

# Machine Learning - 2021Fall - HW4

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1.(1%) 請以block diagram或是文字的方式說明這次表現最好的 model 使用哪些layer module(如 Conv/RNN/Linear 和各類 normalization layer) 及連接方式(如一般forward 或是使用 skip/residual connection) , 並概念性逐項說明選用該 layer module 的理由。

ANS:

本次作業中使兩層雙向LSTM相接一起，證明說雖然字詞的順序在理解語言關係很重要，但是使用的順序並不那麼重要。使用雙向LSTM的方法可以取得不錯的準確率。

後續的Dense層是想說如果使用Dense映射神經單元是否可以取得較好的成果，在準確率上而言是有，但提升效果幾乎微乎其微。我認為應該還是在處理文字上多下工夫才能提高準確率。

Layer (type)	Output Shape	Param #
embedding (Embedding)	(None, None, 50)	500000
bidirectional (Bidirectional)	(None, None, 256)	183296
dropout (Dropout)	(None, None, 256)	0
bidirectional_1 (Bidirectional)	(None, 256)	394240
dense (Dense)	(None, 64)	16448
dropout_1 (Dropout)	(None, 64)	0
dense_1 (Dense)	(None, 32)	2080
dropout_2 (Dropout)	(None, 32)	0
dense_2 (Dense)	(None, 1)	33
Total params: 1,096,097		
Trainable params: 1,096,097		
Non-trainable params: 0		

2.(1%) 請比較 word2vec embedding layer 初始設為 non-trainable/trainable 的差別，列上兩者在 validation/public private testing 的結果，並嘗試在訓練過程中設置一策略改變 non-trainable/trainable 設定，描述自己判斷改變設定的機制以及該結果。

ANS:

3.(1%) 請敘述你如何對文字資料進行前處理，並概念性的描述你在資料中觀察到什麼因此你決定採用這些處理，並描述使用這些處理時作細節，以及比較其實際結果，該結果可以不用具備真正改進。如果你沒有作任何處理，請給出一段具體描述來說服我們為什麼不做處理可以得到好的結果，這個理由不能是因為表現比較好。

ANS:

在部分單字中會有n ' t的設定，我認為如果拆成單字 not的話可能會有助於提高準確率。  
在模型相同的情況下，將n ' t拆解為not後準確率由0.80550提高到0.81530左右。

4.(1%) 請「自行設計」兩句具有相同單字但擺放位置不同的語句，使得你表現最好的模型產生出不同的預測結果，例如 "Today is hot, but I am happy" 與 "I am happy, but today is hot"，並討論造成差異的原因。

ANS:

RNN:

Today is hot, but I am happy. [0.08012492]

I am happy, but today is hot. [0.29768157]

RNN model給 I am happy, but today is hot.的分數較高(不過還是0.5以下所以不算惡意評論)。可見RNN有學到語意的部份，進而判斷說第一句是較為開心的。即RNN 則可以判斷字詞的不同順序會產生不同的語意，並分辨出這是兩個不同的句子，讓兩者輸出的值有些微的不同。

## 5. (4%) Refer to math problem

(<https://hackmd.io/@hAe95tLdTVqEePbZsJyqrw/BkWSTuqPF>)

### 1. Uni-gram language model and Maximum Likelihood Estimation (1%)

ANS:

### 2. LSTM Cell (1%)

when  $t = 1$ ,

$$z = w \cdot x + b = [0, 0, 0, 1] \cdot [0, 1, 0, 3] + 0 = 3 + 0 = 3$$

$$z_i = w_i \cdot x + b_i = [100, 100, 0, 0] \cdot [0, 1, 0, 3] + (-10) = 100 + (-10) = 90$$

$$z_f = w_f \cdot x + b_f = [-100, -100, 0, 0] \cdot [0, 1, 0, 3] + (110) = (-100) + 110 = 10$$

$$z_o = w_o \cdot x + b_o = [0, 0, 100, 0] \cdot [0, 1, 0, 3] + (-10) = 0 + (-10) = -10$$

$$c' = f(z_i)g(z) + cf(z_f) = \frac{1}{1 + e^{-90}} \cdot 3 + 0 \cdot \frac{1}{1 + e^{-10}} = 3$$

$$y = f(z_o)h(c') = \frac{1}{1 + e^{-(-10)}} \cdot 3 = 0$$

when  $t = 2$ ,

$$z = w \cdot x + b = [0, 0, 0, 1] \cdot [1, 0, 1, -2] + 0 = -2$$

$$z_i = w_i \cdot x + b_i = [100, 100, 0, 0] \cdot [1, 0, 1, -2] + (-10) = 90$$

$$z_f = w_f \cdot x + b_f = [-100, -100, 0, 0] \cdot [1, 0, 1, -2] + (110) = 10$$

$$z_o = w_o \cdot x + b_o = [0, 0, 100, 0] \cdot [1, 0, 1, -2] + (-10) = 90$$

$$c' = f(z_i)g(z) + cf(z_f) = \frac{1}{1 + e^{-90}} \cdot 3 + 3 \cdot \frac{1}{1 + e^{-10}} = 1$$

$$y = f(z_o)h(c') = \frac{1}{1 + e^{-90}} \cdot 1 = 1$$

when  $t = 3$ ,

$$z = w \cdot x + b = [0, 0, 0, 1] \cdot [1, 1, 1, 4] + 0 = 4$$

$$z_i = w_i \cdot x + b_i = [100, 100, 0, 0] \cdot [1, 1, 1, 4] + (-10) = 190$$

$$z_f = w_f \cdot x + b_f = [-100, -100, 0, 0] \cdot [1, 1, 1, 4] + (110) = -90$$

$$z_o = w_o \cdot x + b_o = [0, 0, 100, 0] \cdot [1, 1, 1, 4] + (-10) = 90$$

$$c' = f(z_i)g(z) + cf(z_f) = \frac{1}{1 + e^{-190}} \cdot 3 + (-2) \cdot \frac{1}{1 + e^{-(-90)}} = 4$$

$$y = f(z_o)h(c') = \frac{1}{1 + e^{-90}} \cdot 4 = 4$$

when  $t = 4$ ,

$$z = w \cdot x + b = [0, 0, 0, 1] \cdot [0, 1, 1, 0] + 0 = 0$$

$$z_i = w_i \cdot x + b_i = [100, 100, 0, 0] \cdot [0, 1, 1, 0] + (-10) = 90$$

$$z_f = w_f \cdot x + b_f = [-100, -100, 0, 0] \cdot [0, 1, 1, 0] + (110) = 10$$

$$z_o = w_o \cdot x + b_o = [0, 0, 100, 0] \cdot [0, 1, 1, 0] + (-10) = 90$$

$$c' = f(z_i)g(z) + cf(z_f) = \frac{1}{1 + e^{-90}} \cdot 0 + 4 \cdot \frac{1}{1 + e^{-10}} = 4$$

$$y = f(z_o)h(c') = \frac{1}{1 + e^{-90}} \cdot 4 = 4$$

when  $t = 5$ ,

$$\begin{aligned}
 z &= w \cdot x + b = [0, 0, 0, 1] \cdot [0, 1, 0, 2] + 0 = 2 \\
 z_i &= w_i \cdot x + b_i = [100, 100, 0, 0] \cdot [0, 1, 0, 2] + (-10) = 90 \\
 z_f &= w_f \cdot x + b_f = [-100, -100, 0, 0] \cdot [0, 1, 0, 2] + (110) = 10 \\
 z_o &= w_o \cdot x + b_o = [0, 0, 100, 0] \cdot [0, 1, 0, 2] + (-10) = 90 \\
 c' &= f(z_i)g(z) + cf(z_f) = \frac{1}{1 + e^{-90}} \cdot 2 + 4 \cdot \frac{1}{1 + e^{-10}} = 6 \\
 y &= f(z_o)h(c') = \frac{1}{1 + e^{-90}} \cdot 6 = 0
 \end{aligned}$$

when  $t = 6$ ,

$$\begin{aligned}
 z &= w \cdot x + b = [0, 0, 0, 1] \cdot [0, 0, 1, -4] + 0 = -4 \\
 z_i &= w_i \cdot x + b_i = [100, 100, 0, 0] \cdot [0, 0, 1, -4] + (-10) = (-10) \\
 z_f &= w_f \cdot x + b_f = [-100, -100, 0, 0] \cdot [0, 0, 1, -4] + (110) = 110 \\
 z_o &= w_o \cdot x + b_o = [0, 0, 100, 0] \cdot [0, 0, 1, -4] + (-10) = 90 \\
 c' &= f(z_i)g(z) + cf(z_f) = \frac{1}{1 + e^{-(-10)}} \cdot -4 + 6 \cdot \frac{1}{1 + e^{-110}} = 1 \\
 y &= f(z_o)h(c') = \frac{1}{1 + e^{-(-10)}} \cdot 6 = 6
 \end{aligned}$$

when  $t = 7$ ,

$$\begin{aligned}
 z &= w \cdot x + b = [0, 0, 0, 1] \cdot [1, 1, 1, 1] + 0 = 1 \\
 z_i &= w_i \cdot x + b_i = [100, 100, 0, 0] \cdot [1, 1, 1, 1] + (-10) = 190 \\
 z_f &= w_f \cdot x + b_f = [-100, -100, 0, 0] \cdot [1, 1, 1, 1] + (110) = -90 \\
 z_o &= w_o \cdot x + b_o = [0, 0, 100, 0] \cdot [1, 1, 1, 1] + (-10) = 90 \\
 c' &= f(z_i)g(z) + cf(z_f) = \frac{1}{1 + e^{-190}} \cdot 1 + 6 \cdot \frac{1}{1 + e^{-(-90)}} = 1 \\
 y &= f(z_o)h(c') = \frac{1}{1 + e^{-90}} \cdot 1 = 1
 \end{aligned}$$

when  $t = 8$ ,

$$\begin{aligned}
 z &= w \cdot x + b = [0, 0, 0, 1] \cdot [1, 0, 1, 2] + 0 = 2 \\
 z_i &= w_i \cdot x + b_i = [100, 100, 0, 0] \cdot [1, 0, 1, 2] + (-10) = 90 \\
 z_f &= w_f \cdot x + b_f = [-100, -100, 0, 0] \cdot [1, 0, 1, 2] + (110) = 10 \\
 z_o &= w_o \cdot x + b_o = [0, 0, 100, 0] \cdot [1, 0, 1, 2] + (-10) = 90 \\
 c' &= f(z_i)g(z) + cf(z_f) = \frac{1}{1 + e^{-90}} \cdot 2 + 1 \cdot \frac{1}{1 + e^{-10}} = 1 \\
 y &= f(z_o)h(c') = \frac{1}{1 + e^{-90}} \cdot 3 = 3
 \end{aligned}$$

$\therefore \text{Output} = 3$

### 3. Backpropagation through time via Simple RNN (1%)

ANS:

### 4. Multiclass AdaBoost (1%)

ANS:

$$\begin{aligned}
 L(g_t^1 \dots g_t^k) &= \sum_{i=1}^n \exp\left(\frac{1}{k} \sum g_t^k(x_i) - \hat{g}_t^{y_i}(x_i)\right) \\
 &= \sum_{i=1}^n \exp\left(\frac{1}{k-1} \sum_{k \neq \hat{y}_i} g_{t-1}^k(x_i) + \frac{a_t^k f_t(x)}{k-1} - \hat{g}_t^{y_i}(x_i)\right) + \sum_{i=1}^n \exp\left(\frac{1}{k-1} \sum_{k \neq \hat{y}_i} g_{t-1}^k(x_i) - a_t^k f_t(x) - \hat{g}_t^{y_i}(x_i)\right) \\
 \therefore \Delta L &= L(g_t^k) - L(g_{t-1}^k) \\
 &= \sum_{i=1}^n \exp\left(\frac{1}{k} \sum g_t^k(x_i) - \hat{g}_t^{y_i}(x_i)\right) \left(\exp\left(\frac{a_t^k f_t(x)}{k-1}\right) - 1\right) + \sum_{i=1}^n \exp\left(\frac{1}{k} \sum g_t^k(x_i) - \hat{g}_t^{y_i}(x_i)\right) \left(\exp(a_t^k f_t(x)) - 1\right) \\
 &= \sum_{i=1}^n \exp\left(\frac{1}{k} \sum g_t^k(x_i) - \hat{g}_t^{y_i}(x_i)\right) \left(\exp\left(\frac{a_t^k f_t(x)}{k-1}\right) - \exp(a_t^k f_t(x))\right) \\
 \therefore \frac{\partial \Delta L}{\partial a_t} &= \frac{f_t(x)}{k-1} \sum \exp\left(\frac{1}{k} \sum g_t^k(x_i) - \hat{g}_t^{y_i}(x_i)\right) - f_t(x) \sum \exp\left(\frac{1}{k-1} \sum g_{t-1}^k(x_i) - \hat{g}_t^{y_i}(x_i)\right)
 \end{aligned}$$

$$\text{Let } \frac{\partial \Delta L}{\partial a_t} = 0$$

$$\frac{\partial \Delta L}{\partial a_t} = \sum_{k=\hat{y}_i} u_t^n e^{a_t} \frac{1}{k-1} - \sum_{k=\hat{y}_i} u_t^n e^{a_t} = 0$$

$$\Rightarrow z_t \varepsilon_t e^{a_t} \frac{1}{k-1} - z_t (1 - g_t) e^{-a_t} = 0$$

$$\Rightarrow e^{a_t} = (k-1) \left( \frac{1 - \varepsilon_t}{\varepsilon_t} \right)$$

$$\Rightarrow a_t = \ln \left( \sqrt{(k-1) \left( \frac{1 - \varepsilon_t}{\varepsilon_t} \right)} \right)$$