

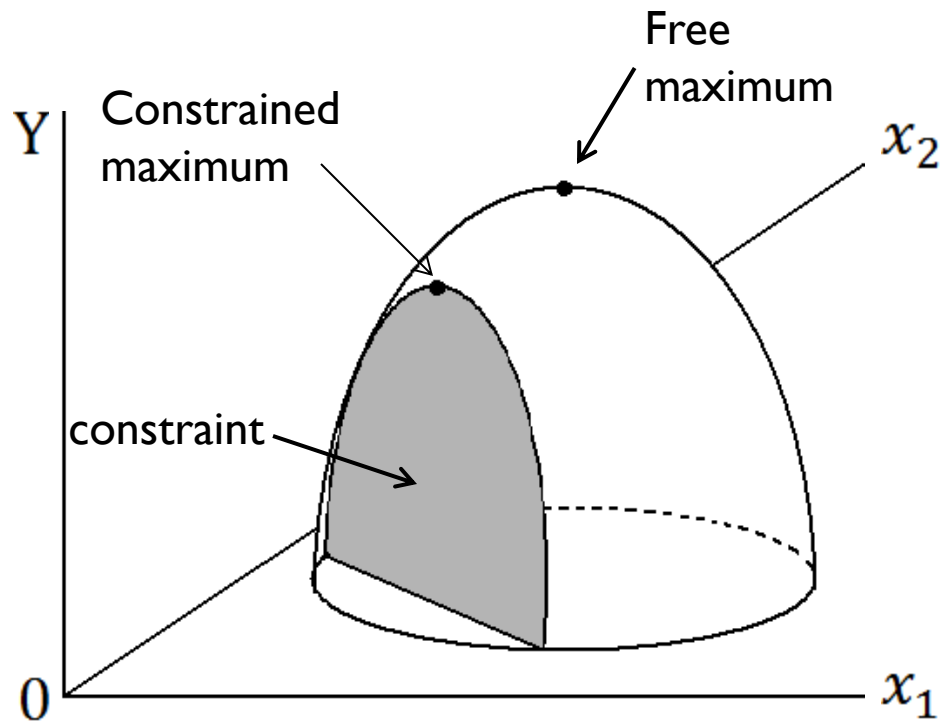


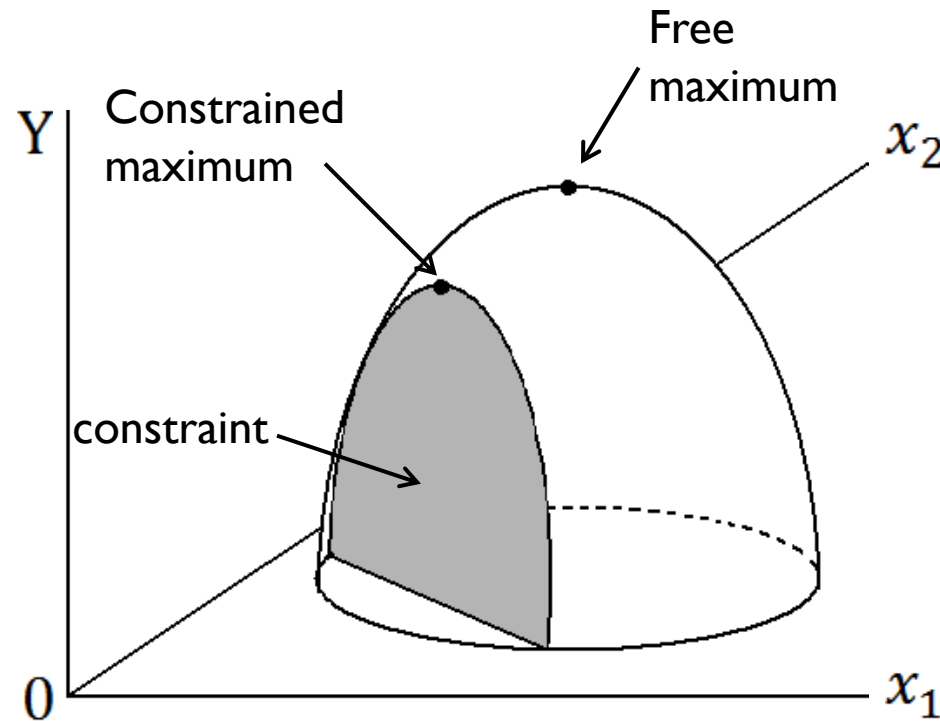
# Constrained Optimization

We want to minimize (or maximize) the objective function, at the same time the solution should obey certain constraints.

# Constrained Optimization

Graphically, the difference between the free optima and the constrained optima can be shown as:





- The free optima occurs at the peak of the surface.
- If we specify a specific relationship between variables  $x_1$  and  $x_2$  (a constraint) then the search for an optimum is restricted to a slice of the surface. The constrained maximum occurs at the peak of the slice.

# Constrained Optimization

- Since economists deal with the allocation of scarce resources among alternative uses, the concept of constraints or restrictions is important.
- There are two approaches to solving constrained optima problems:
  - (i) substitution method
  - (ii) Lagrange multipliers

# Substitution Method

- Consider a firm producing commodity  $y$  with the following production function:

$$y = 5x_1x_2$$

- Without any constraints, the firm can produce an unlimited quantity by utilizing an unlimited amount of  $x_1$  and  $x_2$ .

# Substitution Method

- But suppose the firm has a budget constraint:

Let  $p_{x_1} = \$2/unit$

$p_{x_2} = \$1/unit$

- For simplicity, assume that the maximum amount the firm can spend on these two inputs is \$100.
- So we have the following constraint:

$$2x_1 + x_2 = 100$$

# Substitution Method

- Suppose the economic question facing this firm is maximizing production subject to this budget constraint.
- The solution via the substitution method is to substitute:
  - First, write the constraint in terms of  $x_2$ :

$$2x_1 + x_2 = 100$$

$$\therefore x_2 = 100 - 2x_1$$

# Substitution Method

$$x_2 = 100 - 2x_1$$

- Then substitute this value into the production function, such that:

$$y = 5x_1x_2$$

$$y = 5x_1(100 - 2x_1)$$

$$= 500x_1 - 10x_1^2$$

- With this substitution, the constrained maxima problem is reduced to a free maxima problem with one independent variable.



# Substitution Method

- Now apply the usual optimization procedure:

$$\frac{dy}{dx_1} = 500 - 20x_1 = 0$$

$$-20x_1 = -500$$

$$\text{(critical value)} \quad \therefore x_1 = \frac{-500}{-20} = 25$$

# Substitution Method

$$\frac{dy}{dx_1} = 500 - 20x_1 = 0$$

$$\frac{d^2y}{dx_1^2} = -20 < 0 \quad \therefore \text{relative max}$$

$$\therefore \text{if } x_1 = 25 \text{ then } 100 = 2(25) + x_2$$

$$\therefore 100 - 50 = 50 = x_2$$

- The method of substitution is one way to solve constrained optima problems. This is manageable in some cases. In others, the constraint may be very complicated and substitution becomes complex.

# Lagrange Multipliers

- The constrained optima problem can be stated as finding the extreme value of  $y = f(x_1, x_2)$  subject to  $g(x_1, x_2) = 0$ .
- So Lagrange (a mathematician) formed the augmented function.

$$L = f(x_1, x_2) + \alpha(g(x_1, x_2))$$



denotes the augmented function called the Lagrangian, will behave like the function if the constraint is followed.

# Lagrange Multipliers

- Given the augmented function, the first order condition for optimization (where the independent variables are  $x_1$ ,  $x_2$  and  $\lambda$ ) is as follows:

$$\left. \begin{aligned} \frac{\partial L}{\partial x_1} &= f_1 + \alpha g_1 = 0 \\ \frac{\partial L}{\partial x_2} &= f_2 + \alpha g_2 = 0 \\ \frac{\partial L}{\partial \alpha} &= g(x_1, x_2) = 0 \end{aligned} \right\} \begin{array}{l} \text{Solve simultaneously} \\ \text{for critical values} \end{array}$$

# Lagrange Multipliers

- Using the previous example:

$$L = 5x_1x_2 + \alpha(100 - 2x_1 - x_2)$$

note:  $100 = 2x_1 + x_2$

$\therefore 100 - 2x_1 - x_2 = 0$       to be on the budget line

$$\left. \begin{array}{l} \frac{\partial L}{\partial x_1} = 5x_2 - 2\alpha = 0 \\ \frac{\partial L}{\partial x_2} = 5x_1 - \alpha = 0 \\ \frac{\partial L}{\partial \alpha} = 100 - 2x_1 - x_2 = 0 \end{array} \right\} \begin{array}{l} 3 \text{ unknowns:} \\ x_1, x_2, \alpha \\ 3 \text{ equations} \end{array}$$

# Lagrange Multipliers

$$\left. \begin{aligned} \frac{\partial L}{\partial x_1} &= 5x_2 - 2\alpha = 0 \\ \frac{\partial L}{\partial x_2} &= 5x_1 - \alpha = 0 \\ \frac{\partial L}{\partial \alpha} &= 100 - 2x_1 - x_2 = 0 \end{aligned} \right\} \begin{array}{l} 3 \text{ unknowns:} \\ x_1, x_2, \alpha \\ 3 \text{ equations} \end{array}$$

- Solving these 3 equations simultaneously:

$$5x_2 - 2\alpha = 0$$

$$5x_2 = 2\alpha$$

$$\therefore x_2 = \frac{2\alpha}{5}$$

# Lagrange Multipliers

$$\left. \begin{aligned} \frac{\partial L}{\partial x_1} &= 5x_2 - 2\alpha = 0 \\ \frac{\partial L}{\partial x_2} &= 5x_1 - \alpha = 0 \\ \frac{\partial L}{\partial \alpha} &= 100 - 2x_1 - x_2 = 0 \end{aligned} \right\} \begin{array}{l} 3 \text{ unknowns:} \\ x_1, x_2, \alpha \\ 3 \text{ equations} \end{array}$$

- Solving these 3 equations simultaneously (cont'd):

$$x_1 = \frac{\alpha}{5}$$

# Lagrange Multipliers

$$x_1 = \frac{\alpha}{5}$$

$$x_2 = \frac{2\alpha}{5}$$

- Solving these 3 equations simultaneously (cont'd):

$$\therefore 100 - 2\left(\frac{\alpha}{5}\right) - \left(\frac{2\alpha}{5}\right) = 0$$

$$500 = 4\alpha$$

$$100 = \frac{4\alpha}{5}$$

$$\alpha = 125$$



# Lagrange Multipliers

- This solution yields the same answer as the substitution method, i.e.,

$$x_1 = 25 \qquad x_2 = 50$$

# Lagrange Multipliers

- Economists prefer using the Lagrange technique over the substitution method, because:
  - (i) easier to handle for most cases and
  - (ii) provides additional information.
- The Lagrange multiplier gives how much sensitive the constraint is

# KKT Conditions

- In the presence of inequality constraints, one can use KKT conditions which are necessary conditions for the optimality.
  - These are sufficient also, provided the objective is convex and constraints are linear. (This is what exactly happens in the case of SVMs).

# Constrained Optimization Problem

- Minimize  $f(v)$   
Subject to the constraints  $g_j(v) \leq 0, \quad 1 \leq j \leq n.$

- Lagrangian,

$$\mathcal{L} = f(v) + \sum_{j=1}^n \alpha_j g_j(v)$$

where  $v$  is called *primary* variables and  $\alpha_j$  are the Lagrangian multipliers which are also called *dual* variables.

- $\mathcal{L}$  has to be minimized with respect to primal variables and maximized with respect to dual variables.

# K.K.T Conditions

$$(i) \nabla_v L = 0$$

$$\left. \begin{array}{l} (ii) \alpha_j \geq 0 \\ (iii) \alpha_j g_j(v) = 0 \\ (iv) g_j(v) \leq 0 \end{array} \right\} \text{for all } j = 1 \text{ to } n$$

- K.K.T. Conditions, in general are necessary, i.e., at optimal point these are satisfied. So, if these are not satisfied we know that the point we are concerned is not optimal.

- However, when the objective is a convex function and constraints are all linear functions, then K.K.T conditions are sufficient also.

- The (iv) th one is within the problem statement. So normally first 3 conditions are called the KKT conditions.

# Example.

Minimize  $f(x) = (x - 4)^2 + 5$ , such that  $x \geq 6$ .

$$L = (x - 4)^2 + 5 + \alpha(-x + 6)$$

KKT conditions:

$$(1) \frac{\partial L}{\partial x} = 0, \text{ So } x = \frac{1}{2}(\alpha + 8)$$

$$(2) \alpha(-x + 6) = 0$$

$$(3) \alpha \geq 0$$

(2) and (3) along with the problem constraint, gives  $x = 6$ .

# Example

Minimize  $f(v_1, v_2) = v_1 + v_2$ , such that  $v_1^2 + v_2^2 \leq 1$ .

Solution:  $L = (v_1 + v_2) + \alpha(v_1^2 + v_2^2 - 1)$ .

KKT Conditions

$$(1) \frac{\partial L}{\partial v_1} = 1 + 2\alpha v_1 = 0, \quad \frac{\partial L}{\partial v_2} = 1 + 2\alpha v_2 = 0.$$

$$\text{So, } v_1 = v_2 = -\frac{1}{2\alpha}. \quad \text{So } \alpha \neq 0.$$

$$(2) \alpha \geq 0$$

$$(3) \alpha(v_1^2 + v_2^2 - 1) = 0.$$

From (2) and (3) since  $\alpha > 0$ , we have  $v_1^2 + v_2^2 - 1 = 0$ .

This gives  $\alpha = \frac{1}{\sqrt{2}}$ .

So, we get  $v_1 = v_2 = -\frac{1}{\sqrt{2}}$

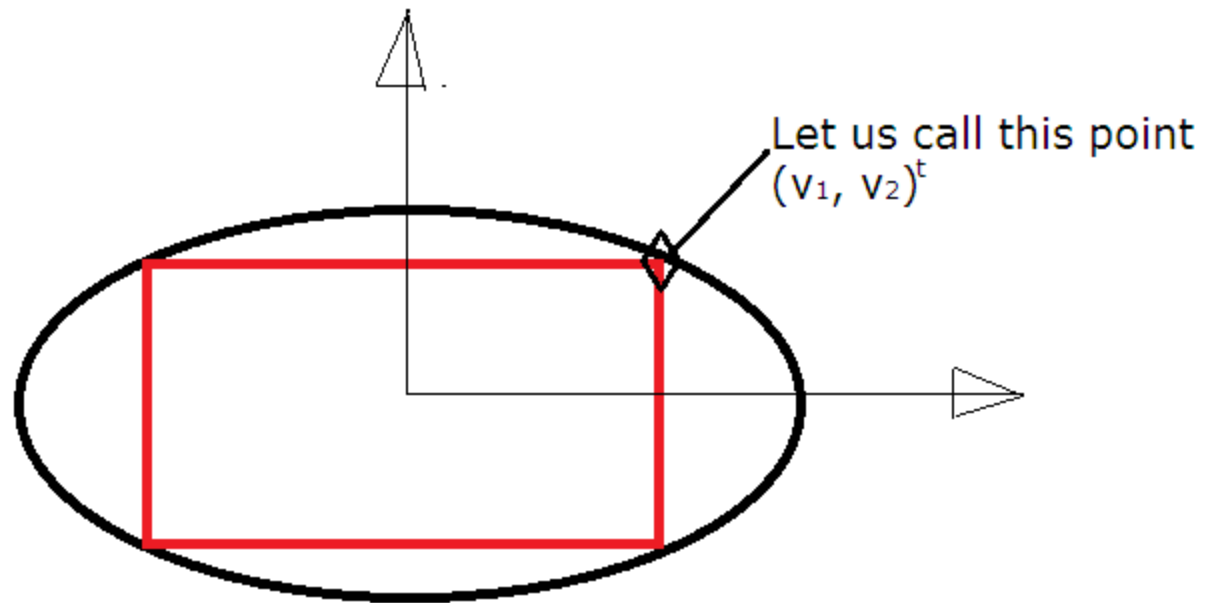
# With both equality and inequality constraints

- We see an example.



# An Example.


- Find maximum perimeter rectangle that is inscribed in the ellipse  $x^2 + 4y^2 = 4$ .



- Maximize the perimeter  $= 4(v_1 + v_2)$ , subject to  $v_1^2 + 4v_2^2 - 4 = 0$ . Also, note we have constraints  $v_1 \geq 0$ , and  $v_2 \geq 0$ .
- Lagrangian,  $L(v_1, v_2, \alpha_1, \alpha_2, \alpha_3) = -4(v_1 + v_2) + \alpha_1(v_1^2 + 4v_2^2 - 4) + \alpha_2(-v_1) + \alpha_3(-v_2)$ .

# KKT Conditions

- $\frac{\partial L}{\partial v_1} = 0$
- $\frac{\partial L}{\partial v_2} = 0$
- $\frac{\partial L}{\partial \alpha_1} = 0$
- $v_1 \alpha_2 = 0, \quad v_2 \alpha_3 = 0$
- $\alpha_1 \geq 0, \quad \alpha_2 \geq 0, \alpha_3 \geq 0$

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- We get  $\alpha_1 = \frac{\sqrt{5}}{2}, \alpha_2 = \alpha_3 = 0$ .
  - We get the solution, ...