X-Armed Bandits

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X-Armed Bandits

- **□** Introduction
- □ Problem Setup
- ☐ The HOO Strategy

•What's bandit problem?

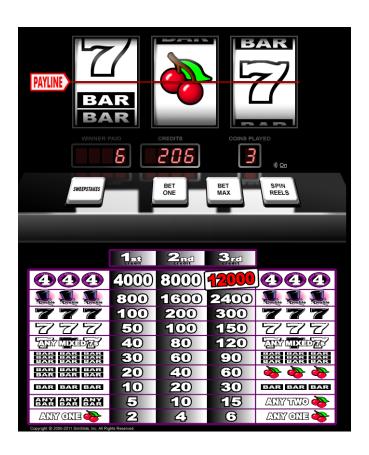
- The multi-armed bandit problem is the problem a gambler faces at a row of slot machines when deciding which machines to play, how many times to play each machine and in which order to play them.
- When played, each machine provides a random reward from a distribution specific to that machine.

•What's bandit problem?

- Free Online Slot Machineshttps://www.freeslots.com/Slot7.htm
- Old fashion Slot Machine







•What's bandit problem?

- The **gambler** pulls the arms of the machines one by one in a sequential manner, simultaneously learning about the machines' **payoff-distributions** and gaining actual monetary reward.
- Thus, in order to maximize his gain, the gambler must choose the next arm by taking into consideration both the urgency of gaining reward ("exploitation") and acquiring new information ("exploration").
- Maximizing the total cumulative payoff is equivalent to minimizing the (total) regret, that is, minimizing the difference between the total cumulative payoff of the gambler and the one of another gambler who chooses the arm with the best meanpayoff in every round.

The Motivation

- Handle the X-armed bandits problems in a unified framework.
- More precisely, we consider a general setting that allows us to study bandits with almost no restriction on the set of arms.
- In particular, we allow the set of arms to be an arbitrary measurable space.

Assumptions

- The **gambler** has some **knowledge** about the behavior of the mean-payoff function
 - in terms of its local regularity around its maxima, roughly speaking
 - since we allow non-denumerable sets,
- There exists a dissimilarity function that constrains the behavior of the mean-payoff function
 - where <u>a dissimilarity function is a measure of the discrepancy between two arms</u> that is neither symmetric, nor reflexive, nor satisfies the triangle inequality.
 - In particular, the dissimilarity function is assumed to locally set a bound on the decrease of the mean-payoff function at each of its global maxima.[?]
- The decision maker can construct a **recursive covering** of the space of arms **in such a way** that the diameters of the sets in the covering **shrink** at a known geometric rate *when measured with this dissimilarity*. [?]

Stochastic bandit problem

- **B** is a pair B = (X,M)
 - $\blacksquare X$ is a measurable space of arms
 - M determines the distribution of rewards associated with each arm
 - We say that M is a **bandit environment** on X.
- Formally, M is an mapping $X \rightarrow M_1(R)$,
 - $\blacksquare M_1(R)$ is the space of probability distributions over the reals.
 - The distribution assigned to $\operatorname{arm} x \in X$ is denoted by M_x
- We require that for each $arm x \in X$, the distribution M_x admits a first-order moment;

Stochastic bandit problem

• We then denote by f(x) its expectation ("mean payoff"),

$$f(x) = \int y \, dM_x(y)$$

- The **mean-payoff function** *f* thus defined is assumed to be measurable.
- For simplicity, we shall also assume that all M_x have bounded supports, included in some fixed bounded interval,³ say, the unit interval [0, 1].
- Then, f also takes bounded values, in [0, 1].

Decision Maker

- A decision maker (the gambler of the introduction) that interacts with a *stochastic bandit problem B* plays a game at discrete time steps according to the following rules.
- In the first round the decision maker can select an arm $X_1 \in X$ and receives a reward Y_1 drawn at random from M_{X_1} .
- In round n > 1 the decision maker can select an arm $X_n \in X$ based on the information available up to time n, that is, $(X_1, Y_1, \ldots, X_{n-1}, Y_{n-1})$, and receives a reward Y_n drawn from M_{X_n} , independently of $(X_1, Y_1, \ldots, X_{n-1}, Y_{n-1})$ given X_n .
- Note that a decision maker may randomize his choice, but can only use information available up to the point in time when the choice is made.

Decision Maker

- The goal of the decision maker is to **maximize** his expected cumulative reward.
- **Equivalently**, the goal can be expressed as **minimizing** the expected cumulative **regret**, which is defined as follows.

$$f^* = \sup_{x \in \mathcal{X}} f(x)$$

be the best expected payoff in a single round.

At round n, the cumulative regret of a decision maker playing B is $\widehat{\nabla} = n \cdot f^* \cdot \nabla^n V$

 $\widehat{R}_n = n f^* - \sum_{t=1}^n Y_t,$

that is, the difference between the maximum expected payoff in n rounds and the actual total payoff.

Pseudo-regret

- In the sequel, we shall restrict our attention to the **expected cumulative regret**, which is defined as the expectation $E[R_n]$ of the cumulative regret R_n .
- Finally, we define the cumulative pseudo-regret as

$$R_n = n f^* - \sum_{t=1}^n f(X_t),$$

- that is, the **actual rewards** used in the definition of the regret are replaced by the **mean-payoffs** of the arms pulled.
- Since (by the tower rule) $\mathbb{E}[Y_t] = \mathbb{E}[\mathbb{E}[Y_t|X_t]] = \mathbb{E}[f(X_t)],$
- the expected values $E[R_n]$ of the cumulative regret and $E[R_n]$ of the cumulative pseudo-regret are the same.
- Thus, we focus below on the study of the behavior of $E[R_n]$

- The HOO strategy (cf., *Algorithm 1*) incrementally builds an estimate of the *mean-payoff function f* over *X*.
- The **core** idea is to estimate f precisely around its maxima, while estimating it loosely in other parts of the space X.
- ■HOO maintains a **binary tree** whose nodes are associated with measurable regions of the arm-space *X* such that the *regions* associated with nodes **deeper** in the tree (further away from the root) represent increasingly *smaller subsets* of *X*.

Parameters: Two real numbers $v_1 > 0$ and $\rho \in (0,1)$, a sequence $(\mathcal{P}_{h,i})_{h \geqslant 0,1 \leqslant i \leqslant 2^h}$ of subsets of \mathcal{X} satisfying the conditions (1) and (2).

Auxiliary function Leaf(\mathcal{T}): outputs a leaf of \mathcal{T} .

Initialization: $\mathcal{T} = \{(0,1)\}\$ and $B_{1,2} = B_{2,2} = +\infty$.

```
1: for n = 1, 2, \dots do
                                                                                    \triangleright Strategy HOO in round n \ge 1
 2: (h,i) \leftarrow (0,1)

    Start at the root

     P \leftarrow \{(h,i)\}
                                                                           \triangleright P stores the path traversed in the tree
                                                                                                  \triangleright Search the tree \mathcal{T}
       while (h,i) \in \mathcal{T} do
 4:
                                                                              ▶ Select the "more promising" child
 5:
             if B_{h+1,2i-1} > B_{h+1,2i} then
                  (h,i) \leftarrow (h+1,2i-1)
 6:
              else if B_{h+1,2i-1} < B_{h+1,2i} then
                  (h,i) \leftarrow (h+1,2i)
 8:
              else

    □ Tie-breaking rule

 9:
                  Z \sim \text{Ber}(0.5)
                                                                                   ⊳ e.g., choose a child at random
10:
                  (h,i) \leftarrow (h+1,2i-Z)
11:
              end if
12:
             P \leftarrow P \cup \{(h,i)\}
13:
         end while
14:
         (H,I) \leftarrow (h,i)
                                                                                                 15:
         Choose arm X in \mathcal{P}_{HJ} and play it

    Arbitrary selection of an arm

16:
```

```
Receive corresponding reward Y
17:
           \mathcal{T} \leftarrow \mathcal{T} \cup \{(H,I)\}
                                                                                                                       ⊳ Extend the tree
18:
           for all (h,i) \in P do
                                                                          \triangleright Update the statistics T and \widehat{\mu} stored in the path
19:
                                                                                          \triangleright Increment the counter of node (h,i)
                T_{h,i} \leftarrow T_{h,i} + 1
20:
                \widehat{\mu}_{h,i} \leftarrow (1 - 1/T_{h,i})\widehat{\mu}_{h,i} + Y/T_{h,i}
                                                                                            \triangleright Update the mean \widehat{\mu}_{h,i} of node (h,i)
21:
           end for
22:
           for all (h,i) \in \mathcal{T} do
                                                                                   \triangleright Update the statistics U stored in the tree
23:
                U_{h,i} \leftarrow \widehat{\mu}_{h,i} + \sqrt{(2\ln n)/T_{h,i}} + \nu_1 \rho^h
                                                                                             \triangleright Update the U-value of node (h,i)
24:
           end for
25:
                                                                                    ▷ B-values of the children of the new leaf
26:
          B_{H+1,2I-1} \leftarrow +\infty
27:
          B_{H+1,2I} \leftarrow +\infty
           T' \leftarrow T
                                                                                              \triangleright Local copy of the current tree T
28:
          while \mathcal{T}' \neq \{(0,1)\} do
                                                                                     29:
                (h,i) \leftarrow \text{LEAF}(\mathcal{T}')

    ▶ Take any remaining leaf

30:
                B_{h,i} \leftarrow \min \Big\{ U_{h,i}, \max \Big\{ B_{h+1,2i-1}, B_{h+1,2i} \Big\} \Big\}
31:
                                                                                                            ▶ Backward computation
                \mathcal{T}' \leftarrow \mathcal{T}' \setminus \{(h,i)\}
                                                                                                            \triangleright Drop updated leaf (h,i)
32:
           end while
33.
34: end for
```

- At each node of the tree, HOO stores some statistics based on the information received in previous rounds.
- In particular, HOO keeps track of the number of times a node was traversed up to round *n* and the corresponding empirical average of the rewards received so far.

```
while (h,i) \in \mathcal{T} do
 4:
              if B_{h+1,2i-1} > B_{h+1,2i} then
                   (h,i) \leftarrow (h+1,2i-1)
 6:
              else if B_{h+1,2i-1} < B_{h+1,2i} then
                   (h,i) \leftarrow (h+1,2i)
              else
 9:
                   Z \sim \text{Ber}(0.5)
10:
                   (h,i) \leftarrow (h+1,2i-Z)
11:
12:
              end if
              P \leftarrow P \cup \{(h,i)\}
13:
         end while
14:
```

- HOO assigns an optimistic estimate (denoted by B) to the maximum mean-payoff associated with each node.
- These estimates are then used to select the next node to "play".
- This is done by traversing the tree, beginning from the root, and always following the node with the highest B-value (cf., lines 4-14 of Algorithm 1).

Algorithm 1

- Once a node is selected, a point in the region associated with it is chosen (*line 16*) and is sent to the environment.
- Based on the point selected and the received reward, the tree is updated (*lines 18–33*).

```
\mathcal{T} \leftarrow \mathcal{T} \cup \{(H,I)\}
18:
              for all (h,i) \in P do
19:
                     T_{h,i} \leftarrow T_{h,i} + 1
20:
                    \widehat{\mu}_{h,i} \leftarrow (1 - 1/T_{h,i})\widehat{\mu}_{h,i} + Y/T_{h,i}
21:
              end for
22:
23:
              for all (h,i) \in \mathcal{T} do
                    U_{h,i} \leftarrow \widehat{\mu}_{h,i} + \sqrt{(2\ln n)/T_{h,i}} + v_1 \rho^h
24:
              end for
25:
              B_{H+1,2I-1} \leftarrow +\infty
26:
             B_{H+1.2I} \leftarrow +\infty
27:
             \mathcal{T}' \leftarrow \mathcal{T}
28:
              while T' \neq \{(0,1)\} do
29:
                     (h,i) \leftarrow \text{LEAF}(\mathcal{T}')
30:
                    B_{h,i} \leftarrow \min \Big\{ U_{h,i}, \max \Big\{ B_{h+1,2i-1}, B_{h+1,2i} \Big\} \Big\}
31:
                     \mathcal{T}' \leftarrow \mathcal{T}' \setminus \{(h,i)\}
32:
              end while
33:
```

Algorithm 1

- In the algorithm listing the **recursive** computation of the **B**-values (*lines 28–33*) makes a local copy of the tree.
- Other **arbitrary** choices in the algorithm as shown here are how tie breaking in the node selection part is done(*lines 9 –12*)
- **or** how a point in the region associated with the selected ¹⁶: node is chosen (*line 16*).

```
28: \mathcal{T}' \leftarrow \mathcal{T}

29: while \mathcal{T}' \neq \{(0,1)\} do

30: (h,i) \leftarrow \text{LEAF}(\mathcal{T}')

31: B_{h,i} \leftarrow \min \{U_{h,i}, \max\{B_{h+1,2i-1}, B_{h+1,2i}\}\}

32: \mathcal{T}' \leftarrow \mathcal{T}' \setminus \{(h,i)\}

33: end while
```

```
else Z \sim \mathrm{Ber}(0.5) (h,i) \leftarrow (h+1,2i-Z) end if
```

Choose arm X in $\mathcal{P}_{H,I}$ and play it

9.

10:

11:

12:

Cover tree

- The tree of coverings which HOO needs to receive as an input is an infinite binary tree whose nodes are associated with subsets of X.
- The nodes in this tree are indexed by **pairs** of integers (h, i); node (h, i) is located at depth h > 0 from the root.
- The range of the second index i associated with nodes at depth h is restricted by $1 \le i \le 2^h$.
- Thus, the root node is denoted by (0, 1).
- By convention, (h+1, 2i-1) and (h+1, 2i) are used to refer to the two children of the node (h, i).
- Let $\mathcal{P}_{h,i} \subset \mathcal{X}$ be the region associated with node (h, i).

Cover tree

By assumption, these regions are measurable and must satisfy the constraints

$$\mathcal{P}_{0,1} = \mathcal{X} \,, \tag{1}$$

$$\mathcal{P}_{h,i} = \mathcal{P}_{h+1,2i-1} \cup \mathcal{P}_{h,2i}$$
, for all $h \geqslant 0$ and $1 \leqslant i \leqslant 2^h$. (2)

■ As a corollary, the regions $\mathcal{P}_{h,i}$ at any level h > 0 cover the space X,

$$\mathcal{X} = \bigcup_{i=1}^{2^h} \mathcal{P}_{h,i},$$

explaining the term "tree of coverings"

3.1 Illustrations

- Figure 1 illustrates correspondence between the nodes of the tree constructed by the algorithm and their associated regions.
- Figure 2 shows trees built by running HOO for a specific environment.

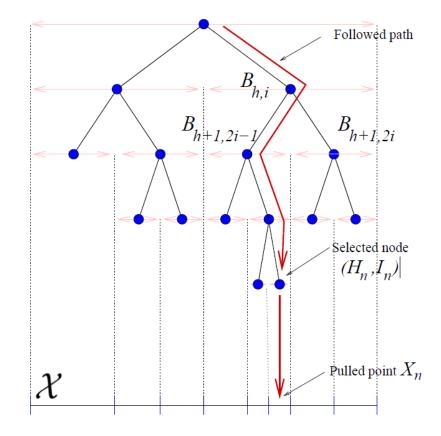


Figure 1: Illustration of the node selection procedure in round n. The tree represents \mathcal{T}_n . In the illustration, $B_{h+1,2i-1}(n-1) > B_{h+1,2i}(n-1)$, therefore, the selected path included the node (h+1,2i-1) rather than the node (h+1,2i).

The HOO Strategy- Illustrations

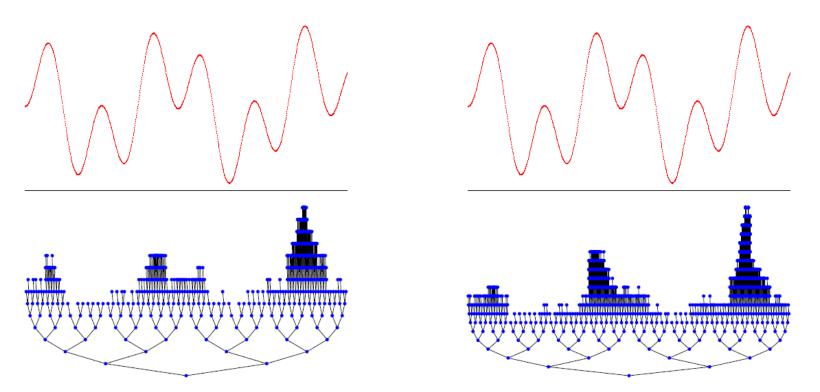


Figure 2: The trees (bottom figures) built by HOO after 1,000 (left) and 10,000 (right) rounds. The mean-payoff function (shown in the top part of the figure) is $x \in [0,1] \mapsto 1/2(\sin(13x)\sin(27x)+1)$; the corresponding payoffs are Bernoulli-distributed. The inputs of HOO are as follows: the tree of coverings is formed by all dyadic intervals, $v_1 = 1$ and $\rho = 1/2$. The tie-breaking rule is to choose a child at random (as shown in the Algorithm 1), while the points in X to be played are chosen as the centers of the dyadic intervals. Note that the tree is extensively refined where the mean-payoff function is near-optimal, while it is much less developed in other regions.