Wie werden Emotionen und Rapport in der Bachelorarbeit gemessen?

Eine tabellarische Aufstellung, welche Werte gemessen werden sollen. Geplant ist es, Aristidou 2015 zu folgen und für die in der 1. Tabelle beschriebenen Werte jeweils 1,5sektime frames zu nutzen???

1. Tabelle: Wie können Labanelemente laut Aristidou 2015¹ gemessen werden?

Labankomponente	Was wird gemessen	Nummer in Aristidou 2015	Was genau zu messen	Bemerkungen
Body	Displacement/Orientation	f1	Feet to hips	Average of both
			distance	sides
		f2	Hand to shoulders distance	Average of both sides
		f3	Right hand to left hand distance	Average of both sides
		f4	Hands to head distance	Average of both sides
	Pelvis height	f5	Distance of root joint from ground	For jumps or kneels or falling
		f6	Different displacements	For see if laying on the ground with legs, Average of both sides
	Centroid	f7	Distance of ground and centroid	
		f8	Distance centroid and pelvis	Style and balance of performance
	Gait size	f9	Distance right foot to left	Motion expression, style
Effort	Head orientation (Space)	f10	Angle between head orientation and body path (trajectory of root joint)	See orientation and direction of motion; moving in same direction as head orientation -> direct movement
	Deceleration of motion (Weight)	f11	Calculate deceleration of root joint	Peaks in deceleration means strong

				weight; no peaks -> light weight
	Movement velocity (Time)	f12	Distance of root joint over time period	_
		f13	Average velocity of hands	
		f14	Average velocity of feet	
	Movement acceleration (Time)	f15	Derivative of hands velocities with respect to time	
		f16	Derivative of feet velocities with respect to time	
		f17	Derivative of hips velocities with respect to time	
	Jerk (Flow)	f18	Derivative of f15 with respect to time	Rate of acceleration or force. Large discontinuities with high jerk -> Bound Few peaks -> Free
Shape	Volume	f19	Bounding volume of all joints	
		f20	Volume upper body	
		f21	Volume lower body	
		f22	Volume left side	
		f23	Volume right side	
	Torso height	f24	Distance head and root joint	See if crouching and torso bending
	Hands level	f25	Relation of hand's position to body	Over head -> upper level Between head and chest -> middle level Low level -> below chest
Space	Distance	f26	Length of projection of root joints	Distance coverage over time

		trajectory to ground	
Area	f27	Area of polygon formed by projection of root joint on ground	

2. Tabelle: Welche Werte werden für die Emotionserkennung gemessen?

Labanelemente (Laut Melzer 2019 ² und Gunes 2015 ³)	Emotion	Werte	Was genau	Woher	Number of features
Jump	Нарру	f5	Distance of root joint from ground	Melzer,	1
Rhythmicity	Нарру	f18?	Derivative of f15 with respect to time	Melzer,	1
Spread	Нарру	f3	Right hand to left hand distance	Melzer,	1
Free and Light	Нарру	f11, fF18	Calculate deceleration of root joint, Derivative of f15 with respect to time	Melzer,	2
Up and Rise	Нарру	f24	Hands to head distance	Melzer,	1
Rotation	Нарру	f10	Angle between head orientation and body path (trajectory of root joint)	Melzer,	1
Passive Weight	Sad	f13, f15	Average velocity of hands, Derivative of hands velocities with respect to time	Melzer,	2
Arms to upper body	Sad	f25	Relation of hand's position to body	Melzer,	1
Sink	Sad	f24	Hands to head distance	Melzer,	1
Head-drop	Sad	f1, f24	Feet to hips distance, Distance head and root joint,	Melzer,	2
Retreat	Fear	z-Axis	Measure changing in z- Position	Melzer,	1
Condense and enclose	Fear	f20	Volume upper body	Melzer,	1
Bind	Fear	f18	Derivative of f15 with respect to time	Melzer,	1
Twist and back	Fear	f10, z-Axis	Angle between head orientation and body path (trajectory of root joint), Measure changing in z- Position	Melzer,	2
Strong	Anger	f11	Calculate deceleration of root joint,	Melzer,	1
Sudden	Anger	f13	Average velocity of hands,	Melzer,	1
Advance	Anger	z-Axis	Measure changing in z- Position	Melzer,	1

Direct	Anger	f10	Angle between head orientation and body path (trajectory of root joint),	Melzer,	1
Hands to head	Surprise	f4,f25	Hands to head distance, Relation of hand's position to body	Gunes	2
Hands above head	Surprise	f4,f25	Hands to head distance, Relation of hand's position to body	Gunes	2
Body shift/backing	Surprise	f20, z-Axis	Volume upper body, Measure changing in z-Position	Gunes	2
Head shake	Surprise	f10	Angle between head orientation and body path (trajectory of root joint),	Gunes	1
Hands to body	Disgust	f25	Relation of hand's position to body	Gunes	1
Orientation changing to right/left	Disgust	f10,f22,f23	Angle between head orientation and body path (trajectory of root joint), Volume left side, Volume right side	Gunes	3
Hands to head + backing	Disgust	f4, z-axis	Hands to head distance, Measure changing in z- Position	Gunes	2
Hands up + backing	Disgust	f25, z-axis	Relation of hand's position to body	Gunes	2
Gesamtzahl an Featu	ires zu mes	sen:f1,3,4,5,1	0,11,12,13,15,18,20,22,23,24,25	,z-Axis: 1 0	6

[•] Die Labanelemente der Emotionen Happiness, Sadness, Fear, Anger sind in Melzer 2019 beschrieben, die Werte für Disgust und Surprise aus Gunes 2015.

3. Tabelle: Welche Werte werden für den Rapport gemessen?

Rapport feature	What to Measure	How to measure	Description	Number of
				Features
Synchrony	Head synchrony	f10, f20, f22, f23,f24 -> compare over time	Angle between head orientation and body path (trajectory of root joint), Volume upper body, Volume left side, Volume right side, Distance head and root joint	5
	Gesture synchrony	f3, f4, f13, f15, f18, f19, f20, f22, f23, f25 -> compare over time	Right hand to left hand distance, Hands to head distance, Average velocity of hands, Derivative of hands velocities with respect to time, Derivative of f15 with respect to time, Bounding volume of all joints, Volume upper body, Volume left side, Volume right side, Relation of hand's position to body	10
	Body synchrony	f10, f20, f22, f23, f24 ->	Angle between head orientation and body path (trajectory of root joint), Volume upper body, Volume left side,	5

		compare over	Volume right side, Distance head and	
		time	root joint	
Nodding	Head	f10	Angle between head orientation and	1
	orientation		body path (trajectory of root joint),	
Eye	Eye	??? ->	(hier gibt es sicher Bibliotheken in	1
contact	orientation of	compare over	Tensorflow?)	
	both	time		
	participiants			
Gesamtzahl an Features zu messen: f3,4,10,13,15,18,19,20,22,23,24,25,z-Axis, Augen: 14				

Referenzen:

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