CPE301 - SPRING 2019

Midterm 1

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Primary Github address: https://github.com/chicosisco/da_sub.git Directory: repository/cpe301/DesignAssignments/midterm1

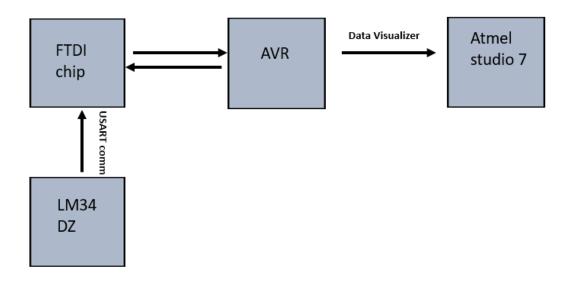
1. COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS

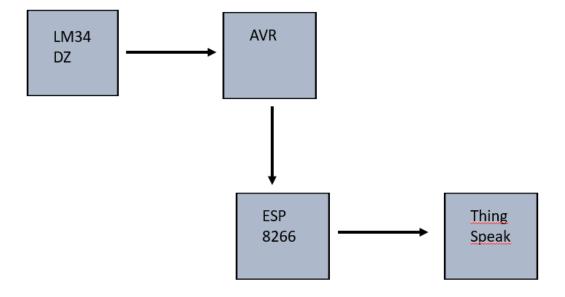
The components used for this assignment are the next:

a. Atmega328p Xplained Mini

- b. ESP8266 module
- c. ESPlorer Software
- d. ESP8266 Flasher Software
- e. FTDI chp
- f. Atmel Studio 7

Block diagrams used for this assignment





2. INITIAL/MODIFIED/DEVELOPED CODE OF Midterm 1

```
#define F CPU 1600000UL
#define BAUD RATE 9600
#include <avr/interrupt.h>
#include <avr/io.h>
#include <util/delay.h>
int over_flow=0;
void usart_init ();
void usart_send (unsigned char ch);
int main (void)
{
       usart_init ();
       /** Setup and enable ADC **/
       ADMUX = (0<<REFS1) | // Reference Selection Bits
       (1<<REFS0) | // AVcc - external cap at AREF
       (O<<ADLAR) // ADC Left Adjust Result
(1<<MUX2) // Analog Channel Selection Bits
       (0<<MUX1)
                      // ADC5 (PC5 PIN27)
       (1<<MUX0);
       ADCSRA = (1<<ADEN) // ADC ENable
```

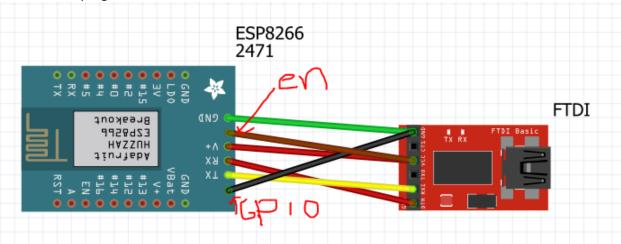
```
// ADC Start Conversion
       (0<<ADSC)
       (0<<ADATE) // ADC Auto Trigger Enable
       (0<<ADIF) // ADC Interrupt Flag
                   // ADC Interrupt Enable
       (0<<ADIE)
                  // ADC Prescaler Select Bits
       (1<<ADPS2)
       (0<<ADPS1)
       (1<<ADPS0);
//DDRB |=(1<<DDB4); // setting PB1 as output</pre>
       TIMSK0 = (1 << TOIE0);
                              // setting initial value for counter
       TCNT0 = 0;
                              // enable global interrupts
       sei();
       TCCROB |=(1<<CSO2)|(1<<CSOO); // setting prescaler to 1024
while (1)
             ADCSRA = (1<<ADSC); //start conversion
             while((ADCSRA&(1<<ADIF))==0);//wait for conversion to finish</pre>
             ADCSRA |= (1<<ADIF);
             if (over_flow==61)
                                    // when TCNT0 overflows 61 times, then the
information is updated
             {
                   //functions
                   void read_adc(void); //Read LM34 to ADC
                   void adc_init(void); // Initialize ADC
                   void usart_init( unsigned int ubrr ); // initialize comms
                   void usart_send(char *data); //usart string
                   volatile unsigned int adc_temp; // raw temperature variable
                   volatile unsigned int temp; // Volatile Fahrenheit temperature
variable
                   char outs[256]; // String being send to usart commands
                   volatile char received_data; //receiving usart comm
                   // commands
                   //AT check
                   char AT[] = "AT\r\n";
                   //Set device mode
                   char AT_CWMODE[] = "AT+CWMODE=1\r\n";
                   // Wifi connection, SSID and Password
                   char AT_CWJAP[] = "AT+CWJAP=\"SSID\",\"Password\"\r\n";
                   //device IP Address Mode
                   char AT_CIPMUX[] = "AT+CIPMUX=0\r\n";
                   // Start connection to Thingspeak.com website, 80
                   char AT_CIPSTART[] =
"AT+CIPSTART=\"TCP\",\"api.thingspeak.com\",80\r\n";
                   // string length=100
                   char AT CIPSEND[] = "AT+CIPSEND=100\r\n";
                   // Send commands
                   _delay_ms(200);
```

```
usart_send(AT);
                   delay ms(5000);
                   usart send(AT CWMODE);
                   _delay_ms(5000);
                   usart_send(AT_CWJAP);
                   _delay_ms(15000);
                   usart_send(AT_CIPMUX);
                   delay ms(10000);
                   usart send(AT CIPSTART);
                   _delay_ms(10000);
                   usart_send(AT_CIPSEND);
                   _delay_ms(5000);
                   PORTC^=(1<<5);
                                 // Read ADC value from LM34
                   read_adc();
                   temp;
                    // Print Data to Thingspeak using the info provided below
                   snprintf(outs, sizeof(outs), "https://api.thingspeak.com/KEY\r\n",
temp);
                   usart send(outs);//send info
                   _delay_ms(10000);
                   int a = ADCL;
                   a = a \mid (ADCH << 8);
                   a = (a/1024.0) * 5000/10;
                   usart_send((a/100)+'0');
                   a = a \% 100;
                   usart_send((a/10)+'0');
                   a = a \% 10;
                   usart_send((a)+'0');
                   usart_send('\r');
                   over_flow=0;
             }
             //_delay_ms(1000);
       }
       return 0;
 }
// timer_0 overflow interrupt
ISR(TIMER0_OVF_vect)
       while (!(TIFR0 & 0X01)==0);
       TCNT0=0X00; //resetting counter to zero
       TIFR0=0X01; // reset the overflow flag
       over_flow++; //increasing overflow counter
}
```

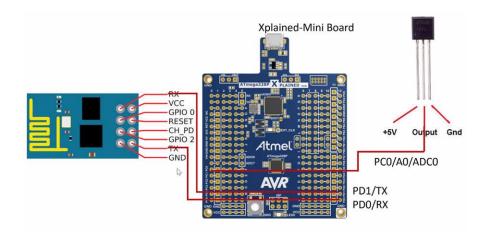
```
void usart_init (void)
{
       UCSROB = (1 << TXENO);
       UCSROC = (1 << UCSZO1) | (1 << UCSZOO);
       UBRROL = F_CPU/16/BAUD_RATE-1;
}
void usart_send (unsigned char ch)
{
       while (! (UCSR0A & (1<<UDRE0))); //wait until UDR0 is empty</pre>
       UDR0 = ch;
                                                                //transmit ch
}
void usart_print(char* str)
       int i = 0;
       while(str[i] != 0)
       usart_send(str[i]);
}
```

3. SCHEMATICS

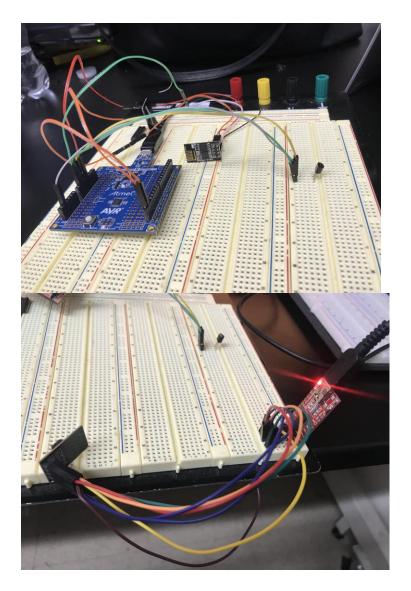
Schematic to program



Schematic to send data to

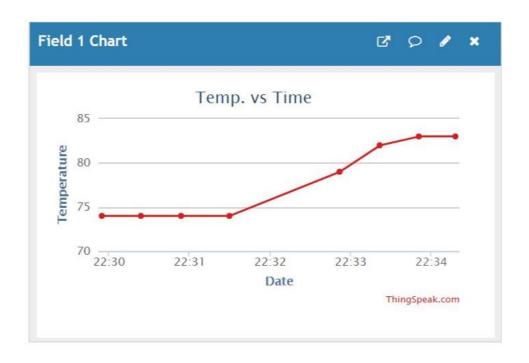


4. SCREENSHOTS OF BOARD SET UP



5. SCREENSHOTS OF EACH TASK OUTPUT





6. VIDEO LINKS OF EACH DEMO

https://youtu.be/VALUa6F95FM

7. GITHUB LINK OF THIS DA

https://github.com/chicosisco/da_sub.git

Student Academic Misconduct Policy

http://studentconduct.unlv.edu/misconduct/policy.html

"This assignment submission is my own, original work".

Francisco Mata Carlos