

SIMULTANEOUS PERTURBATION STOCHASTIC APPROXIMATION

SPSA

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Overview

- BACKPROPAGATION BASED NEURAL NETWORK
- SPSA vs GRADIENT DESCENT
- SPSA BASED NEURAL NETWORK

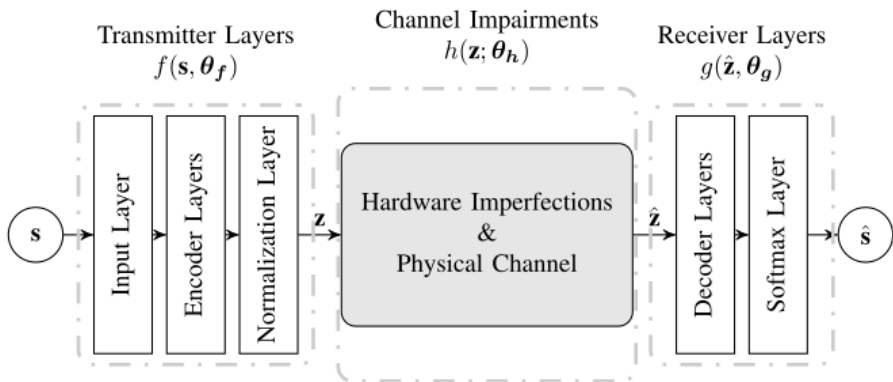


Figure: General Neural Net Framework for an end-to-end communication [2]

Neural Network Configurations

Number of encoder layers	2
Hidden encoder layer dimensions	{16,7}
Number of Decoder layers	2
Hidden decoder layer dimensions	{7, 16}
Batch size	16
Output Layer	LogSoftmax
Activation Function	RELU
Loss Function	NLLLoss
Optimizer	Adam Optimizer

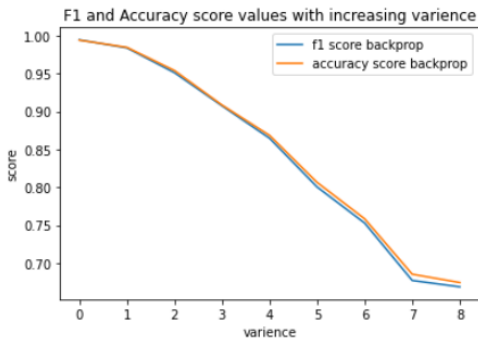


Figure: F1 and Accuracy Score plots for NN with backpropagation

SPSA Algorithm

Algorithm 1 SPSA Algorithm

- 1: **Parameters:** $a > 0, A \geq 0, c > 0, \alpha \in (0, 1], \gamma \in (1/6, 1/2]$ and a distribution \mathcal{D} .
 - 2: **for** $k = 1, 2, 3, \dots$ **do**
 - 3: Sample a vector $\Delta \sim \mathcal{D}$
 - 4: $a_k = \frac{a}{(k+A)^\alpha}$
 - 5: $c_k = \frac{c}{k^\gamma}$
 - 6: $\hat{g} = \frac{J(\theta + c_k \Delta) - J(\theta - c_k \Delta)}{2 c_k \Delta}$
 - 7: $\theta \leftarrow \theta - a_k \cdot \hat{g}$
 - 8: **end for**
-

Figure: SPSA Algorithm [2]

SPSA and Gradient Descent Convergence

Gradient Descent is also proved to converge for Differentiable and convex functions [3], we can use subgradient descent variatio for non-differentiable functions. SPSA method is proved to converge for continuous (need not be differentiable) convex functions [1]

SPSA vs Gradient Descent

We compared Gradient Descent vs SPSA for many functions,

Function	Algorithm	Convergence Value	Average Time Taken	Final Point of Convergence
$y = x^2 + x + 2$	Back Propagation	-0.5	149 ms \pm 2.19 ms	-0.5000000000000027
	SPSA		309 ms \pm 4.2 ms	-0.5000000000000001
$y = x \sin x$	Back Propagation	-5	152 ms \pm 2.07 ms	4.913180439434884
	SPSA		315 ms \pm 6.03 ms	4.91317337
$y = x $	Back Propagation	0	255 ms \pm 115 ms	0.0085930954226148
	SPSA		366 ms \pm 106 ms	-8.93737133e - 20

In the third case, we used SubGradient Descent instead of Gradient Descent as we can't use Gradient Descent for a non-differentiable function. This clearly shows SPSA can dominate over subgradient Descent for non-differentiable function at the cost of time.

For a convex function $f : \mathbb{R}^n \rightarrow \mathbb{R}$,

$$f(y) \geq f(x) + \nabla f(x)^T (y - x)$$

for all x, y . Hence, linear approximation always underestimates f .

A **subgradient** of convex $f : \mathbb{R}^n \rightarrow \mathbb{R}$ at any x is $g \in \mathbb{R}^n$ such that,

$$f(y) \geq f(x) + \nabla g^T (y - x)$$

for all y ,

- Always exist
- If f differentiable at x , then $g = \nabla f(x)$

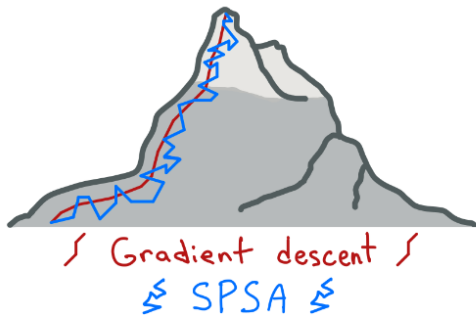


Figure: Image taken from the Internet showing convergence paths taken by SPSA and Gradient Descent [\[link\]](#)

Neural Network with SPSA

Using the algorithm mentioned in the above figure 3 we implemented a Neural Network with the following values of the SPSA hyperparameters and the general hyperparameters as mentioned in the above table 5.

a	0.05
A	25
c	0.1
alpha	0.9
beta	0.3

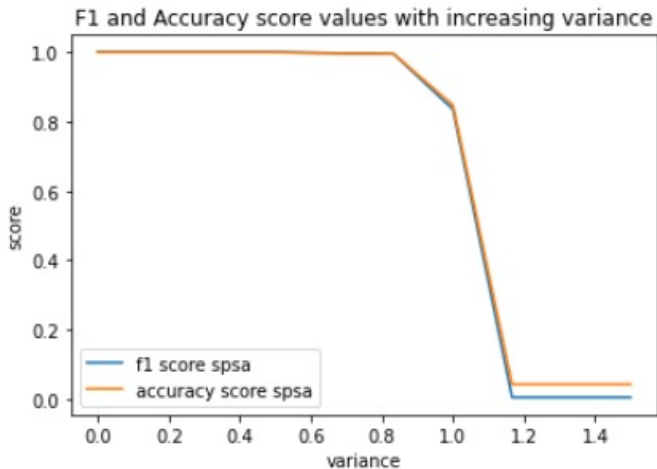


Figure: Neural Net with SPSA

References

- [1] Ying He, M.C. Fu, and S.I. Marcus. “Convergence of simultaneous perturbation stochastic approximation for nondifferentiable optimization”. In: *IEEE Transactions on Automatic Control* 48.8 (2003), pp. 1459–1463. DOI: 10.1109/TAC.2003.815008.
- [2] Vishnu Raj and Sheetal Kalyani. “Backpropagating Through the Air: Deep Learning at Physical Layer Without Channel Models”. In: *IEEE Communications Letters* 22.11 (2018), pp. 2278–2281. DOI: 10.1109/LCOMM.2018.2868103.
- [3] Wardi Shapiro A. “Y. Convergence analysis of gradient descent stochastic algorithms.”. In: *Journal of Optimization Theory and Applications* 91.2 (1996), pp. 439–454. DOI: 10.1007/BF02190104.