearestCenter(p))$$
$$= \max_{c \in C} \max_{p \in cluster(c)} d(p, c)$$

### Each Cluster is a Ball



## k-center Clustering

#### Given a set X of n points in the metric space (X, d)

■ Find a set *C* of *k* points (cluster centers) in *X* that minimizes,

$$cost(C) = \max_{p \in X} d(p, NearestCenter(p))$$

$$= \max_{c \in C} \max_{p \in cluster(c)} d(p, c)$$

$$= \max_{c \in C} radius(c)$$

#### Outline

1 Discrete *k*-center

- 2 The First Algorithm
- 3 The Second Algorithm
- 4 Drawbacks

## **Choices for Optimal Distances**

$$cost(C) = \max_{c \in C} radius(c)$$

$$= \max_{c \in C} \max_{p \in cluster(c)} d(p, c)$$

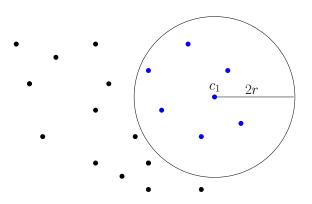
- OPT is one of the  $\binom{n}{2} \le n^2$  distances: we can *guess* the optimal radius by trying out all choices
- We can assume we know the optimal radius

# An Algorithm for *k*-center (Hochbaum-Shmoys '85)

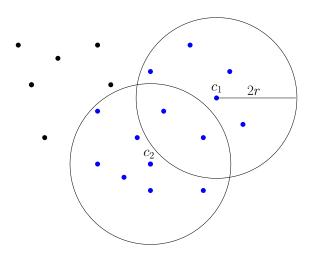
#### Algorithm Greedy 1

```
Require: Set of points X, radius r
  1: T ← X
 2: C \leftarrow \emptyset
 3: while T \neq \emptyset do
         Take any point x in T
     C \leftarrow C \cup \{x\}
     if |C| = k + 1 then
              return False
 7:
         end if
 8.
         for each p \in T \setminus \{x\} do
 9:
              if d(p, x) \leq 2 \cdot r then
10.
                  T \leftarrow T \setminus \{p\}
11:
12.
                  Add p to cluster(x)
13:
              end if
         end for
14:
15 end while
16: return C
```

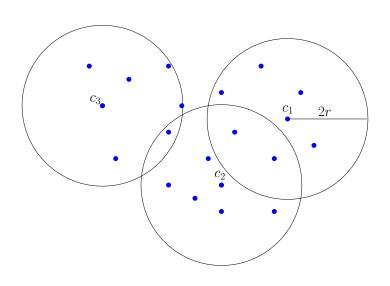
## Demonstration of Greedy 1



## Demonstration of Greedy 1



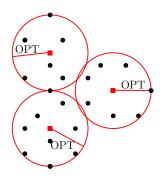
## Demonstration of Greedy 1



## Analysis of Greedy 1

- Suppose the given radius  $r \ge OPT$
- Claim: The algorithm returns at most *k* centers/clusters
  - Optimal solution can cover all points with k balls of radius OPT

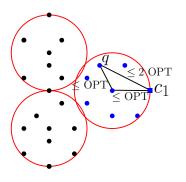
# Covering by Optimal Solution



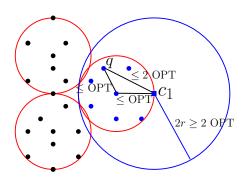
### Analysis of Greedy 1

- Suppose the given radius  $r \ge OPT$
- Claim: The algorithm returns at most *k* centers/clusters
  - Optimal solution can cover all points with k balls of radius OPT
  - Consider the center  $c_1$  chosen; all the points in the optimal cluster containing  $c_1$  are removed from T after 1st iteration

#### Points in a Cluster has Diameter 2-OPT



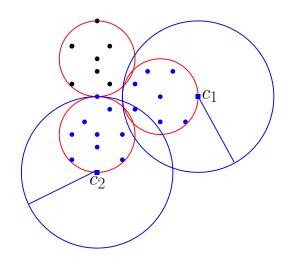
## Removing All Points of the Optimal Cluster



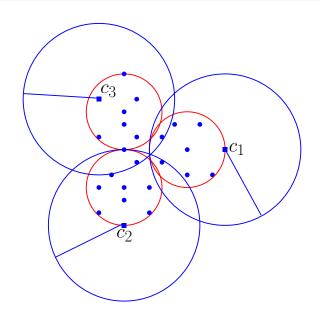
### Analysis of Greedy 1

- Suppose the given radius  $r \ge OPT$
- Claim: The algorithm returns at most *k* centers/clusters
  - Optimal solution can cover all points with k balls of radius OPT
  - Consider the center  $c_1$  chosen; all the points in the optimal cluster containing  $c_1$  are removed from T after 1st iteration; need a figure
  - In every iteration, points of at least one cluster gets removed

## Removing All Points of the 2nd Optimal Cluster



## Removing All Points of the 3rd Optimal Cluster



#### Analysis of Greedy 1

- Suppose the given radius  $r \ge OPT$
- Claim: The algorithm returns at most *k* centers/clusters
  - Optimal solution can cover all points with k balls of radius OPT
  - Consider the center  $c_1$  chosen; all the points in the optimal cluster containing  $c_1$  are removed from T after 1st iteration; need a figure
  - In every iteration, points of at least one cluster gets removed
  - T is empty after at most *k* iterations
  - The algorithm returns a set of centers

#### Analysis of Greedy 1

- Suppose the given radius  $r \ge OPT$
- Claim: The algorithm returns at most *k* centers/clusters
  - Optimal solution can cover all points with k balls of radius OPT
  - Consider the center  $c_1$  chosen; all the points in the optimal cluster containing  $c_1$  are removed from T after 1st iteration; need a figure
  - In every iteration, points of at least one cluster gets removed
  - T is empty after at most *k* iterations
  - The algorithm returns a set of centers

For r = OPT, we obtain a 2-approximation

### Time Complexity

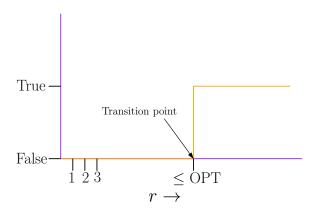
#### Algorithm Greedy 1

```
Require: Set of points X, radius r
 1: T ← X
 2: C ← Ø
 3: while T \neq \emptyset do
        Take any point x in T
 4.
     C \leftarrow C \cup \{x\}
     if |C| = k + 1 then
             return False
 7.
        end if
         for each p \in T \setminus \{x\} do
 9:
             if d(p, x) \leq 2 \cdot r then
10:
                 T \leftarrow T \setminus \{p\}
11.
                 Add p to cluster(x)
12:
             end if
13.
         end for
14:
15 end while
16: return C
```

## Time Complexity of Greedy 1

- While loop runs at most k + 1 times and the for loop runs at most n 1 times. Time complexity is O(nk)
- If we have to run for all possible guesses, then complexity is at most  $n^2 \cdot O(nk) = O(n^3k)$
- Our algorithm works for  $r \ge OPT$

## Our algorithm works for $r \ge OPT$



## Time Complexity of Greedy 1

- While loop runs at most k + 1 times and the for loop runs at most n 1 times. Time complexity is O(nk)
- If we have to run for all possible guesses, then complexity is at most  $n^2 \cdot O(nk) = O(n^3k)$
- Our algorithm works for  $r \ge OPT$
- Do a binary search on the range [min, max]
- Time complexity is  $n^2 + (\log n^2 \cdot O(nk)) = O(n^2 + nk \log n)$

#### Outline

1 Discrete *k*-center

- 2 The First Algorithm
- 3 The Second Algorithm
- 4 Drawbacks

■ We don't want to guess the optimal radius

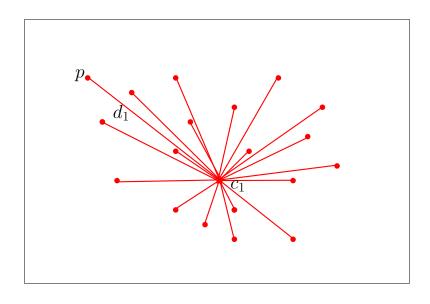
- We don't want to guess the optimal radius
- Diameter  $\Delta(X)$  is the maximum interpoint distance

- We don't want to guess the optimal radius
- Diameter  $\Delta(X)$  is the maximum interpoint distance
- For k = 2, if the two maximum-distance points are in the same ball, radius is  $\geq \Delta(X)/2$

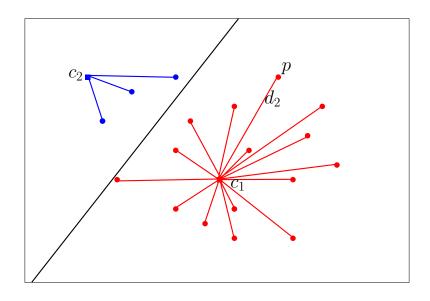
- We don't want to guess the optimal radius
- Diameter  $\Delta(X)$  is the maximum interpoint distance
- For k = 2, if the two maximum-distance points are in the same ball, radius is  $\geq \Delta(X)/2$
- This is as good as not splitting the points into 2 groups

- We don't want to guess the optimal radius
- Diameter  $\Delta(X)$  is the maximum interpoint distance
- For k = 2, if the two maximum-distance points are in the same ball, radius is  $\geq \Delta(X)/2$
- This is as good as not splitting the points into 2 groups
- So, the two maximum-distance points should be in different groups
- This is the intuition behind our algorithm

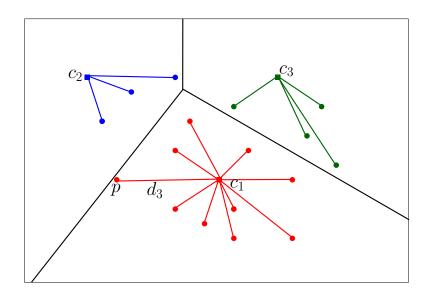
# Picking the 1st center



## Picking the 2nd center



# Picking the 3rd center



# Another Algorithm for *k*-center (Gonzalez, Dyer, Frieze '85)

#### Algorithm Greedy 2

```
Require: Set of points X
```

- 1: Select an arbitrary center  $c_1$
- 2:  $\mathbf{C} \leftarrow \{\mathbf{c}_1\}$
- 3: **for** i = 2 to k **do**
- 4:  $c_i \leftarrow \arg \max_{p \in X} d(p, C) \quad \triangleright d(p, C) = \min_{c \in C} d(p, c)$
- 5:  $C \leftarrow C \cup \{c_i\}$
- 6: end for
- 7: **return** *C*

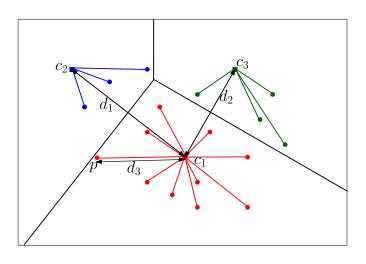
## Time Complexity of Greedy 2

- The for loop runs k 1 times
- Inside the for loop, we do n \* k distance computations. Time complexity is  $O(nk^2)$

### Time Complexity of Greedy 2

- The for loop runs k 1 times
- Inside the for loop, we do n \* k distance computations. Time complexity is  $O(nk^2)$
- We can keep track of the nearest center for each point in an array
- Inside the for loop, when we add a new center, we need to update at most *n* entries
- Time complexity is O(nk)

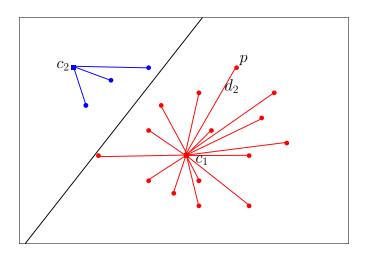
# Analysis of Greedy 2



 $d_1 \geq d_2 \geq \ldots \geq d_k$ ; our cost is  $d_k$ 

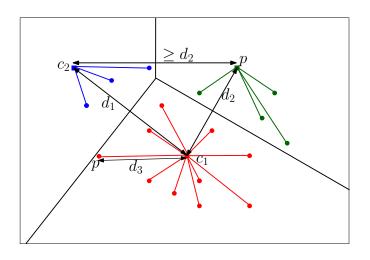
- $c_2$  is  $d_1$  away from  $c_1$
- $c_3$  is  $c_2$  away from  $c_1$  and  $c_2$

# Analysis of Greedy 2



p is  $d_2$  away from  $c_1$ 

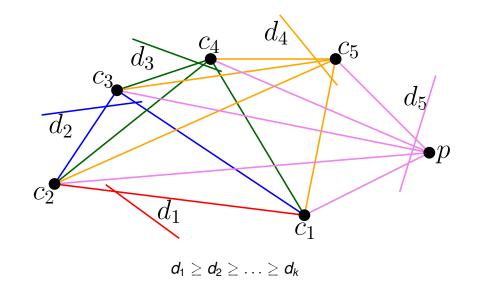
# Analysis of Greedy 2



p is  $d_2$  away from  $c_1$  and  $c_2$ 

- $c_2$  is  $d_1$  away from  $c_1$
- $c_3$  is  $d_2$  away from  $c_1$  and  $c_2$
- lacksquare  $c_k$  is  $d_{k-1}$  away from  $c_1, c_2, \ldots, c_{k-1}$
- The maximum-distance point p is  $d_k$  away from  $c_1, c_2, \ldots, c_k$

### k + 1 points in X pairwise $d_k$ away



- lacksquare  $c_2$  is  $d_1$  away from  $c_1$
- $\bullet$   $c_3$  is  $d_2$  away from  $c_1$  and  $c_2$
- lacksquare  $c_k$  is  $d_{k-1}$  away from  $c_1, c_2, \ldots, c_{k-1}$
- The maximum-distance point p is  $d_k$  away from  $c_1, c_2, \ldots, c_k$
- So, among the k + 1 points  $\{c_1, c_2, \dots, c_k, p\}$ , 2 points must be in a single optimal cluster

- lacksquare  $c_2$  is  $d_1$  away from  $c_1$
- $c_3$  is  $d_2$  away from  $c_1$  and  $c_2$
- lacksquare  $c_k$  is  $d_{k-1}$  away from  $c_1, c_2, \ldots, c_{k-1}$
- The maximum-distance point p is  $d_k$  away from  $c_1, c_2, \ldots, c_k$
- So, among the k + 1 points  $\{c_1, c_2, \dots, c_k, p\}$ , 2 points must be in a single optimal cluster
- The diameter of this optimal cluster is  $\geq d_k$ , so radius is  $\geq d_k/2$

**Plan:** To show: 
$$OPT \ge d_k/\alpha \implies our \cos d_k \le \alpha \cdot OPT$$

- lacksquare  $c_2$  is  $d_1$  away from  $c_1$
- $c_3$  is  $d_2$  away from  $c_1$  and  $c_2$
- lacksquare  $c_k$  is  $d_{k-1}$  away from  $c_1, c_2, \ldots, c_{k-1}$
- The maximum-distance point p is  $d_k$  away from  $c_1, c_2, \ldots, c_k$
- So, among the k + 1 points  $\{c_1, c_2, \dots, c_k, p\}$ , 2 points must be in a single optimal cluster
- The diameter of this optimal cluster is  $\geq d_k$ , so radius is  $\geq d_k/2$
- We obtain a 2-approximation

#### Outline

1 Discrete *k*-center

- 2 The First Algorithm
- 3 The Second Algorithm
- 4 Drawbacks

#### Drawbacks of the *k*-center model

Does not work if the clusters are not uniform

#### Drawbacks of the *k*-center model

- Does not work if the clusters are not uniform
- A large cluster/ball can get split: Dissection effect

#### Drawbacks of the *k*-center model

- Does not work if the clusters are not uniform
- A large cluster/ball can get split: Dissection effect
- Extremely sensitive to outliers

