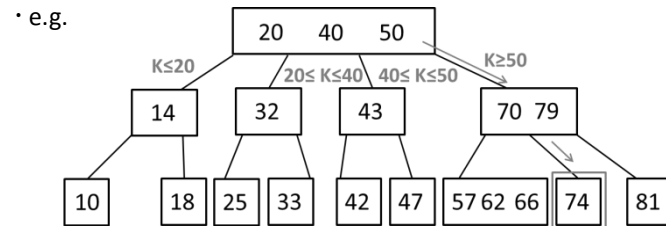


505 22240 / ESOE 2012 Data Structures: Lecture 12

2-3-4 Trees and Sorting

§ 2-3-4 Trees

- Perfectly balanced tree.
- `find()`, `insert()`, and `remove()` take worst-case $O(\log n)$ time.
- Each node has 2, 3, or 4 children, except leaves, which are all at bottom level.
- Each node stores 1, 2, or 3 entries.
- # of children is # of entries + 1 or zero



- ★ “Bottom-up” 2-3-4 trees: the effects of node splits at the bottom of the tree can work their way back up toward the root.
- ★ We’ll discuss “top-down” 2-3-4 trees (faster), in which insertion and deletion finish at the leaves.

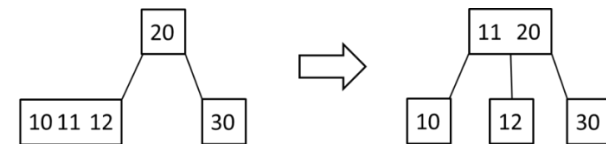
© Operations

① Entry `find(const K& k);`

- Start at root. Check for `k` at each node. If it’s not present, move down to appropriate child. Continue until `k` is found, or not found at leaf.
- e.g. `find(74)`
- You can define an inorder traversal on 2-3-4 trees analogous to binary trees and visit keys in sorted order.

② `void insert(const K& k, const V& v);`

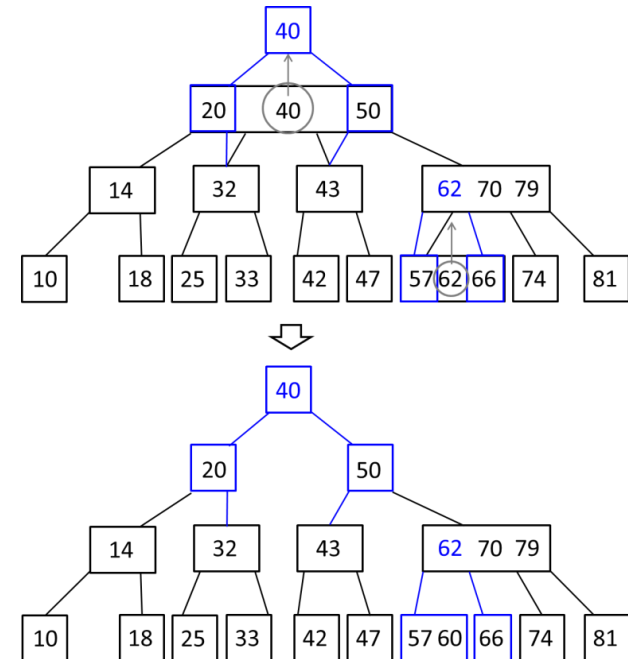
- Walks down tree in search of `k`, like `find()`.
- If it finds `k`, it proceeds to `k`’s “left child” and continues.
- Whenever `insert()` encounters a 3-key node, middle key is placed in the parent node (parent has at most 2 keys; has room for third).
- The other two keys in the 3-key node are split into two separate 1-key nodes.
- e.g. (portion trees)



e.g. `insert(60)`

Kick middle key (40) upstairs.

Create new root to hold 40.



- ★ Why we split 3-key nodes: (and move its middle key up one level)
- To make sure there's room for new key in leaf.
- To make room for any key that's kicked upstairs.
- ★ Sometimes insertion increases depth of tree by creating a new root.

③ `void remove (const K& k);` similar to `remove()` on binary trees.

- Find key k.

If it's in leaf, remove it.

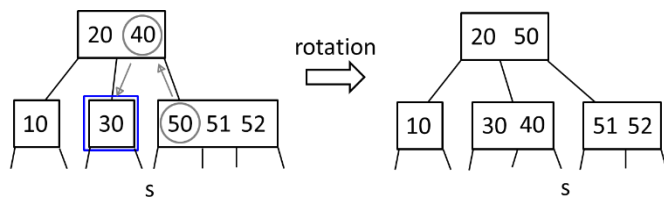
If in internal node, replace it with entry with next higher key. That entry is always in a leaf. In either case, you remove an entry from a leaf in the end.

⇒ Eliminates 1-key nodes (except the root) so key can be removed from leaf without emptying it.

Rule1: `remove()` encounters 1-key node (except root)

⇒ Tries to steal key from an adjacent sibling.

- e.g. `remove(30)`

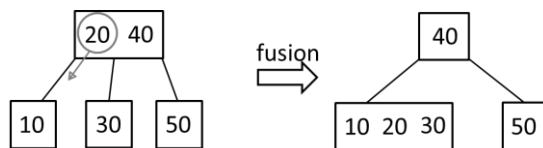


Rule2:

- If no adjacent sibling has > 1 key, steal a key from parent.

⇒ Parent (unless it's root) has ≥ 2 keys.

- e.g. `remove(10)`



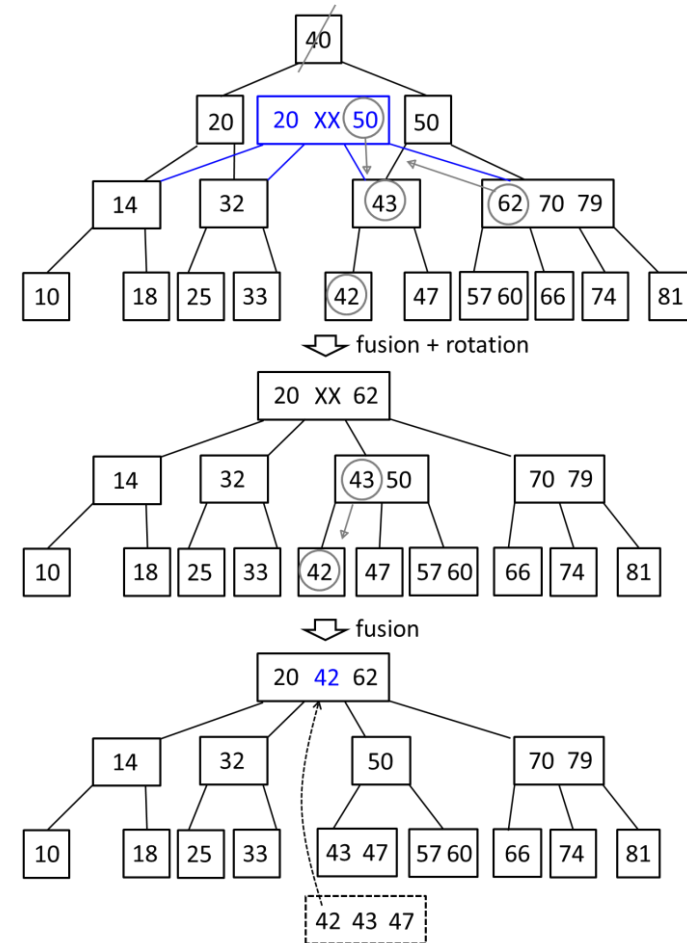
- The sibling is also absorbed, 1-key node becomes 3-key node.

Rule3:

- If parent is root & contains only one key, and sibling has only one key.

⇒ Fuse into 3-key node → the new root. Depth of tree decreases by one.

- e.g. `remove(40)`



◎Running times

• A 2-3-4 tree with depth d has between 2^d and 4^d leaves.

• Total # of nodes is $n \geq 2^{d+1} - 1$

$$d \in O(\log n)$$

• Time spent visiting node $\in O(1)$, per node.

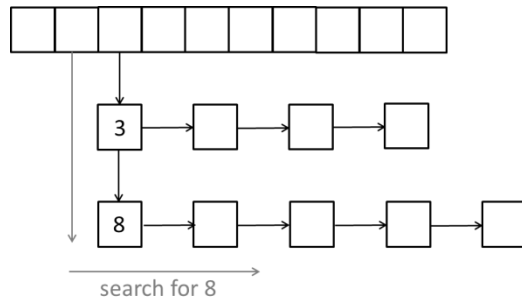
• $\text{find}()$, $\text{insert}()$, $\text{remove}()$: worst-case times: $O(d) = O(\log n)$.

• Compare with binary search tree: $\underline{\Theta(n)}$ worst-case time.

◎Another approach to duplicate keys

• Collect all entries that share a common key in one node.

• Each node's entry is list of entries.



• Simplifies implementation of $\text{findAll}()$, which finds all entries with a specified key.

§ Sorting

◎Insertion Sort

• Runs in $O(n^2)$ time, employ a list S .

• Invariant: S is sorted.

• Algorithm:

```
Start with empty list S & unsorted list I of n items
for(each item x in I) {
    Insert x into S, in sorted order
}
```

• If S is linked list, $\Theta(n)$ worst-case time to find right position.

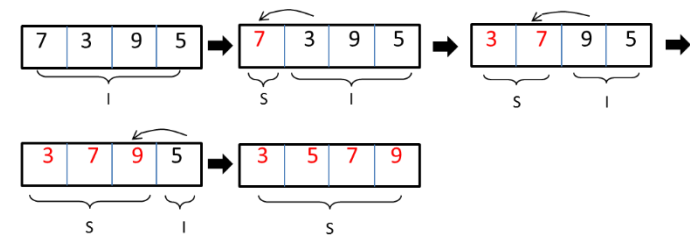
• If S is array, $\Theta(n)$ worst-case time to shift higher items over.

• If S is array, insertion sort is in-place.

• *In-place sort* is a sorting algorithm that keeps the sorted items in the same array.

• If S is a balanced search tree (e.g., 2-3-4 tree), running time $\in O(n \log n)$.

• e.g.



◎Selection Sort

• Invariant : S is sorted.

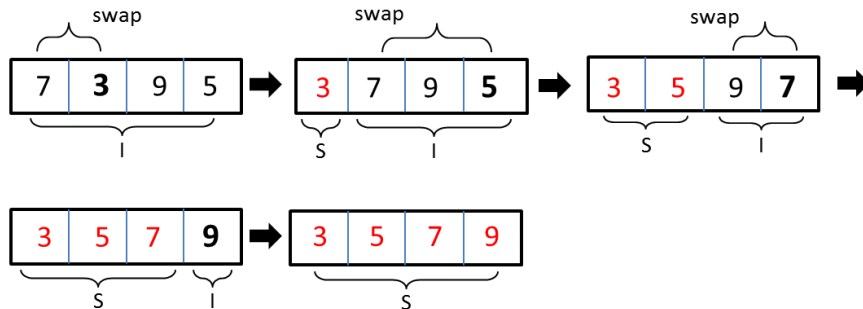
• Algorithm:

```
Start with empty list S & unsorted list I of n items
for(i=0; i<n; i++) {
    x = item in I with smallest key.
    Remove x from I.
    Append x to end of S.
}
```

- Whether S is array or linked list, $\Theta(n^2)$ time even in best case.

- In-place selection sort.

- e.g.



©Heapsort

- Selection sort where I is a heap.

- Algorithm:

```

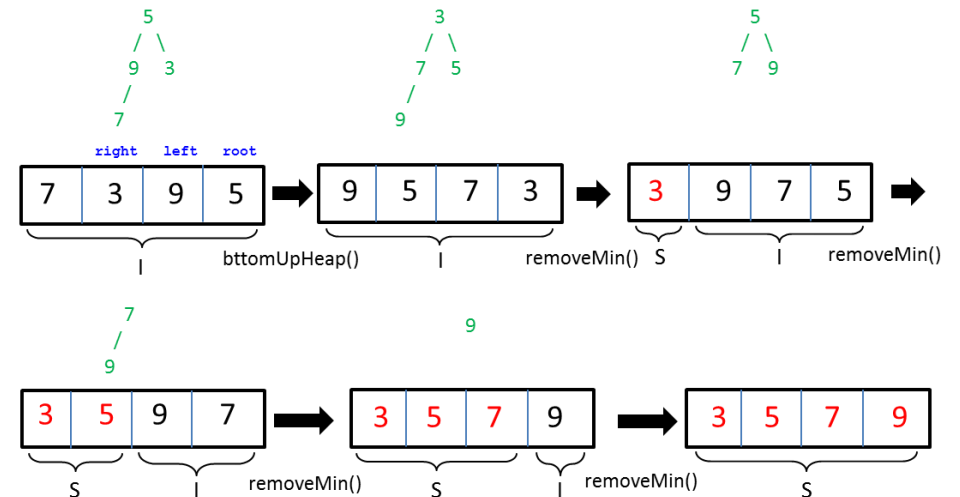
Start with empty list S and unsorted list I of n items
Toss all items in I onto heap h (ignoring heap-order)
h.bottomUpHeap(); ← O(n) time
// Enforces the heap-order property
for (i=0; i<n; i++) {
    x = h.removeMin(); ← O(log n) time
    Append x to the end of S.
}

```

- Heapsort runs in $O(n \log n)$ time.

- In-place: maintain heap backward at the end of the array (in reverse order).

- e.g.



- Excellent for arrays, clumsy for linked lists.

©Mergesort

- Mergesort is based on the observation that it's possible to merge 2 sorted lists into one sorted list in linear time.

- In fact, we can do it with queues:

Let Q1 & Q2 be 2 sorted queues.

Let Q be empty queue.

while (neither Q1 nor Q2 is empty) {

 item1 = Q1.front();

 item2 = Q2.front();

 Move smaller of item1 & item2 from present queue to end of Q.

}

Concatenate remaining non-empty queue (Q1 or Q2) to end of Q.

- Mergesort is a recursive divide-and-conquer algorithm:

Start with unsorted list I of n items.

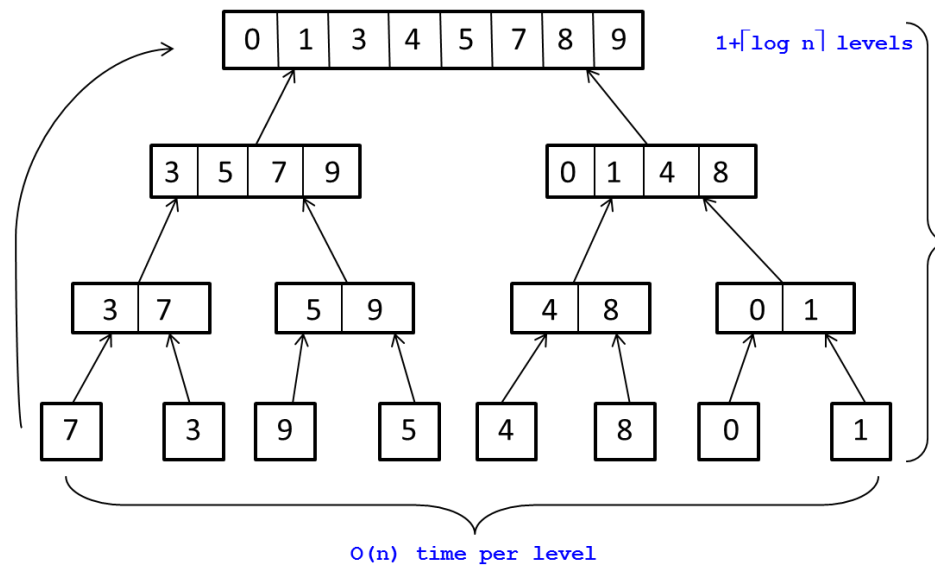
Break I into halves I1 & I2, having $\lceil n/2 \rceil$ & $\lfloor n/2 \rfloor$ items.

Sort I1 recursively, yielding S1.

Sort I2 recursively, yielding S2.

Merge S1 & S2 into one sorted list S.

- e.g. the diagram (tree) shown below is not a data structure, but a sequence of recursive calls.



- $O(n \log n)$ time.
- Natural for linked lists.
- Not in-place sort for arrays.