

$$1. \quad G(s) = \frac{(s+1)(s+2)}{s(s+3)(s+4)} = \frac{A}{s} + \frac{B}{s+3} + \frac{C}{s+4}$$

$$= \frac{1/6}{s} + \frac{-2/3}{s+3} + \frac{3/2}{s+4}$$

$$\begin{array}{r} A(1 \ 7 \ 12) \\ B(1 \ 4 \ 0) \\ C(1 \ 3 \ 6) \\ \hline 1 \ 3 \ 2 \end{array}$$

$$H_s = \frac{C}{s+\alpha} \rightarrow H_z = \frac{Cz}{z-e^{-\alpha T}}$$

$$\rightarrow G(z) = \frac{1}{6} \frac{z}{z-1} - \frac{2}{3} \frac{z}{z-e^{-3T}} + \frac{3}{2} \frac{z}{z-e^{-4T}}, \quad T=0.1$$

$$G(s) = \frac{27}{(s+2)(s^2+4s+13)} = \frac{27}{(s+2)((s+2)^2+3^2)}$$

$$= \frac{3}{s+2} + \frac{-3s-6}{(s+2)^2+3^2}$$

$$\Rightarrow \frac{3z}{z-e^{-2T}} - 3 \frac{z^2 - ze^{-2T} \cos(3t)}{z^2 - 2ze^{-2T} \cos(3t) e^{-4T}}, \quad T=0.1$$

$$\begin{array}{r} q(1 \ 4 \ 15) \\ A(1 \ 2 \ 0) \\ B(0 \ 1 \ 2) \end{array}$$

2.

a)

```
>> clear
>> syms s
>> Ts=(s+1)*(s+2)/s/(s+3)/(s+4)

Ts =

((s + 1)*(s + 2))/(s*(s + 3)*(s + 4))

>> Td=ztrans(ilaplace(Ts))

Td =

z/(6*(z - 1)) - (2*z)/(3*(z - exp(-3))) + (3*z)/(2*(z - exp(-4)))
```

b)

```
>> clear
>> syms s
>> Ts=27/((s+2)*(s^2+4*s+13))

Ts =

27/((s + 2)*(s^2 + 4*s + 13))

>> Td=ztrans(ilaplace(Ts))

Td =

(3*z)/(z - exp(-2)) + (3*z*exp(2)*(cos(3) - z*exp(2)))/(exp(4)*z^2 - 2*cos(3)*exp(2)*z + 1)
```

3.

$$F(z) = \frac{(z+1)(z+0.3)(z+0.4)}{z(z-0.2)(z-0.5)(z-0.7)} = \frac{-1.7143}{z} + \frac{12}{z-0.2} + \frac{-36}{z-0.5} + \frac{26.7143}{z-0.7}$$

$$= z^{-1} \left(-1.7143 + \frac{12z}{z-0.2} + \dots \right)$$

$$\rightarrow f(k) = -1.7143 \delta(k-1) + 12 \times 0.2^{(k-1)} u(k-1) - 36 \times 0.5^{(k-1)} u(k-1) + 26.7143 \times 0.7^{(k-1)} u(k-1)$$

$$= -1.7143 \delta(k-1) + (60 \times 0.2^k - 72 \times 0.5^k + 38.1633 \times 0.7^k) u(k-1) \quad \star$$

4.

```
>> syms z
>> F = ((z+1)*(z+0.3)*(z+0.4))/(z*(z-0.2)*(z-0.5)*(z-0.7))

F =

((z + 1)*(z + 2/5)*(z + 3/10))/(z*(z - 1/2)*(z - 1/5)*(z - 7/10))

>> iztrans(F)
|
ans =

60*(1/5)^n - 72*(1/2)^n - (12*kronckerDelta(n - 1, 0))/7 + (1870*(7/10)^n)/49 - (1282*kronckerDelta(n, 0))/49
```

5.

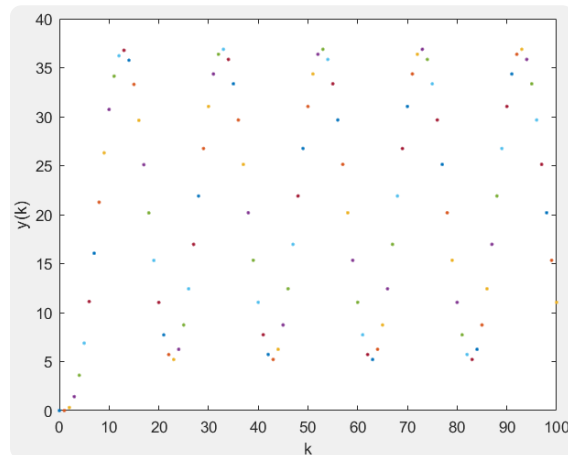
$$a. G(z) = \frac{Y(z)}{U(z)} = \frac{z+1}{(z-1)(z-0.7)} = \frac{z+1}{z^2-1.7z+0.7}$$

$$Y(z)(z^{-1}-1.7z^{-2}+0.7z^{-2}) = U(z)(z^{-1}+z^{-2})$$

$$\rightarrow y(k) - 1.7y(k-1) + 0.7y(k-2) = u(k-1) + u(k-2) \quad \star$$

b.

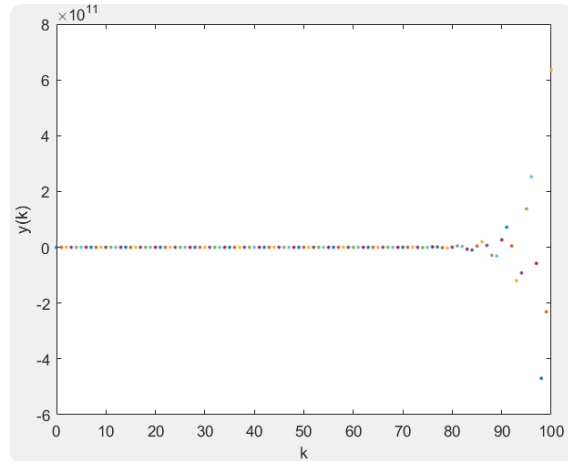
```
>> clear
>> syms k z;
>> T=0.01;
>> u=sin(10*pi*k*T);
>> Uz=ztrans(u);
>> Yz=(z+1)/((z-1)*(z-0.7))*Uz;
>> y(k)=iztrans(Yz,k);
>> for k=0:100
    yd=y(k);
    plot(k,yd,'.')
    hold on
end
>> xlabel('k');
>> ylabel('y(k)');
```



$$c. \quad T(z) = \frac{G}{1+G} = \frac{\frac{z+1}{(z-1)(z-0.7)}}{1 + \frac{z+1}{(z-1)(z-0.7)}} = \frac{z+1}{z^2 - 0.7z + 1.7} \quad \times$$

d.

```
>> clear
>> syms k z;
>> T=0.01;
>> u=sin(10*pi*k*T);
>> Uz=ztrans(u);
>> Yz=(10*(z+1)/(z^2-0.7*z+1.7))*Uz;
>> y(k)=iztrans(Yz,k);
>> for k=0:100
    yd=y(k);
    plot(k,yd,'.')
    hold on
end
>> xlabel('k');
>> ylabel('y(k)');
```



$$6. \quad G(z) = (1 - z^{-1}) \mathcal{Z}\left(\frac{G(s)}{s}\right) = (1 - z^{-1}) \left(\frac{Tz^{-1}}{(1-z^{-1})^2} - \frac{1}{1-z^{-1}} + \frac{1}{1-e^{-T}z^{-1}} \right)$$

$$\frac{G(s)}{s} = \frac{1}{s^2(s+1)}, \quad y(t) = t - 1 + e^{-t}$$

$$\therefore G(z) = (z-1) \left(\frac{T}{(z-1)^2} + \frac{1}{z-e^{-T}} - \frac{1}{z-1} \right)$$

by matlab

$$\rightarrow T(z) = \frac{G}{1+G} = - \frac{ze^T - Te^T - z + T - e^T + 1}{e^T z^2 + (Te^T - 2e^T)z + e^T - T}$$

jury array:

$$\begin{array}{ccc} e^T & Te^T - 2e^T & e^T - T \\ e^T - T & Te^T - 2e^T & e^T \end{array} \Rightarrow e^T > 0 \rightarrow \text{unboundary}$$

$$\begin{array}{cc} 2T - Te^{-T} & T(T-2) \\ T(T-2) & 2T - Te^{-T} \end{array} \Rightarrow 2 > Te^{-T} \rightarrow \text{unboundary}$$

$$\begin{array}{c} 2T - Te^{-T} - \frac{T^2(T-2)^2}{2T - Te^{-T}} \end{array} \Rightarrow 1 > \left(\frac{T(T-2)}{2T - Te^{-T}} \right)^2$$

$$0 < T < 3.922 \quad \times$$

$$\begin{array}{r}
 7. \quad \begin{array}{cccccc}
 1 & 2.6 & -0.56 & -2.05 & 0.0775 & 0.35 \\
 0.35 & 0.0775 & -2.05 & -0.56 & 2.6 & 1
 \end{array} \\
 \hline
 \begin{array}{cccccc}
 0.8775 & 2.5729 & 6.1575 & -1.8540 & -0.8325 & \\
 -0.8325 & -1.8540 & 0.1575 & 2.5729 & 0.8775 & \\
 \hline
 0.0877 & 0.8140 & 0.3069 & 0.5869 & & \\
 0.5869 & 0.3069 & 0.8140 & 0.0877 & & \\
 \hline
 -3.8407 & & & & &
 \end{array}
 \end{array}$$

→ system is not stable *

$$8. \quad a) G(z) = \frac{4z^{-1} - 4z^{-2} + 8.4z^{-3}}{1 + 12z^{-1} + 7.2z^{-2} + 3.2z^{-3}}$$

$$x(k+1) = Ax(k) + Bu(k), \quad y(k) = Cx(k)$$

$$\text{controllable canonical form: } A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3.2 & -7.2 & -12 \end{pmatrix} \quad B = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad C = \begin{pmatrix} 8.4 \\ -4 \\ 4 \end{pmatrix}^T$$

$$\text{observable ...: } A = \begin{pmatrix} 0 & 0 & -3.2 \\ 1 & 0 & -7.2 \\ 0 & 1 & -12 \end{pmatrix} \quad B = \begin{pmatrix} 8.4 \\ -4 \\ 4 \end{pmatrix} \quad C = (0 \ 0 \ 1)$$

$$b) \quad z^3 + 12z^2 + 7.2z + 3.2 = 0$$

$$c) \quad \begin{array}{cccc}
 1 & 12 & 7.2 & 3.2 \\
 3.2 & 7.2 & 12 & 1 \\
 \hline
 -9.24 & & &
 \end{array}$$

→ negative, not stable