Recap of Last Class

- Characteristics of embedded systems
 - Real-time, low power, performance constraints
- Why use a microprocessor
 - Alternatives: ASIC, microprocessor, FPGA
 - Microprocessor: reprogramability, performance/power ratio

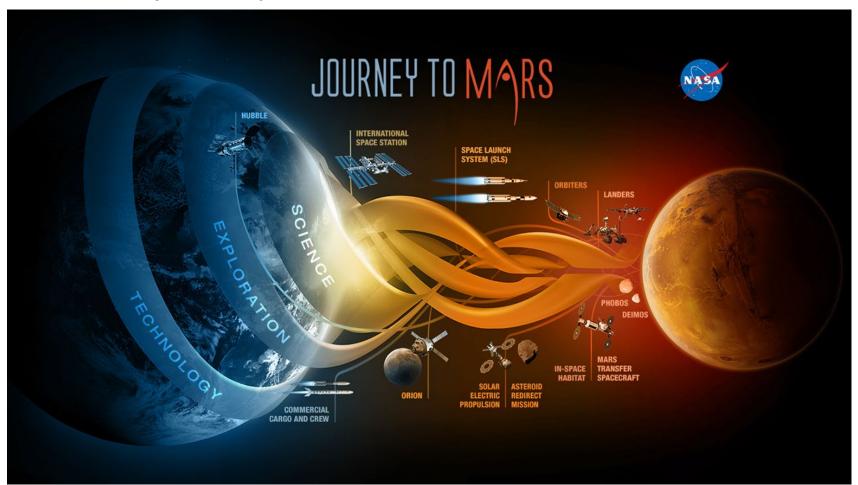
ECE 175 Embedded Systems Design

Design Methodology II

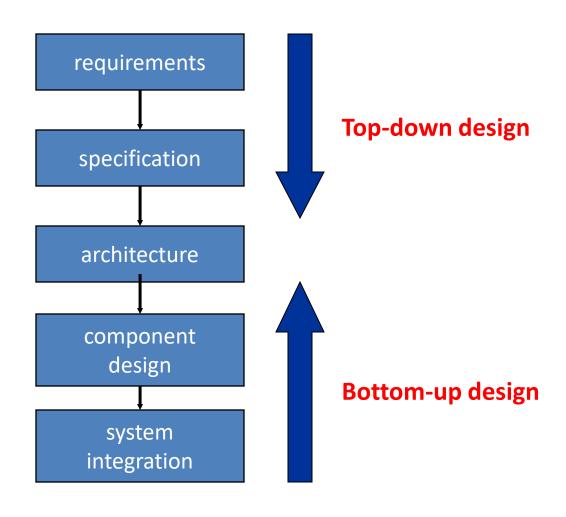
Wei Gao

How to fly to Mars?

NASA's journey to Mars



Design Methodologies



Requirements

- Plain language description of what the user wants and expects to get.
- May be developed in several ways:
 - Talking directly to customers;
 - Providing prototypes to users for comment.
- Functional vs. non-functional requirements
 - Functional: output as a function of input
 - Non-functional: timing constraints, power consumption, size, weight, etc.

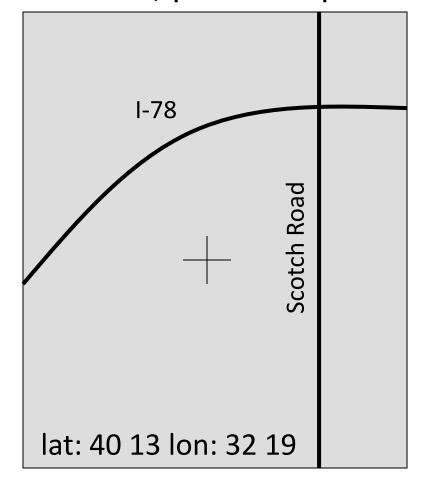
Requirements Form

```
name
purpose
inputs
outputs
functions
performance
manufacturing cost
power
physical size/weight
```

Example: GPS Moving Map Requirements

Purpose: Obtains position from GPS, paints map

from local database.



GPS Moving Map Requirements

Functionality

- For car driving use, not for airplanes or boats
- Show major roads and landmarks.

User interface

- At least 400 x 600 pixel screen.
- Three buttons max.
- Pop-up menu.

Performance

- No more than 1 sec power-up.
- Lock onto GPS within 15 seconds.
- Update location every 0.25 sec.

GPS Moving Map Requirements

- Cost: street price no more than \$100
- Physical size/weight: Should fit in hand.
- Power consumption: Should run for at least 8 hours on four AA batteries.

GPS Map Requirements From

name GPS moving map

purpose consumer-grade

moving map for driving

inputs power button, two

control buttons

outputs back-lit LCD 400 X 600

functions 5-receiver GPS; three

resolutions; displays

current lat/lon

performance updates screen within

0.25 sec of movement

manufacturing cost \$100 cost-of-goods-

sold

power 100 mW

physical size/weight no more than 2: X 6:,

12 oz.

Specification

- More precise description of the system:
 - should not imply a particular architecture;
 - provides input to the architecture design process.
- May include functional and non-functional elements.
- UML: Unified Modeling Language
 - Not required in this course

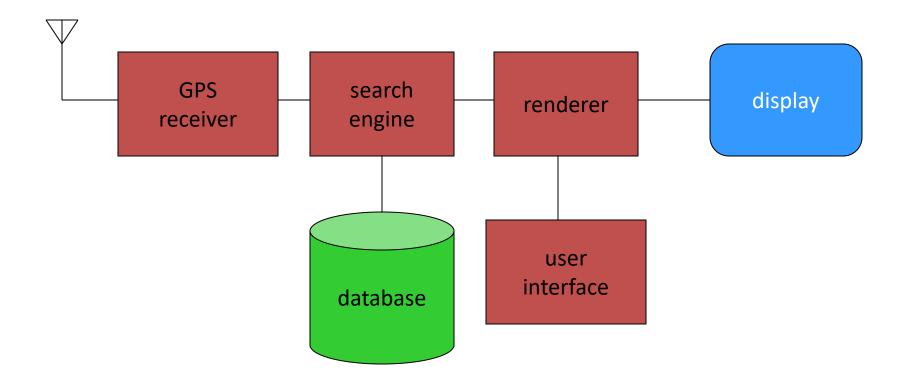
GPS Specification

- Should include:
 - what is received from GPS;
 - map data, format;
 - user interface, menu items;
 - operations required to satisfy user requests;
 - background operations needed to keep the system running
 - Event-driven or periodic?.

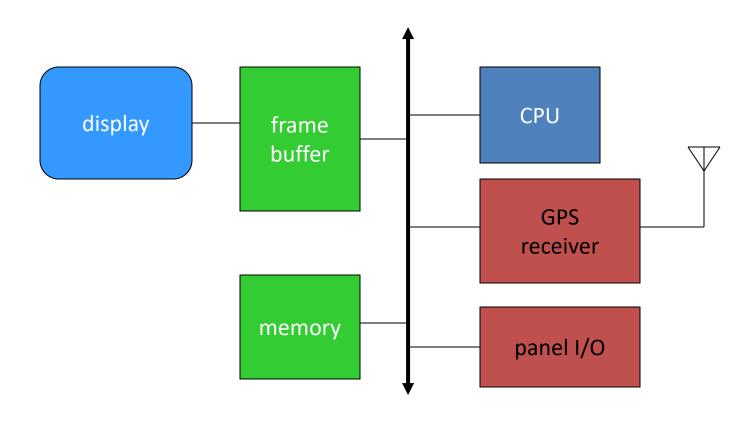
Architecture Design

- What major components can satisfy the specifications?
- Hardware components:
 - CPUs, memory, GPS receiver, etc.
- Software components:
 - Topographical database, access functions, etc.
- Must take into account functional and non-functional specifications.

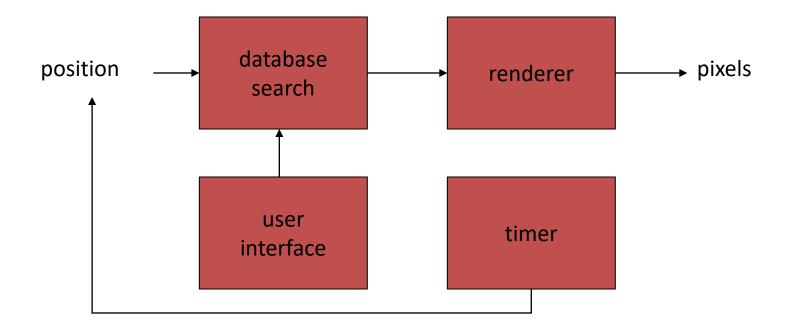
GPS Moving Map Block Diagram



GPS Moving Map Hardware Architecture



GPS Moving Map Software Architecture



Designing Hardware and Software Components

- Must spend time architecting the system before you start coding.
- Components maybe
 - ready-made
 - modified from existing designs
 - designed from scratch
- Components in an embedded system will be covered in following classes

System Integration

- Put together the components.
 - Many bugs appear only at this stage.
 - Individual components should be tested first!

Summary

- Characteristics of embedded systems
 - Non-functional requirements: real-time, low-power, low-cost
- Why do we use microprocessors today?
- Embedded systems pose many design challenges:
 - Design time
 - Deadlines
 - Power
 - Cost
 - •
- Design methodologies help us manage the design process.
 - Top-down vs. bottom-up

Homework Assignment 1

- On design methodology
- 3% of your final grade
 - Individual work, no collaboration is allowed
- One-week turnaround time
 - Due on 1/26 before class
 - Submit your work on Canvas as a separate file