## Recap from last class

- Timers and counters
  - Watchdog timer
- Practical I/O interfaces
  - Parallel I/O vs. serial I/O
  - General mode: master/slave connections
  - Inter-integrated Circuit (I<sup>2</sup>C or I2C)
  - Serial Peripheral Interface (SPI)
  - Universal Serial Bus (USB)
  - General-Purpose IO (GPIO)

# ECE 1175 Embedded Systems Design

### **ARM Architecture**

Wei Gao

# **ARM Architecture**

Dominant architecture for embedded systems



### **ARM Architecture**

- Who is ARM?
  - Founded in November 1990
  - Designs the ARM range of RISC processor cores
  - Licenses ARM core designs to semiconductor partners who fabricate and sell to their customers
  - Software tools, boards, debug hardware, application software, bus architectures, peripherals etc



# **ARM Partnership**

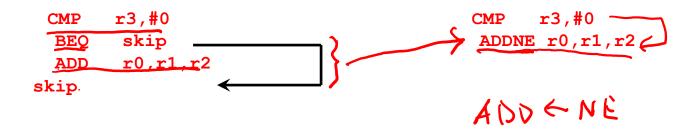


## **ARM Instruction Sets**





- ARM instructions can be made to execute conditionally by postfixing them with the appropriate condition code field.
  - This improves code density and performance by reducing the number of forward branch instructions.



### **Condition Codes**

- The possible condition codes are listed below:
  - Note AL is the default and does not need to be specified

Suffix	Description	Flags tested
EQ	Equal	Z=1
NE	Not equal	Z=0
CS/HS	Unsigned higher or same	C=1
CC/LO	Unsigned lower	C=0
MI	Minus	N=1
PL	Positive or Zero	N=0
VS	Overflow	V=1
VC	No overflow	V=0
HI	Unsigned higher	C=1 & Z=0
LS	Unsigned lower or same	C=0 or Z=1
GE	Greater or equal	N=V
LT	Less than	N!=V
GT	Greater than	Z=0 & N=V
LE	Less than or equal	Z=1 or N=!V
AL	Always	

# Examples of conditional execution

Use a sequence of several conditional instructions

```
if (a==0) func(1);

CMP r0,#0

MOVEO r0,#1

BLEO func
```

Set the flags, then use various condition codes

```
if (a==0) x=0;
if (a>0) x=1;

CMP r0,#0

MOVEQ r1,#0

MOVGD r1,#1
```

Use conditional compare instructions

```
if (a==4 || a==10) x=0;

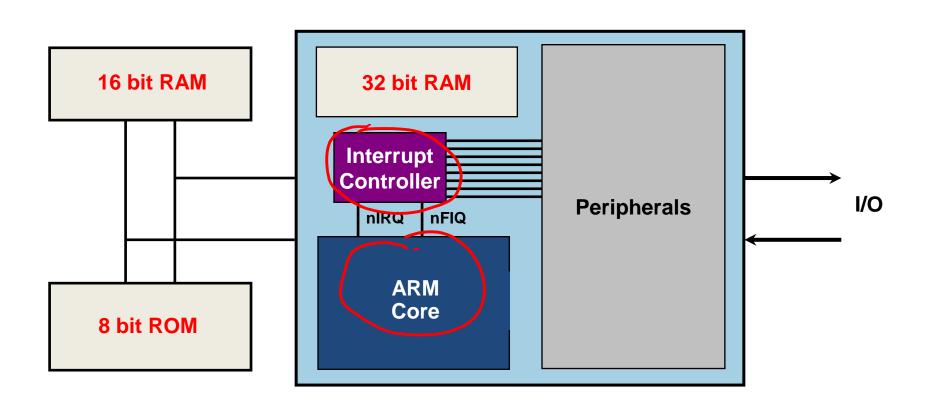
CMP r0,#4

CMPNE r0,#10

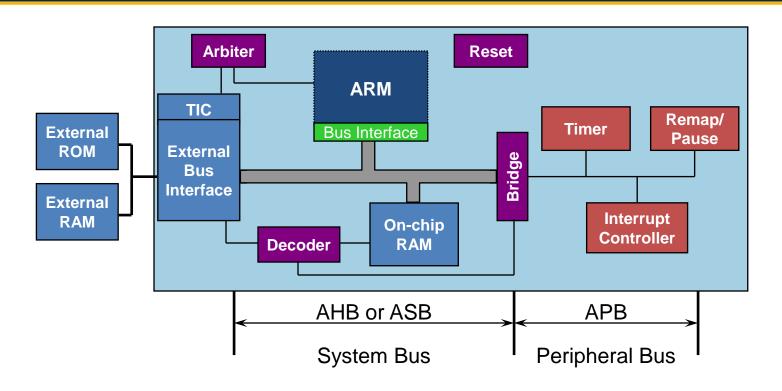
MOVEQ r1,#0
```

# ARM System Design Controller. ~ Special





# **ARM Bus System**



#### AMBA

Advanced Microcontroller Bus Architecture

#### ADK

Complete AMBA Design Kit

#### ACT

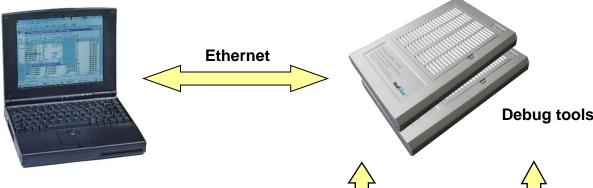
AMBA Compliance Testbench

#### PrimeCell

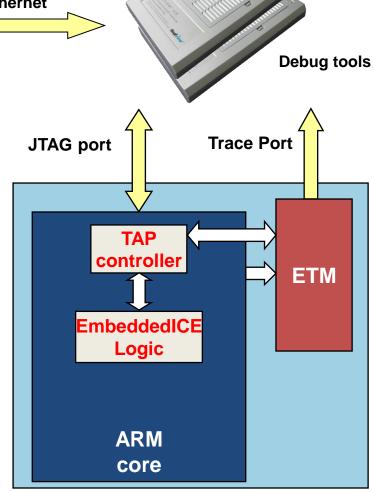
ARM's AMBA compliant peripherals

# **Debugging ARM**

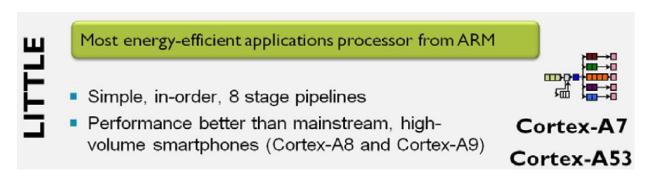
Debugger (+ optional trace tools)



- EmbeddedICE Logic
  - Provides breakpoints and processor/system access
- JTAG interface (ICE)
  - Converts debugger commands to JTAG signals
- Embedded trace Macrocell (ETM)
  - Compresses real-time instruction and data access trace
  - Contains ICE features (trigger & filter logic)
- Trace port analyzer (TPA)
  - Captures trace in a deep buffer

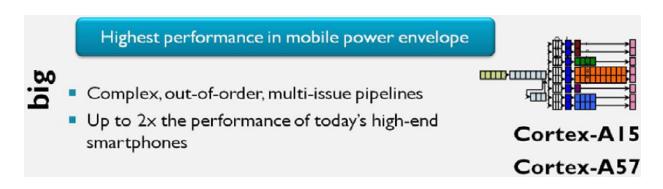


- ARM: Same architecture, different micro-architecture
  - Cortex A7:



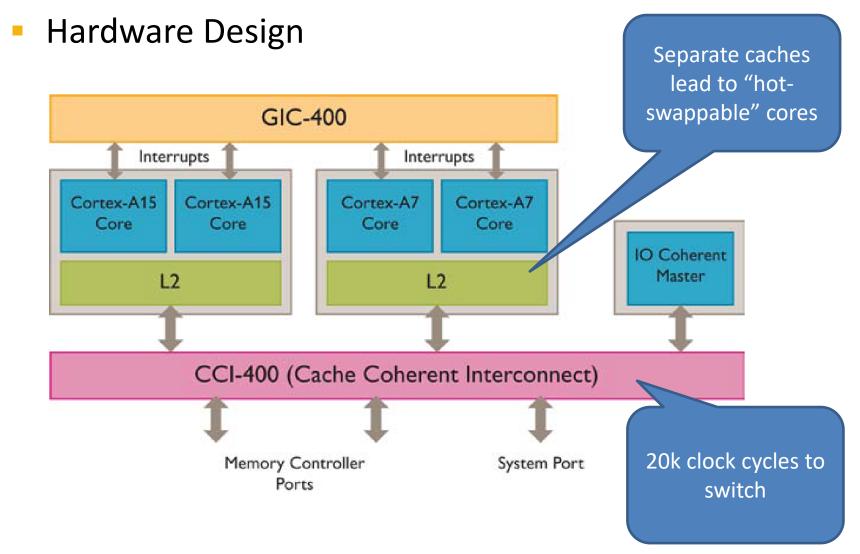
4 ARM
WHEX A.7.

Cortex A15:



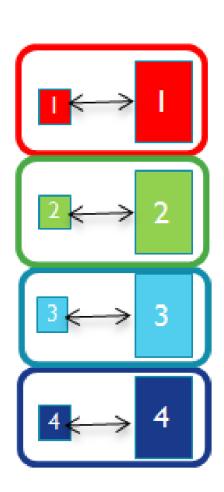
- ARM: Same architecture, different micro-architecture
- Design principle
  - Prompt switch between the big and little cores
  - Only computation intensive tasks on the big cores
  - Little cores for I/O-expensive tasks



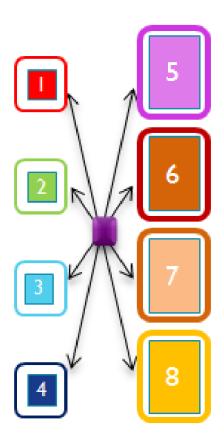


- Software Design: How to switch between cores
  - Clustered switching via CPU migration
  - Pairing the big and little cores
  - Only one core in each pair can be active at one time

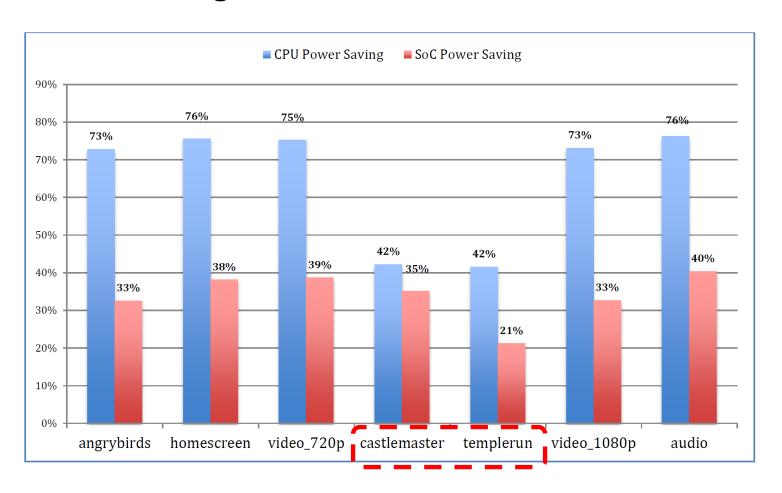
- Various implementations
  - Example: <u>In-kernel switcher from Linaro</u>



- Software Design: When to switch between cores
  - Global task scheduling
  - Based on the difference of computing capability
  - Thread-level scheduling based on their computing needs
    - RMS/EDF scheduling policy is then applied
  - Unused processors can be powered off



#### Power saving



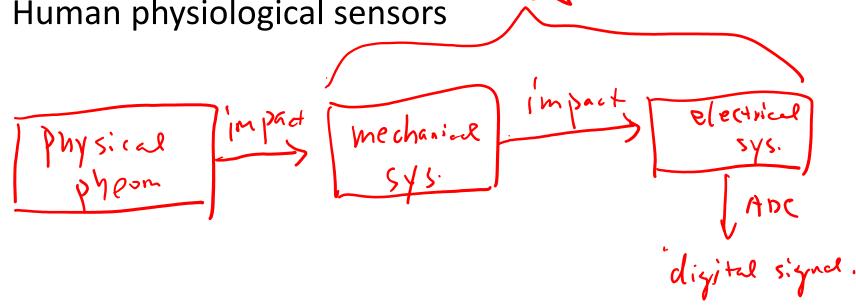
# ECE 1175 Embedded Systems Design

# **Embedded Sensor Designs**

Wei Gao

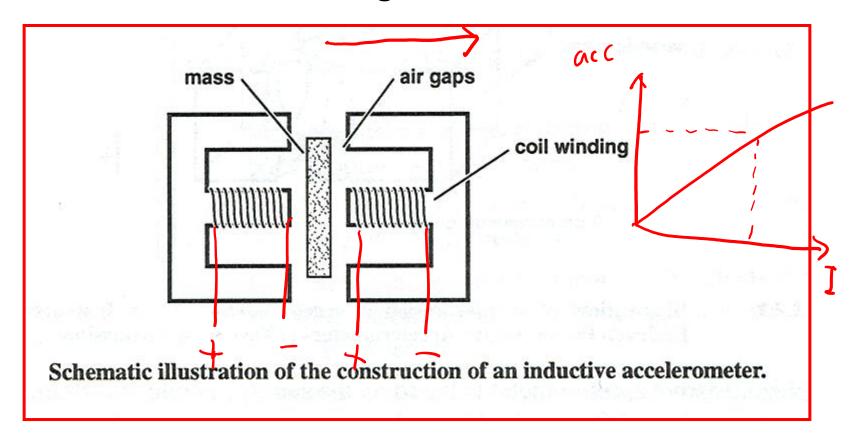
# **Great variety of on-board sensors**

- Accelerometer and gyroscope
- Ambient light
- Heart beat sensor
- Human physiological sensors



## Accelerometer

Inductive-based sensing



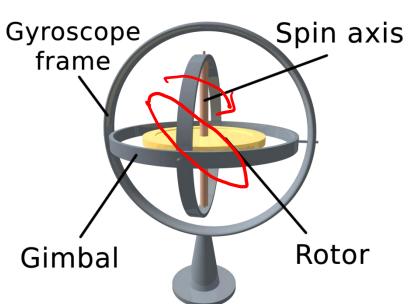
## Gyroscope

Measure or maintain orientation



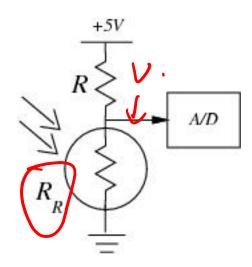
Working based on angular momentum

Consisting of a spinning mass on an axel



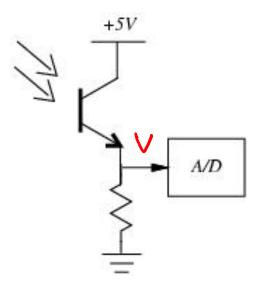
# **Ambient Light Sensor**

- Photo-resistor based
  - voltage divider  $V_{signal} = (5V) R_R/(R + R_R)$ 
    - Choose R=R<sub>R</sub> when ambient light is midrange
    - Cheap



# **Ambient Light Sensor**

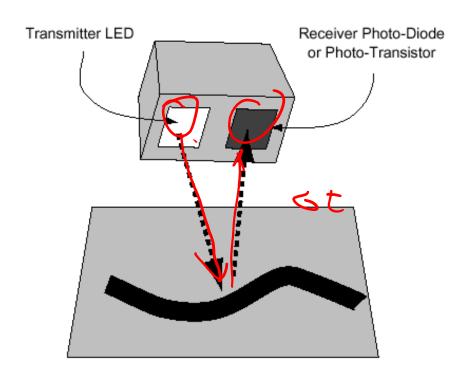
- Photo-transistor based
  - Greater sensitivity

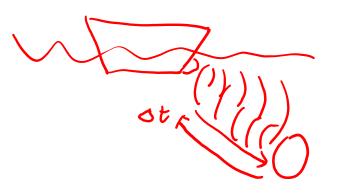


# **Proximity Sensor**

- An application of reflective opto-sensors
  - Using invisible beams: IR or ultrasonic

Somar

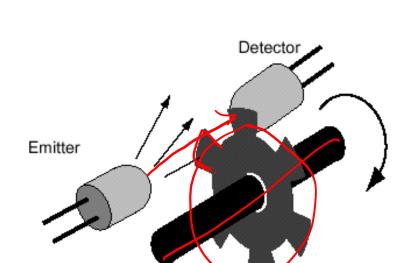




# **Proximity Sensor**

Extension: break beam sensors

The emitter and detector are facing each other





Tachometer: RPM measurement

### **Heart Beat Sensor**

Widely provided at wearables



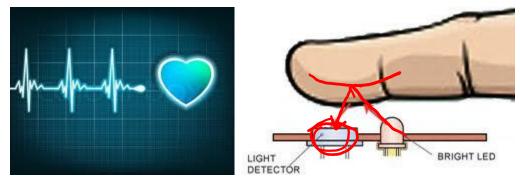


Difficulty: what's happening inside the body?

### **Heart Beat Sensor**



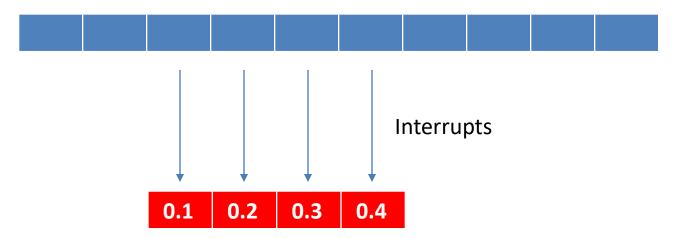
- How does it work?
  - Optoelectronics-based solution



- More blood pumping (heart squeezing) leads to more light absorption
- Less blood pumping (heart relaxing) leads to less light absorption
- Light detector: light-sensitive resistor -> voltage variation

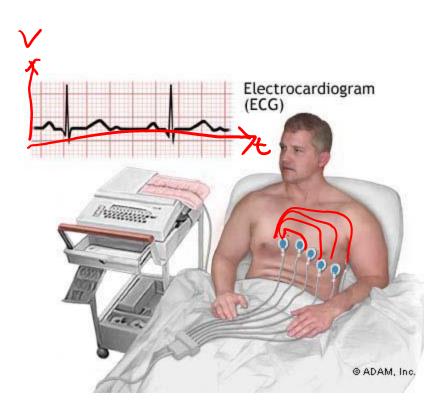
### **Heart Beat Sensor**

- Connecting the sensor to the system
  - Counting the heart beat: N per every 60 seconds
    - Weighted moving average



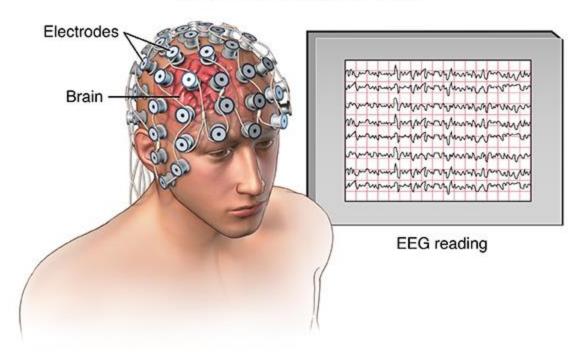
- Reducing the latency
  - Sampling over 10 seconds instead of 60 seconds

- Electrocardiography (ECG)
  - Electrical patterns of heart beating



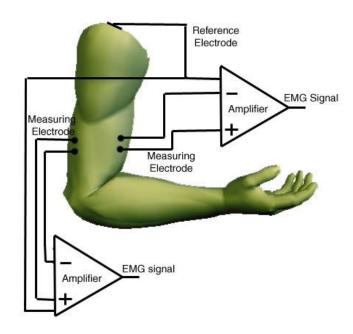
- Electroencephalography (EEG)
  - Electrical response to brain activity

#### Electroencephalogram (EEG)

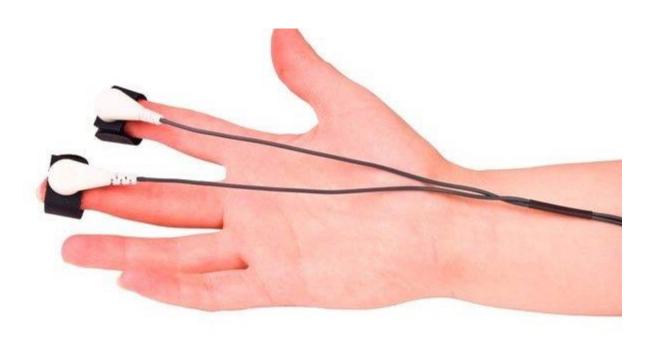


- Electromyography (EMG)
  - Electric response to muscle movement

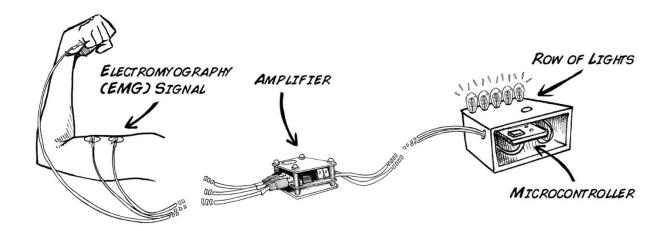




Galvanic Skin Response (GSR)



# Actuation through your body



- Signal processing: denoising and smoothing
- Pattern recognition: classification & feature extraction
- I/O interfacing

# Commonality

- A system that changes "physical" to "cyber"
  - Physical: a mechanical device that varies with the target being measured
  - Middleware: mechanical changes -> electrical changes
  - Cyber: digital interface that is readable by computer

New sensing modularities?