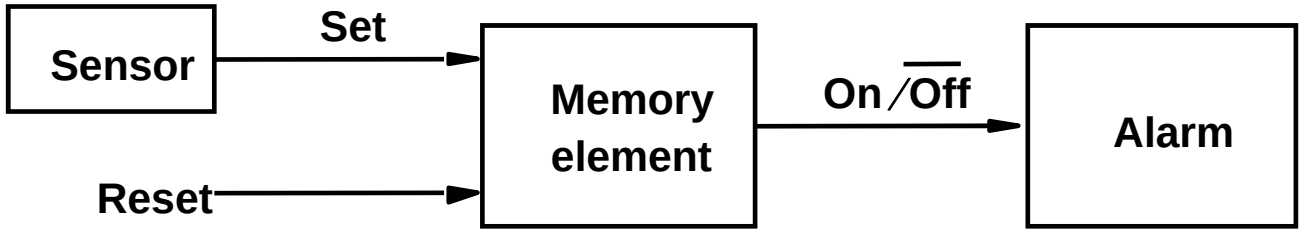
Lecture 7
Flip-Flops, Registers, Counters, and a Simple Processor

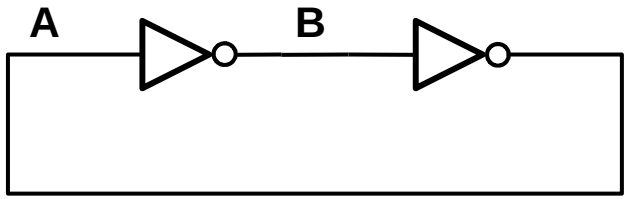
吳文中

“States” in a Circuit

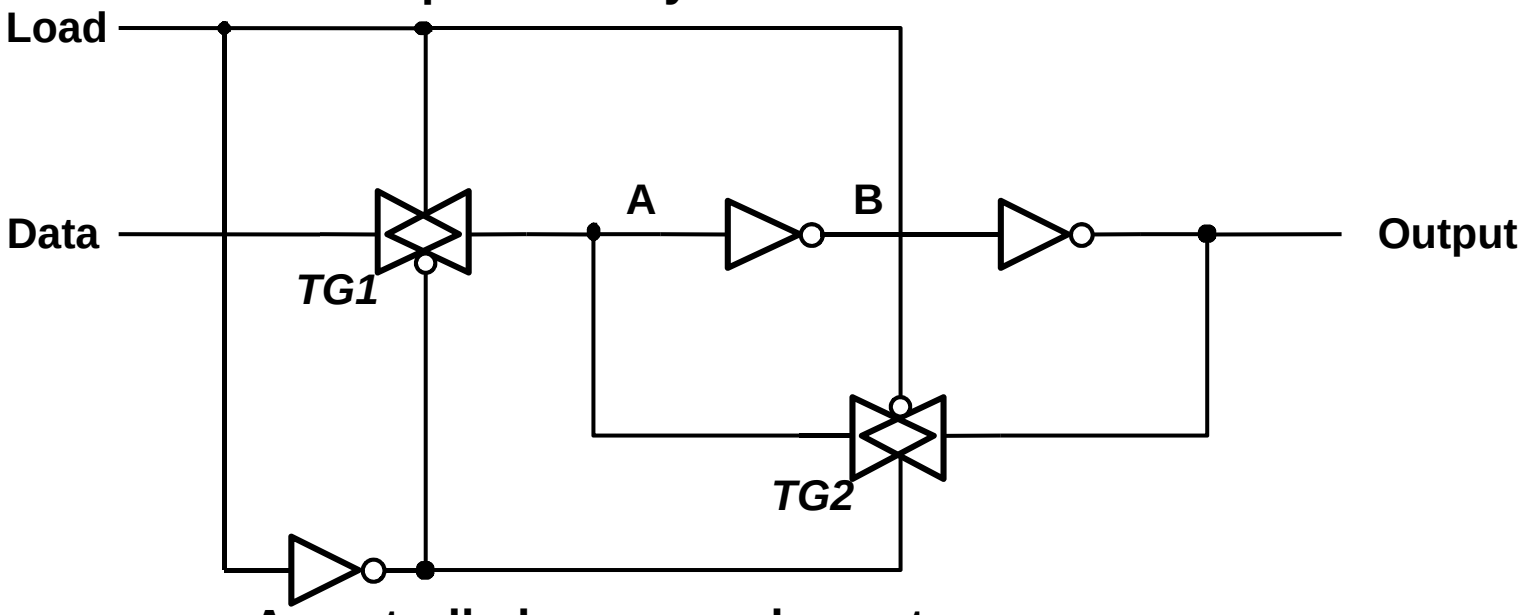


Control of an alarm system.

Memory Element Implementations



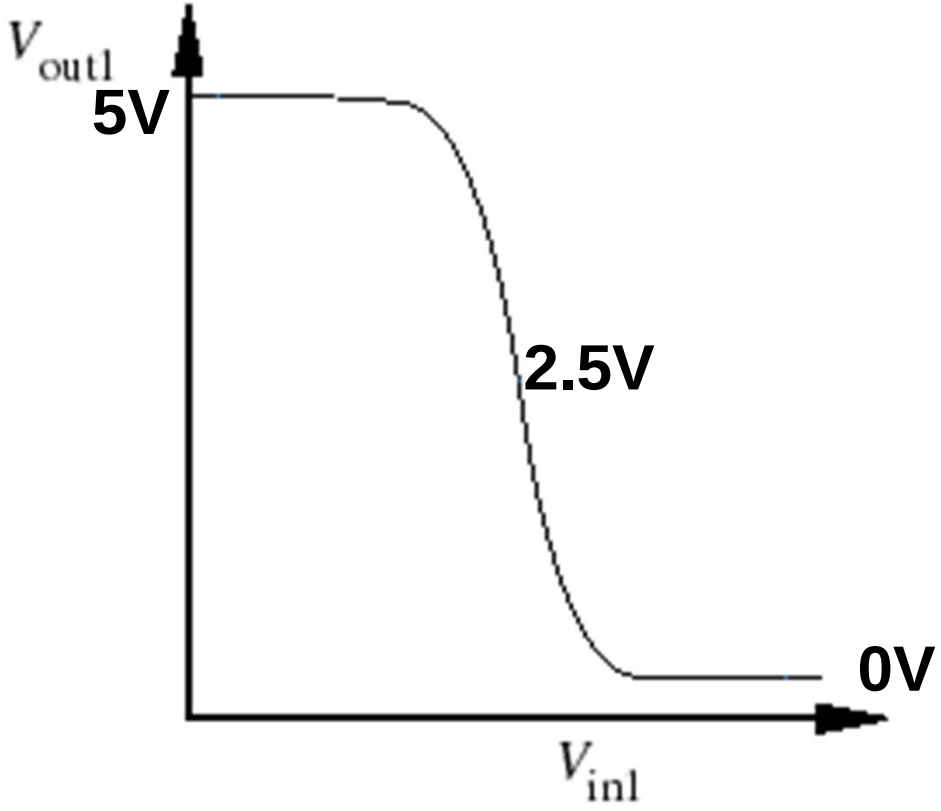
A simple memory element.



A controlled memory element.

Analog analysis

- Assume pure CMOS thresholds, 5V rail
- Theoretical threshold center is 2.5 V



Analog analysis

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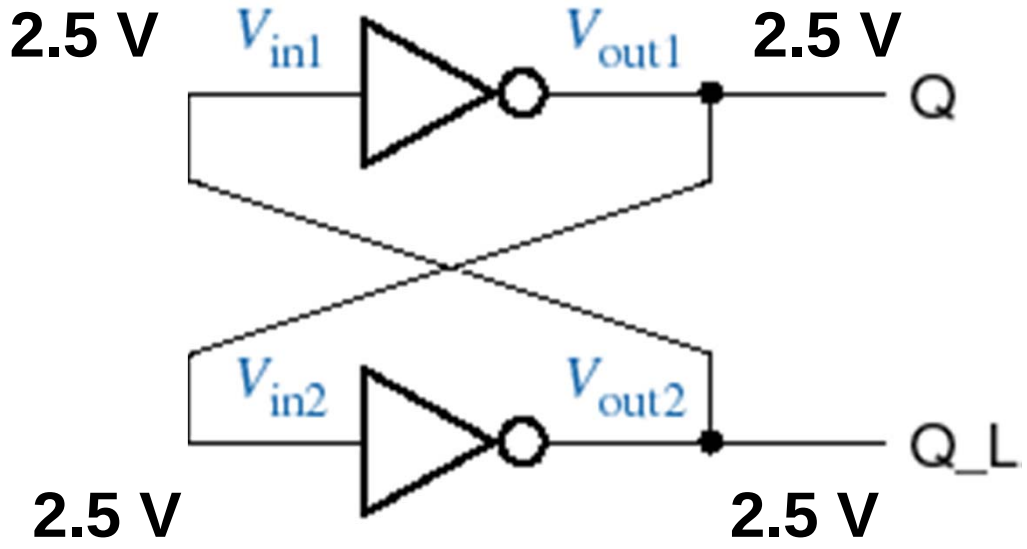

Analog analysis

- Assume pure CMOS thresholds, 5V rail
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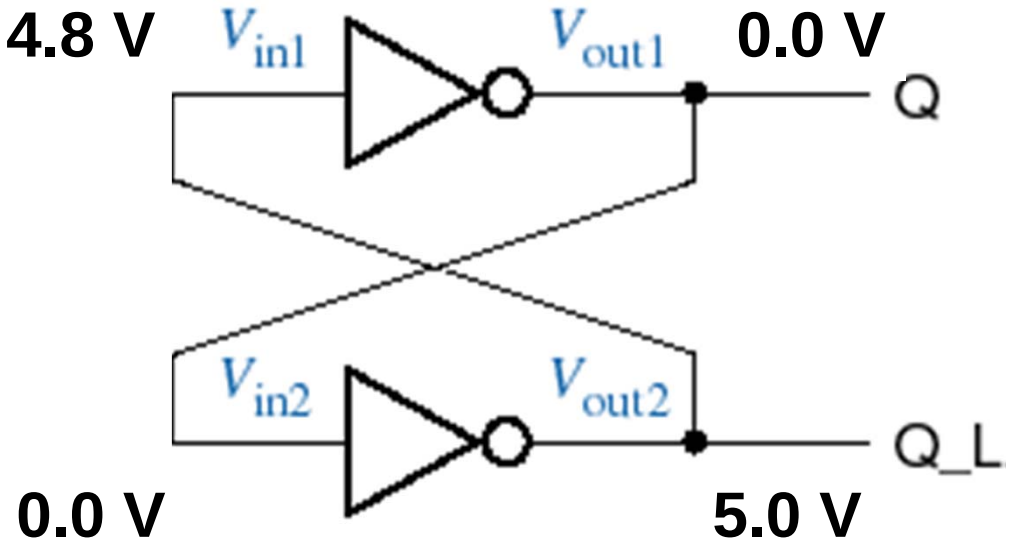
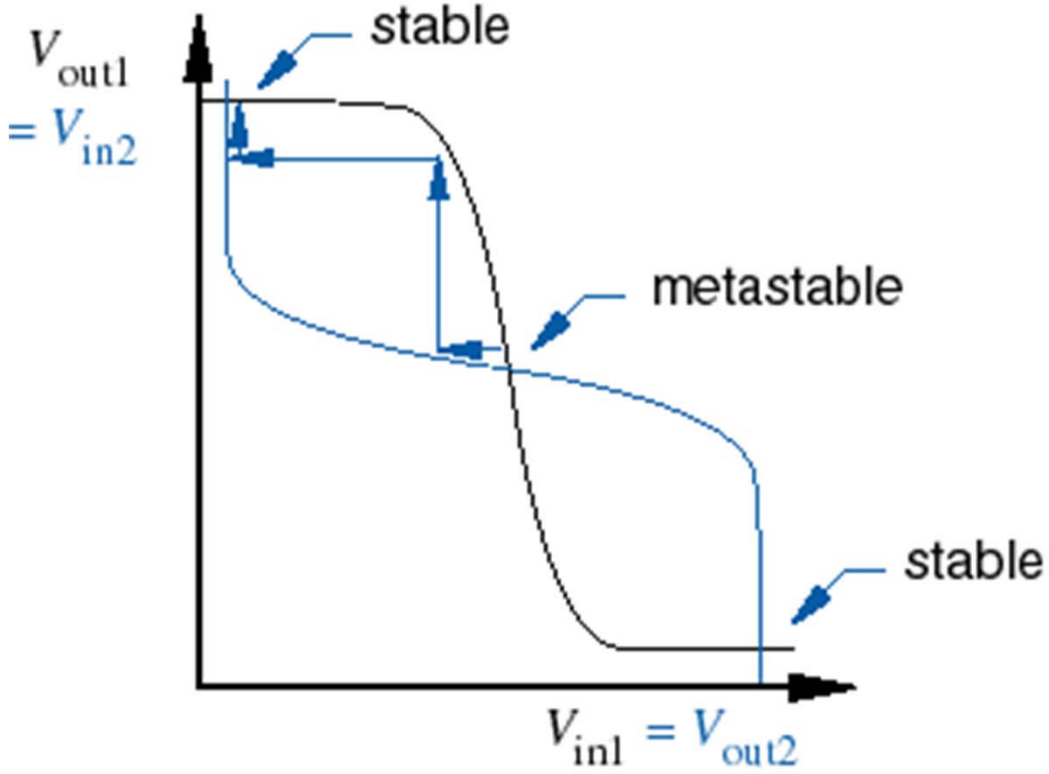


Metastability

- Metastability is inherent in any bistable circuit



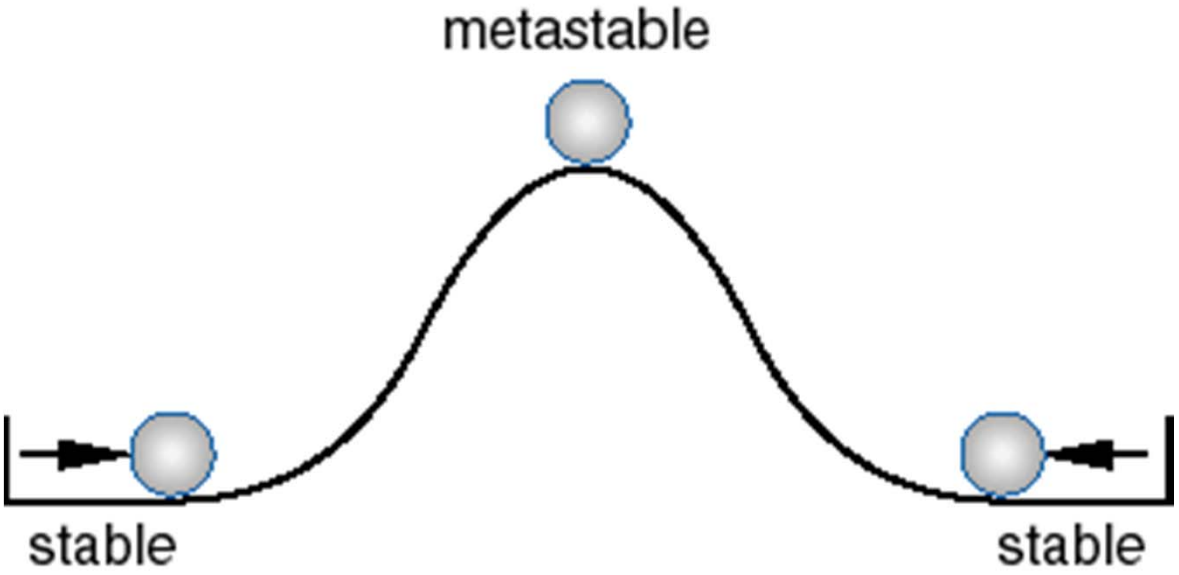
Transfer function:

$$V_{out1} = T(V_{in1})$$

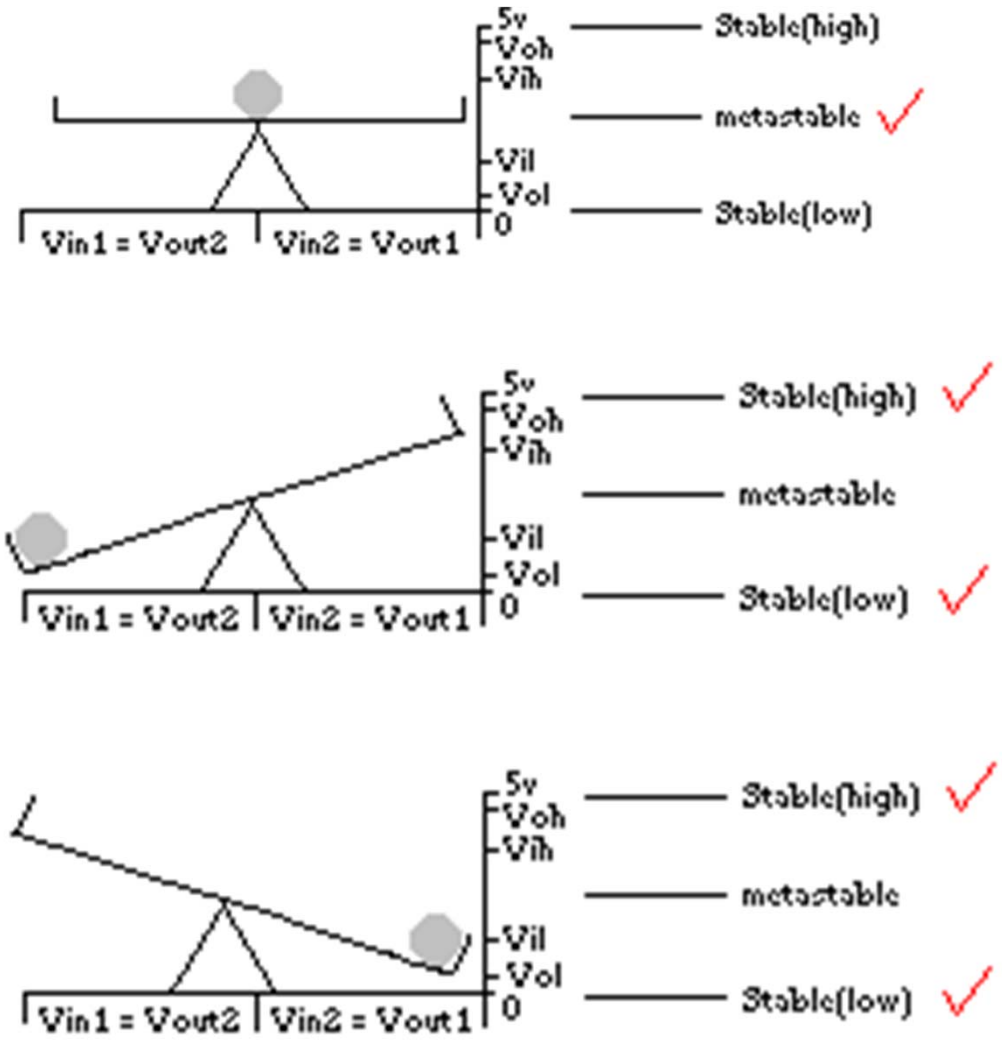
$$V_{out2} = T(V_{in2})$$

- Two stable points, one metastable point

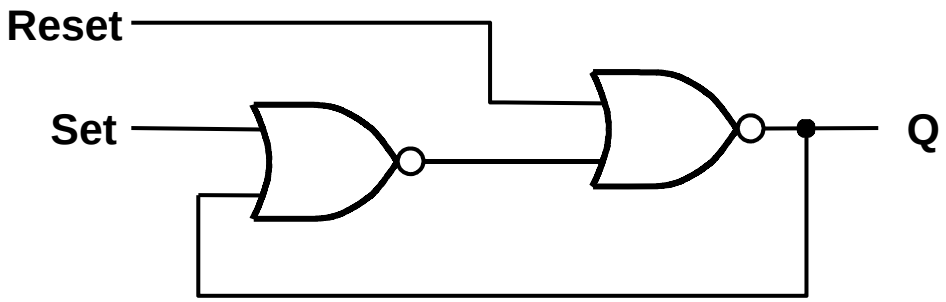
Another look at metastability



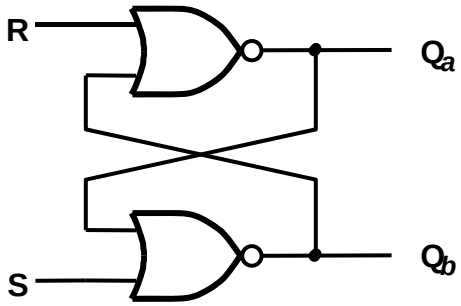
Stable and Metastable



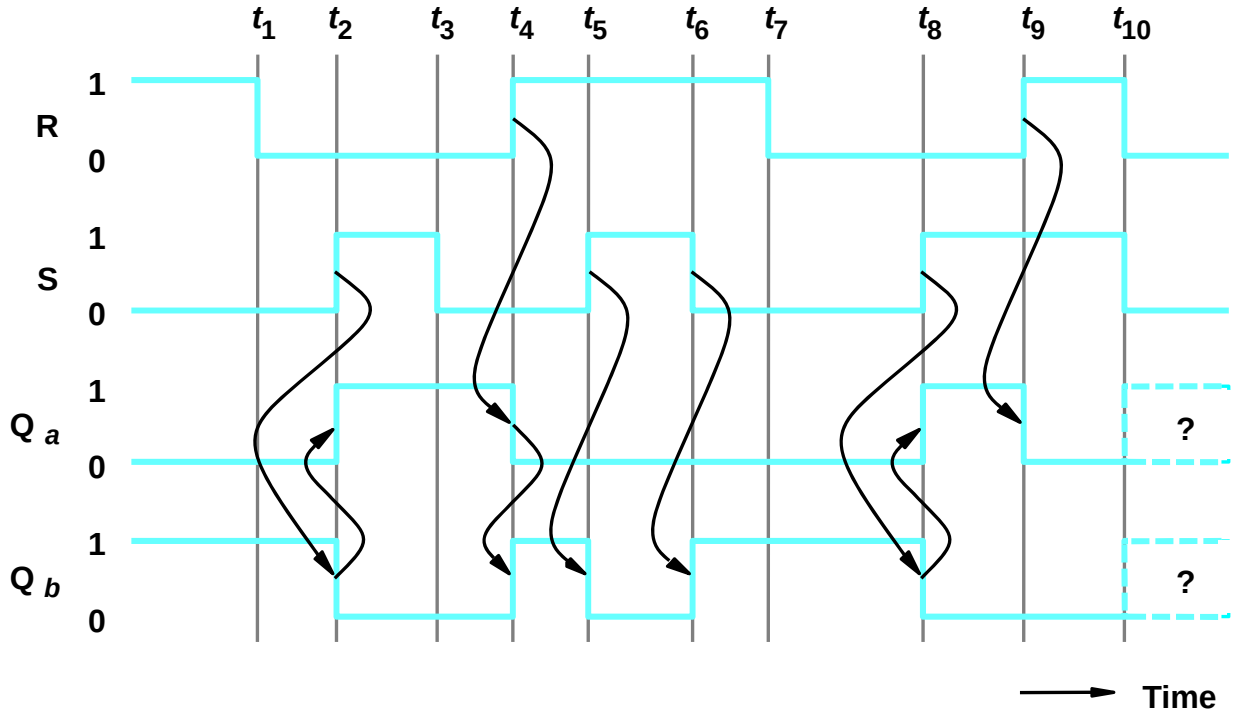
BASIC (RS) Latch



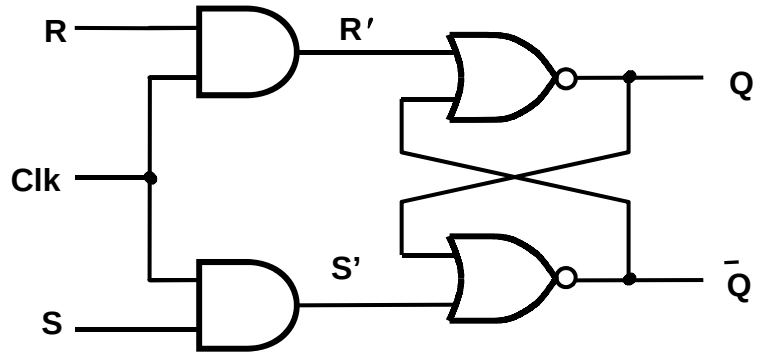
A Basic Latch Built with NOR Gates



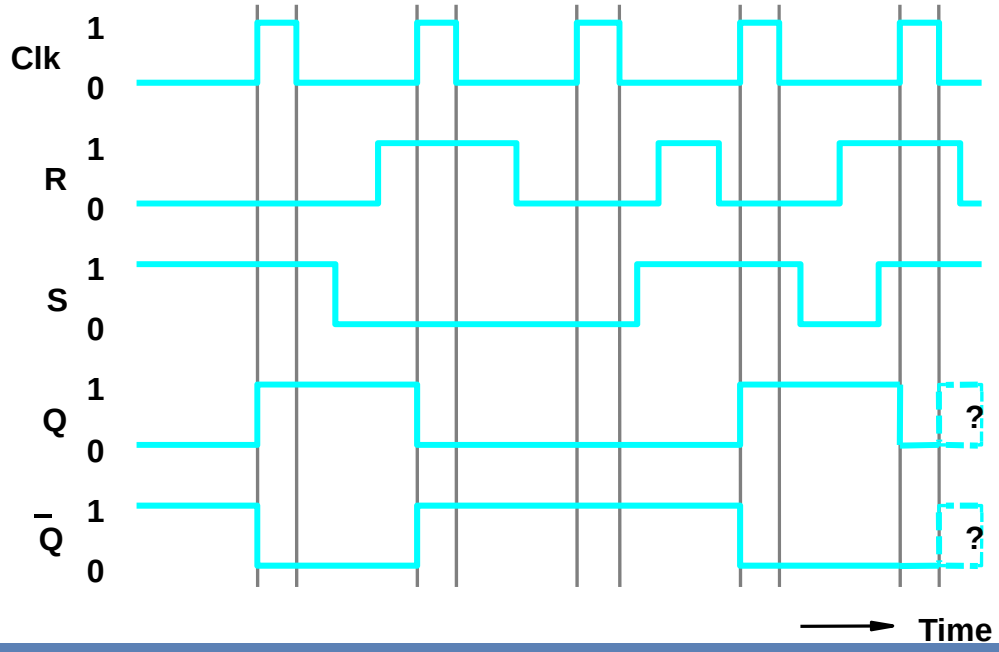
S	R	Q_a	Q_b	
0	0	0/1	1/0	(no change)
0	1	0	1	
1	0	1	0	
1	1	0	0	

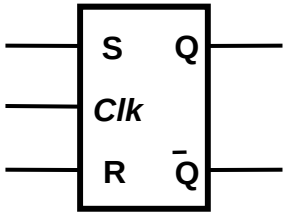


Gates SR Latch

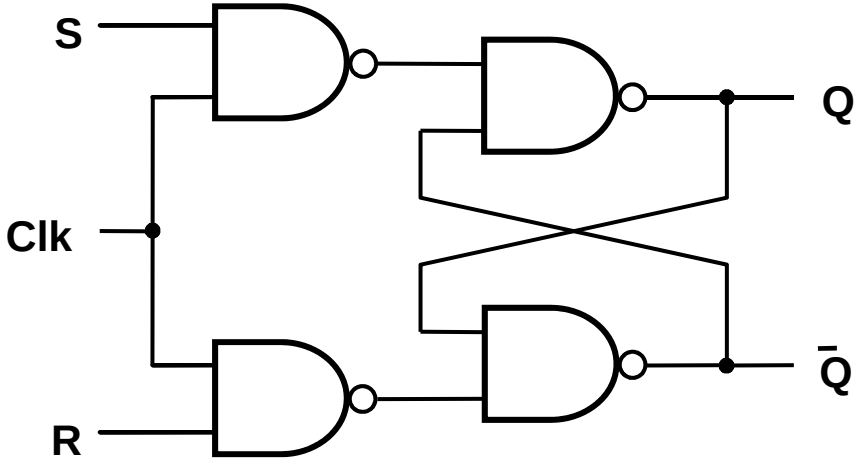


Clk	S	R	Q(*t* + 1)
0	x	x	Q(*t*) (no change)
1	0	0	Q(*t*) (no change)
1	0	1	0
1	1	0	1
1	1	1	x



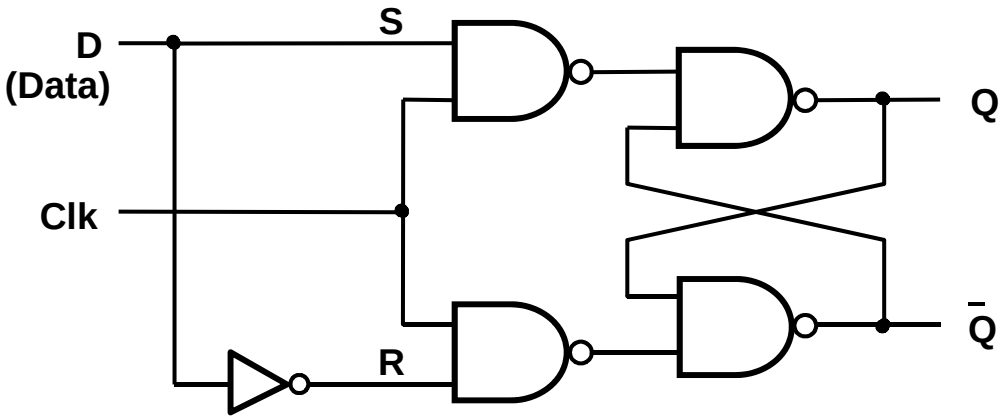


Gated SR Latch with NAND Gates

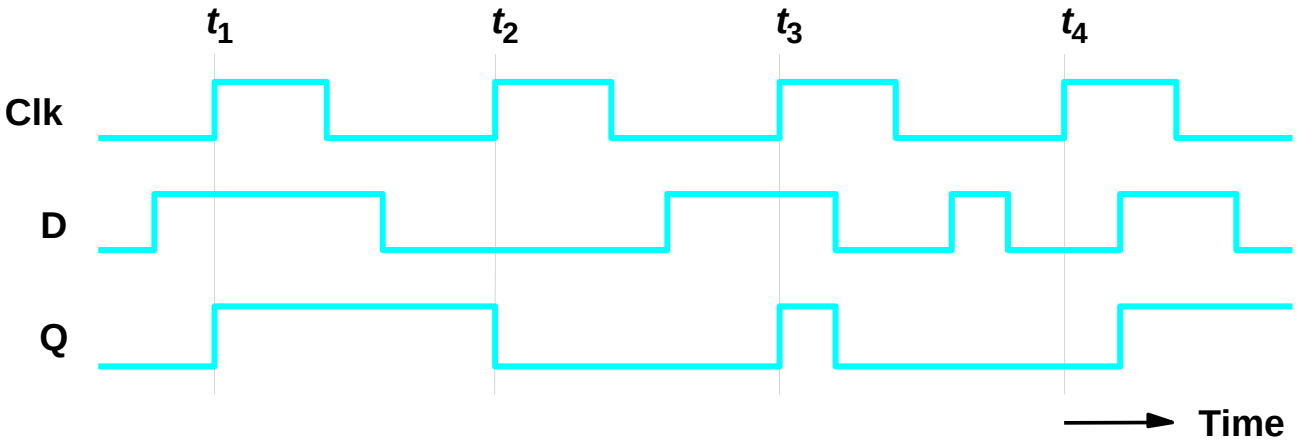


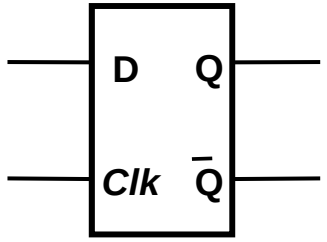
Clk	S	R	Q(*t* + 1)
0	x	x	Q(*t*) (no change)
1	0	0	Q(*t*) (no change)
1	0	1	0
1	1	0	1
1	1	1	x

Gated D Latch



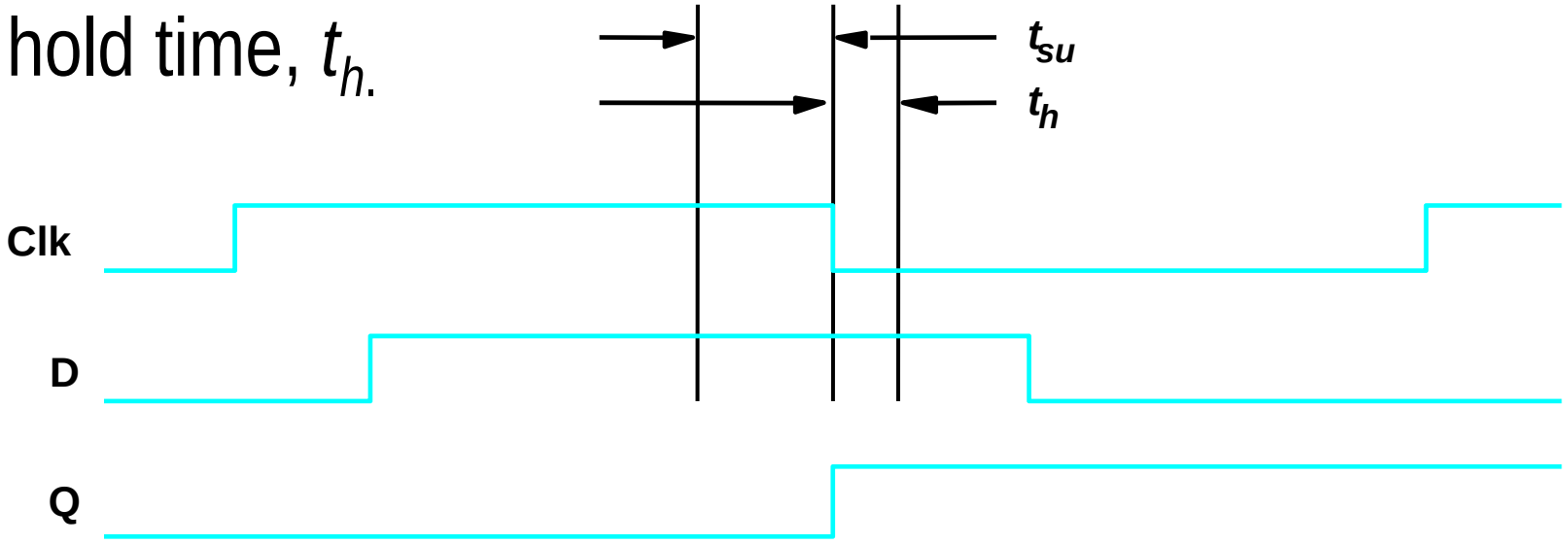
Clk	D	Q(*t* + 1)
0	x	Q(*t*)
1	0	0
1	1	1



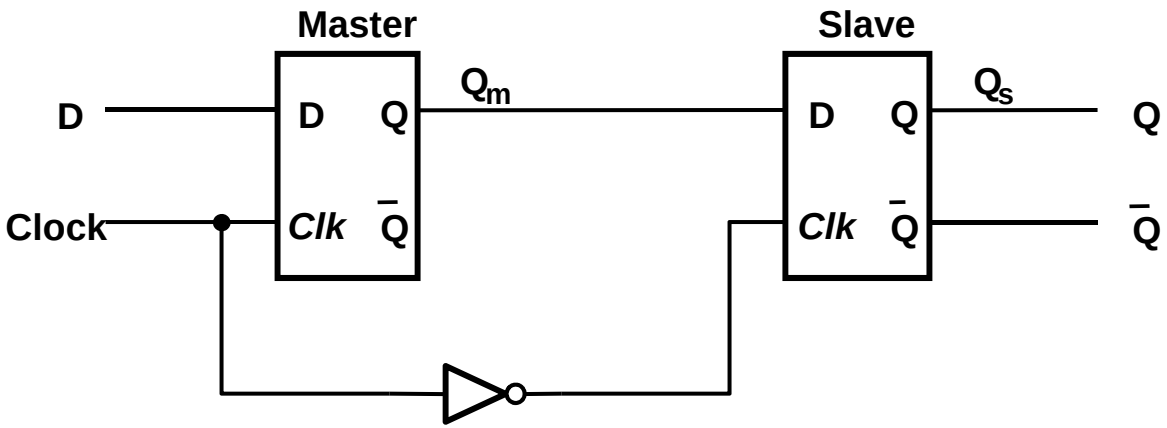


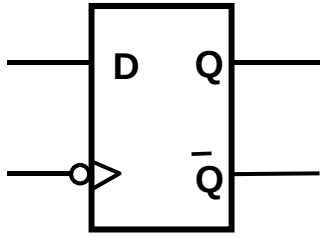
Effects of Propagation Delays

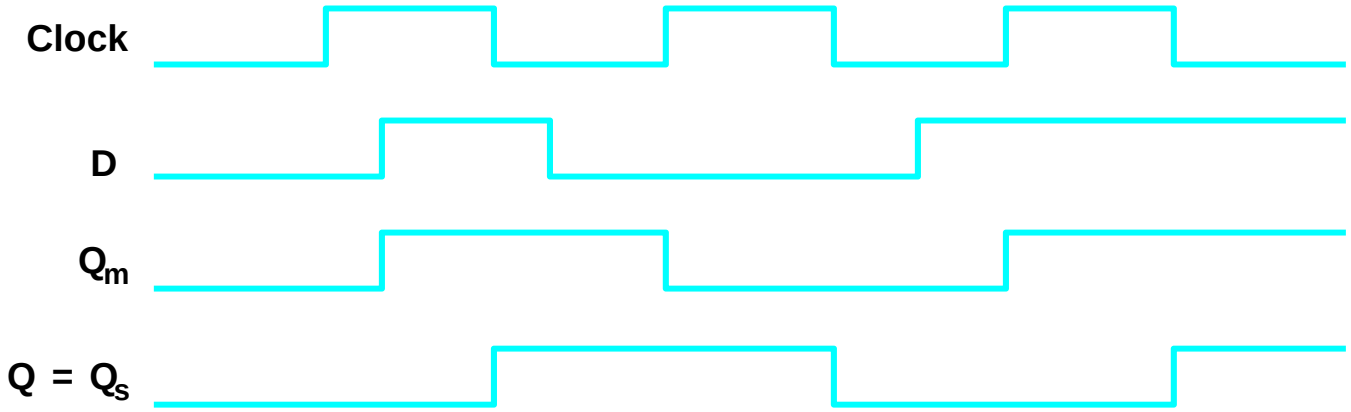
- The minimum time that the *D* signal must be stable prior to the negative edge of the *Clk* signal is called setup time, t_{su}.
- The minimum time that the *D* signal must remain stable after the negative edge of the *Clk* signal is called hold time, t_h.



Master-Slave D Flip-Flop

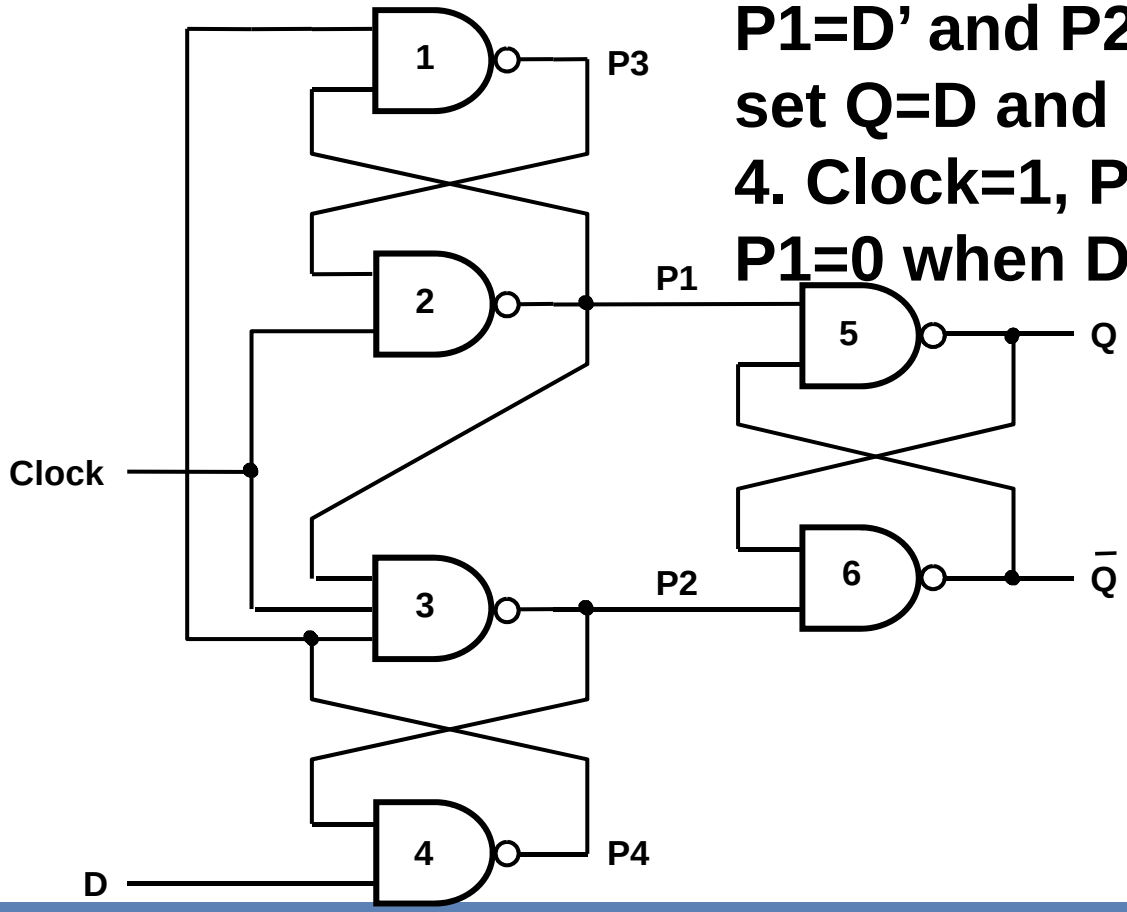


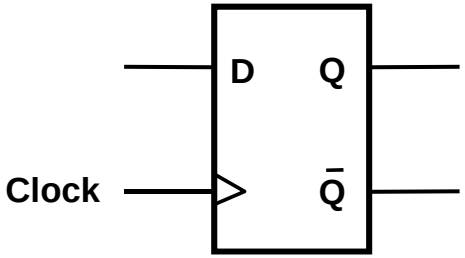




A Positive-edge-triggered D Flip-Flop

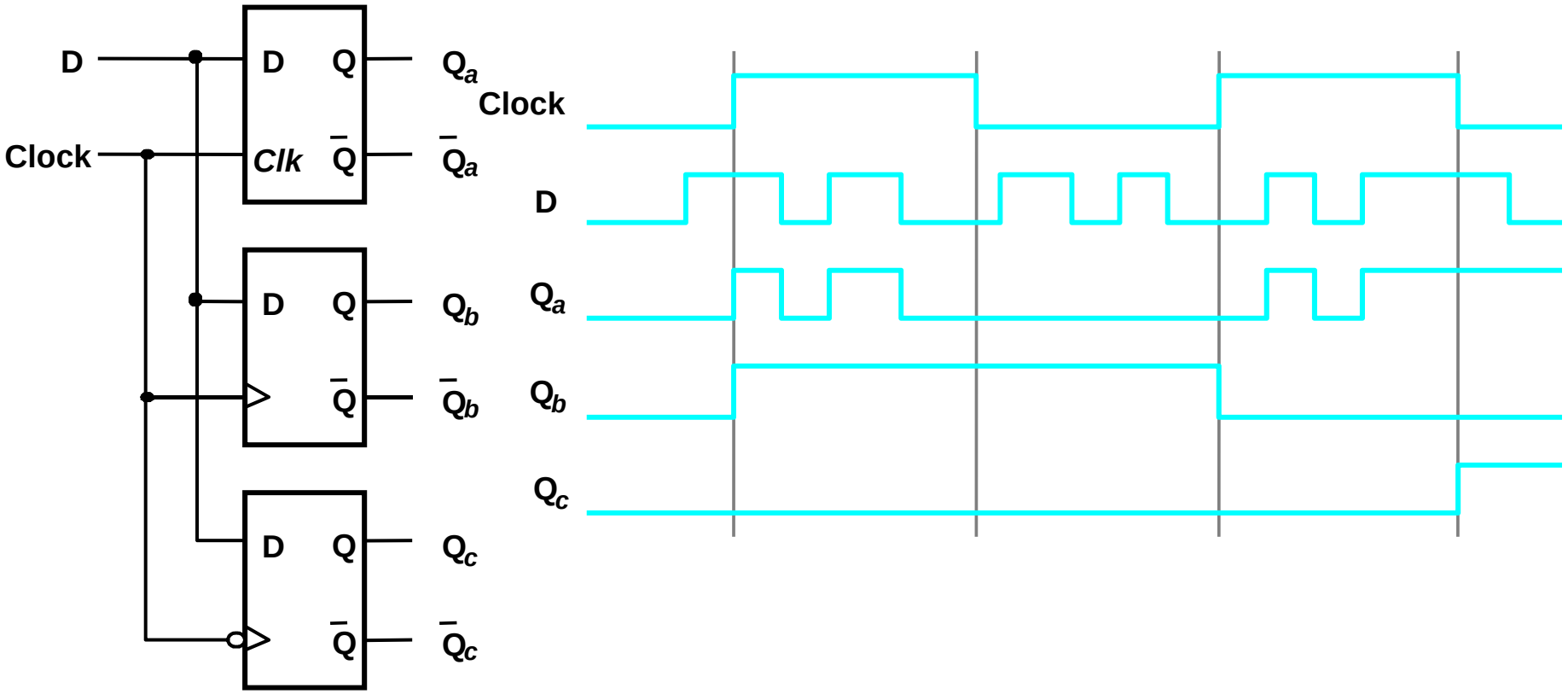
1.Clock=0, P1=P2=1; Latch Hold.
2. P4=D' and P3 = D
3. Clock 0 to 1 (positive edge), P1=D' and P2=D which set Q=D and Q'=D'
4. Clock=1, P2=0 when D=0; P1=0 when D=1



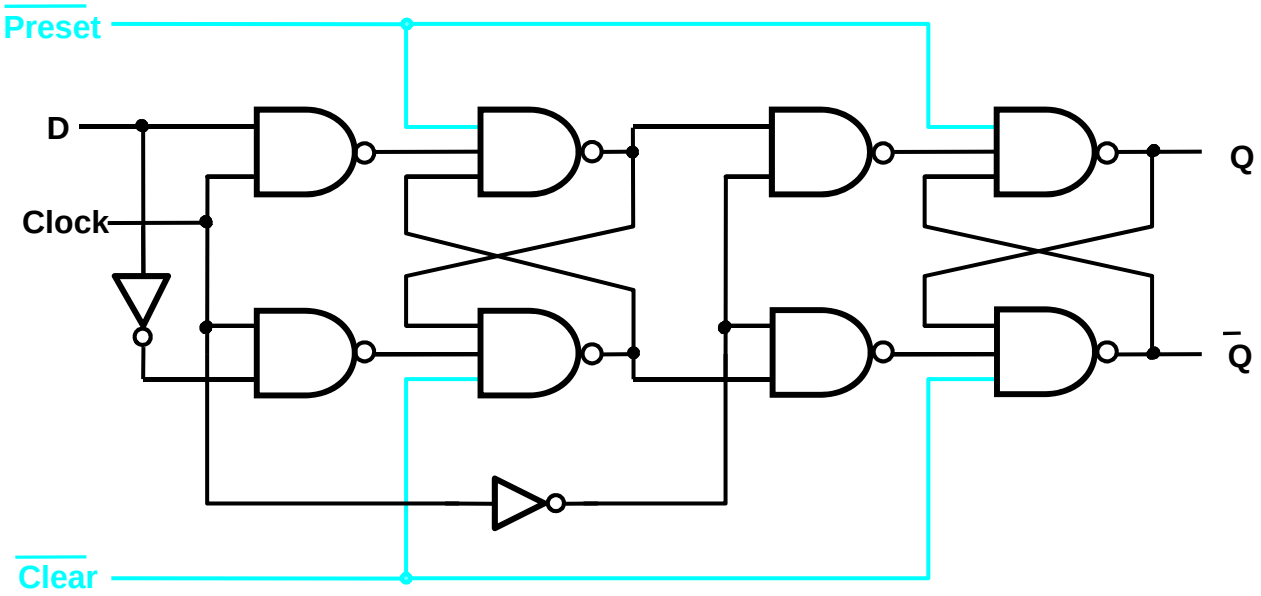


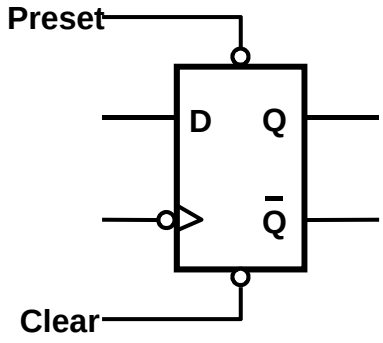
(b) Graphical symbol

Level-Sensitive versus Edge-Triggered

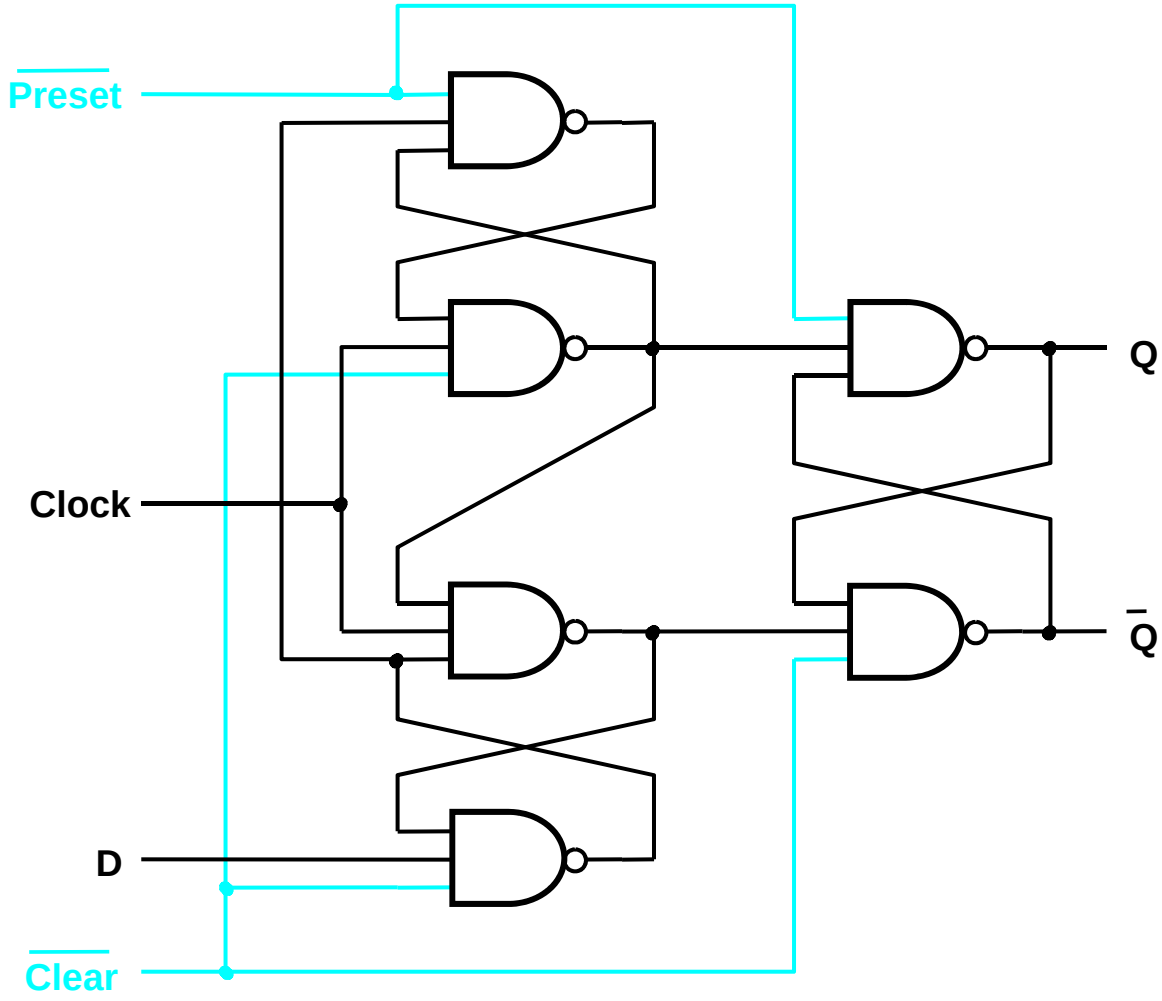


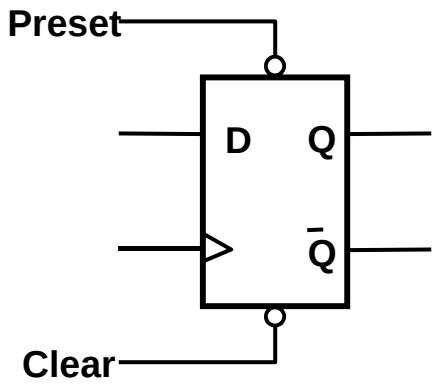
Master-Slave D Flip-flop with Clear and Preset

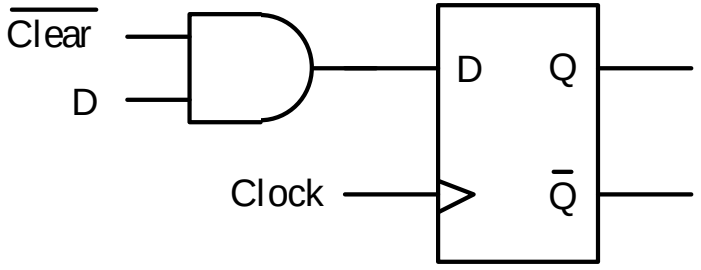




Positive-edge-trigger D Flip-flop with Clear and Preset

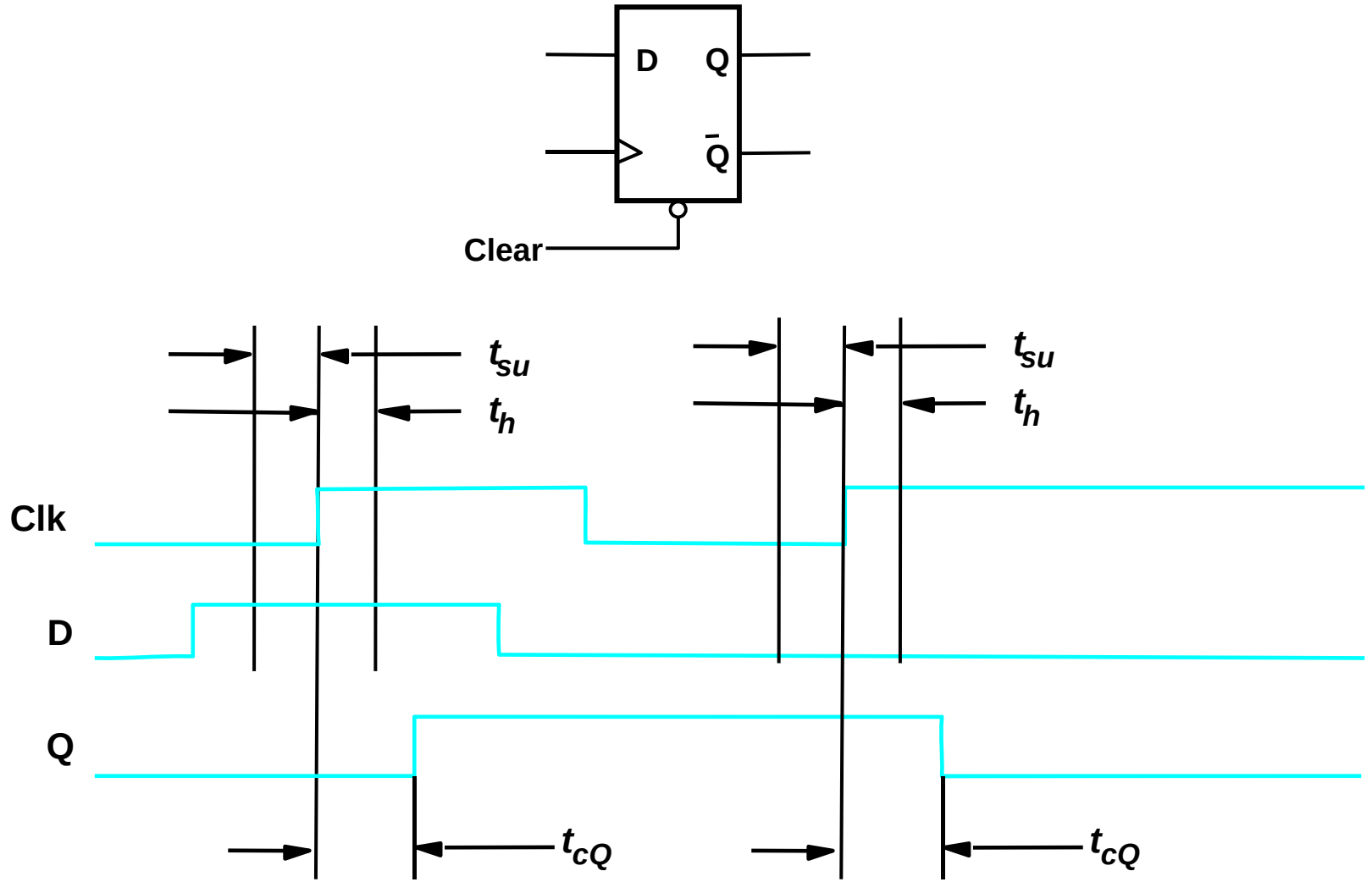




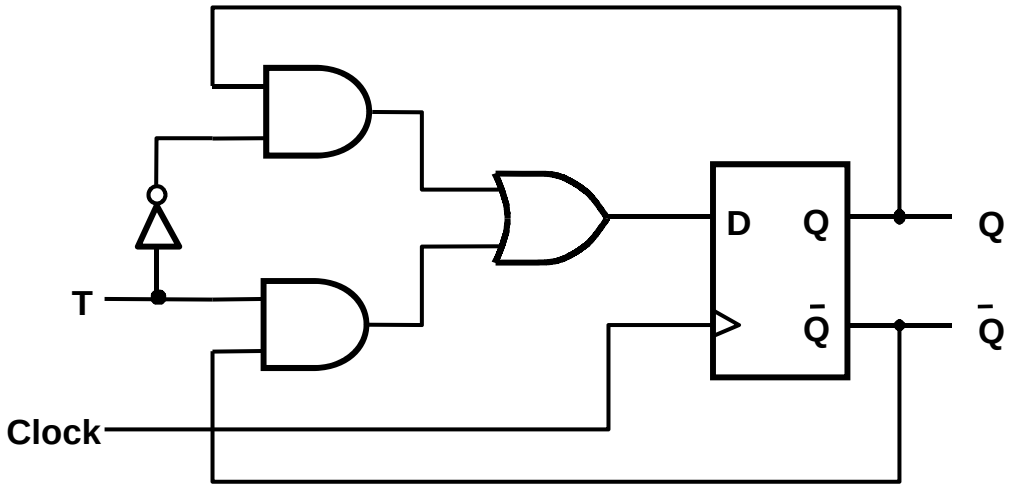


Adding a synchronous clear

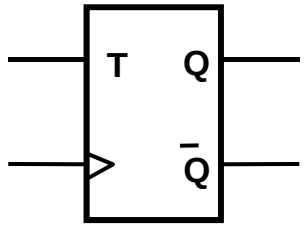
Flip-Flop Timing Parameter

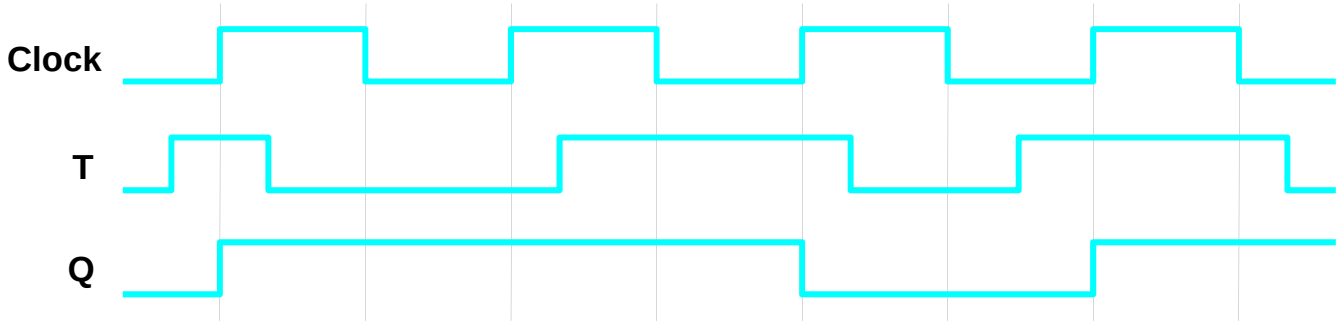


T Flip-Flop



T	$Q(t+1)$
0	$Q(t)$
1	$\bar{Q}(t)$

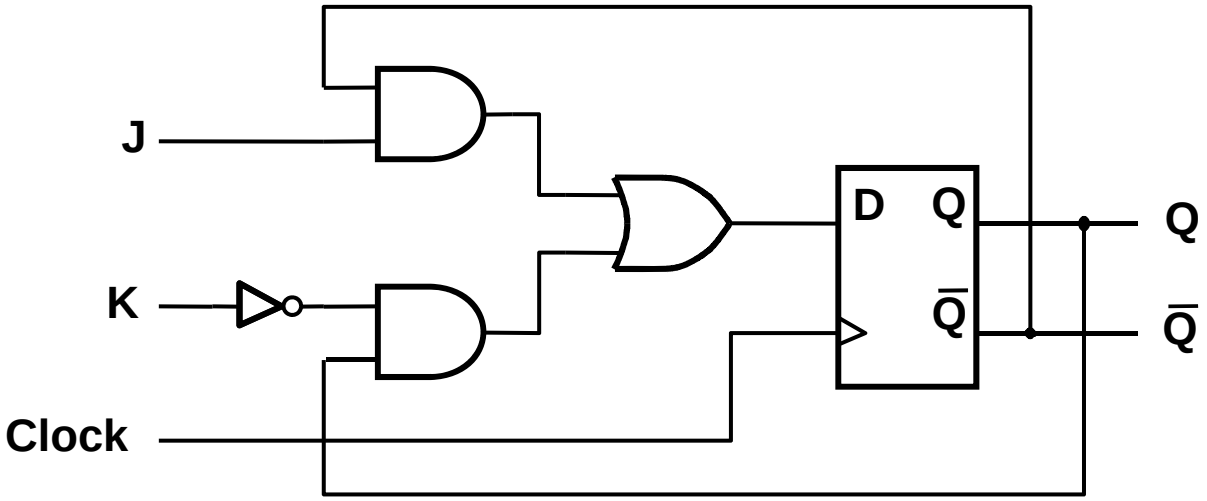




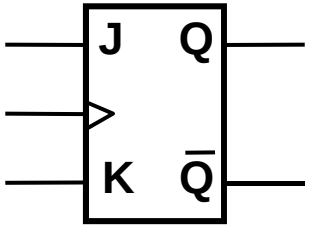
Configurable Flip-Flops

- In general purpose chips like PLDs, the flip-flops that are provided are sometimes *configurable*, which means that a flip-flop circuit can be configured to be either D, T, or some type.
- HOW?

JK Flip-Flop



J	K	Q (t+1)
0	0	Q (t)
0	1	0
1	0	1
1	1	$\bar{Q}$ (t)



Summary of Terminology

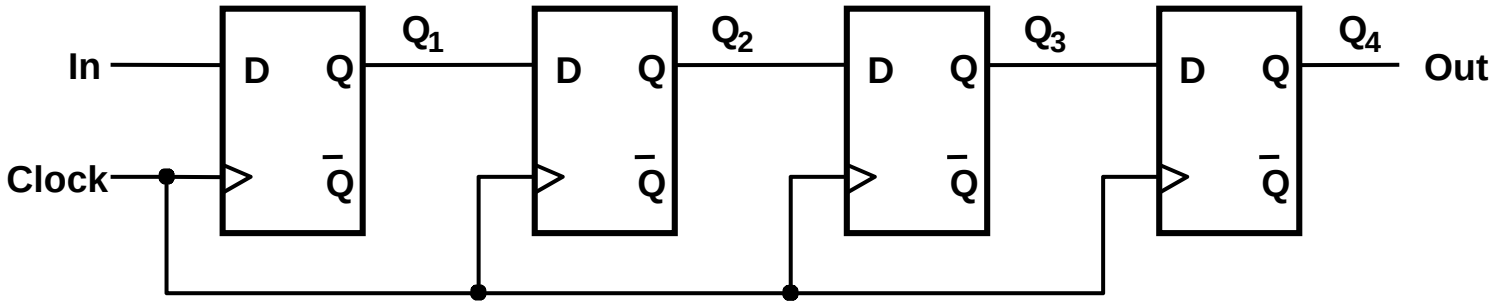
- **Basic latch** is a feedback connection of two NOR gates or two NAND gates, which can store one bit of information. It can be set to 1 using S or 0 using R.
- **Gated latch** is a basic latch that includes input gating and a control input signal.
  - **Gated SR latch** uses the S and R inputs to set the latch to 1 or reset to 0 (do have R=S=0 exception).
  - **Gated D latch** uses the D input to force the latch into a state that has the same lotic value as the D input

- A **flip-flop** is a storage element based on the bated latch principle, which can have its output sate changed only on the edge of the controlling clock signals.
  - **Edge-triggerd flip-flop** is affected only by the input values present when the active edge of the clock occurs.
  - **Master-slave flip-flop** is built with two gated latches. The master stage is active during half of the clock cycle, and the slave stage is active during the other half. The output value of the flip-flop changes on the edge of the clock that activates the transfer into the slave stage. It can be edge-triggered or level sensitive. (Gated D latch=>edge-triggered; Gates SR latch=> level-sensitive)

Registers

- A flip-flop stores one bit of information.
- When a **set** of *n* flip-flops is used to store *n* bits of information, such as an *n*-bit number, we refer to these flip-flops as a *register*.
- A common clock is used for each flip-flop in a register.

Shift Register

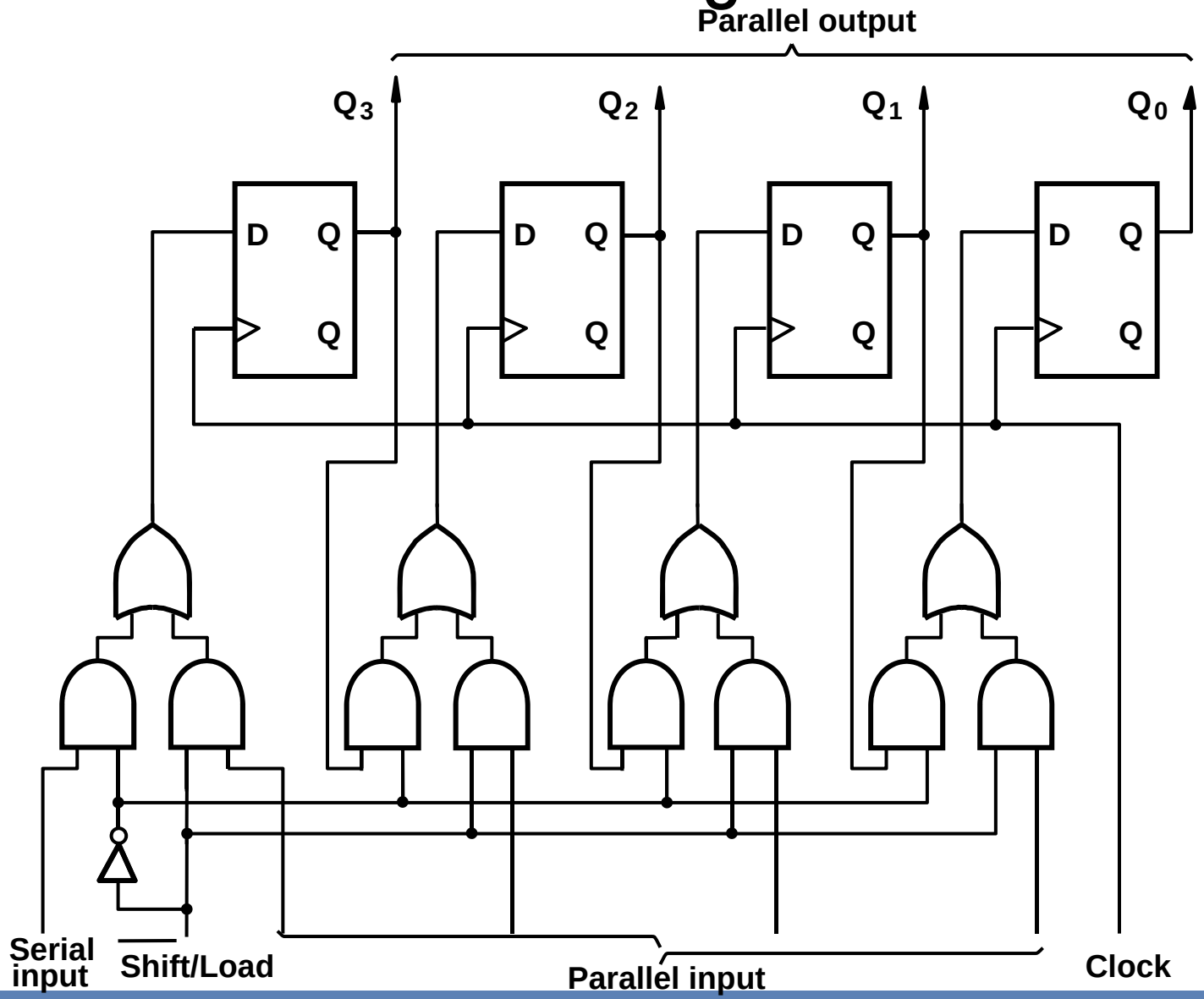


	In	Q_1	Q_2	Q_3	Q_4 = Out
t_0	1	0	0	0	0
t_1	0	1	0	0	0
t_2	1	0	1	0	0
t_3	1	1	0	1	0
t_4	1	1	1	0	1
t_5	0	1	1	1	0
t_6	0	0	1	1	1
t_7	0	0	0	1	1

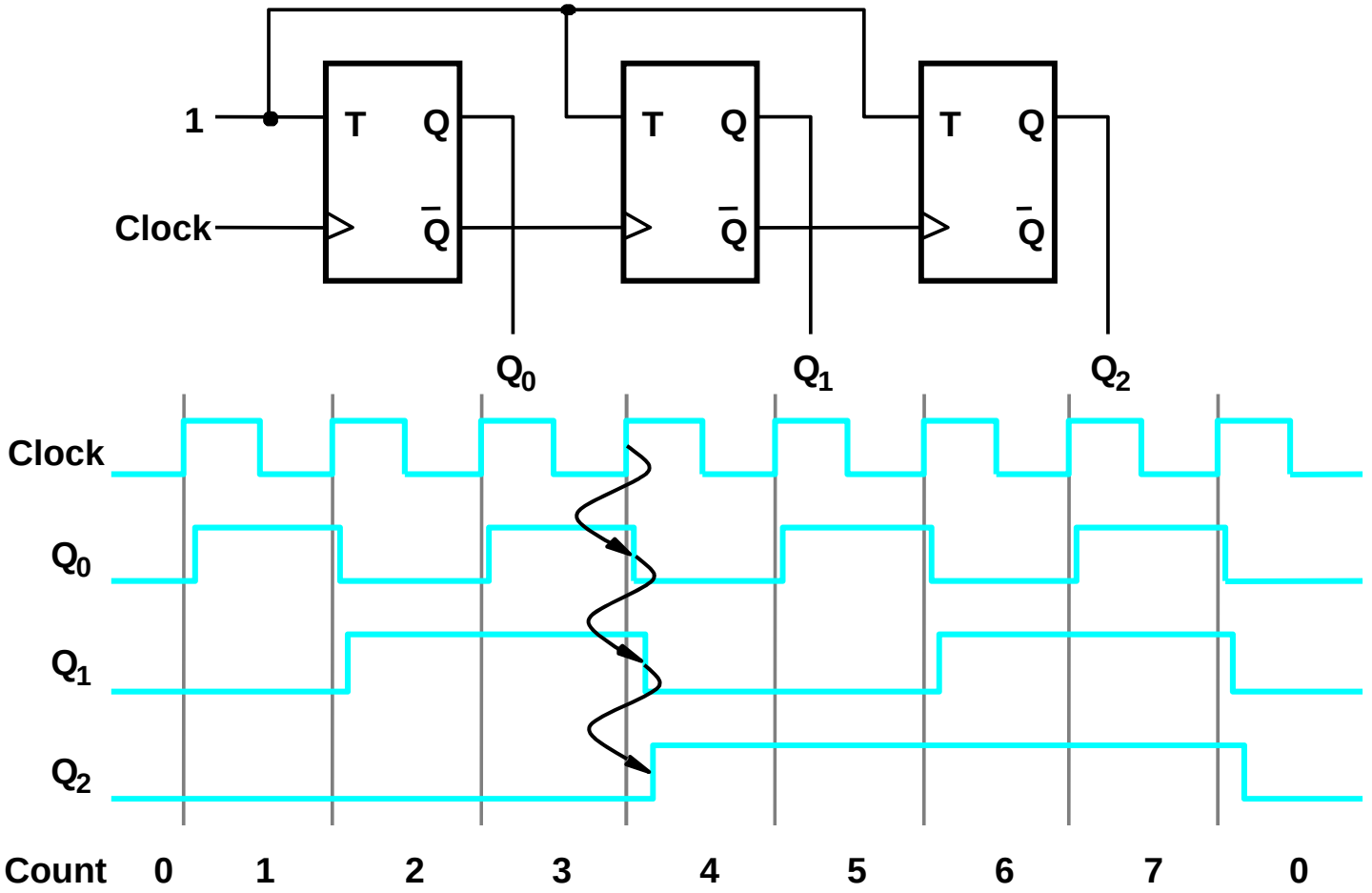
Parallel versus Serial

- Transmitting n bits at once using n separate wires. We say this scheme is **parallel transfer**.
- Transmitting n bits at once using a single wire, by performing the transfer one bit at a time, in n consecutive clock cycles. We say this scheme is **serial transfer**.

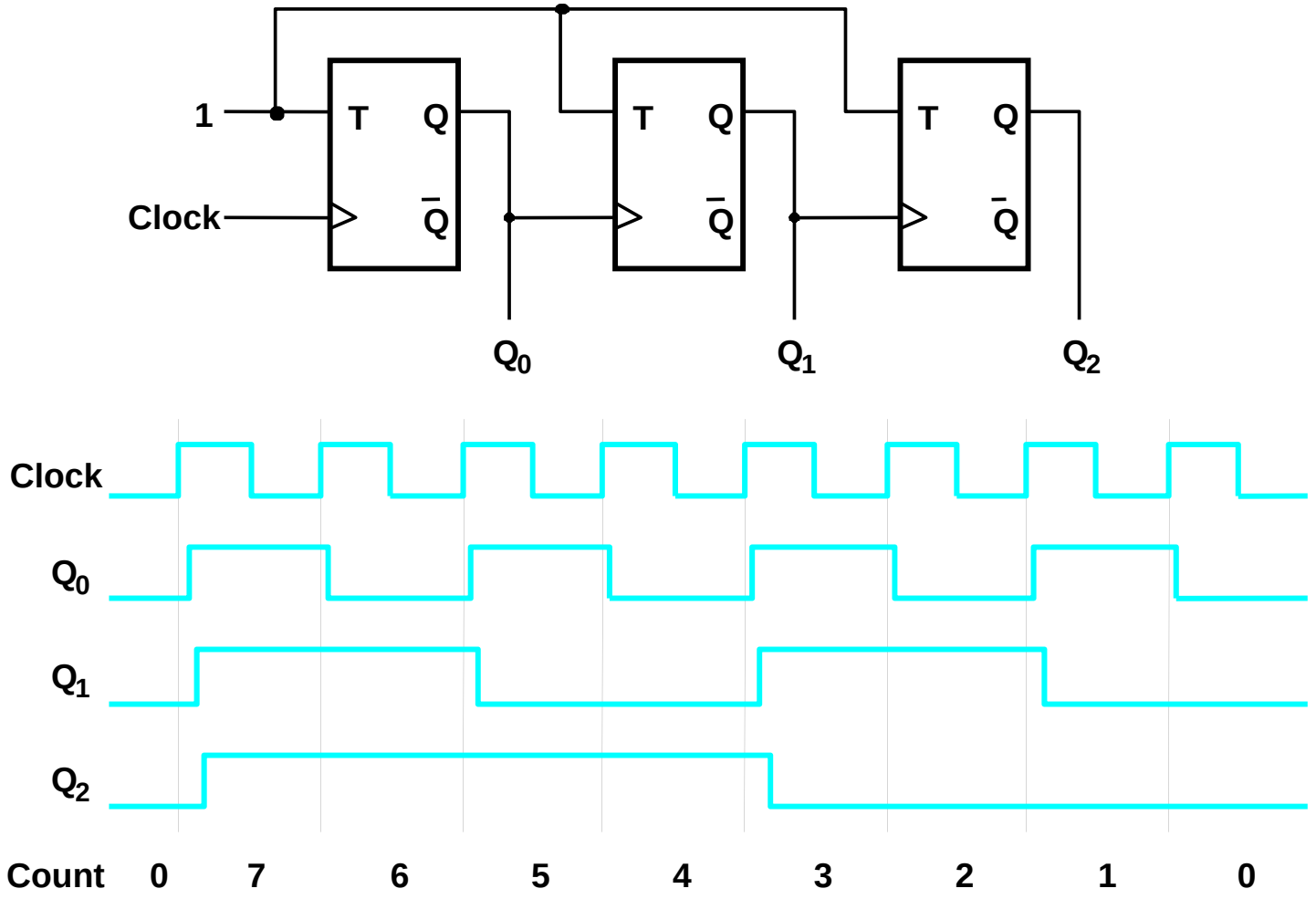
Parallel-Access Shift Register



Asynchronous Up-Counter with T Flip-flops



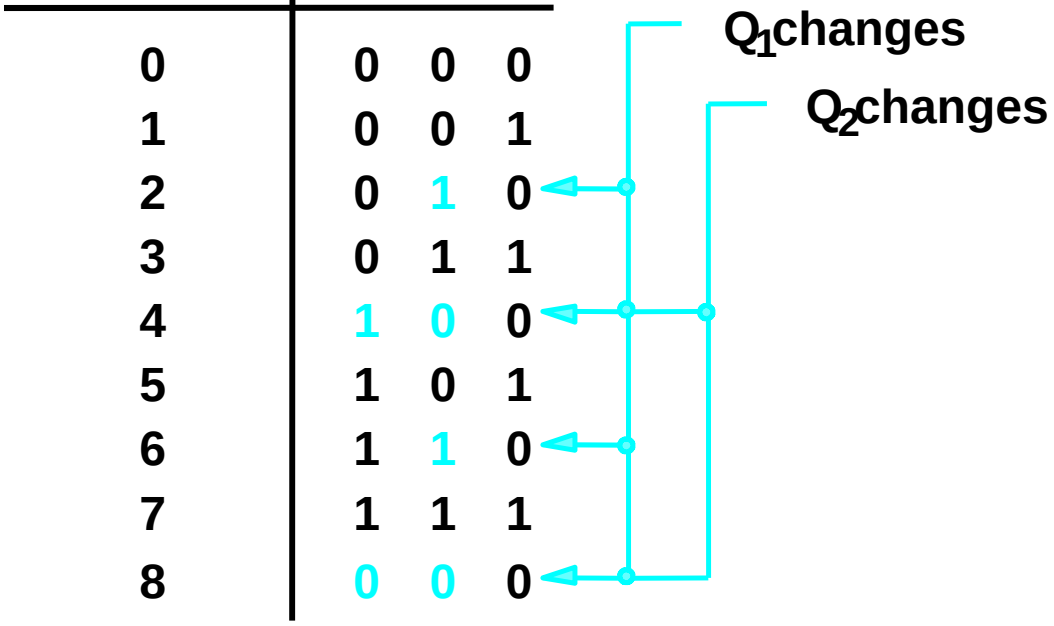
Asynchronous Down-Counter with T Flip-flops



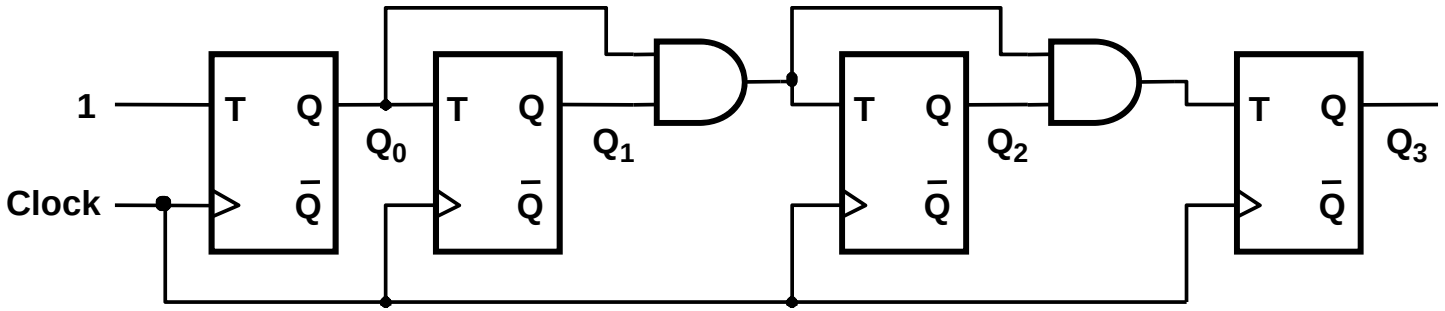
Synchronous Counter with T Flip-flops

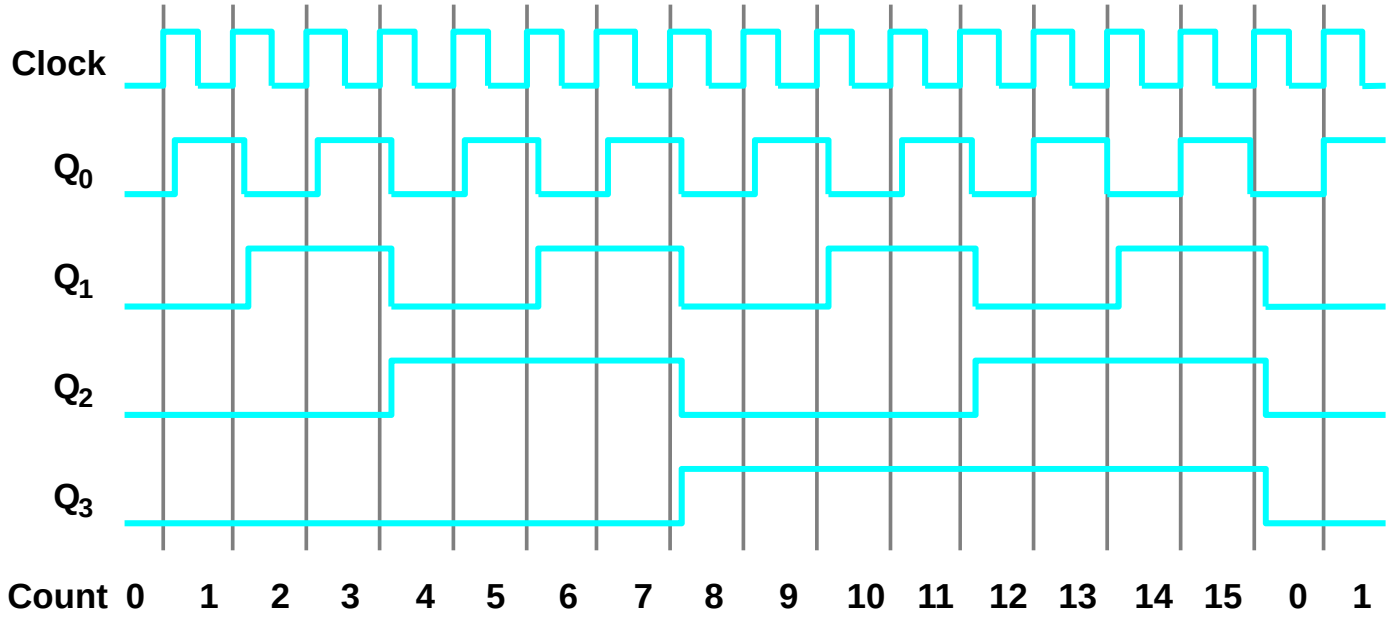
- $T_0=1$
- $T_1=Q_0$
- $T_2=Q_0Q_1$
- $T_3=Q_0Q_1Q_2$
- $T_n=Q_0Q_1\cdots Q_{n-1}$

Clock cycle	Q_2	Q_1	Q_0
0	0	0	0
1	0	0	1
2	0	1	0
3	0	1	1
4	1	0	0
5	1	0	1
6	1	1	0
7	1	1	1
8	0	0	0

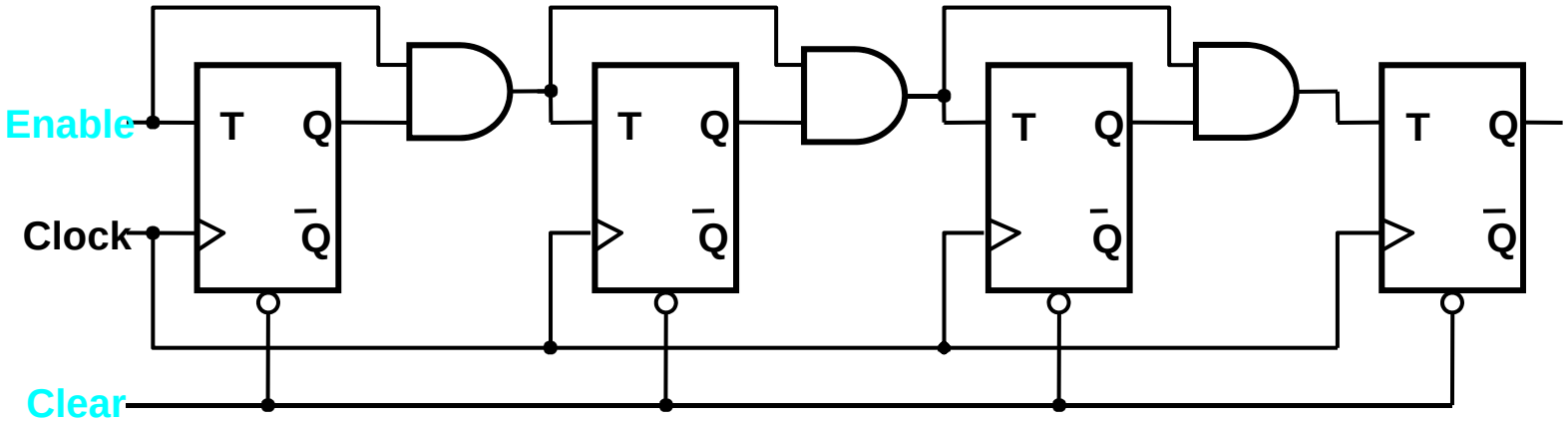


Synchronous Counter with T Flip-flops





Enable and Clear

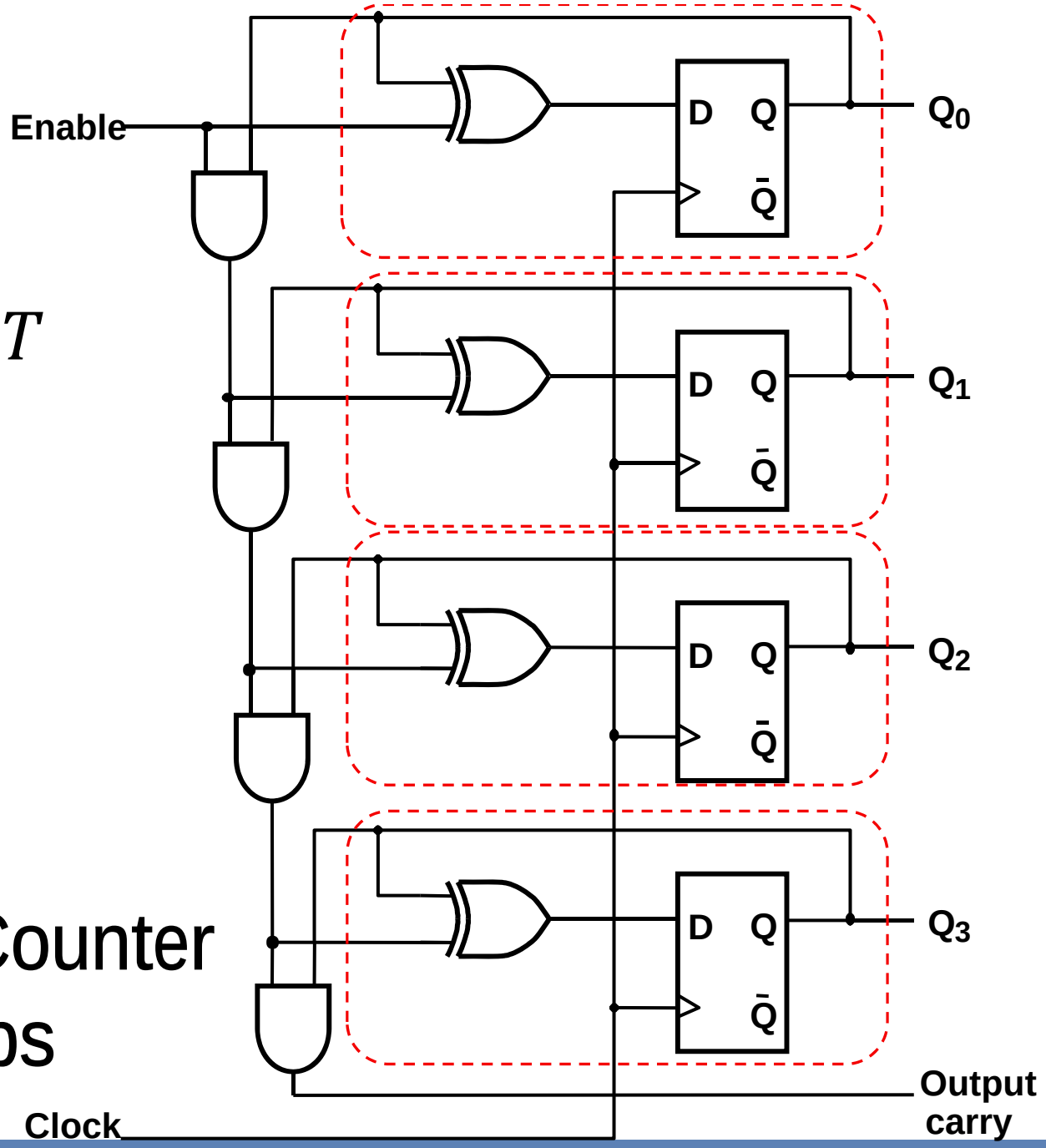


Synchronous Counter with D Flip-flops

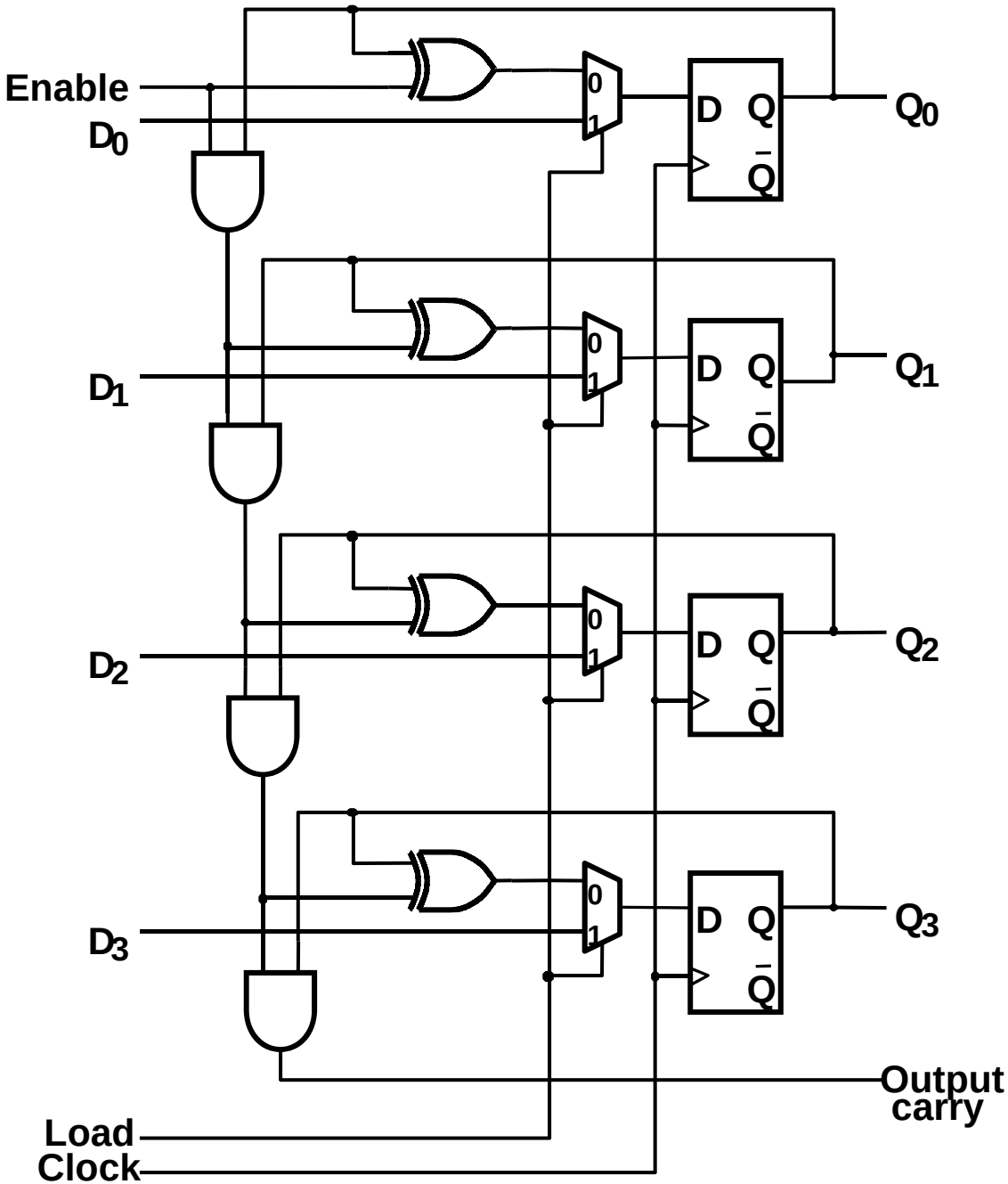
- $D_0 = \overline{Q_0} = 1 \oplus Q_0 (= Q_0 \oplus Enable)$
- $D_1 = Q_1 \oplus Q_0 (\cdot Enable)$
- $D_2 = Q_2 \oplus Q_1 Q_0 (\cdot Enable)$
- $D_3 = Q_3 \oplus Q_2 Q_1 Q_0 (\cdot Enable)$
- $D_i = Q_i \oplus Q_{i-1} Q_{i-2} \ldots . Q_1 Q_0 (\cdot Enable)$

Synchronous Counter with D Flip-flops

- $D = Q\bar{T} + \bar{Q}T$
  $= Q \oplus T$

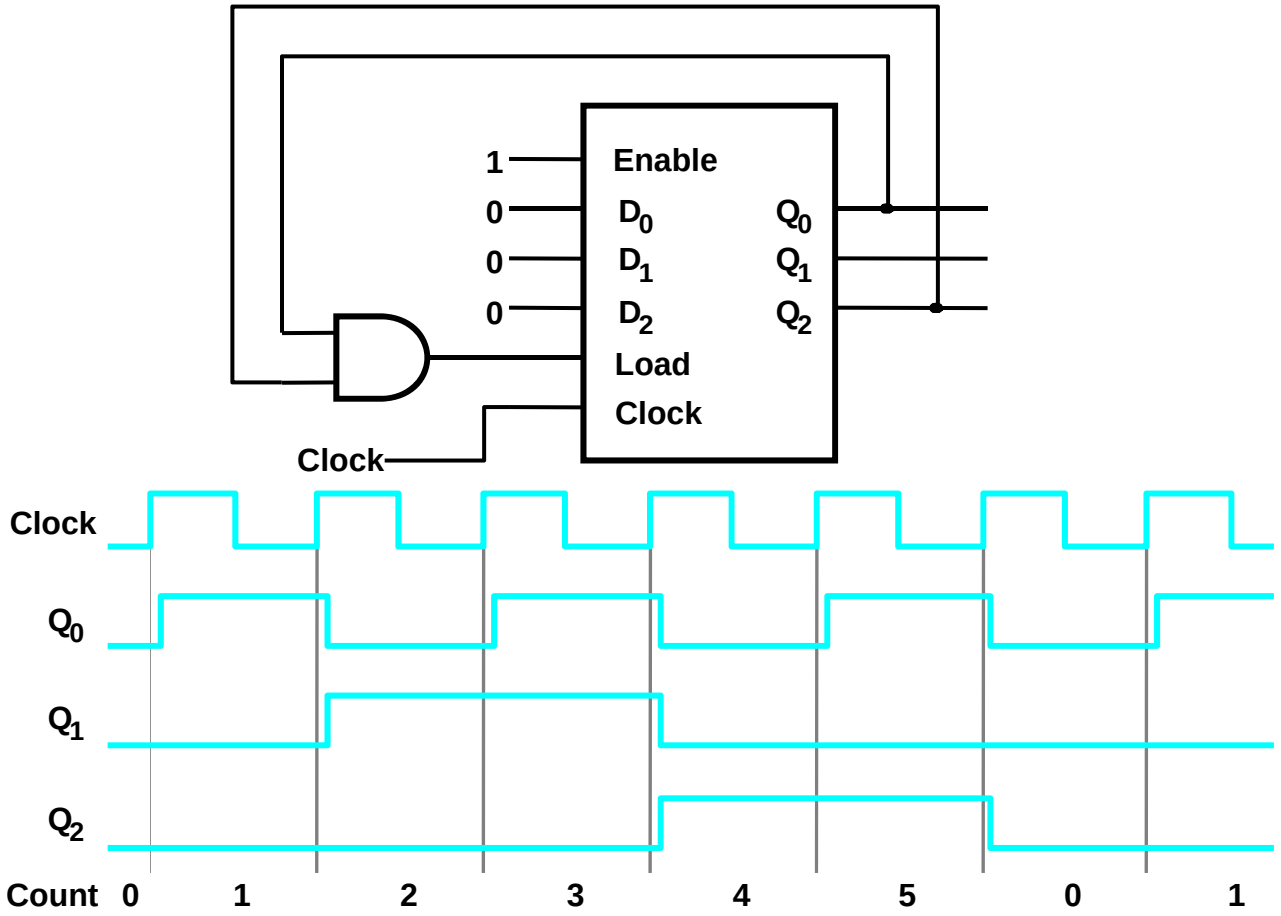


Counter with Parallel-load



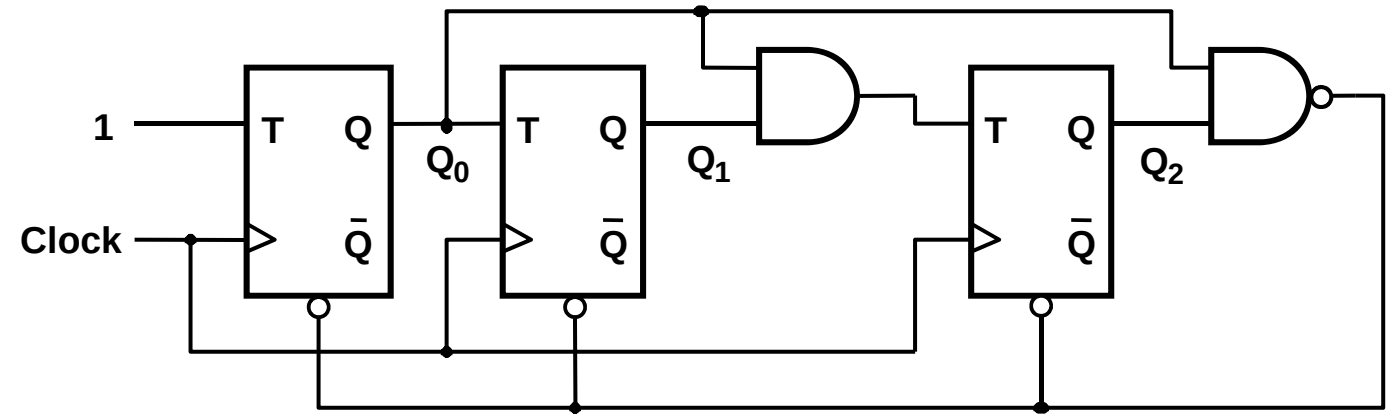
A Modulo-6 Counter with Synchronous Reset

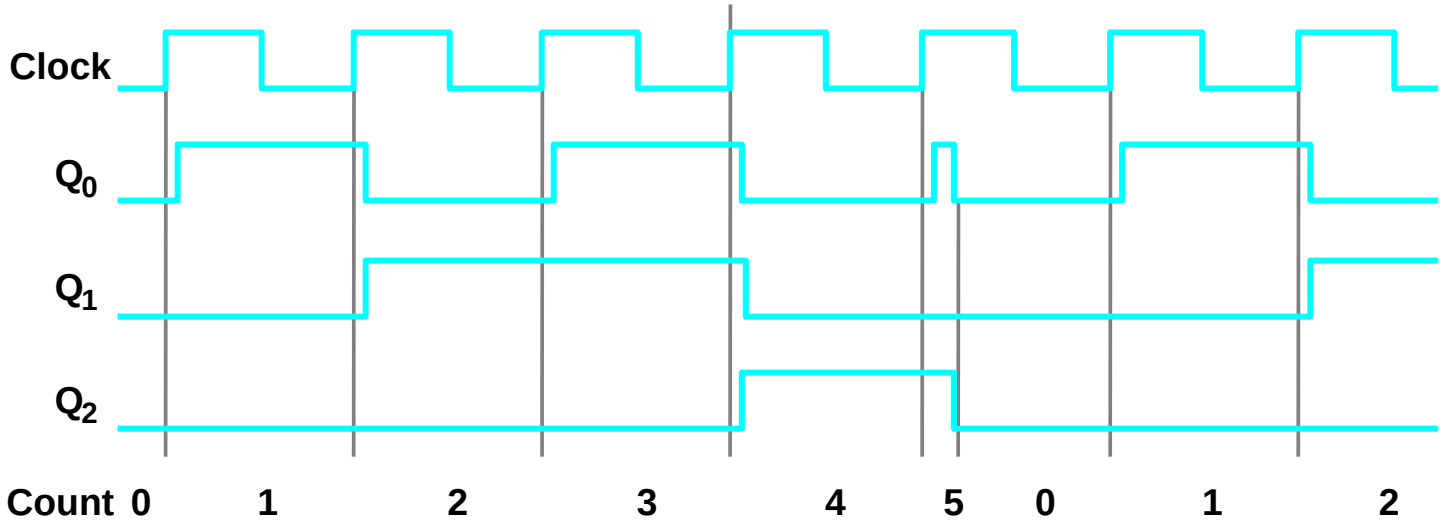
- Counting sequence: 0,1,2,3,4,5,0,1, and so on.



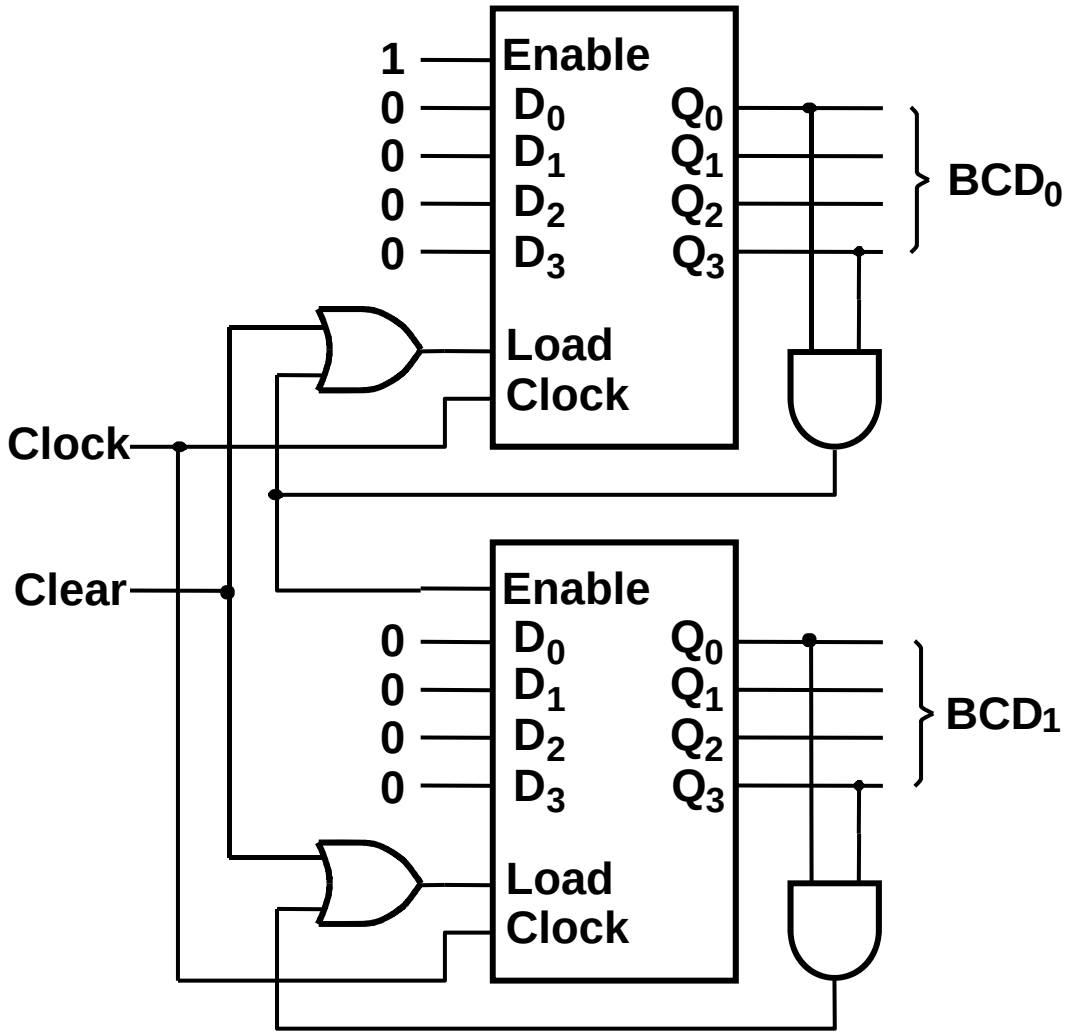
A Modulo-6 Counter with Asynchronous Reset

- Modulo 5 or 6?

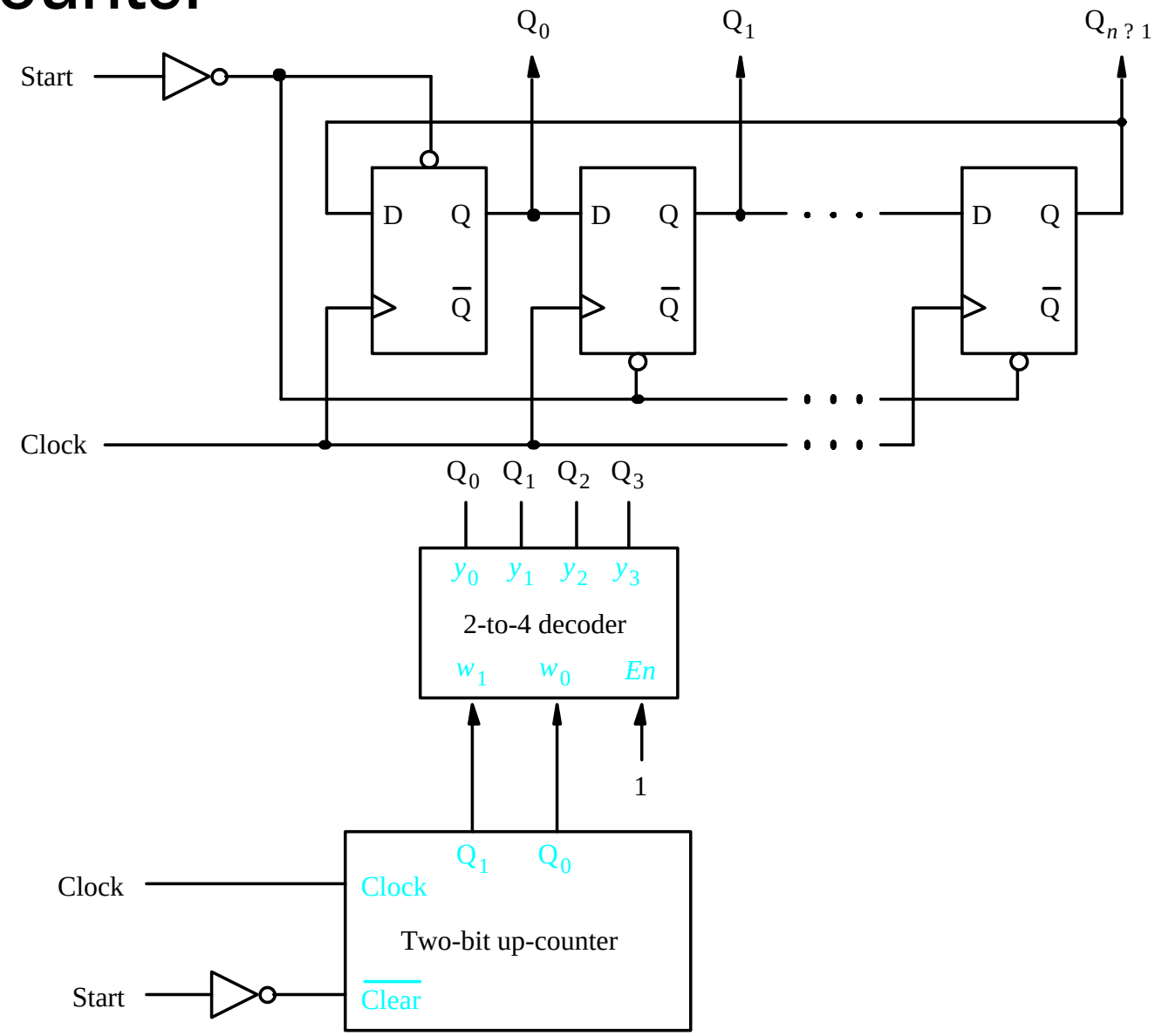




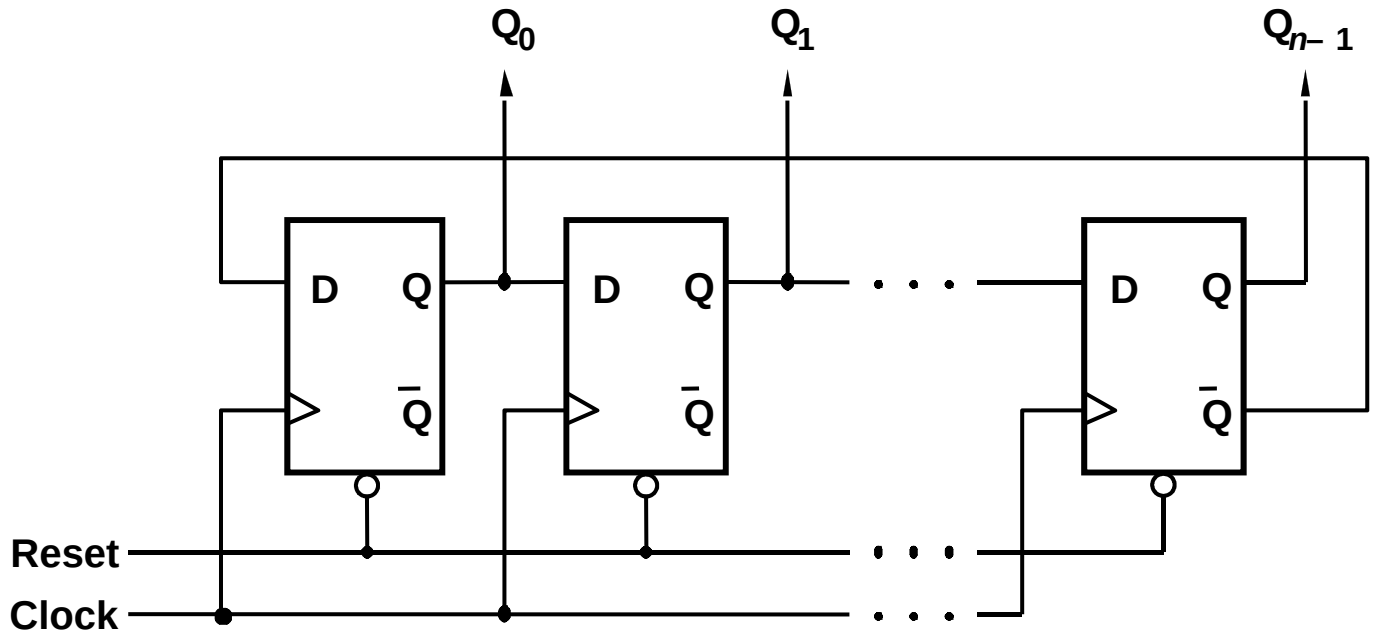
BCD Counter


1
0
0
0
0
Enable
D0
D1
D2
D3
Q0
Q1
Q2
Q3
Load
Clock
BCD0
Clock
Clear
Enable
D0
D1
D2
D3
Q0
Q1
Q2
Q3
Load
Clock
BCD1

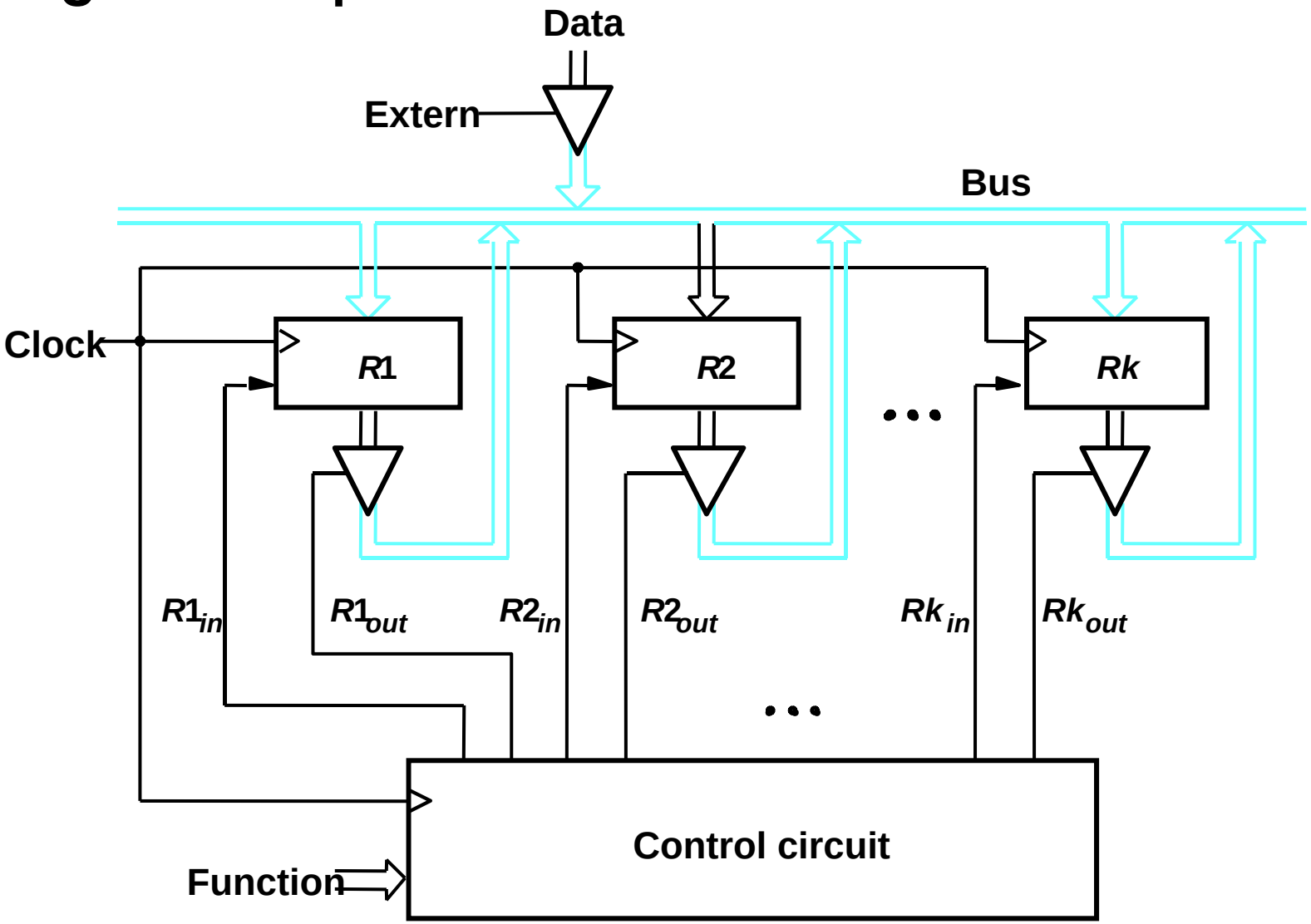
Ring Counter



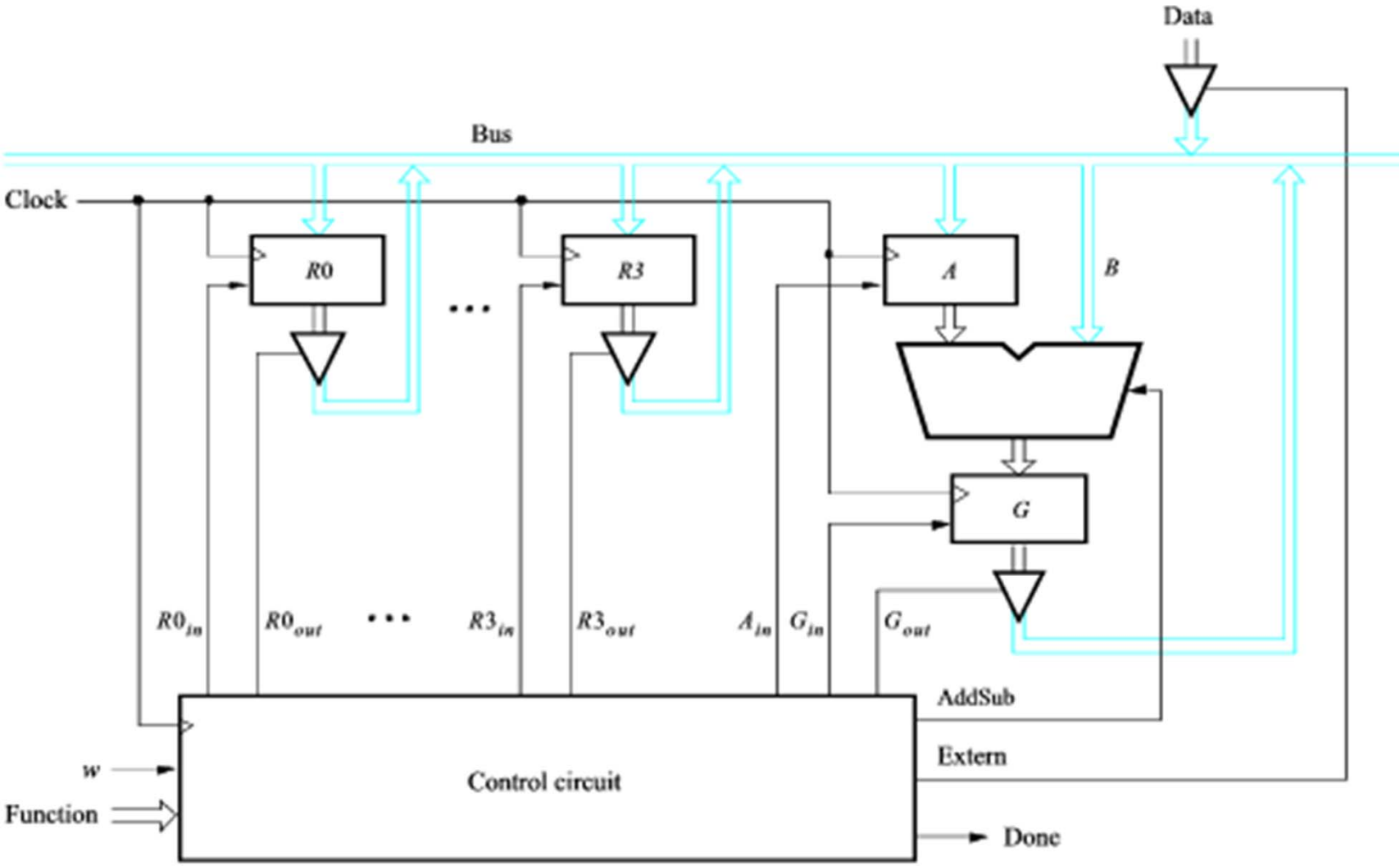
Johnson Counter



Design Example: Bus Structure



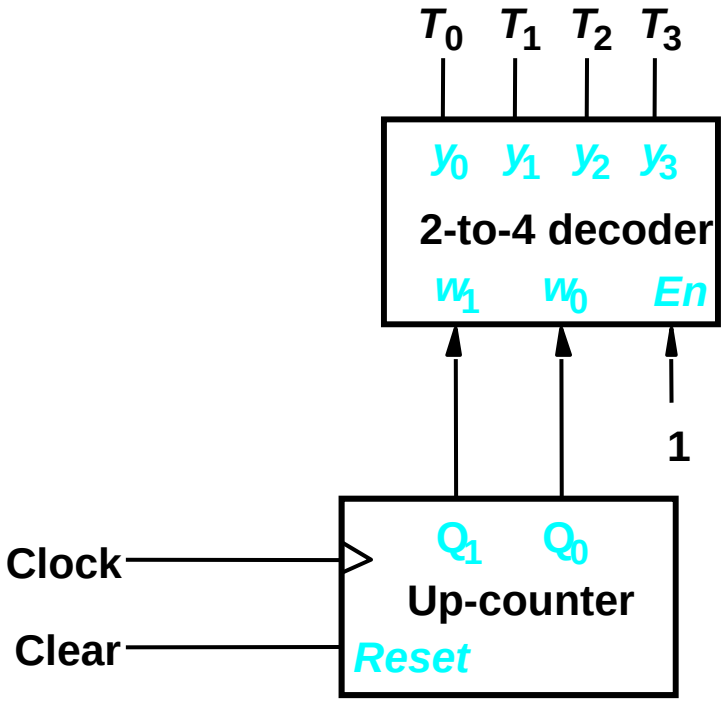
Simple Processor



Operation Performed in the Processor

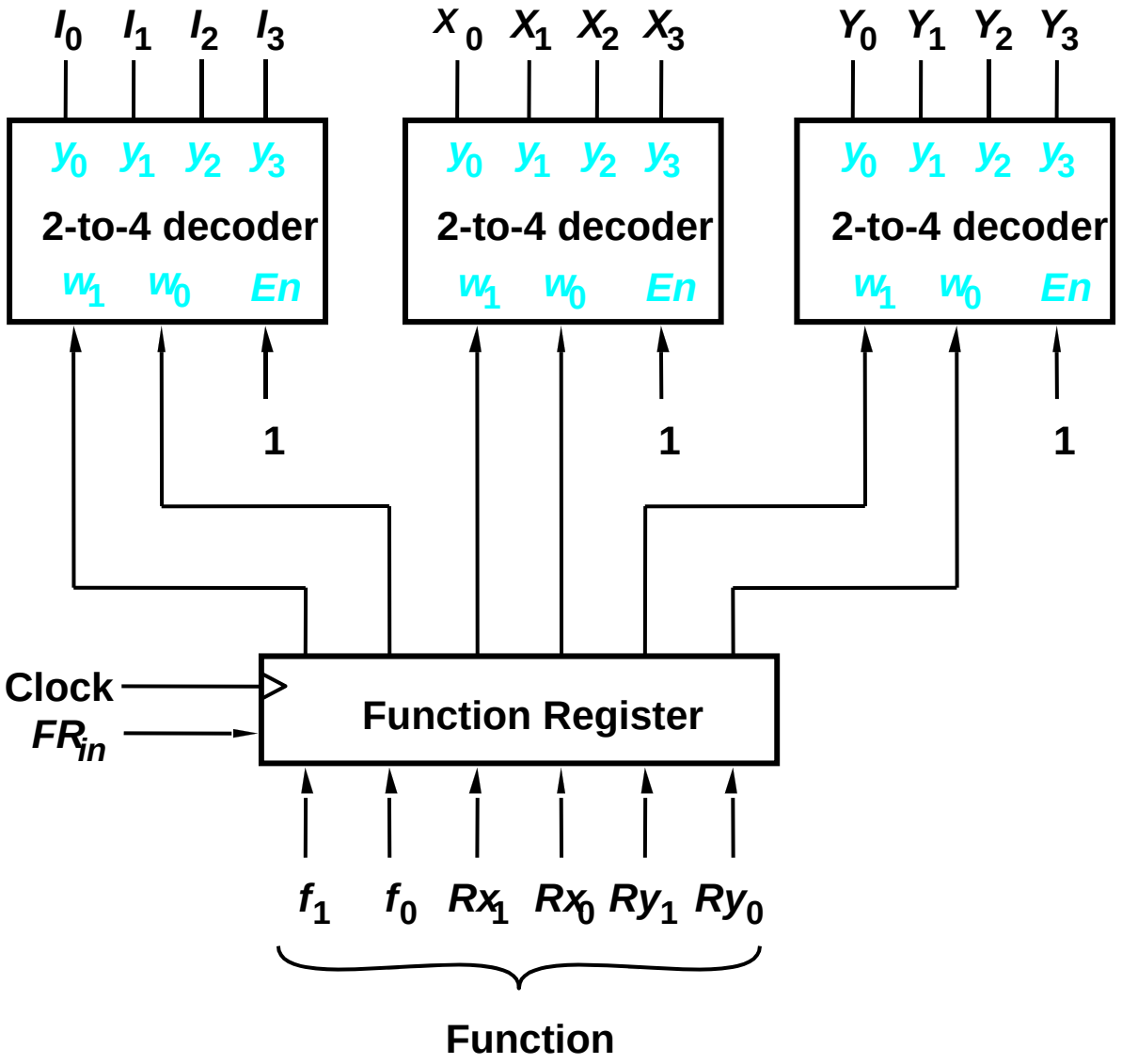
Operation	Function performed
Load Rx,$Data$	$Rx \leftarrow Data$
Move Rx, Ry	$Rx \leftarrow [Ry]$
Add Rx, Ry	$Rx \leftarrow [Rx] + [Ry]$
Sub Rx, Ry	$Rx \leftarrow [Rx] - [Ry]$

Control Circuit

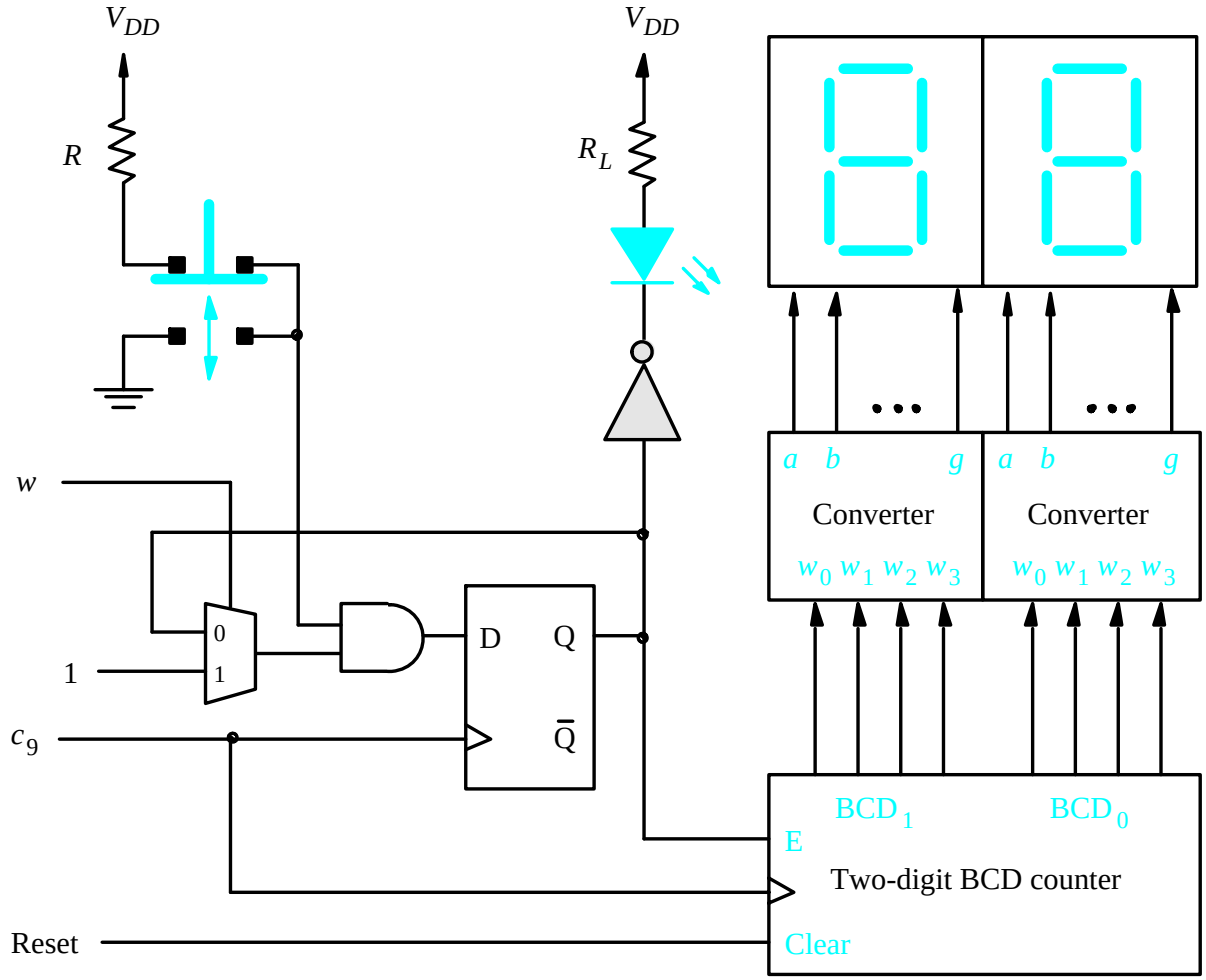


	T_1	T_2	T_3
(Load): I_0	*Extern*, $R_{in} = X$, *Done*		
(Move): I_1	$R_{in} = X$, $R_{out} = Y$, *Done*		
(Add): I_2	$R_{out} = X$, A_{in}	$R_{out} = Y$, G_{in}, $AddSub = 0$	G_{out}, $R_{in} = X$, *Done*
(Sub): I_3	$R_{out} = X$, A_{in}	$R_{out} = Y$, G_{in}, $AddSub = 1$	G_{out}, $R_{in} = X$, *Done*

Control Circuit

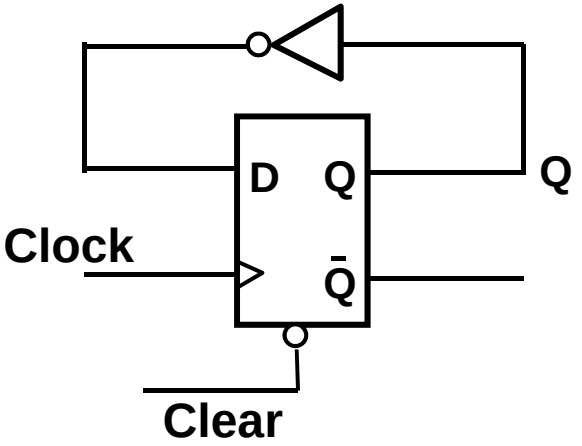


Reaction Timer



Timing Analysis

- $T_{min} = t_{cQ} + t_{NOT} + t_{su}$
- $F_{max} = \frac{1}{T_{min}}$
- A simple flip-flop circuit
  - $T_{min} = 1.0 + 1.1 + 0.6 = 2.7ns$
  - $F_{max} = \frac{1}{2.7ns} = 370.37\text{MHz}$



Timing Analysis for a 4-bit Counter

- $T_{min} = t_{cQ} + 3(t_{AND})$
  $+\mathrm{t_{XOR}} + t_{su}$
  $= 1.0 + 3(1.2) + 1.2 + 0.6$
  $= 6.4ns$
- $F_{max} = \frac{1}{6.4ns} = 156.25$ MHz