## Read data

```
In[1]= a = Import["~/t191229a.csv", "CSV"];
In[2]= Dimensions[a]
Out[2]= {9881, 11}
In[3]= b = Transpose[a];
In[4]= Dimensions[b]
Out[4]= {11, 9881}
In[5]= time = b[[1]];

x1 = Tc1, x2 = Tc2, x3 = Tc4, x4 = Tc5, x5 = Tc3 - 1, x6 = Tc3
- 2, x7 = Tc3 - 3
In[6]= x1 = b[[2]]; x2 = b[[3]];
In[7]= x3 = b[[4]]; x4 = b[[5]];
```

## **Time Convolution**

ln[8]:= x5 = b[[6]]; x6 = b[[7]]; x7 = b[[8]];

#### 620 - 810

```
In[9]:= time[[2]]
 \mathsf{Out}[9] = 5.7
 In[10]:= time[[8000]]
Out[10]= 805.5
In[11]:= ListPlot[time]
       1000
        800
        600
Out[11]=
        400
        200
                       2000
                                    4000
                                                 6000
                                                              8000
                                                                          10000
```

20

19

18

500

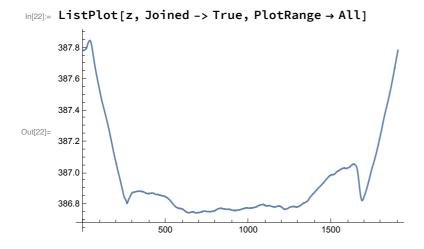
Out[17]=

```
ln[12]:= y1 = {}; y2 = {};
In[26]:= t1 = { };
In[13]:= x1[[1]]
Out[13]= 19.1875
log[14]:= Do[If[time[[i1]] > 619.9 && time[[i1]] < 810.1, AppendTo[y1, x1[[i1]]]],
       {i1, Length[time]}]
In[15]:= Do[If[time[[i1]] > 619.9 && time[[i1]] < 810.1, AppendTo[y2, x2[[i1]]]],
       {i1, Length[time]}]
In[27]:= Do[If[time[[i1]] > 619.9 && time[[i1]] < 810.1, AppendTo[t1, time[[i1]]]],</pre>
       {i1, Length[time]}]
In[16]:= ListPlot[y1, Joined → True, PlotRange → All]
      24
      22
Out[16]=
      20
      18
                     500
                                   1000
                                                 1500
In[17]:= ListPlot[y2, Joined \rightarrow True, PlotRange \rightarrow All]
      22
      21
```

ln[20] = z = (0.1 / 201.) Table[y1.RotateLeft[y2, k], {k, 1, Length[y1]}];

1500

1000



# **Delay Time**

```
ln[28]:= zm = Max[Table[z[[i]], {i, 1, 200}]]
Out[28] = 387.848
In[31]:= X = {}
Out[31]= \{ \}
ln[32]:= Do[If[z[[i]] == zm, AppendTo[x, i]], {i, Length[z]}]
In[34]:= x[[1]]
Out[34]= 41
In[40]:= tl = tl[[x[[1]]]]
Out[40] = 624.
In[39]:= ts = t1[[1]]
Out[39]= 620.
```

## delay time

In[41]:= **tl - ts** 

Out[41]= 4.