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In[1]:= la = m*ht2/2 - k*h2/2
Out[1]= - $\frac{h^2 k}{2} + \frac{ht^2 m}{2}$ 

In[2]:= q = D[la, ht]
Out[2]= ht m

In[3]:= f = D[la, h]
Out[3]= -h k

In[4]:= s = q /. {ht  $\rightarrow$  D[h[t], t], h  $\rightarrow$  h[t] }
Out[4]= m h'[t]

In[5]:= c = f /. {ht  $\rightarrow$  D[h[t], t], h  $\rightarrow$  h[t] }
Out[5]= -k h[t]

In[6]:= EL = c - D[s, t]
Out[6]= -k h[t] - m h''[t]

In[7]:= la = m*L2*ht2/2 - m*g*L*(1 - Cos[h])
Out[7]=  $\frac{1}{2} ht^2 L^2 m - g L m (1 - \cos[h])$ 

In[8]:= q = D[la, ht]
Out[8]= ht L2 m

In[9]:= s = q /. {ht  $\rightarrow$  D[h[t], t], h  $\rightarrow$  h[t] }
Out[9]= L2 m h'[t]

In[10]:= dl = D[la, h]
Out[10]= -g L m Sin[h]

In[11]:= c = D[la, h] /. {ht  $\rightarrow$  h'[t], h  $\rightarrow$  h[t] }
Out[11]= -g L m Sin[h[t]]

In[12]:= EL = c - D[s, t]
Out[12]= -g L m Sin[h[t]] - L2 m h''[t]

In[13]:= EL = Simplify[EL / (m*L) ]
Out[13]= -g Sin[h[t]] - L h''[t]

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In[19]:= w[la_] := Module[{q, f, o, d, c, s, r, EL},
  q = D[la, ht]; f = D[la, h]; o = D[la, htt];
  d = {htt → D[h[t], {t, 2}], ht → D[h[t], t], h → ht[t]};
  c = f /. d;
  s = q /. d;
  r = o /. d;
  EL = c - D[s, t] + D[r, {t, 2}];
  EL]

In[20]:= w[la]
Out[20]=
-g L m Sin[ht[t]] - L2 m h''[t]
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