

# CLINICAL APPLICATIONS OF COMPUTATIONAL MEDICINE

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# WORK DISTRIBUTION

- Video: Neo, Delun Zhang, Yuya Yuan
- Code: Jeff
- Robotics arm: All



# OUR PLAN



## Week 1 (July 5 - July 11)

- **Objective: Preparation and Local Research**

- \* Study the theory and implementation of the three normal estimation methods.
- \* Set up and configure the development environment.
- \* Acquire point cloud datasets for local testing.
- \* Implement the three methods and conduct initial local tests.

## Week 2 (July 12 - July 25)

- **Objective: Integration, Testing and Data Collection**

- \* Integrate the three methods into the robotic system and conduct functional tests.
- \* Collect data from the tests for further analysis.
- \* Develop evaluation criteria, focusing on positioning accuracy and processing speed.

## Week 3 (July 26 - July 30)

- **Objective: Data Analysis and Video Production**

- \* Analyze test data and compare results to identify the best method.
- \* Prepare presentation materials.
- \* Produce a presentation video, covering project background, implementation, test results, and conclusions.

## Week 4 (July 31 - August 6)

- **Objective: Presentation Preparation**

- \* Prepare for possible questions

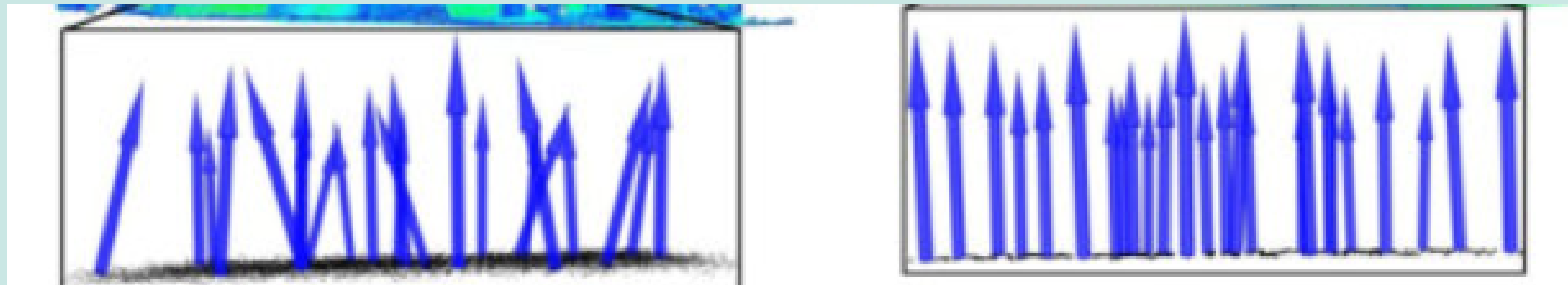
# WHAT WE HAVE DONE THIS WEEK

- Dive into three methods to calculate normal vectors
- Finished the first method (using [open3d lib](#))



# WORKFLOW

1. Read ply files
2. Downsampling
3. Calculate normal vectors
4. Average K closest points' normal vectors to lower the potential error





# QUESTIONS





**THANK YOU FOR  
LISTENING**

