## Finding Contexual Preferrable Products from Online Reviews

Paper 280

## **ABSTRACT**

In this paper we study the problem of review guided context aware recommendation systems (RGCARS). The major challenge in RGCARS is the sparseness of explicit feedback. Most reviews are not annotated by a context label. To fully exploit the value of online reviews, we prensent a semi-supervised classifier to identify context relevant reviews. We further treat the irrelevant reviews as missing not at random observations. In particular, our model is based on the marginal utility theory, which studies the increase in satisfaction consumers gain by purchasiing a product. We propose two assumptions that simulate the generation of context irrelevant reviews, one delineates the odds of a user publishing irrelevant reviews from not getting enough satisfaction in the context, the other explores the connection between context independent and context aware satisfactions. We conduct comprehensive experiments on real data sets, revealing typical recommendation scenarios such as cold start recommendations, context aware recommendation, visuallization and so on. Experimental results demonstrate that our models outperform state-of-the-art methods.

#### **KEYWORDS**

context aware recommendation systems, online review mining, missing not at random, probabilistic graphic model, utility surplus

#### 1 INTRODUCTION

Product recommender is an indispensible component of modern E-commerce ecosystems. It facilitates the interaction between enterprises and users by predicting the preferred items for each user. Despite of user preference, it is also neccessary to consider the contextual situation in which the product is consumed. Context Aware Recommendation Systems (CARS) take contextual information into account, including when, where and with whom the item is purchased, to deliver more accurate recommendations that best suit user needs. CARS have been successfully applied in a few areas, including travel [6], music [8], web news [31] and so on. As more and more people use review sites to share shopping experiences, recently a few researchers explore the feasibility of Review Guided Context Aware Recommendation Systems (RGCARS) and generate promising results [17, 15, 11, 19].

Fig. ?? depicts a review guided context aware restaurant recommender based on a small selection of real-world online reviews. Suppose a user Bob is looking for a place to go with his girlfriend, restaurant A seems to be a perfect option. Two reviews (review 1 and 2) explicitly express positive feedback under the context "dating" for restaurant A. However, if Bob is seeking a party night, the RGCARS should output restaurant B as a more appropriate result. There are also two explicit positive reviews (review 4 and 5) under the context "party" for restaurant B. It is easy to see that RGCARS benefit by finer modeling of context aware user preference. For

example, the reviews in Fig. ?? suggest that under context "dating", users are more sensitive to the quality of food, while under context "party", good food is not the first priority.



Figure 1: Selected reviews for two restaurants from www.yelp.ca. Reviews are shortened for the limited space. Number of starts for each indicate user rating. Reviews in violet recangles are context explicit feedback, reviews in yellow recangles are context implicit feedback

Naturally, one key problem in RGCARS is to integrate review contents and ratings into the recommender framework. Most previous researches do so by transforming reviews to contextual ratings [17, 19]. They essentially assign each product with a static profile. However, consumers usually observe different aspects of the same product and sketch inconsistent product profiles. For example, in Fig. ??, for the same restaurant, reviewer 1 and 2 enjoyed delicious food and posted positive feedback, while reviewer 3 had an opposite experience and published negative feedback.

To connect the dots among products, user preferences and purchases within different contexts, we propose a recommender framework which is inspired by marginal utility theory [34]. Utility surplus is an economic concept to measure consumer's "satisfaction" or "pleasure". It is the aggregation of user preferences over several commodity features of interest. We expand the definition of utility surplus to a context aware setting: when a consumer is pleasant with the purchase under the context, he/she will post a piece of positive review; otherwise, he/she will post a negative piece. Therefore, given the product descriptions and the opinions of online reviews, the contextual user preferences can be inferred.

Another issue which, to the best of our knowledge, has not yet been studied by previous RGCARS, is the context explicit and implicit feedback in online reviews. As shown in Fig. ??, reviews which offer explicit expressions for a given context are regarded as context explicit feedback. Simply treating all reviews as explicit feedback could be problematic. Firstly, most reviews are not explicitly annotated by a context label. Due to the ambiguity of natural language, it is impracticable to match all reviews with some predefined contextual phrases. To address this challenge, we need a classifier to automatically discover context explicit feedback. Secondly, the absence of contextual information in some reviews make

them context implicit feedback. For example, in Fig. ?? review 3 and 6 are implicit feedback regarding any context, while review 1 and 2 are implicit feedback for context "party" and review 5 is implicit feedback for context "dating". Ignoring context implicit feedback as random missing instances is intuitively not optimal as it may distort inferences about the user preferences. For example, if we only consider explicit feedback within "dating" for restaurant A, the model may be biased to inaccurately higher predictions. The presense of implicit feedback requires models that handle missing not at random observations.

The contributions of this paper are three-fold. (1) We present a unified framework to fully exploit the value of online reviews, including explicit and implicit contextual feedback, for context aware product recommendation. The framework gives economic interpretatation for producing the explicit feedback, as well as observing the feedback. We testify these assumptions by modeling that the probability of writing an explicit review is dependent on the contextual utility alone, or the comparison of contextual utility and context-independent unitility of the product for the user. (2) Due to the high volume of online reviews, it is impossible to manually label all context related reviews. We propose a semi-supervised classifier to learn the hidden contexts from a few roughly labeled instances and a large number of unlabeled instances. It helps to clarify ambiguous expressions and to identify the true contexts. (3) We perform comprehensive experiments on real data sets. We apply and extend our models to many typical ecommerce scenarios, such as cold-start recommendation, context-aware recommendation and visualization. Experimental results show that the proposed framework outperforms state-of-the-art methods with or without text mining techniques.

The rest of this paper is organized as follows. We provide a brief discussion on related work in section 2. We introduce the overall framework in Sec. 3, and its components (contextual opinion classification model, utility model with complete observations or missing observations) in section 4, 5 and 6, respectfully. The experimental results are described and analyzed in section 7. Finally, we conclude our work in section 8.

#### 2 RELATED WORK

RGCARS are genetically related to two areas: contextual aware recommendation systems and online review mining.

#### 2.1 Context Aware Recommendation Systems

Most recommender systems use numeric user ratings to construct a rating matrix, and apply collaborative filtering approaches to recommend items for users with similar tastes [7]. There are two types of collaborative filtering techniques. One is based on retrieving nearest neighbors, performances of which are enhanced by modifying the similarity measurements, such as removing the global effect of nearest neighbors [5]. The other is based on matrix factorization [14] to approximate the observed ratings with hidden user preferences and item features. Probabilistic versions of matrix factorization are also prodominant [27]. For binary relevance data, researchers present methodologies that target different object functions, most of which are ranking related measures. For example, BPR [26] maximizes the likelihood of pair-wise rankings, CliMF [28] directly maximizes the

mean reciprocal rank to improve top-k recommendations, ListRank-MF [29] minimizes a loss function that represents the uncertainty between training lists and output lists.

Recently, constext aware recommender systems (CARS) have attracted both academic and industrial attentions [2]. The performance of CARS has been verified by a live controlled experiment [9]. There are three types of approaches to incorporate contextual information in the recommendation process. The first type is to pre-filter, i.e. select contextualized ratings data and factorize each context specific rating matrix [1]. The second type is to post-filter, i.e. split the resulting items to different contexts after recommendation [4]. The third type is to model the context, i.e. as a latent variable in BNN [22], or as a latent factor in matrix factorization [3]. or as tensor factorization [31, 13]. Empirical study has shown that which approach is better depends on the application [23]. The sparsity of rating data is an obstacle for CARS. A typical improvement is to integrate other resources, i.e. demographic information [16], sequential patterns [10], or, as we might review in the next subsection, texts in online reviews [17, 15, 11, 19].

## 2.2 Online Review Mining

Online review mining has been an active research area. Most existing researches are efforts that summarize reviews and extract certain information, i.e. opinion polarities [18], user groups according to their interests [30], aspects of products [20], and so on. Online review mining often requires a skillful combination of natural language processing (NLP) and machine learning models. An omnipotent model does not exist for every domain.

Information extracted from online reviews is helpful in recommender systems. For example, identifying product aspects and user opinions is crucial for predicting a user's rating [24], estimating the review quality can "up-weight" or "down-weight" the importance of individual rating while performing collaborative filtering [25]. For CARS, online review mining also assists the recommendation process in POI recommender [6], hotel recommender [15], and restaurant recommender[17], etc..

For RGCARS, most researches in literature directly utilize the extracted conextual opinions to form preference data, and then pipe the explicit feedback with a CARS model. For example, a tensor factorization model is presented in [15], which imitates a user who favors reviews written by people with the same intent, nationality and tasts. An extended LDA is presented in [11], which jointly models users, items and contexts. In [17], the contextural information is integrated into a probabilistic latent relational model, which factorizes ratings to item specific features, as well as a combination of the current context and a user's long term preference. In [19] a simple recommendation model is used to aggregate opinions over each product feature.

## 3 METHODOLOGY OVERVIEW

We consider the most common form of consumer reviews on popular e-commerce sites, such as Amazon, and social media sites, such as TripAdvisor and Yelp. The consumer reviews are in the format of a short passage of texts accompanied by a numerical rating. Suppose in the pre-processing, we extract a predefined set of contextual factors  $F = \{f\}$ , which can be any textual phrases in natural languages,

i.e. "with my girlfriend", "at Christmas Eve", etc. We also identify the commodity features  $C = \{c\}$ , i.e. "good food", "wonderful staff", etc. The associated opinions for the contextual factors and commodity features are denoted by  $O = \{o\}$ , as listed in Tab. ??. The detailes of pre-processing are described in Sec. 7. We present a castcade framework which sequentially solves the following two problems.

**Contextual Opinion Categorization** Suppose there are a set of reviews  $E = \{e\}$ , where each review consists of the user's opinion on the corresponding contextual factors and commodity features, a few reviews are labeled by a set of K conext labels  $L = \{l_k\}, 1 \le k \le K$ , predict if a review is relevant to any context. If so, the review is an explicit response, r = 1, predict whether the opinion for the context x is positive or negative. Since there are only a few lableled instances available, the multi-class problem requires a semi-supervision approach.

**Context Aware Recommendation** Given a set of explicit and implicit contextual review feedback of a group of users  $U = \{u\}$  on a universe of commodities  $V = \{v\}$ , estimate how a user will like an item under a context.

In model based collaborative filtering, i.e. matrix factorization, user feedback is usually determined by latent variables for user preferences U and item features V. In RGCARS, an additional hidden variable a is introduced for each context. If all the reviews are explicit feedback, i.e.  $\forall r, r = 1$ , the problem is tackled by maximizing the likelihood of generating the reviews p(X|A, U, V). We present a utility model for complete observations in Sec. 5.

However, if implicit feedback is incorporated, i.e.  $\exists r, r = 0$ , then the opinions in implicit feedback is missing  $X^{mis} \neq \emptyset$ , the likelihood is defined as follows.

$$p(X^{obs},R|A,U,V) = \int_{X^{mis}} p(X|A,U,V) p(R|X,A,U,V) \quad \ (1)$$

When R is independent given X,  $p(X^{obs}, R|A, U, V) \propto p(X^{obs}|A, U, V)$ , it degrades to the utility model for complete observations. When R and X are dependent, a model is needed to stimulate the process of generating R given X. We present two variants of the utility model for missing not at random observations in Sec. 6.

## 4 OPINION CLASSIFICATION

Suppose the labeled reviews can be grouped into K+1 categories:  $\{E_1, \dots, E_K, E_{K+1}\}$ , where  $E_k$  represents reviews related to context k, the last category  $E_{K+1}$  consists of reviews that doesn't belong to any context. A softmax [12] regression for this multi-class categorization problem is to minimize:

$$L(\mathbf{b}) = -\Sigma_k \Sigma_{e \in E_k^+} \log \frac{\exp \mathbf{b_k f_e}}{\Sigma_{k'} \exp \mathbf{b_{k'} f_e}}$$
 (2)

where  $\mathbf{f_e}$  is the vector denotion of contextual factors in a review e. In the prediction, we assign a K-dimensional label  $\mathbf{l}$  for each instance, the context distribution for an unlabeled review  $\mathbf{f_e}$  is then computed by  $p(l_{e,k}=1|\mathbf{f_e}) = \frac{\exp \mathbf{b_k} \mathbf{f_e}^T}{\sum_{k'} \exp \mathbf{b_{k'}} \mathbf{f_e}^T}$  As mentioned in previous sections, the size of online reviews is

As mentioned in previous sections, the size of online reviews is too large for complete human annotations. It is critical to use characteristics of online reviews to facilitate contextual label prediction. We have the following assumptions.

- (1) **Selection Bias** We argue that selection bias exists in consumers purchasing a product. For example, fast food restaurants are more often chosen for casual lunch, and luxe restaurants are reserved for major celebrations. As reviews are associated to commodities, the prior distribution of contexts for each commodity is not uniform. If we randomly sample reviews to annotate, then the context distribution of a commodity in the sample set is an approximate estimate of the true context distribution. For example, if the commodity has a context distribution  $P\tilde{X}_v = \{\text{"party:"0.1,"banquet:"0.8,"weekday lunch:"0.1} \text{ in the sample set, then we expect the context "banquet" is also dominant in the unlabeled reviews.}$
- (2) **User Activity** Surveys on social media usage often report that consumers are willing to share their opinions (either prises or complaints). We claim that the user activity, which is the portion of context related reviews, is controlled by consumer demographics and irrelevant to the classifier. For example, the prior distribution of context and non-context related reviews, denoted as  $\tilde{PU}$ , is shared among all reviews and would be expected to stay stable for unlabeled reviews.

We construct  $\tilde{P}_v$  as a K + 1-dimensional vector for each item v.

$$P_{v,k} = \begin{cases} \tilde{PU_1} \tilde{PX^{v,k}} & 1 \le k \le K \\ \tilde{PU_2} & k = K+1 \end{cases}$$
 (3)

Following the above assumptions, we devise the KL-divergence between distribution of review samples and the estimated distribution in unlabeled reviews  $p^c(\mathbf{l}|\mathbf{b})$  based on the parameter  $\mathbf{b}$ , which is  $D(\tilde{p}||p(l|\mathbf{b})) = \Sigma_c D_{KL}(\tilde{p}^c||p^c(l|\mathbf{b}))$  Given a set of labeled reviews E on commodities  $C^+ = \{c\}$ , and a large number of unlabeled reviews EU, in order to learn the classifier parameters  $\mathbf{b}$ , we first compute the prior distribution  $\tilde{p}^c$  by equation 3 from  $\tilde{P}U$  and  $\tilde{P}X$ , and then optimize the following loss function.

$$\min_{\mathbf{b}} - \frac{1}{E^{+}} \log p(E^{+}|\mathbf{b}) + \lambda_{p} D(\tilde{p}||p(l|\mathbf{b})) + \lambda_{c} ||\mathbf{b}||_{2}$$
 (4)

where the first term is to maximize the likelihood for generating the labeled reviews; the second term is to maximize the similarity between context distribution from sampled annotations and unlabeled data; the third term is a rugularizer to avoid over-fitting.

In the pre-processing, we adopt a dictionary based procedure to identify opinionated phrases and their orientations, and pair them with the closest commodity features and contextual factors. For context related reviews, i.e. labeled by  $\exists k, l_k = 1$ , we denote the set of positive reviews as  $E_k^+$ , negative reviews as  $E_k^-$ . Conventional collaborative filtering use biased ratings instead of the absolute value of ratings to indicate preferences. Here we borrow the idea and compare the rating  $s_{u,v}$  to a Bayesian estimate of the user specific average rating  $\tilde{s_u}$ .

$$\tilde{s_u} = \frac{\bar{s_u} \times N_u + \bar{s} \times N}{N + N_u} \tag{5}$$

where  $s_u^-$  is the empirical average rating for user u,  $N_u$  is the number of ratings for u,  $\bar{s}$  is the average rating for all users. N is the minimum number of ratings required to calculate the Bayesian estimate for  $\tilde{s_u}$ . If  $N_u < N$ ,  $\tilde{s_u} = \bar{s}$ . If the target rating  $s_{u,v} > \tilde{s_u}$ , the review is included in  $E_k^+$ , otherwise it will be put into  $E_k^-$ .

# 5 UTILITY MODEL WITH COMPLETE OBSERVATIONS

## **5.1** Utility Surplus

In Economics, utility is an important property of any commodity. It measures the satisfaction consumers get by purchasing an item. Money, as a special case of commodity, can also be measured by a utility function. If the consumer is willing to pay a certain amount of money, which is the price  $v_p$ , to purchase an item v, then the utility surplus  $US(u,v) = UC(u,v) - UM(u_p,v_p)$ , which is the commodity utility UC minus the money utility UM, will be positive.

Usually, the commodity utility can not be directly counted, but can be inferred from observed consumptions. Moreover, a common assumption is that the commodity utility can be modeled as a linear combination of user preferences over commodity features. We extend this theory to the CARS problem. Suppose the user preference is represented by u, and contextual preference is represented by a, then the commodity utility under context k is measured by a combination of user specifict utility and context aware utility:  $UC_k(u,v) = \sum_c (\alpha a_{k,c} + (1-\alpha)u_c)v_c$ , where  $a_{k,c}$  is the contextual preference under context k to the commodity feature c,  $u_c$  is the user preference to c, and  $v_c$  is the quality of item v on feature c.

The utility function of money could be more complicated. However, in this scenario, the consumers are paying a very small portion of money, compared to their incomes. So according to the law of diminishing marginal utility, a linear function can be adopted to measure the decrease of consumer satisfaction by losing the money, i.e.  $UM(u_p, v_P) = u_P v_P$ . Here  $u_P$  can also be interpreted as users' sensitiveness to price.

We make the following manipulation to ensure that the score coincides with a probability.

$$p(x_{u,v,k} = 1|\mathbf{u}, \mathbf{a}, \mathbf{v}) = g(UC_k(\mathbf{u}, \mathbf{v})) = \frac{1}{1 + \exp{-UC_k(\mathbf{u}, \mathbf{v})}}$$
(6)

The economic interpretation is clear. If the user is satisfied with the consumption for the context,  $US_k(u, v) > 0$ , then p(c|x) > 0.5, which suggests that it is possible to choose the write a positive review.

## 5.2 Basic Model

Intuitively, if a product is strongly associated with a particular feature, i.e. a restaurant is famous for its dessert, then consumers are more likely to have positive opinions about that feature. Therefore it is naturally to model the probability of user praising a product feature by v. As shown in 2(a), in the basic model, we present the following generation process.

- Generate user preference from a multivariate Gaussian distribution  $u \sim \mathcal{N}(u; 0, \sigma_u^2)$ , contextual preference  $a_k \sim \mathcal{N}(a_k; 0, \sigma_a^2)$ , item specific feature strength  $v_c \sim Beta(v_c; \zeta_a, \zeta_b)$  for each user, item-feature, and context respectfully. Generate global vocabulary distribution over the feature phrases  $\theta \sim Dirichlet(\theta; \xi)$ .
- For each review written by u on v under context k
  - Publish a positive review  $x \sim Bern(x; g(UC_k(u, v)))$
  - For each product feature
    - \* Choose feature phrases  $c \sim Discrete(c; \theta)$

\* Select an opinion polarity to describe the feature  $o \sim Bern(o; v_c)$ 

The parameters  $\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{a}$  are obtained by maximizing the posterior function  $\log L(\mathbf{U}, \mathbf{V}, \mathbf{a})$  in Equ.7.

$$L(U,V,a) = p(U,V,a|X,O,C,\sigma_u,\sigma_a,\zeta_a,\zeta_b,\xi) \propto p(X,O,C,U,V,a|\sigma_u,\sigma_a,\zeta_a,\zeta_b,\zeta_b,\zeta_b)$$
(7)

Reviews which have been identified as positive or negative feedback on context k in Sec 4 have clear meanings. Therefore, the "absolute" baseline is to use the recognized explicit reviews with predicted label  $l_{u,v,k}=1$  as training instances, i.e.  $x_{u,v,k}=1$  for reviews in  $E_k^+$  with higher than average ratings,  $x_{u,v,k}=0$  for reviews in  $E_k^-$  with low ratings. We utilize steepest descent in each update step in the inference algorithm 1

In the above "absolute" baseline, implicit feedback with label  $l_{u,v,k}=0$  is not considered. As mentioned in Sec. 1, implicit feedback contains context free reviews and neutral opinions. Our biased rating mechanism in Sec. 4 has the advantage of transforming neutral opinions to binary preferential data. For a context irrelevant review, a "fuzzy" alternate is to treat them as possible training instances with the possibility of being a positive explicit feedback  $p(x_{u,v,k}=1)=l(\mathbf{b})$  computed by the prediction equation Equ. 2. To sum up, the "fuzzy" strategy assigns a weight  $l_{u,v,k}$  to each review. For an annotated review related to context k,  $l_{u,v,k}=1$ . For a test instance  $l_{u,v,k}=\frac{\exp b_k f_e}{\sum_{k'} \exp b_{k'} f_e}$ .

## Algorithm 1: Learning Process for model basic

**Input:** A set of positive and negative feedback x, a set of feature opinion pairs  $\{< c, o >\}$ 

Output: a, V, U Initialize a, V, U;

while not convergent do

$$\begin{array}{l} \mbox{for } x_{u,\, v,\, k} \in \mathbf{x} \ \mbox{do} \\ & t_{x_{u,\, v,\, k}, \mathbf{a}_k, \mathbf{v}, \mathbf{u}} = \\ & l_{u,\, v,\, k} \frac{\{-\exp\left[(-\alpha \mathbf{a}_k - (1-\alpha)\mathbf{u})\mathbf{v}\right]\}^{x_{u,\, v,\, k}} \mathbf{1}^{1-x_{u,\, v,\, k}}}{1+\exp\left[(-\alpha \mathbf{a}_k - (1-\alpha)\mathbf{u})\mathbf{v}\right]}; \\ \mbox{end} \\ & \mbox{for } \mathbf{u} \in \mathbf{U} \ \mbox{do} \\ & | \mathbf{u} = \mathbf{u} - \lambda_t \left[-(1-\alpha)\Sigma_k \Sigma_{x_{u,\, v,\, k} \in \mathbf{x}} t_{x_{u,\, v,\, k}, \mathbf{a}_k, \mathbf{v}, \mathbf{u}} \mathbf{v} - \frac{\mathbf{u}}{\pi \sigma_u^2}\right]; \\ \mbox{end} \\ & \mbox{for } \mathbf{v} \in \mathbf{V} \ \mbox{do} \\ & | \mathbf{v} = \mathbf{v} - \lambda_t \{\Sigma_k \Sigma_{x_{u,\, v,\, k} \in \mathbf{x}} [-\alpha \mathbf{a}_k - (1-\alpha)\mathbf{u})\mathbf{u}] t_{x_{u,\, v,\, k}, \mathbf{a}_k, \mathbf{v}, \mathbf{u}} + (\zeta_a - 1)\mathbf{v}.^{-1} + (\zeta_b - 1)(1-\mathbf{v}).^{-1}\}; \\ \mbox{end} \\ & \mbox{for } \mathbf{a}_k \in \mathbf{a} \ \mbox{do} \\ & | \mathbf{a}_k = \mathbf{a}_k - \lambda_t [-\alpha \Sigma_{x_{u,\, v,\, k} \in \mathbf{x}} \mathbf{v} t_{x_{u,\, v,\, k}, \mathbf{a}_k, \mathbf{v}, \mathbf{u}} - \frac{\mathbf{a}_k}{\pi \sigma_a^2}]; \\ \mbox{end} \\ \mbox{end} \end{array}$$

## 6 UTILITY MODEL WITH MNAR OBSERVATIONS

The "absolute" strategy in model basic is in its essence a model with missing at random observations. When the observations are not missing at random, as shown in Sec. 3, the optimal parameters

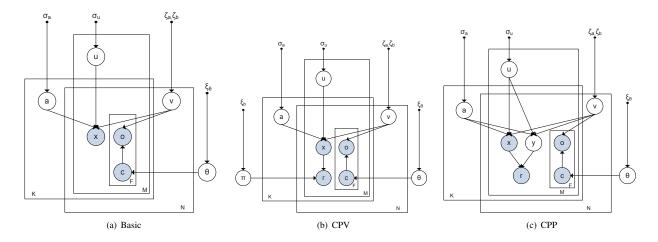


Figure 2: Plate notation for utility models

should be inferred by maximizing the joint likelihood of responses and feedback. Depending on the relationship between  $x_{u,v,k}$  and  $r_{u,v,k}$ , we present two models, i.e. conditional probability on the value of feedback (CPV) and conditional probability on the pairwise preference (CPP).

### 6.1 Model CPV

In model CPV, we assume that the probability of producing a response is dependent on the value of feedback. The conditional probability p(r|x) is denoted as  $\Pi$ , where  $\forall x, \Sigma_r \pi_{r,x} = 1, \forall r, \pi_{r,x} > 0$ . For example,  $\pi_{1,1} > \pi_{0,1}$  indicates that users are more willing to brag about a positive purchase. Model CPV has the following generation process.

- Generate user preference from a multivariate Gaussian distribution  $u \sim \mathcal{N}(u; 0, \sigma_u^2)$ , contextual preference  $a_k \sim \mathcal{N}(a_k; 0, \sigma_a^2)$ , item specific feature strength  $v_c \sim Beta(v_c; \zeta_a, \zeta_b)$  for each user, item-feature, and context respectfully. Generate global vocabulary distribution over the feature phrases  $\theta \sim Dirichlet(\theta; \xi)$ .
- For each review written by u on v under context k
  - Generate contextual polarity  $x \sim Bern(x; g(UC_k(a, u, v)))$
  - Generate response  $r \sim Bernr; \Pi_x$
  - For each product feature
    - \* Choose feature phrases  $c \sim Discrete(c; \theta)$
    - \* Select an opinion polarity to describe the feature  $o \sim Bern(o; v_c)$

We apply an EM algorithm for inference. In the M-step, instead of maximizing the expection of joint log-likelihood, we conduct a one-step update along the line search direction. The inference is shown in Alg. 2.

## 6.2 Model CPP

Empirical studies [33] discovered the phenomenan of extreme reviews. Intuitively, a stronger emotion, either positive or negative, is more likely to trigger a response. In this sense, model CPP explains the generation of extreme reviews by introducing an auxiliary

 $y_{u,v,k}$ , which is the pairwise comparison between contextual and non contextual utility. It assumes that the response is not only related to the contextual utility, but also dependent on the non contextual utility. As shown in Tab. 1, the reviewers respond to extreme circumstances, i.e. if the user is satisfied with the product under the context  $x_{u,v,k} = 1$ , and the satisfaction is larger than the non contextual satisfaction  $y_{u,v,k} = 1$ , then the user will post a comment; if the user is disappointed with the product under the context  $x_{u,v,k} = 0$ , and the anger is stronger than the non contextual counterpart  $y_{u,v,k} = 0$ , then a comment is expected; otherwise, the comments will be missing.

As shown in Fig. ??, we present the following generation process.

- Generate user preference from a multivariate Gaussian distribution  $u \sim \mathcal{N}(u; 0, \sigma_u^2)$ , contextual preference  $a_k \sim \mathcal{N}(a_k; 0, \sigma_a^2)$ , item specific feature strength  $v_c \sim Beta(v_c; \zeta_a, \zeta_b)$  for each user, item-feature, and context respectfully. Generate global vocabulary distribution over the feature phrases  $\theta \sim Dirichlet(\theta; \xi)$ .
- For each review written by u on v under context k
  - Generate contextual polarity  $x \sim Bern(x; g(UC_k(a, u, v)))$
  - Generate conventional polarity  $y \sim Bern(y; g(UC_k(a, u, v) UC(u, v)))$
  - Generate response  $r \sim Discrete \pi$
  - For each product feature
    - \* Choose feature phrases  $c \sim Discrete(c; \theta)$
    - \* Select an opinion polarity to describe the feature  $o \sim Bern(o; v_c)$

To maximize the likelihood in Equ. 8, we present the EM algorithm in Alg. 3. Similar to Alg. 2, we increase the objective by line search update in the M-step.

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Algorithm 3: Learning Process for model CPP
Algorithm 2: Learning Process for model CPV
            Input: A set of positive and negative feedback x, a set of
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    Input: A set of positive and negative feedback x, a set of
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 implicit feedback x^{mis}, a set of feature opinion pairs
                                                                           feature opinion pairs \{\langle c, o \rangle\}
          Output: a, V, U, \Pi
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 \{< c, o > \}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    Output: a, V, U
            Initialize a, V, U, \Pi;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    Initialize a, V, U;
            while not convergent do
                                          E-Step;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    while not convergent do
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    E-step: for r_{u,v,k} = 0 do
                                          for x_{u,v,k} \in \mathbf{x} do
                                                                         q(x, u, v, k) =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   for x, y \in \{0, 1\} do
                                                                                  \Pi_{x,1}^{r_{u,v,k}} (1-\Pi_{x,1})^{(1-r_{u,v,k})} \frac{1}{1+\exp[(-\alpha \mathbf{a_k} - (1-\alpha)\mathbf{u})\mathbf{v}]}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          x_{u,v,k} = \exp[(-\alpha \mathbf{a_k} - (1-\alpha)\mathbf{u})\mathbf{v}] q^{(\bar{x}_u^x, v, k}, y_{u,v,k}) =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        \frac{1+\exp[(-\alpha \mathbf{a_k}-(1-\alpha)\mathbf{u})\mathbf{v}]}{1+\exp[(-\alpha \mathbf{u}-(1-\alpha)\mathbf{a_k})\mathbf{v}]} \frac{1}{1+\exp[(-\alpha \mathbf{u}-(1-\alpha)\mathbf{a_k})\mathbf{v}]} \frac{1}{1+\exp[(-\alpha \mathbf{u}-(1-\alpha)\mathbf{u})\mathbf{v}]} \frac{1}{1+\exp[(-\alpha \mathbf{u
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     1+exp[(-\alpha \mathbf{u}-(1-\alpha)\mathbf{a_k})\mathbf{v}]
                                                                         Normalize q(x, u, v, k) over x \in \{0, 1\};
                                          end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   end
                                          M-step;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   Normalize q(x_{u,v,k}, y_{u,v,k}|r_{u,v,k}, \mathbf{v}, \mathbf{u}, \mathbf{a_k});
                                          for x_{u,v,k} \in \mathbf{x} do
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    end
                                                                         t_{x_{u,v,k},a_{\mathbf{k}},\mathbf{v},\mathbf{u}} = \frac{\{-\exp\left[(-\alpha \mathbf{a_{\mathbf{k}}} - (1-\alpha)\mathbf{u})\mathbf{v}\right]\}^{x_{u,v,k}} \mathbf{1}^{1-x_{u,v,k}}}{1+\exp\left[(-\alpha \mathbf{a_{\mathbf{k}}} - (1-\alpha)\mathbf{u})\mathbf{v}\right]}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    M-step: for x_{u,v,k} \in \mathbf{x} do
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   t_{X_{\mathbf{u},\,\upsilon,\,k},\,\mathbf{a_k},\,\mathbf{v},\,\mathbf{u}} = \frac{\{-\exp\left[(-\alpha\mathbf{a_k} - (1-\alpha)\mathbf{u})\mathbf{v}\right]\}^{x_{u},\,\upsilon,\,k}\,\mathbf{1}^{1-x_{u},\,\upsilon,\,k}}{1+\exp\left[(-\alpha\mathbf{a_k} - (1-\alpha)\mathbf{u})\mathbf{v}\right]}
                                          end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 s_{X_{u,v,k},\mathbf{a_k,v,u}} = \frac{\left\{-\exp\left[(-\alpha \mathbf{a_k} + \alpha \mathbf{u})\mathbf{v}\right]\right\}^{y_{u,v,k}} \mathbf{1}^{1-y_{u,v,k}}}{1+\exp\left[(-\alpha \mathbf{a_k} + \alpha \mathbf{u})\mathbf{v}\right]}
                                          for u \in U do
                                                                           \mathbf{u} = \mathbf{u} - \lambda_t [-(1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_k, v, u} \mathbf{v} - (1 - \alpha) \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} t_{x_{u,v,k}}, \mathbf{a_
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    end
                                                                                    \alpha \sum_{k} \sum_{x_{u,v,k} \in \mathbf{X}^{mis}} \sum_{x} q(x,u,v,k) t_{x_{u,v,k},\mathbf{a_k},\mathbf{v},\mathbf{u}} \mathbf{v} - \mathbf{v}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    for u \in U do
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     \mathbf{u} = \mathbf{u} - \lambda_t \left[ \sum_k \sum_{x_{u,v,k} \in \mathbf{x}} (-(1-\alpha)t_{x_{u,v,k}, \mathbf{a_k}, \mathbf{v}, \mathbf{u}} + \right]
                                          end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            \alpha s_{x_{u,v,k},\mathbf{a_k},\mathbf{v},\mathbf{u}})\mathbf{v} + \Sigma_k \Sigma_{x_{u,v,k} \in \mathbf{x}^{mis}} \Sigma_{x,y \in \{0,1\}} (-(1 - \mathbf{x}^{mis})\mathbf{x}^{mis})\mathbf{x}^{mis}
                                          \quad \text{for } v \in V \text{ do}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             (\alpha)q(x,y)q(x_{u,v,k},y_{u,v,k})t_{x_{u,v,k}=x,a_k,v,u} +
                                                                         \mathbf{v} = \mathbf{v} - \lambda_t \{ \sum_{k \geq x_{u,v,k} \in \mathbf{x}} [-\alpha \mathbf{a_k} - (1 - \alpha \mathbf{a_k})] \}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            \alpha s_{x_{u,v,k}=1-x,\mathbf{a_k},\mathbf{v},\mathbf{u}})\mathbf{v} - \frac{\mathbf{u}}{\pi \sigma_v^2}];
                                                                                    (\alpha)\mathbf{u}]t_{x_{u,v,k},\mathbf{a_k},\mathbf{v},\mathbf{u}} + \sum_k \sum_{x_{u,v,k} \in \mathbf{x}^{mis}} [-\alpha \mathbf{a_k} - (1 - \alpha \mathbf{a_k})]t_{x_{u,v,k},\mathbf{a_k},\mathbf{v},\mathbf{u}} + \sum_k \sum_{x_{u,v,k} \in \mathbf{x}^{mis}} [-\alpha \mathbf{a_k}]t_{x_{u,v,k},\mathbf{u}} + \sum_k \sum_{x_{u,v,k} \in \mathbf{
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    end
                                                                                    \alpha)u]\Sigma_x q(x, u, v, k) t_{x_{u,v,k}, \mathbf{a_k}, \mathbf{v}, \mathbf{u}} + (\zeta_a - 1) \mathbf{v}.^{-1} +
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    for v \in V do
                                                                                    (\zeta_b - 1)(1 - \mathbf{v}).^{-1};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   \mathbf{v} = \mathbf{v} - \lambda_t \{ \sum_{k \geq x_{u,v,k} \in \mathbf{x}} [(-\alpha \mathbf{a_k} - (1 - \alpha \mathbf{a_k})) - (1 - \alpha \mathbf{a_k}) \} 
                                          end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            (\alpha)\mathbf{u})t_{x_{u,v,k},\mathbf{a_k},\mathbf{v},\mathbf{u}} + (-\alpha\mathbf{a_k} + \alpha\mathbf{u})s_{x_{u,v,k},\mathbf{a_k},\mathbf{v},\mathbf{u}}] +
                                          \text{ for } a_k \in a \text{ do }
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             \sum_{k}\sum_{x_{u,v,k}\in\mathbf{X}^{mis}}\sum_{x,y\in\{0,1\}}q(x_{u,v,k},y_{u,v,k})[(-\alpha\mathbf{a_k}-
                                                                         \mathbf{a}_{\mathbf{k}} = \mathbf{a}_{\mathbf{k}} - \lambda_t \left[ -\alpha \sum_{x_{u,v,k} \in \mathbf{x}} \mathbf{v} t_{x_{u,v,k},\mathbf{a}_{\mathbf{k}},\mathbf{v},\mathbf{u}} - \right]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             (1-\alpha)\mathbf{u})t_{x_{u,\tau}, k}=x, \mathbf{a_k}, \mathbf{v}, \mathbf{u} + (-\alpha \mathbf{a_k} +
                                                                                  \alpha \Sigma_{x_{u,v,k} \in \mathbf{x}^{mis}} \mathbf{v} \Sigma_{x} q(x,u,v,k) t_{x_{u,v,k},\mathbf{a_k},\mathbf{v},\mathbf{u}} - \frac{\mathbf{a_k}}{\pi \sigma^2}];
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             (\alpha \mathbf{u}) s_{x_{u,v,k}=1-x,\mathbf{a_k},\mathbf{v},\mathbf{u}} + (\zeta_a - 1) \mathbf{v}^{-1} + (\zeta_b - 1) (1 - 1) \mathbf{v}^{-1
                                          end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             v).^{-1};
                                          for x \in \{0, 1\} do
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   end
                                                                         \Pi_{x,1} =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   for a_k \in a do
                                                                                       \frac{\sum_{x_{u,v,k}\in\mathbf{x}}r_{u,v,k}+\sum_{x_{u,v,k}\in\mathbf{x}mis}q(x,u,v,k)r_{u,v,k}+\zeta_{a}-1}{|\mathbf{x}|+Sigma_{x_{u,v,k}\in\mathbf{x}mis}q(x,u,v,k)+\Sigma j\in a,b(\zeta_{j}-1)};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             \mathbf{a_k} - \lambda_t \left[ -\alpha \sum_{x_{u,v,k} \in \mathbf{x}} \left[ \mathbf{v} t_{x_{u,v,k}, \mathbf{a_k}, \mathbf{v}, \mathbf{u}} - \alpha s_{x_{u,v,k}, \mathbf{a_k}, \mathbf{v}, \mathbf{u}} \right] + \right.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             -\alpha \Sigma_{x_{u,\upsilon,k} \in \mathbf{x}^{mis}} [\Sigma_{x,y \in \{0,1\}} \mathbf{v} t_{x_{u,\upsilon,k},\mathbf{a_k},\mathbf{v},\mathbf{u}}]
                                          end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            \alpha s_{x_{u,v,k},\mathbf{a_k},\mathbf{v},\mathbf{u}}]q(x_{u,v,k},y_{u,v,k})-\frac{\mathbf{a_k}}{\pi\sigma_n^2}];
            end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   end
```

**Table 1: The NOR distribution of** p(r|x, y)

p(r x,y)	Х	у
1	1	1
1	0	0
0	1	0
0	0	1

## 7 EXPERIMENT

In this section, we want to study the following questions. (1) How do we evaluate review guided context aware recommender systems? (2) How does each component of our framework perform, compared

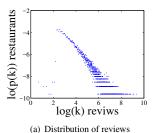
with state-of-the-art methods? Towards this end, we design a set of experimental protocals.

#### 7.1 Experimental Setup

We use a real data set, which is crawled from the largest Chinese review sites<sup>1</sup>. We will refer this data set as the dianping data set. We crawl a total number of 2593268 reviews on 15292 restaurants located in Beijing. As shown in figure 3(a), the review distribution

end

<sup>&</sup>lt;sup>1</sup>dianping.com



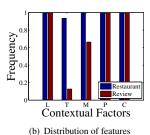


Figure 3: Statistics of data sets

is a truncated power-law distribution. The log probability logp(k) of restaurants with k reviews is linear with log(k).

The commodity features are extracted as follows. We first manually build a dictionary containing all the possible aspects of a restaurant, example aspects include "food", "parking", "service" and so on. Then we run a sentiment classifier [18] to extract the opinion (positive or negative) of the review on each aspect. Thus the commodity features are pairs consisting of an aspect and an opinion polarity, e.g. "food+" is an extracted feature for the following review phrase "very good food". In the dianping data set, the price is sometimes demonstrated with the review. In case the price is missing in the review, we use the average price of the restaurant.

The predefined categories for contextual factors used in our experiments include time, location, companion, price and cuisine. We define 5 time factors, including morning, noon, afternoon, night and weekend. Time phrases in a review are matched to one of the 5 time factors. The location factors are collected from dianping, including 43 commercial districts in Beijing. The location factors are identical to all reviews corresponding to the same restaurant. There are 4 types of companion factors(boss, friend, family, couple) and 5 different ranges of number of companions(1, 2, 3 – 4, 5 – 10,  $\geq$  10). The price factors are preprocessed to be 7 categories( 20, 20 – 50, 50 – 80, 80 – 120, 120 – 200, 200 – 500, 500 – 800,  $\geq$  800). The cuisine factors contain 95 types of cuisines.

All commodity features and contextual factors are binary valued. We count the probability of restaurants and reviews that the contextual factors appear for more than once. As shown in figure 3(b), cuisine, location and price factors (denoted as "C", "L", and "P" in the axis) appear in all restaurants and reviews. A fairy number of people take notes on who they eat with(companion factors denoted as "M" in the axis), almost all restaurants have at least one record with companion information. Fewer reviews mention when (time factors denoted as "T" in the axis) the experience happens, but the percentage of restaurants with at least one review containing time phrases is much larger.

We define 5 contexts, namely "Business Banquet", "Party", "Family Get-together", "Dating" and "Eat for Leisure". We pick 27 most popular restaurants and annotate randomly 15% of the reviews (17662 reviews). We observe that the context distribution is unbalanced. Most reviews (61%) are labeled as irrelevant to any context, which suggests the predominance of implicit feedback. 19% reviews are labeled to be positive about "Party". We sample 25% of the size of positive instances from the collection of reviews related to each

Table 2: The top contextual factors in each group with the largest  $b_L^{\chi}$ 

Context	Business	Party	Family	Dating	Leisure
Time	noon	afternoon	noon	weekend	weekend
Loc.	E.40th St.	Houhai	Zoo	Sanlitun	Houhai
Comp.	boss	friend	family	family	family
No. Comp.	5-10	3-4	3-4	2	3-4
Price	200-500	50-80	200-500	80-120	120-200
Cuisine	roast duck	hotpot	Russian	ryori	fastfood

contexts  $\bar{x}$ , and construct a relatively balanced negative training set  $E^-x$ , with approximately 125% of the size of  $E^+x$ . In annotation and opinion categorization, we only deal with reviews with positive opinions. That is, we first filter out reviews with negative ratings, for a "cleaner" training set.

The step size is set to be  $\alpha=1$ . The coefficient related to variable std, denoted by  $\lambda_p, \lambda_u, \lambda_c$  are decided by cross-validation. For the results below, the values are set to be  $\lambda_p=\frac{1}{|E|}, \lambda_u=1, \lambda_c=0.01$ . The combination weight for contextual and user preference is set to be  $\alpha=0.5$ .

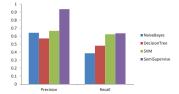
## **7.2** Context Categorization Performance

We next analyze how the semi-supervised mechanism improves the categorization. The comparative methods are Naive Bayes, SVM, and Decision Tree. The evaluation metrics are precision and recall rates averaged across all contexts. As shown in Fig. 4(a), traditional classifiers suffer from the insufficiency of training instances. The semi-supervision obtains best performance in both metrics. The improvement of precision is in particular significant. Due to the fact of "silent majority", a constraint in prior distribution leads to more accurate classification hyperplane. Figure 4(b) shows the KL-divergence of the predicted context distribution and the prior distribution from the annotated reviews of sample size 5%, 10%, 15% respectfully. We can see that the KL-divergence is quite small, and is decreasing as the sample size increases.

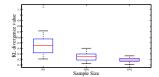
### 7.3 Cold-start Recommendation

We next study cold-start recommendation on which most RGCARS focus. We use the intelligent ranking provided by dianping as the gold standard. Precision At Top Ten (P@10) is the evaluation metric. The comparative methods include (1) MostPop, a naive baseline where restaurants are ordered by the number of reviews; (2)TextRating [15], a scoring system based on online review mining; (3)CLDA [11], a LDA alike model for query driven context aware recommendation. We set the query keywords to be the context; (4) our basic model with the "absolute" strategy, where  $\alpha = 1$ .

As shown in Tab. ??, our model achieves best results in all contexts, with all pre-procession of textual contents being identical. It shows that the utility surplus model can capture the underlying



(a) Comparative categorization performance



(b)  $D_{KL}$  with different sample sizes

Figure 4: Performance of contextual categorization

Table 3: Comparative performance of cold-start recommendation

Context	dating	business	family	party	leisure
MostPop	0.7	0.2	0.1	0.8	0.1
TextRating	0.6	0.1	0.2	0.4	0.4
CLDA	0.8	0.4	0.1	0.8	0.1
Basic-absolute	0.8	0.7	0.2	1.0	1.0

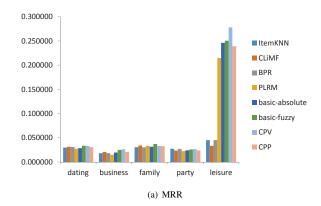
relationships among user preferences, product features, purchases and reviews. We also notice that utilizing the information in online reviews does not gurantee improvement of the cold-start recommender, especially for context "business banquet", "dating" and "party". This may be caused by the ambiguity of natural language. Erros in extracting the opinions and features from online reviews may cause damage to the recommender. In our model, ratings are important factors for judging the polarity of feedback. Thus our model is more false tolerant to a noisy NLP miner.

## 7.4 Context aware recommendation

The final task to be evaluated is context aware recommendation. We filter our users with at least 5 reviews for training, and select 10% of the reviews by users with at least 20 reviews for testing. An ideal masurement, for recommendation systems with implicit feedback, is based on predictions of all items for an user, whether they are observed or missing. When such test data is not available, rating based measurements will be imprecise. We use MRR and NDCG as the approximate evaluation metrics. MRR is the mean reciprocal rank of the highest rated restarant of the ground truth in the test set. It is targeted to acquire the best option. NDCG measures quality of the predicted rankings of all ground truth items. We compare our basic models with two strategies (basic-absolute, basic-fuzzy), two variant models (CPV and CPP) with a wide range of state-of-the-art methods, including traditional recommendation models (ItemKNN), models with implicit feedback (CLiMF [28], BPR [26]) and models

based on online review mining(PLRM [17]). The results are plot in Fig. 5(a) and Fig. 5(b).

We have the following observations. (1) Our models generally outperform other state-of-the-art methods in terms of MRR and NDCG, for most contexts. Similar to the cold-start recommendation in Tab. ??, our models are significantly better for context "leisure". (2) A universal trend exists that models utilizing implicit feedback yield higher results than models which don't, i.e. CliMF and BPR are better than ItemKNN, basic-fuzzy and CPV are better than basic-absolute. This phenomenan highlights the importance of implicit feedback. (3) Compared with CPV, CPP is more sensetive to contexts. As CPP place strict constraints on extreme reviews, it might be more appropriate for less common contexts.



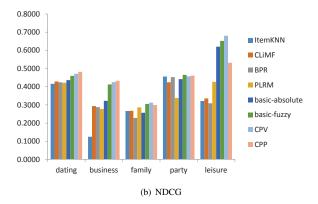


Figure 5: Comparative performance of context aware recommender system

## 8 CONCLUSION

In this paper, we mainly focus on exploring the potencial of implicit feedback in a review guided context aware recommender system. We present new models, based on the utility surplus theory, to tackle the implicit feedback problem by treating them as complete observations or missing not at random observations. We systematically compare the assumptions and performances of thes models. The most important academic contribution of this paper is that, to the best of our knowledge, the unique types of implicit feedback (both

context free and context aware) have not yet been studied by the community. Therefore our research might shed some insight into mining online reviews for recommender system, and other applications. Further research issues include adapting and testfying more assumption in the missing not at random model. For example, the inter homogenity of online communities, and applying the CPP model to appropriate contexts.

#### 9 ACKNOWLEDGEMENT

Chen Lin is partially supported by China Natural Science Foundation under Grant Nos. NSFC61102136, NSFC61472335, CCF-Tencent Open Research Fund under Grant No. CCF-Tencent20130101, Base Research Project of Shenzhen Bureau of Science, Technology, and Information under Grand No. JCYJ20120618155655087, Baidu Open Research under Grant No.Z153283.

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