

Vision



Object List

bottle,
red cylinder toy,
red triangle toy,
red square toy

Speech2text



Optional

User Command

Can you organize
these toys here?

Episodic
Memory
(Order2Taskplan)

Robot Task Plan

*cylinder toy **grasp** cylinder toy
red cylinder toy **move** box
triangle toy **grasp** triangle toy
triangle toy **move** box
square toy **grasp** square toy
square toy **move** box
...*