# BOCHNER INTEGRATION AND AN APPLICATION IN STOCHASTIC PROCESSES

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## 1. Introduction

In this note, we discuss the Bochner integration and an application in showing the distributions of  $\int_0^T X_t dt$  and  $\int_0^T Y_t dt$  coincide, given two progressively measurable stochastic processes X, Y.

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#### 2. Bochner Integration

Given a measure space  $(X, \Sigma, \mu)$  and a real Banach Space  $(V, |\cdot|_V)$ , we say a  $(\Sigma, \mathcal{B}_V)$  measurable function  $s: X \to V$  is **simple** if

$$s(x) = \sum_{i=1}^{n} \mathbb{1}_{E_i}(x)v_i,$$

where  $\{E_i\}\subseteq\Sigma$  are disjoint, and  $v_i$  are distinct elements in V.

We say such s is *integrable*, and its integral is defined as

$$\int_X s d\mu := \sum_{i=1}^n \mu(E_i) v_i,$$

if  $\mu(E_i)$  is finite whenever  $v_i \neq 0$ .

A  $(\Sigma, \mathscr{B}_V)$  measurable function  $f: X \to V$  is said to be **Bochner integrable**, if there exists a sequence of integrable simple functions  $\{s_n\}_{n=1}^{\infty}$  s.t.

$$\lim_{n \to \infty} \int_X |f - s_n|_V d\mu = 0,$$

and its integral is defined as

$$\int_{Y} f d\mu := \lim_{n \to \infty} \int_{Y} s_n d\mu,$$

where the first integral is in the sense of Lebesgue integral and the second convergence is in the sense of  $|\cdot|_V$  norm topology.

#### **Remark 2.1.** we make several natural remarks here:

- (1) It's easy to show that  $\{\int_X s_n d\mu\}_{n=1}^{\infty}$  is a Cauchy sequence in the Banach space V, and hence by its completeness the limit exists. If f takes value in a general normed space, we may have trouble that this Cauchy sequence does not necessary to converge.
- (2) It's also easy to show that if there is another such sequence of simple functions, the integral of f does not change. That is, the Bochner integral is well-defined (independent of choices).
- (3) Moreover, f is Bochner integrable if and only if  $\int_X |f|_V d\mu < \infty$ , and we may denote  $\mathcal{L}^1(X;V)$  to be the set of all such functions. It is easy to see  $\mathcal{L}^1(X;V)$  is a vector space (linearity is here!) and  $\int_X |\cdot|_V d\mu$  is a semi-norm on it, and hence by using the standard trick: taking the quotient space w.r.t the equivalence relation  $f \sim g$  if  $f = g \ \mu$ -a.e.,

$$L^1(X;V) \coloneqq \mathcal{L}^1(X;V)/\!\!\sim$$

is a Banach space equiped with the norm  $|\cdot|_{L^1(X;V)} := \int_X |\cdot|_V d\mu$ .

(4) From our definition, simple functions are naturally dense in  $L^1(X; V)$ , of course w.r.t. the  $|\cdot|_{L^1(X;V)}$  norm topology.

(5) If f is Bochner integrable, then the following usual inequality holds:

$$|\int_{E} f d\mu|_{V} \le \int_{E} |f|_{V} d\mu,$$

- for all  $E \in \Sigma$ , where  $\int_E f d\mu := \int_X f \mathbb{1}_E d\mu$  as usual. (6) Typically, Suppose  $T: V \to V'$  is a continous linear operator between Banach space V and V', and f is Bochner integrable. Then,
  - $Tf: X \to V'$  is also Bochner integrable;
  - the Bochner integral commutes with T:

$$\int_X Tf d\mu = T \int_X f d\mu$$

(7) Lastly, given a Bochner integrable function f, for all  $E \in \Sigma$ ,  $\nu : E \mapsto \int_E f d\mu$  is a countably-additive V-valued measure on X, and  $\nu \ll \mu$ .

## 2.1. Dominated Convergence Theorem for Banach-valued functions.

More importantly, we still have our beloved *Dominated Convergence Theorem*, perhaps after a redefinition w.r.t to a completion of the measure  $\mu$ .

**Theorem 2.2** (Dominated Convergence Theorem for Banach-valued functions). Suppose  $\{f_n\}_{n=1}^{\infty}\subseteq L^1(X;V), f_n\to f \text{ $\mu$-a.e., and there } \exists g\in L^1(X,\Sigma,\mu) \text{ s.t. } |f_n(x)|_V\leq g(x) \text{ for } f(x)=0$  $\mu$ -a.e.  $x \in X$ . Then,  $f \in L^1(X; V)$ ,

$$f_n \to f$$
 in  $L^1(X; V)$ ,

and hence

$$\int_X f d\mu = \lim_{n \to \infty} \int_X f_n d\mu,$$

where the second convergence is in the sense of  $|\cdot|_V$  norm topology.

The proof is clear by applying the usual Dominated Convergence Theorem [Folland Theorem 2.24] to  $|f_n - f|_V \le 2g$  and observe

$$\left| \int_X f d\mu - \int_X f_n d\mu \right|_V \le \int_X |f_n - f|_V d\mu \to 0.$$

## 2.2. Luzin's Theorem for Banach-valued functions.

Now we have sufficient ingredients, it is time to present the main result: Luzin's Theorem for Banach-valued functions.

**Theorem 2.3** (Luzin's Theorem for Banach-valued functions). If  $f:[a,b]\to V$  is  $(\mathcal{L}_{[a,b]},\mathscr{B}_V)$ measurable ( $\mathcal{L}_{[a,b]}$  is the class of all Lebesgue measurable sets included in [a,b]) and  $\varepsilon > 0$ , then there is a compact set  $K_{\varepsilon} \subseteq [a,b]$  s.t. the Lebesgue measure  $m(K_{\varepsilon}^{c}) < \varepsilon$  and  $f|_{K}$  is continuous.

To prove this version of Luzin's, we give several natural lemmas<sup>1</sup>.

**Lemma 2.4.** If  $f_n \to f$  in  $L^1(X; V)$ , there is a subsequence  $\{f_{n_i}\}$  s.t.  $f_{n_i} \to f$  a.e.

**Lemma 2.5** (Egorov's for Banach-valued functions). Suppose  $\mu(X) < \infty$ , and  $\{f_n\}$ , f are  $(\Sigma, \mathcal{B}_V)$ -measurable functions on X s.t.  $f_n \to f$  a.e. Then,  $\forall \varepsilon > 0, \exists E_\varepsilon \subseteq X$  s.t.  $\mu(E) < \varepsilon$  and  $f_n \to f$  uniformly on  $E^c$ .

**Lemma 2.6.** If  $\mu$  is a Lebesgue-Stieltjes measure on  $\mathbb{R}$ , then compactly supported continuous functions  $f: \mathbb{R} \to V$  are dense in  $L^1(\mathbb{R}; V)$ , with respect to the  $|\cdot|_{L^1(\mathbb{R}; V)}$  norm topology.

Now we could prove the Luzin's in the usual way

Proof. We first assume f is bounded, i.e.  $\sup_{x\in[a,b]}|f(x)|_V<\infty$ , and then we combine lemma 2.4 and lemma 2.6 that there is a sequence of compactly supported continuous functions  $\{f_n\}$  s.t.  $f_n\to f$  a.e. Then, as  $m([a,b])=b-a<\infty$ , we could apply Egorov's (lemma 2.5), for a given  $\varepsilon>0$ ,  $\exists E_\varepsilon\subseteq[a,b]$  s.t.  $m(E_\varepsilon)<\varepsilon$  and  $f_n\to f$  uniformly on  $E_\varepsilon^c$ . That is, as the uniform limit of continuous functions on  $E_\varepsilon^c$ , f is continuous on  $E_\varepsilon^c$ . Finally, recall Lebesgue measurable sets could be approached from inside by compact sets. That is, as  $m(E_\varepsilon^c)>b-a-\varepsilon$ ,  $b-a-\varepsilon$  is not the sup and hence  $\exists$  compact  $K_\varepsilon\subseteq E_\varepsilon^c$  s.t.  $m(K_\varepsilon)>b-a-\varepsilon$ .  $K_\varepsilon$  is what we are looking for.

If f is unbounded, we can consider the sets  $E_n = [a, b] \cap \{x : |f(x)|_V \le n\}$  for  $n \in \mathbb{N}$ , which is measurable and have finite measure since [a, b] has finite measure. Then, we can apply the previous arguments to each  $f|_{E_n}$ , which is a bounded function, to obtain a sequence of compact  $K_n \subseteq E_n$  s.t.

$$m(K_n^c) < \frac{\varepsilon}{2^n},$$

and  $f|_{K_n}$  is continuous. Then, typically,  $f|_{\cap_{n\in\mathbb{N}}K_n}$  is continuous and  $\cap_{n\in\mathbb{N}}K_n$  is still compact, with

$$m(\bigcup_{n\in\mathbb{N}}K_n^c)\leq \sum_{n\in\mathbb{N}}m(K_n^c)<\varepsilon.$$

#### 3. An application

# 3.1. Stochastic Analysis Preliminaries.

Recall that, given a filtered probability space  $(\Omega, \mathscr{F}, \mathbb{F} := \{\mathscr{F}_t\}_{0 \le t \le T}, \mathbb{P})$ 

• A stochastic process is a real-valued<sup>2</sup> function  $X : [0,T] \times \Omega \to \mathbb{R}$  that is  $(\mathscr{B}_{[0,T]} \times \mathscr{F}, \mathscr{B}_{\mathbb{R}})$  measurable.

<sup>&</sup>lt;sup>1</sup>We attached the proofs in the appendix.

 $<sup>^2</sup>$ We use the real-valued functions for simplicity, but similar notion could be developed for complex-valued functions.

- For given fixed  $t \in [0,T]$ , we view  $X_t := X(t,\cdot) : \Omega \to \mathbb{R}$  as a random variable (simply a  $(\mathcal{F}, \mathcal{B}_{\mathbb{R}})$ -measurable function). Equivalently, we could view X as X:  $[0,T] \to L^0(\Omega)$  with  $X(t) := X_t$ , where  $L^0(\Omega)$  is the space of all random variables  $Z:\Omega\to\mathbb{R}$ . For  $p\in[0,\infty]$ ,  $L^p(\Omega)$  are as usual.
- A stochastic process X is progressively measurable if its restriction  $X|_{[0,t]}:[0,t]\times\Omega\to$  $\mathbb{R}$  is  $(\mathscr{B}_{[0,t]} \times \mathscr{F}_t, \mathscr{B}_{\mathbb{R}})$  measurable for all  $t \in [0,T]$ , denoted as  $X \in \mathbb{L}^0(\mathbb{F})$ . For  $p \in [1, \infty], \mathbb{L}^p(\mathbb{F}) := \mathbb{L}^0(\mathbb{F}) \cap L^p([0, T] \times \Omega)$  are as usual.
- The distribution of a random variable Z is a Borel measure, denoted as  $\mu_Z: \mathscr{B}_{\mathbb{R}} \to$ [0,1], is defined as

$$\mu_Z(A) := \mathbb{P}(Z \in A).$$

We say such two random variables  $Z_1, Z_2$  have the same distribution, denoted as  $Z_1 \stackrel{(d)}{=} Z_2$ , if  $\mu_{Z_1} = \mu_{Z_2}$ .
• The *finite distribution* of a stochastic process X is a collection of Borel measures

$$\{\mu_{X_{t_1},...,X_{t_n}}\}_{\text{all }0 \le t_1 < t_2 < ... < t_n \le T},$$

where

$$\mu_{X_{t_1},...,X_{t_n}}(A) := \mathbb{P}\Big((X_{t_1},...,X_{t_n}) \in A\Big)$$

for all  $A \in \mathscr{B}_{\mathbb{R}^n}$ .

• Moreover, we say such two stochastic processes X, Y have the same finite distribution, denoted as  $X \stackrel{(d)}{=} Y$ , if  $\mu_{X_{t_1}, \dots, X_{t_n}} = \mu_{Y_{t_1}, \dots, Y_{t_n}}$ , for any  $0 \le t_1 < t_2 < \dots < t_n \le T$ .

## 3.2. Main Proposition.

We want to show that

**Proposition 3.1.** Given  $(\Omega, \mathscr{F}, \mathbb{F} := \{\mathscr{F}_t\}_{0 \le t \le T}, \mathbb{P})$  and  $X, Y \in \mathbb{L}^0(\mathbb{F})$ , if  $X \stackrel{(d)}{=} Y$ , then  $\int_0^T X_t dt \stackrel{(d)}{=} \int_0^T Y_t dt.$ 

We first give out a lemma.

**Lemma 3.2.** Suppose  $X, Y \in \mathbb{L}^0(\mathbb{F})$  and  $X \stackrel{(d)}{=} Y$ . If X is continuous in t for a.e.  $\omega$ , then Y is also continuous in t a.e.  $\omega$ .

Proof of the Proposition 3.1.

Assume X, Y bounded (i.e.  $X, Y \in \mathbb{L}^{\infty}(\mathbb{F})$  and equivalently  $X, Y : [0, T] \to L^{\infty}(\Omega)$ .) and X continuous. By lemma 3.2, Y is also continuous. Then, consider partition of  $\pi_n: \{t_i :=$  $\frac{i}{2^n}T$ ,  $i = 0, ..., 2^n$  and

$$X_t^{\pi_n} := \sum_{i=0}^{n-1} X_{t_i} \mathbb{1}_{\{t_i \le t < t_{i+1}\}}$$

and

$$Y_t^{\pi_n} := \sum_{i=0}^{n-1} Y_{t_i} \mathbb{1}_{\{t_i \le t < t_{i+1}\}}.$$

It is clear, as X, Y has same finite distribution, that

$$\int_0^T X_t^{\pi_n} dt = \sum_{i=0}^{n-1} X_{t_i} \Delta t_{i+1} \stackrel{(d)}{=} \sum_{i=0}^{n-1} Y_{t_i} \Delta t_{i+1} = \int_0^T Y_t^{\pi_n} dt.$$

Notice  $X^{\pi_n} \to X$  pointwisely in  $t, Y^{\pi_n} \to Y$  in t pointwisely, and boundedness of X, Y, by dominated convergence theorem (Theorem 2.2), we know

$$\int_0^T X_t dt = \lim_{n \to \infty} \int_0^T X_t^{\pi_n} dt \stackrel{(d)}{=} \lim_{n \to \infty} \int_0^T Y_t^{\pi_n} dt = \int_0^T Y_t dt.$$

To see the  $\stackrel{(d)}{=}$  above, denote  $Z_n := \int_0^T X_t^{\pi_n} dt$ ,  $\tilde{Z}_n := \int_0^T Y_t^{\pi_n} dt$ ,  $Z := \int_0^T X_t dt$  and  $\tilde{Z} := \int_0^T Y_t dt$ . By Folland 6.8(c), after taking a union of  $\mathbb{P}$ -null sets, we have  $Z_n \to Z$ ,  $\tilde{Z}_n \to \tilde{Z}$  uniformly on  $\Omega \setminus E$  with  $\mathbb{P}(E) = 0$ . For a given closed  $A \subseteq \mathbb{R}$ , we denote a  $\varepsilon$ -perturbation of A,  $A_{\varepsilon} := \{x \in \mathbb{R} : |x - y| < \varepsilon \text{ for some } y \in A\}$ . we **claim**:

$$\bigcap_{\varepsilon>0} \bigcup_{N\in\mathbb{N}} \bigcap_{n\geq N} \{\omega \notin E : Z_n(\omega) \in A_{\varepsilon}\} = \{\omega \notin E : Z(\omega) \in A\}$$

and similarly  $\bigcap_{\varepsilon>0}\bigcup_{N\in\mathbb{N}}\bigcap_{n\geq N}\{\omega\notin E:\tilde{Z}_n(\omega)\in A_\varepsilon\}=\{\omega\notin E:\tilde{Z}(\omega)\in A\}$ . Then, as  $Z_n\stackrel{(d)}{=}\tilde{Z}_n$ ,

$$\mathbb{P}\Big(\{\omega \not\in E: Z(\omega) \in A\}\Big) = \mathbb{P}\Big(\{\omega \not\in E: \tilde{Z}(\omega) \in A\}\Big),$$

and we are done as  $\mathscr{B}_{\mathbb{R}}$  is generated by closed sets.

To see the claim,  $\supseteq$  direction is clear by the uniform convergence on  $E^c$ . For the other direction, let  $\omega \in \bigcap_{\varepsilon>0} \bigcup_{N\in\mathbb{N}} \bigcap_{n\geq N} \{\omega \notin E : Z_n(\omega) \in A_{\varepsilon}\}$ . For a given  $\varepsilon/2$ ,  $\exists N_1$  s.t.  $Z_n(\omega) \in A_{\varepsilon/2}$  for all  $n\geq N_1$ . Pick a  $y_{\varepsilon}$  s.t.

$$|Z_n(\omega) - y_{\varepsilon}| < \frac{\varepsilon}{2}.$$

Also, the uniform convergence on  $E^c$  allows us to choose  $N_2$  s.t.

$$|Z(\omega) - Z_n(\omega)| < \frac{\varepsilon}{2}$$

for all  $n \geq N_2$ . We choose  $N = N_1 \vee N_2$ , and hence we have for all  $\varepsilon, \exists y_{\varepsilon} \in A$ 

$$|Z(\omega) - y_{\varepsilon}| \le |Z(\omega) - Z_n(\omega)| + |Z_n(\omega) - y_{\varepsilon}| < \varepsilon,$$

i.e.  $Z(\omega)$  is a limit point of A and hence  $Z(\omega) \in A$  as A is closed.

Now for general bounded X,Y, we apply the Luzin's (Theorem 2.3), and, after taking a intersection of two compact sets, we may assume that  $\forall \delta > 0$ ,  $\exists K_{\delta} \subseteq [0,T]$  s.t.  $m(K_{\delta}^c) < \delta$ , and  $X|_{K_{\delta}}$ ,  $Y|_{K_{\delta}}$  are continuous. Apply the same discretization and perturbation technique, we have

$$\int_{K_{\delta}} X_t dt = \lim_{n \to \infty} \int_{K_{\delta}} X_t^{\pi_n} dt \stackrel{(d)}{=} \lim_{n \to \infty} \int_{K_{\delta}} Y_t^{\pi_n} dt = \int_{K_{\delta}} Y_t dt.$$

Then, we choose  $\delta_m := \frac{1}{m|X|_{\infty}} \wedge \frac{1}{m|Y|_{\infty}}$ , denote  $K_m := K_{\delta_m}$ , and hence we have

$$\int_{K_m^c} |X_t|_{\infty} dt \le |X|_{\infty} m(K_m^c) < |X|_{\infty} \delta_m \le 1/m,$$

and observe that

$$|\int_{0}^{T} X_{t}dt - \int_{K_{m}} X_{t}dt|_{\infty} = |\int_{K_{m}^{c}} X_{t}dt|_{\infty} \le \int_{K_{m}^{c}} |X_{t}|_{\infty}dt < \frac{1}{m},$$

i.e.  $\int_{K_m} X_t dt \to \int_0^T X_t dt$  uniformly except on a  $\mathbb{P}$ -null set E. Similarly, after taking a union of  $\mathbb{P}$ -null sets, we may say  $\int_{K_m} Y_t dt \to \int_0^T Y_t dt$  uniformly except on the same  $\mathbb{P}$ -null set E. Then, we further apply the perturbation technique on  $\int_{K_m} X_t dt$ ,  $\int_0^T X_t dt$  and we may conclude  $\int_0^T X_t dt \stackrel{(d)}{=} \int_0^T Y_t dt$ .

Finally, for general X, Y, we follow the standard space truncation  $X^{(n)} := X \wedge n$ . It gives an a.e. convergence and hence allows us to follow the same perturbation procedure.

**Remark 3.3.** In fact this is a trivial application, as all we need to apply the perturbation technique is the a.e. convergence, which could be achieved by using  $\mathbb{P}$ -a.e. defined  $(\int_0^T X_t dt)(\omega) := \int_0^T X(t,\omega) dt$  from the Fubini's. Anyway, it is good to realize the integration for vector-valued functions.

#### 4. Reference

- K. Yosida, Functional analysis, Springer, Ch. 8, §1., 1980
- G.B. Folland. Real Analysis: Modern Techniques and Their Applications, Second Edition, 1999.
  - W. Rudin. Functional analysis. New York: McGraw-Hill, 1973

#### 5. Appendix

To prove Lemma 2.4, we add the following generalized notion of convergence in measure and lemma.

We say that a sequence of  $(\Sigma, \mathcal{B}_V)$ -measurable functions  $\{f_n\}$  on  $(X, \Sigma, \mu)$ 

• converges in measure to f if, for every  $\varepsilon > 0$ , we have

$$\lim_{n \to \infty} \mu(\{x : |f_n(x) - f(x)|_V \ge \varepsilon\}) = 0.$$

• Cauchy in measure if, for every  $\varepsilon > 0$ , we have

$$\mu(\lbrace x: |f_n(x) - f_m(x)|_V \ge \varepsilon\rbrace) \to 0$$

as  $n, m \to \infty$ .

**Lemma 5.1.** Suppose  $\{f_n\}$  is Cauchy in measure, then there is  $(\Sigma, \mathcal{B}_V)$ -measurable function f s.t.  $f_n \to f$  in measure, and there is a subsequence  $f_{n_j}$  that  $f_{n_j} \to f$  a.e. Moreover, if  $f_n \to g$  in measure, then f = g a.e.

Corollary 5.2. If  $f_n \to f$  in measure, then there is a subsequence  $\{f_{n_j}\}$  s.t.  $f_{n_j} \to f$  a.e. Lemma 5.3. if  $f_n \to f$  in  $L^1(X; V)$ , then  $f_n \to f$  in measure.

Together, lemma 2.4 is proved.

Proof of Lemma 5.1. Since  $\forall \varepsilon > 0$ ,  $\lim_{n,m\to\infty} \mu(\{x: |f_n(x) - f_m(x)|_V \ge \varepsilon\}) = 0$ , we choose  $n_1$  large enough to be the first index s.t.  $\mu(\{x: |f_n(x) - f_{n+1}(x)|_V \ge 2^{-1}\}) < 2^{-1}$ . Similarly, We could choose  $\{g_j\} = \{f_{n_j}\}$  s.t. if  $E_j := \{x: |g_j(x) - g_{j+1}(x)|_V \ge 2^{-j}\}$ , then  $\mu(E_j) \le 2^{-j}$ . Denote  $F_k := \bigcup_{j\ge k} E_j$ , and hence  $\mu(F_k) \le \sum_{j=k}^{\infty} 2^{-j} = 2^{1-k}$ , and if  $x \notin F_k$ , i.e.  $x \in \bigcap_{j\ge k} E_j^c$  for  $i \ge j \ge k$ , we have

$$|g_i(x) - g_j(x)|_V \le \sum_{l=j}^{i-1} |g_l(x) - g_{l+1}(x)|_V \le \sum_{l=j}^{i-1} 2^{-l} < 2^{1-j}.$$

Consider  $x \in \bigcup_{k=1}^{\infty} F_k^c$ , then  $x \in F_k^c$  for some k, and in here we have  $|g_i(x) - g_j(x)|_V < 2^{1-j}$  for all  $i \ge j \ge k$ . Pick  $K \ge k$  s.t.  $2^{1-K} < \varepsilon$ , and then, whenever  $i \ge j \ge K$ 

$$|g_i(x) - g_j(x)|_V < 2^{1-j} \le 2^{1-K} < \varepsilon,$$

i.e.  $\{g_j\}$  pointwise Cauchy in  $\bigcup_{k=1}^{\infty} F_k^c$ . Observe  $\mu(\left(\bigcup_{k=1}^{\infty} F_k^c\right)^c) = \mu(\bigcap_{k=1}^{\infty} F_k) = \lim_{k \to \infty} \mu(F_k) = 0$ , and hence we know  $\{g_j\}$  pointwise Cauchy almost everywhere. Define

$$f(x) := \begin{cases} \lim_{j \to \infty} g_j(x) & \text{if } x \in \bigcup_{k=1}^{\infty} F_k^c \\ \mathbf{0} & \text{otherwise} \end{cases}.$$

It is easy to see f is  $(\Sigma, \mathscr{B}_V)$ -measurable and hence  $f_{n_j} = g_j \to f$  a.e.

We left to show  $f_n \to f$  in measure. To see this, observe by triangle inequality

$$\{x:|f_n(x)-f(x)|_V\geq\varepsilon\}\subseteq\{x:|f_n(x)-f_{n_j}(x)|_V\geq\frac{\varepsilon}{2}\}\cup\{x:|f_{n_j}(x)-f(x)|_V\geq\frac{\varepsilon}{2}\},$$

where the later two sets have small measure when  $n, j \to \infty$ , one given by convergence in measure and the other given by the a.e. pointwise convergence.

If  $f_n \to g$  in measure, similarly, observe that

$$\{x:|f(x)-g(x)|_{V}\geq\varepsilon\}\subseteq\{x:|f(x)-f_{n}(x)|_{V}\geq\frac{\varepsilon}{2}\}\cup\{x:|f_{n}(x)-g(x)|_{V}\geq\frac{\varepsilon}{2}\},$$

i.e.  $\mu(\{x:|f(x)-g(x)|_V\geq\varepsilon\})=0$  for all  $\varepsilon>0$ . Note

$$\{x: |f(x) - g(x)|_V > 0\} = \bigcup_{m \in \mathbb{N}} \{x: |f(x) - g(x)|_V \ge \frac{1}{m}\},\$$

we conclude f = g a.e. by the continuity from below.

Proof of Lemma 5.2.

Let  $E_{n,\varepsilon} := \{x : |f_n(x) - f(x)|_V \ge \varepsilon\}$ , then

$$\varepsilon \mu(E_{n,\varepsilon}) \le \int_{E_{n,\varepsilon}} |f_n - f| d\mu \le \int_X |f_n - f| d\mu \to 0$$

as  $n \to \infty$ .

Proof of Lemma 2.5.

Let  $f_n \to f$  pointwise on K with  $\mu(K^c) = 0$ . Note

$$K = \bigcap_{k=1}^{\infty} \bigcup_{N \in \mathbb{N}} \bigcap_{n > N} \{x : |f_n(x) - f(x)|_V < \frac{1}{k} \}.$$

That is, for any fixed k,  $K(k) := \bigcup_{N \in \mathbb{N}} \bigcap_{n \geq N} \{x : |f_n(x) - f(x)|_V < \frac{1}{k} \}$  has full measure. For  $N \in \mathbb{N}$ , denote

$$E_N(k) := \bigcup_{n > N} \{x : |f_n(x) - f(x)|_V \ge \frac{1}{k} \}.$$

Observe  $E_N(k)$  decreases as N increases, and

$$K(k) = \bigcup_{N \in \mathbb{N}} E_N(k)^c = \Big(\bigcap_{N \in \mathbb{N}} E_N(k)\Big)^c.$$

Thus,  $F(k) := \bigcap_{N \in \mathbb{N}} E_N(k)$  is a null set. By continuity from above, we may choose  $N_k$  s.t.  $\mu(E_{N_k}(k)) < \varepsilon 2^{-k}$ . Denote  $E := \bigcup_{k=1}^{\infty} E_{N_k}(k)$ , so we have  $\mu(E) \le \sum_{k=1}^{\infty} \mu(E_{N_k}(k)) < \varepsilon$ .

On  $E^c$ , observe  $E^c \subseteq E_{N_k}(k)^c$  for any k. Therefore, For any  $\varepsilon' > 0$ , there is a k s.t.  $\frac{1}{k} < \varepsilon$ , and for  $\forall x \in E^c \subseteq E_{N_k}(k)^c$ ,  $|f_n(x) - f(x)|_V < \frac{1}{k} < \varepsilon'$  whenever  $n \ge N_k$ , i.e.  $f_n \to f$  uniformly on  $E^c$ .

Proof of Lemma 2.6.

By linearity and denseness of simple functions in  $L^1(\mathbb{R}; V)$ , it suffice to show any simple function of form  $s(x) := \mathbb{1}_E(x)\mathbf{1}$  (we abuse the term to say it is a *indicator*) could approximated arbitrarily close in  $|\cdot|_{L^1(X;V)}$  by a compactly supported continuous function, where  $E \in \mathcal{L}_{\mathbb{R}}$  Lebesgue-Stieltjes measurable set, and  $\mathbf{1}$  is a unit vector in V.

Recall that E could be approximated by a finite union of open intervals  $\{I_i\}_{i=1}^n$  s.t.  $\mu(E \triangle \cup_{i=1}^n I_i) < \varepsilon$ . Note

(1) 
$$\int_{Y} |\mathbb{1}_{E} \mathbf{1} - \mathbb{1}_{\bigcup_{i=1}^{n} I_{i}} \mathbf{1}|_{V} d\mu = \int_{Y} |\mathbb{1}_{E} - \mathbb{1}_{\bigcup_{i=1}^{n} I_{i}}| d\mu = \mu(E \triangle \bigcup_{i=1}^{n} I_{i}) < \varepsilon.$$

So we know the indicator of any E could be approximated arbitrarily by a indicator of finite union of open intervals.

Meanwhile, for the indicator of an open interval  $\mathbb{1}_{(a,b)}\mathbf{1}$ , we could approximate by constructing

$$f_{\varepsilon}(x) \coloneqq \begin{cases} \mathbf{1} & \text{if } x \in [a + \frac{\varepsilon}{2}, b - \frac{\varepsilon}{2}] \\ Linear & \text{if } x \in [a - \frac{\varepsilon}{2}, a + \frac{\varepsilon}{2}] \cup [b - \frac{\varepsilon}{2}, b + \frac{\varepsilon}{2}] \\ \mathbf{0} & \text{otherwise} \end{cases}$$

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