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Section: AL1

ECE 408/CS483 Milestone 2 Report

1. Show output of rai running Mini-DNN on the basic GPU convolution implementation for batch size of 1k images. This can either be a screen capture or a text copy of the running output. Please do not show the build output. (The running output should be everything including and after the line "*Loading fashion-mnist data...Done*").

Loading fashion-mnist data...Done

Loading model...Done

Conv-GPU==

Layer Time: 77.0541 ms

Op Time: 5.9116 ms

Conv-GPU==

Layer Time: 64.0177 ms

Op Time: 21.3389 ms

Test Accuracy: 0.886

real 0m9.692s

user 0m9.385s

sys 0m0.264s

2. For the basic GPU implementation, list Op Times, whole program execution time, and accuracy for batch size of 100, 1k, and 10k images.

Batch Size	Op Time 1	Op Time 2	Total Execution Time	Accuracy
100	0.576163ms	2.07154ms	1.155	0.86
1000	5.9116ms	21.3389ms	9.692s	0.886
10000	57.6449ms	216.506ms	1m35.722s	0.8714

3. List all the kernels that collectively consumed more than 90% of the kernel time and what percentage of the kernel time each kernel did consume (start with the kernel that consumed the most time, then list the next kernel, until you reach 90% or more).

100.0 266531896 2 133265948.0 59588959 206942937 conv_forward_kernel

4. List all the CUDA API calls that collectively consumed more than 90% of the API time and what percentage of the API time each call did consume (start with the API call that consumed the most time, then list the next call, until you reach 90% or more).

68.3	1035951641	8	129493955.1	18405	568180534	cudaMemcpy
17.6	266559704	6	44426617.3	2929	206945842	cudaDeviceSynchronize
12.9	196307942	8	24538492.7	67234	191712660	cudaMalloc

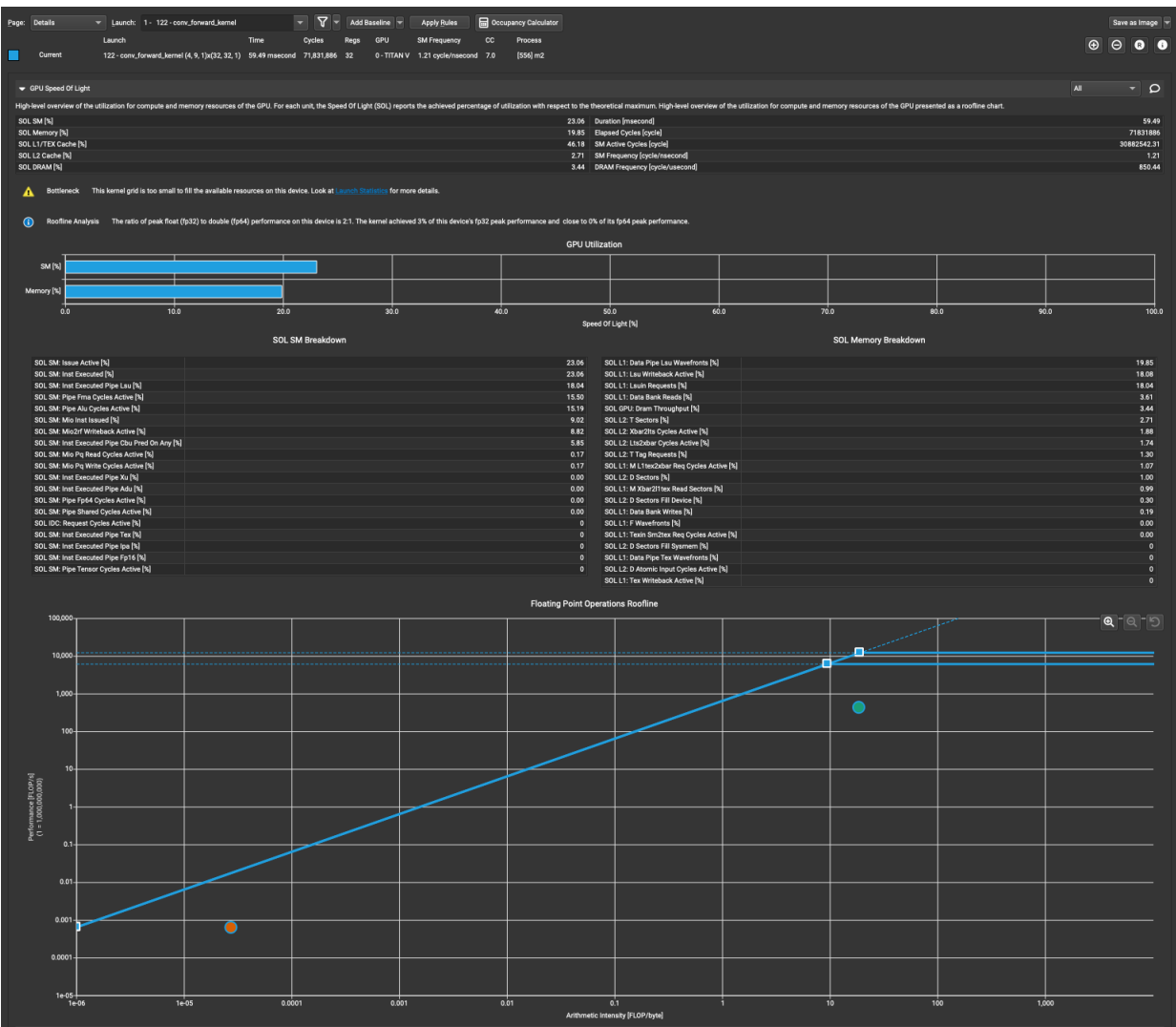
5. Explain the difference between kernels and CUDA API calls. Please give an example in your explanation for both.

Kernel means the user code which will be run parallelized on the GPU device. CUDA API call, on the other hand, is a pre-defined function that generally interacts between the host and the device.

For example, the `conv_forward_kernel` is the kernel we implemented for our own convolution. It will be executed across several grids and blocks with multiple threads simultaneously. The `cudaMemcpy` is the CUDA API which we'll call whenever we need to copy data between the host and the device.

6. Show a screenshot of the GPU SOL utilization

1 - 122 - conv_forward_kernel



4- 143 - conv_forward_kernel

