

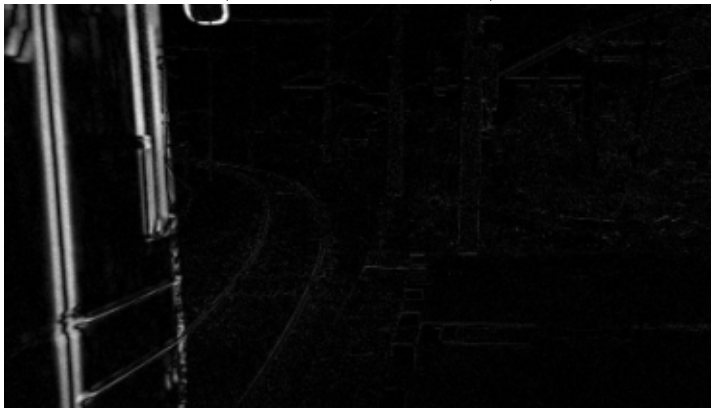
(a) Previous Frame ( $I_t$ )



(b) Current Frame ( $I_{t+1}$ ) with MVs



(c) Residual w/o Motion Comp.  
(Direct Difference)



(d) Residual w/ Motion Comp.  
(Prediction Error,  $4 \times 4$ )



→ MV