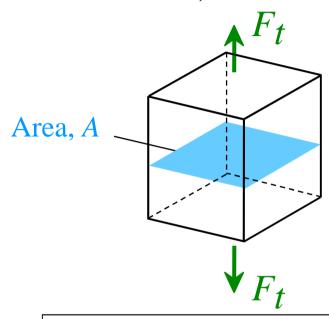
# Chapter 8: Mechanical Properties

### ISSUES TO ADDRESS...

- Stress and strain: What are they and why are they used instead of load and deformation?
- Elastic behavior: When loads are small, how much deformation occurs? What materials deform least?
- Plastic behavior: At what point does permanent deformation occur? What materials are most resistant to permanent deformation?
- Toughness and ductility: What are they and how do we measure them?

# **Engineering Stress**

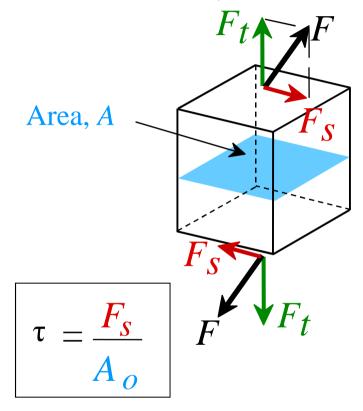
• Tensile stress,  $\sigma$ :



$$\sigma = \frac{F_t}{A_o} = \frac{lb_f}{in^2} \text{ or } \frac{N}{m^2}$$

original area before loading

• Shear stress, τ:

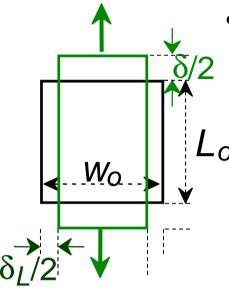


:. Stress has units:  $N/m^2$  or  $lb_f/in^2$ 

# **Engineering Strain**

• Tensile strain:

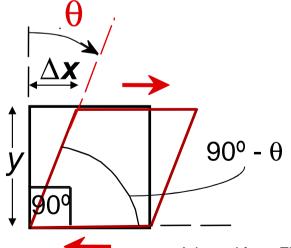
$$\varepsilon = \frac{\delta}{L_o}$$



• Lateral strain:

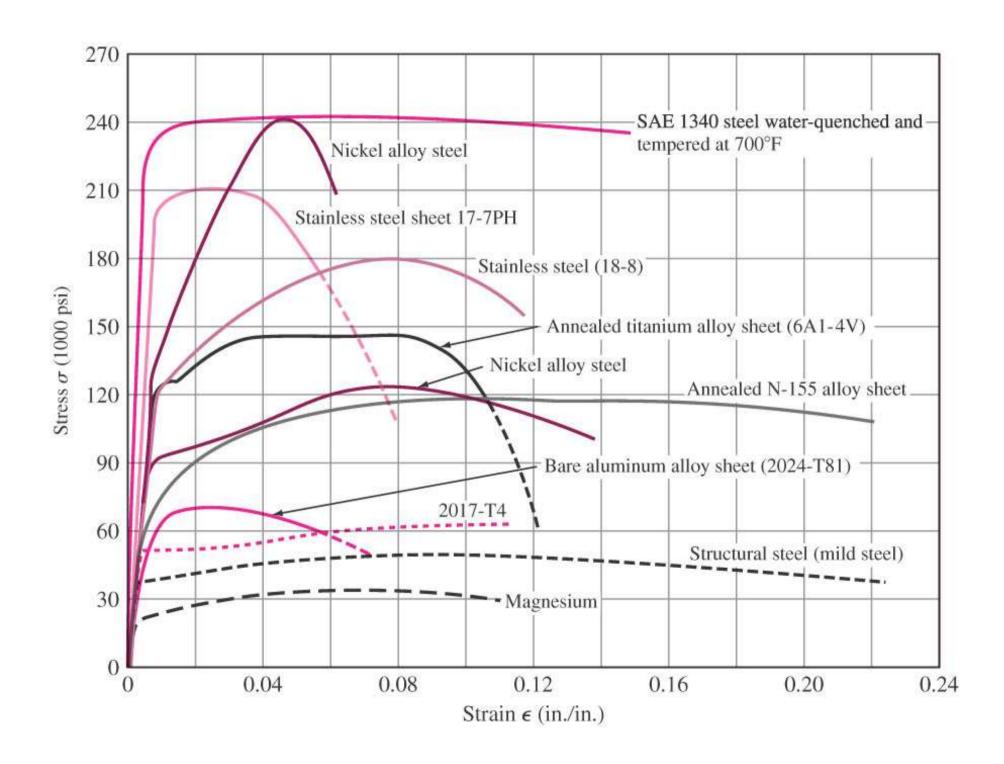
$$\varepsilon_L = \frac{-\delta_L}{W_O}$$

• Shear strain:



$$\gamma = \Delta x/y = \tan \theta$$

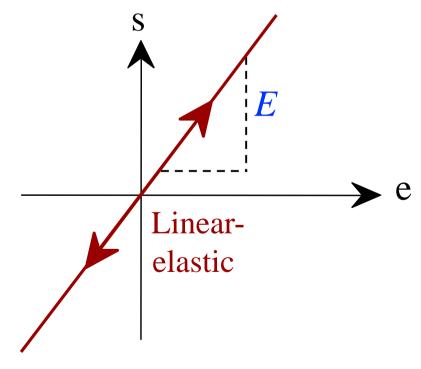
Strain is always dimensionless.

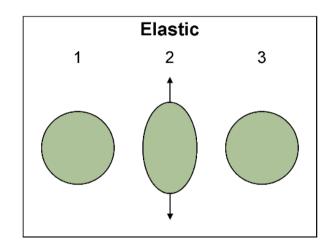


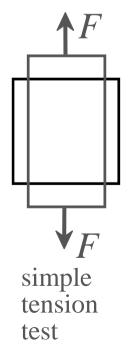
### **Linear Elastic Properties**

- Modulus of Elasticity, E: (also known as Young's modulus)
- Hooke's Law:

$$\sigma = E \varepsilon$$







### Poisson's ratio, n

### • Poisson's ratio, v:

$$\mathbf{v} = -\frac{\varepsilon_{x}}{\varepsilon_{z}} = -\frac{\varepsilon_{y}}{\varepsilon_{z}}$$

metals:  $v \sim 0.33$ 

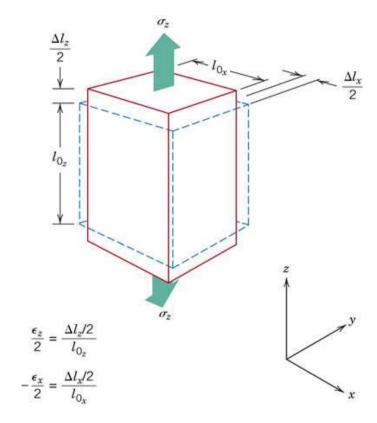
ceramics: v ~ 0.25

polymers:  $v \sim 0.40$ 

### Units:

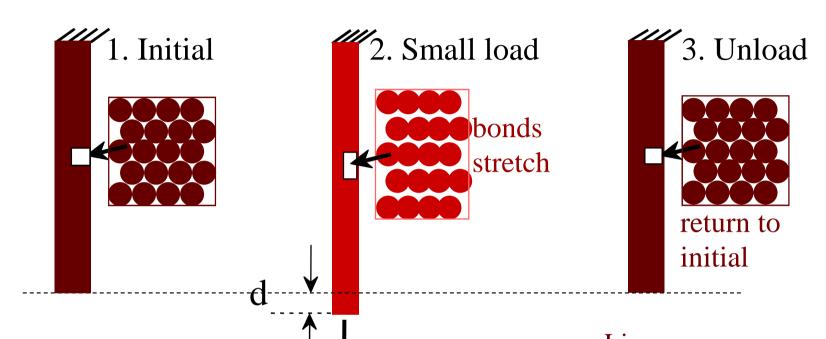
*E*: [GPa] or [psi]

v: dimensionless



- v > 0.50 density increases
- v < 0.50 density decreases (voids form)

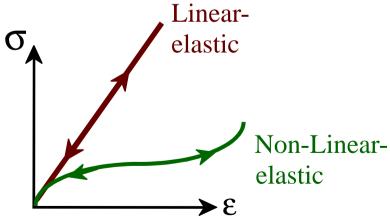
### **Elastic Deformation**



• Hooke's Law:

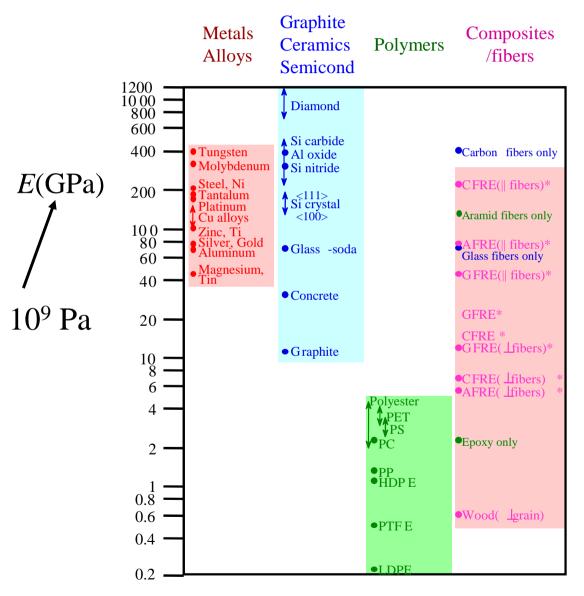
$$\sigma = E \varepsilon$$

$$\sigma = \frac{F}{A}$$
  $\varepsilon = \frac{\delta}{L_o}$ 



Elastic means reversible!

## Young's Moduli: Comparison



Based on data in Table B2, Callister 7e.

Composite data based on reinforced epoxy with 60 vol% of aligned carbon (CFRE), aramid (AFRE), or glass (GFRE) fibers.

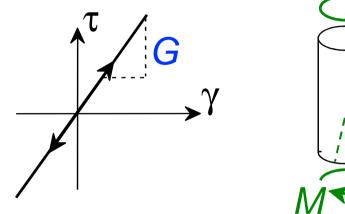
### Other Elastic Properties

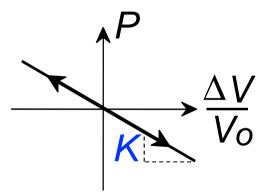
 Elastic Shear modulus, G:

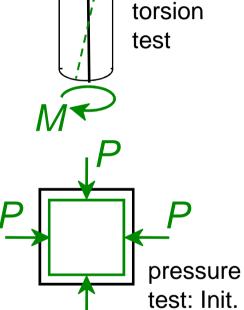
$$\tau = G \gamma$$

 Elastic Bulk modulus, K:

$$P = -K \frac{\Delta V}{V_O}$$







simple

 $vol = V_O$ .

Vol chg.

$$= \Delta V$$

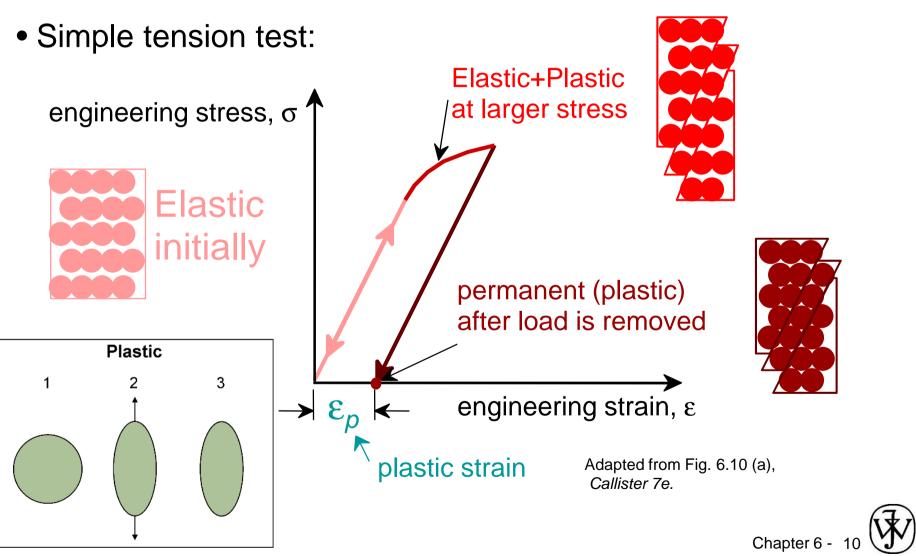
$$G = \frac{E}{2(1+v)}$$

$$G = \frac{E}{2(1+v)} \qquad K = \frac{E}{3(1-2v)}$$

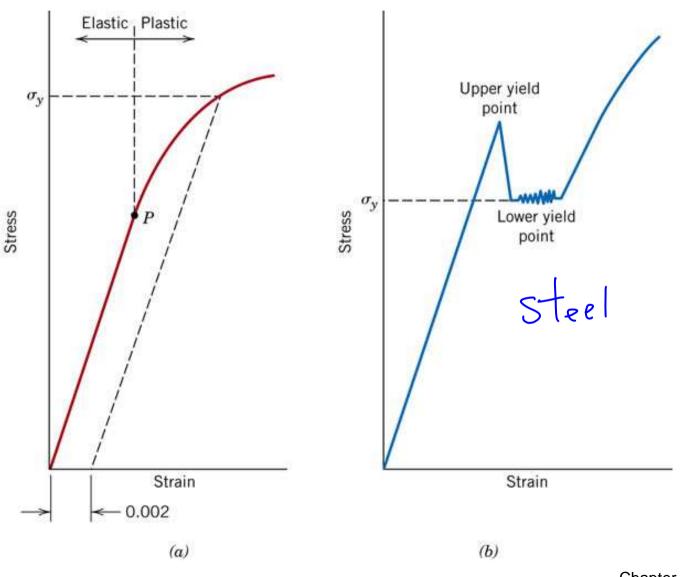
Special relations for isotropic materials:

### **Plastic (Permanent) Deformation**

(at lower temperatures, i.e.  $T < T_{melt}/3$ )



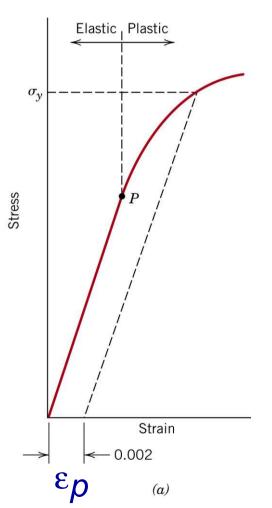
## Figure 6.10



# Yield Strength, σ<sub>y</sub>

• Stress at which noticeable plastic deformation has

occurred.



when  $\varepsilon_p = 0.2\%$ 

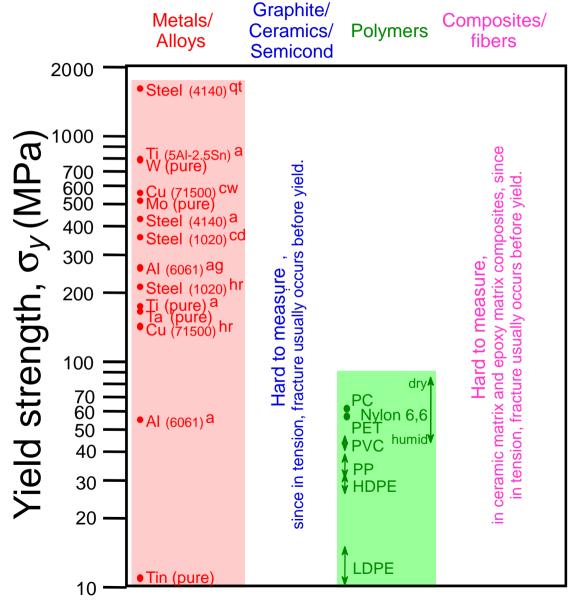
 $\sigma_y$  = yield strength

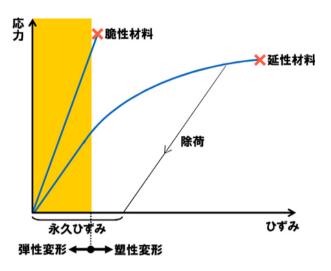
Note: for 2 inch sample

$$\varepsilon = 0.002 = \Delta z/z$$

$$\Delta z = 0.004$$
 in

# **Yield Strength: Comparison**





### Room T values

Based on data in Table B4, *Callister 7e*.

a = annealed

hr = hot rolled

ag = aged

cd = cold drawn

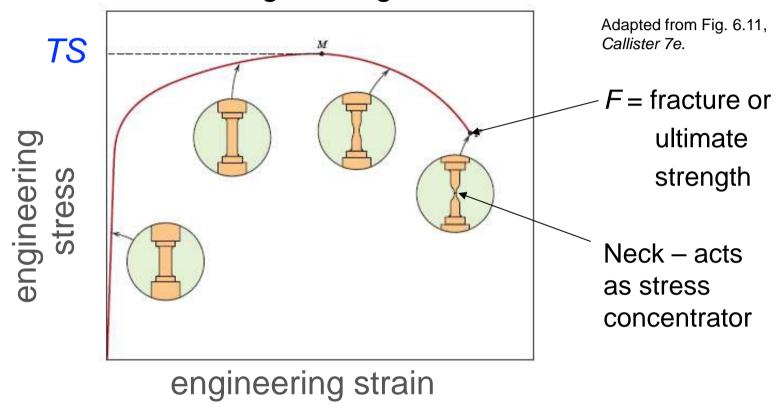
cw = cold worked

qt = quenched & tempered



### **Tensile Strength, TS**

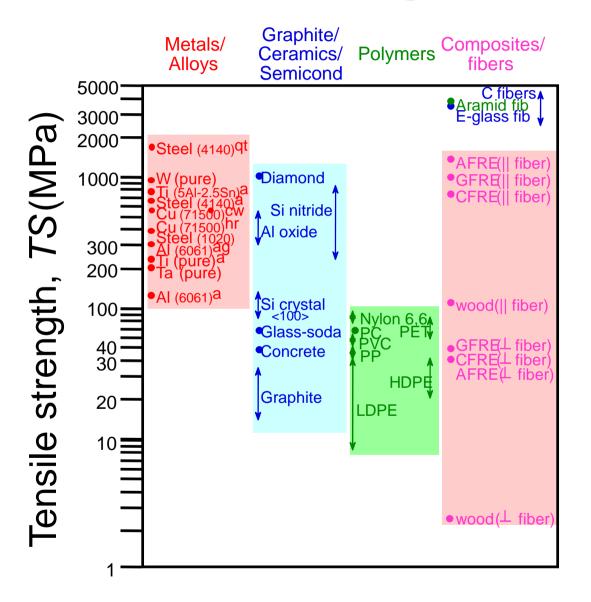
• Maximum stress on engineering stress-strain curve.

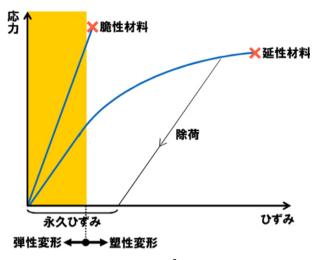


- Metals: occurs when noticeable necking starts.
- Polymers: occurs when polymer backbone chains are aligned and about to break.



# **Tensile Strength: Comparison**





Based on data in Table B4, *Callister 7e*.

a = annealed

hr = hot rolled

ag = aged

cd = cold drawn

cw = cold worked

qt = quenched & tempered

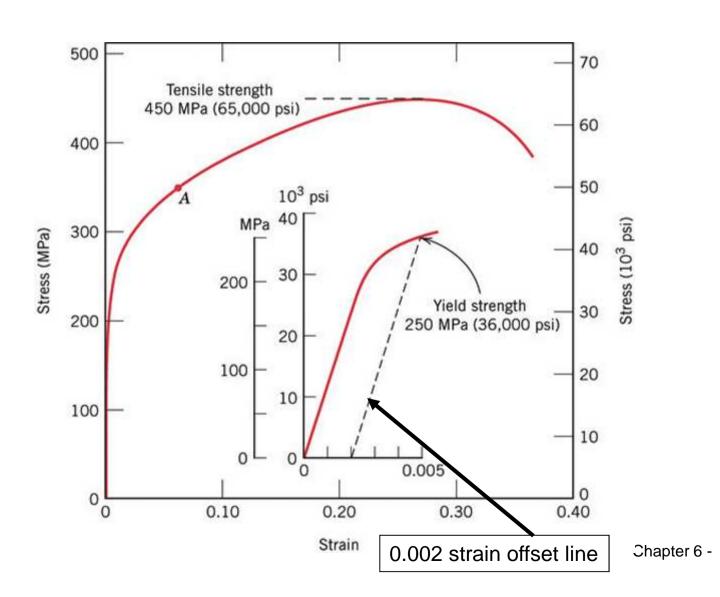
AFRE, GFRE, & CFRE =

aramid, glass, & carbon fiber-reinforced epoxy composites, with 60 vol%

fibers.

Chapter 6 - 15

# Mechanical Property Determinations from Stress-Strain Plot (Example 6.3)



# Solution (6.3)

rise over the run, or the change in stress divided by the corresponding change in strain; in mathematical terms,

$$E = \text{slope} = \frac{\Delta \sigma}{\Delta \epsilon} = \frac{\sigma_2 - \sigma_1}{\epsilon_2 - \epsilon_1}$$
 (6.10)

Inasmuch as the line segment passes through the origin, it is convenient to take both  $\sigma_1$  and  $\epsilon_1$  as zero. If  $\sigma_2$  is arbitrarily taken as 150 MPa, then  $\epsilon_2$  will have a value of 0.0016. Therefore,

$$E = \frac{(150 - 0) \text{ MPa}}{0.0016 - 0} = 93.8 \text{ GPa}$$

which is very close to the value of 97 GPa given for brass in Table 6.1.

- **(b)** The 0.002 strain offset line is constructed as shown in the inset; its intersection with the stress-strain curve is at approximately 250 MPa, which is the yield strength of the brass.
- (c) The maximum load that can be sustained by the specimen is calculated by using Equation 6.1, in which  $\sigma$  is taken to be the tensile strength, from Figure 6.12, 450 MPa. Solving for F, the maximum load, yields

$$F = \sigma A_0 = \sigma \left(\frac{d_0}{2}\right)^2 \pi$$

$$= (450 \times 10^6 \text{ N/m}^2) \left(\frac{12.8 \times 10^{-3} \text{ m}}{2}\right)^2 \pi = 57,900 \text{ N}$$

(d) To compute the change in length,  $\Delta l$ , in Equation 6.2, it is first necessary to determine the strain that is produced by a stress of 345 MPa. This is accomplished by locating the stress point on the stress-strain curve, point A, and reading the corresponding strain from the strain axis, which is approximately 0.06. Inasmuch as  $l_0 = 250$  mm, we have

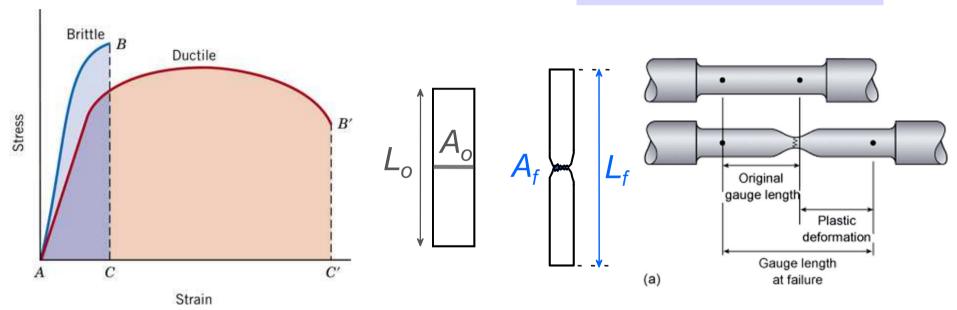
$$\Delta l = \epsilon l_0 = (0.06)(250 \text{ mm}) = 15 \text{ mm}$$



# **Ductility**

• Plastic tensile strain at failure:

$$\%EL = \frac{L_f - L_o}{L_o} \times 100$$

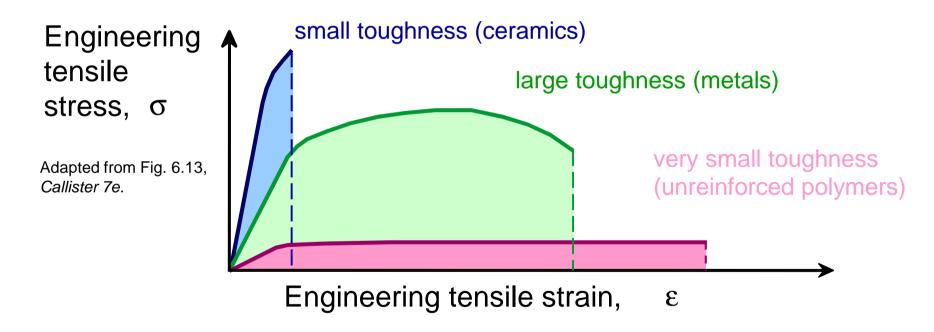


• Another ductility measure:

$$%RA = \frac{A_o - A_f}{A_o} \times 100$$

### **Toughness**

- Energy to break a unit volume of material
- Approximate by the area under the stress-strain curve.



Brittle fracture: elastic energy

Ductile fracture: elastic + plastic energy



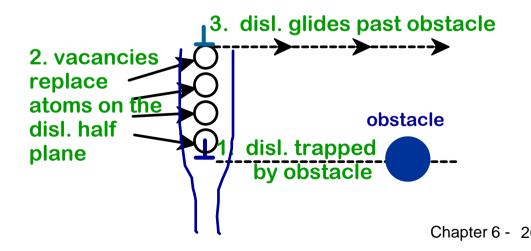
### σ-ε Behavior vs. Temperature

• Results for polycrystalline iron:

Adapted from Fig. 6.14 of Callister 6e.

800
600
400
200° C
25° C
25° C
300 C
25° C
300 C

- σy and TS decrease with increasing test temperature.
- %EL increases with increasing test temperature.
- Why? Vacancies help dislocations past obstacles.



### **True Stress & Strain**

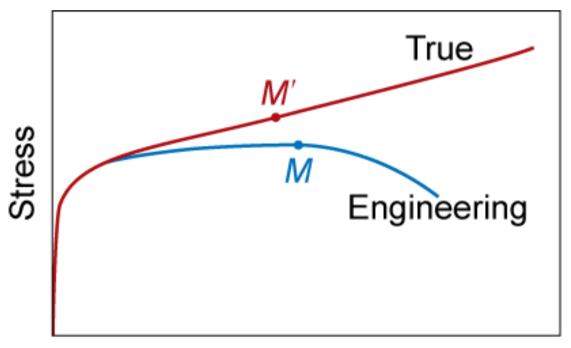
Note: S.A. changes when sample stretched

$$\sigma_T = F/A_i$$

$$\sigma_{T} = F/A_{i}$$
  $\sigma_{T} = \sigma(1+\varepsilon)$ 
 $\varepsilon_{T} = \ln(\ell_{i}/\ell_{o})$   $\varepsilon_{T} = \ln(1+\varepsilon)$ 

$$\sigma_{\tau} = \sigma(1+\varepsilon)$$

$$\varepsilon_T = \ln(1+\varepsilon)$$



Adapted from Fig. 6.16, Callister 7e.

### Example 6.4

#### **Ductility and True-Stress-at-Fracture Computations**

A cylindrical specimen of steel having an original diameter of 12.8 mm is tensile-tested to fracture and found to have an engineering fracture strength  $\sigma_t$  of 460 MPa. If its cross-sectional diameter at fracture is 10.7 mm, determine:

- (a) The ductility in terms of percent reduction in area
- (b) The true stress at fracture

#### Solution

(a) Ductility is computed using Equation 6.12, as

$$%RA = \frac{\left(\frac{12.8 \text{ mm}}{2}\right)^{2} \pi - \left(\frac{10.7 \text{ mm}}{2}\right)^{2} \pi}{\left(\frac{12.8 \text{ mm}}{2}\right)^{2} \pi} \times 100$$
$$= \frac{128.7 \text{ mm}^{2} - 89.9 \text{ mm}^{2}}{128.7 \text{ mm}^{2}} \times 100 = 30\%$$

(b) True stress is defined by Equation 6.15, where in this case the area is taken as the fracture area  $A_f$ . However, the load at fracture must first be computed from the fracture strength as

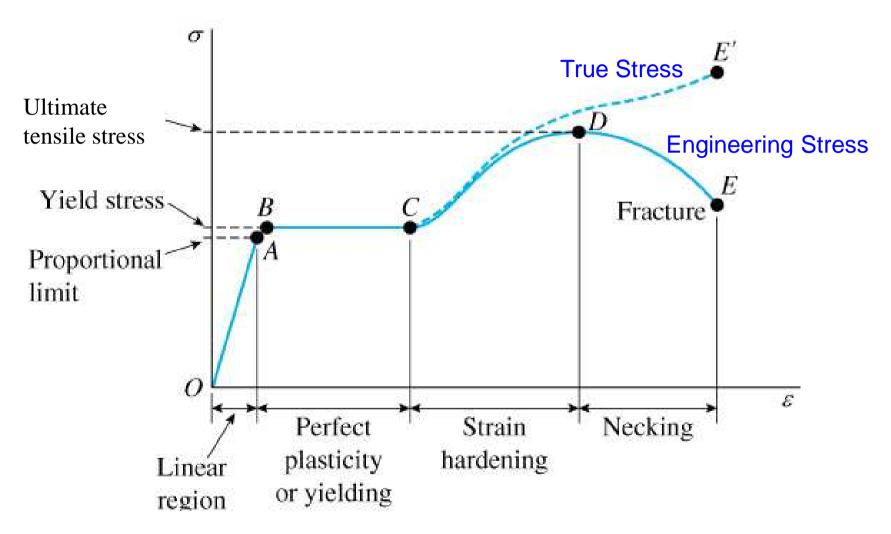
$$F = \sigma_f A_0 = (460 \times 10^6 \text{ N/m}^2)(128.7 \text{ mm}^2) \left(\frac{1 \text{ m}^2}{10^6 \text{ mm}^2}\right) = 59,200 \text{ N}$$

Thus, the true stress is calculated as

$$\sigma_T = \frac{F}{A_f} = \frac{59,200 \text{ N}}{(89.9 \text{ mm}^2) \left(\frac{1 \text{ m}^2}{10^6 \text{ mm}^2}\right)}$$

$$= 6.6 \times 10^8 \,\text{N/m}^2 = 660 \,\text{MPa}$$

# Stress-Strain Diagram

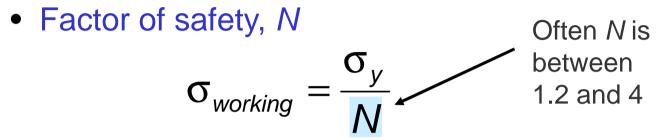


- •For most purposes, engineering stresses and strains are used.
- •Necking: plastic instability, localized plastic deformation
  Chapter 6 23

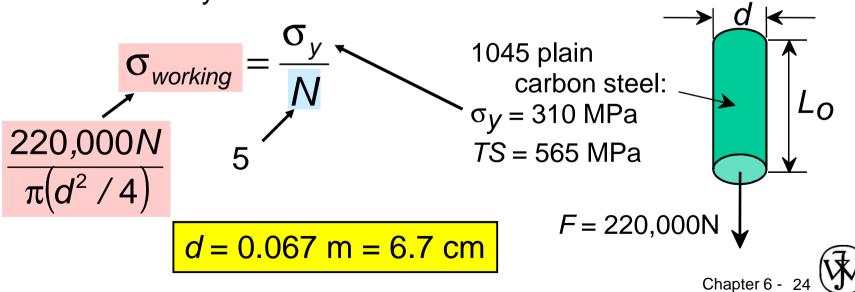


### **Design or Safety Factors**

Design uncertainties mean we do not push the limit.

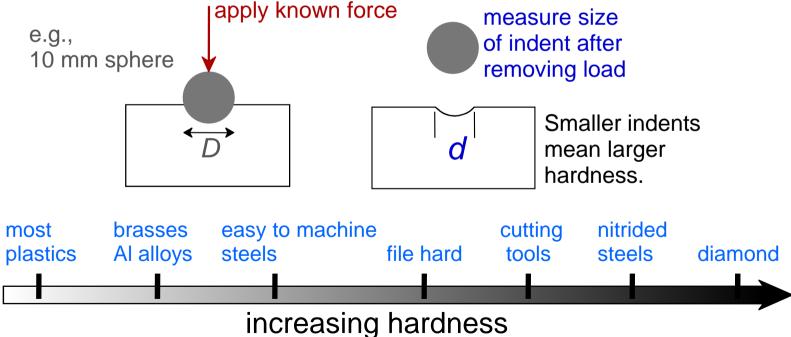


• Example: Calculate a diameter, *d*, to ensure that yield does not occur in the 1045 carbon steel rod below. Use a factor of safety of 5.



### **Hardness**

- Resistance to permanently indenting the surface.
- Large hardness means:
  - --resistance to plastic deformation or cracking in compression.
  - --better wear properties.



# Hardness Testing

- Several common types of hardness test.
- Gives a measure of strength and wear resistance.
- The hardness is affected by work hardening of the material around the indentation.
- Various scales depend on the penetration device shape.

Brinell, Vickers, Knoop, Rockwell.



### **Hardness: Measurement**

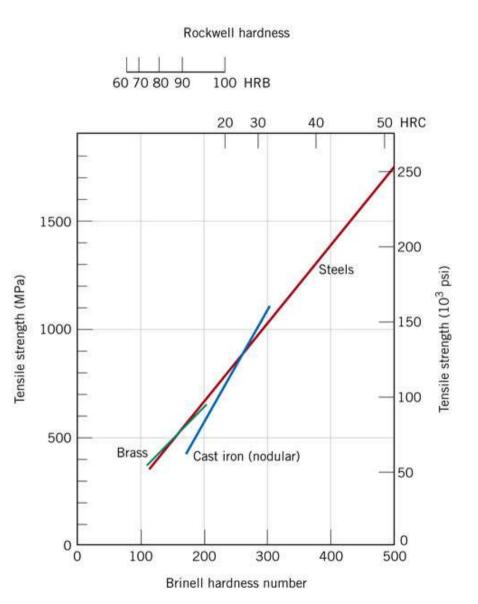
Table 6.5 Hardness-Testing Techniques

Test	Indenter	Shape of Indentation			Formula for
		Side View	Top View	Load	Hardness Numbera
Brinell	10-mm sphere of steel or tungsten carbide		$\rightarrow d$	P	$HB = \frac{2P}{\pi D[D - \sqrt{D^2 - d^2}]}$
Vickers microhardness	Diamond pyramid	136°	$d_1$ $d_1$	P	$HV = 1.854P/d_1^2$
Knoop microhardness	Diamond pyramid	l/b = 7.11 b/t = 4.00	b	P	$HK = 14.2P/l^2$
Rockwell and superficial Rockwell	Diamond cone; $\begin{cases} \frac{1}{16}, \frac{1}{8}, \frac{1}{4}, \frac{1}{2}, -in, -in, -in, -in, -in, -in, -in, -in$	120°		60 kg 100 kg 150 kg 15 kg 30 kg 45 kg Superficial Rockwell	ell

<sup>&</sup>quot;For the hardness formulas given, P (the applied load) is in kg, whereas D, d,  $d_1$ , and l are all in mm.

Source: Adapted from H. W. Hayden, W. G. Moffatt, and J. Wulff, *The Structure and Properties of Materials*, Vol. III, *Mechanical Behavior*. Copyright © 1965 by John Wiley & Sons, New York. Reprinted by permission of John Wiley & Sons, Inc.

# Hardness v.s. Tensile Strength



TS(MPa)=3.45 X HB

### Summary

- Stress and strain: These are size-independent measures of load and displacement, respectively.
- **Elastic** behavior: This reversible behavior often shows a linear relation between stress and strain. To minimize deformation, select a material with a large elastic modulus (**E** or **G** or **v**).
- Plastic behavior: This permanent deformation behavior occurs when the tensile (or compressive) uniaxial stress reaches σ<sub>V</sub>.
- Toughness: The energy needed to break a unit volume of material.
- Ductility: The plastic strain at failure.
- Resilience, Temperature, Hardness, Safety Factor