CSE 417T
Introduction to Machine Learning

Lecture 15
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Logistics

- Homework 4 is due April 1 (Friday)

- Keep track of your own late days
  - Gradescope doesn't allow separate deadlines
  - Your submissions won't be graded if you exceed the late-day limit

Logistics: E-Chapters of LFD

- The textbook offers a set of e-chapters
  - Chap 6: Similarity-Based Methods
  - Chap 7: Neural Networks
  - Chap 8: Support Vector Machines
  - Chap 9: Learning Aides
  - Appendix B: Linear Algebra
  - Appendix C: The E-M Algorithm

- How to access e-chapters
  - http://amlbook.com/eChapters.html
  - "To access the e-Chapters, please download the PDFs below and open them with *the **first word of Chapter 4*** as the password. Enjoy!"

Exam 1 Discussion

I plan to finish grading this week and return the exam.

Recap

Ensemble Learning

- Goal: Utilize a set of weak learners to obtain a strong learner.

- Format of ensemble learning
  - Construct many diverse weak learners
  - Aggregate the weak learners

Bagging:
- Construct diverse weak learners
  - (Simultaneously) bootstrapping datasets
  - Train weak learners on them

- Aggregate the weak learners
  - Uniform aggregation

Boosting
- Construct diverse weak learners
  - Adaptively generating datasets
  - Train weak learners on them

- Aggregate the weak learners
  - Weighted aggregation

Bagging and Random Forest

- Construct many random trees
  - Bootstrapping datasets (sample with replacement from D)
  - Learn a max-depth tree for each of them
  - Other randomizations (not required in HW4)
    - When choosing split features, choose from a random subset (instead of all features)
    - Randomly project features (similar to non-linear transformation) for each tree

- Aggregate the random trees
  - Classification: Majority vote $\bar{g}(\vec{x}) = sign\left(\frac{1}{M}\sum_{m=1}^{M} g_m(\vec{x})\right)$
  - Regression: Average $\bar{g}(\vec{x}) = \frac{1}{M}\sum_{m=1}^{M} g_m(\vec{x})$

Note for HW4:
Recommend to transform the labels to +1/-1 for the convenience of aggregation.

Outline of a Boosting Algorithm

- Initialize D_1 (usually the same as the initial dataset D)

- For $t = 1$ to T
  - Learn g_t from D_t
  - Reweight the distribution and obtain D_{t+1} based on g_t and D_t

- Output weighted-aggregate$(g_1, \dots, g_T)$
  - Classification: $G(\vec{x}) = \bar{g}(\vec{x}) = sign\left(\frac{1}{T}\sum_{t=1}^{T}\alpha_t g_t(\vec{x})\right)$
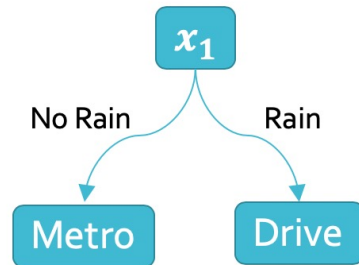
Questions

How to learn g_t from D_t

How to reweight the distribution and obtain D_{t+1}

How to perform weighted aggregation

AdaBoost Algorithm

How to learn g_t from D_t
- Decision stump

How to reweight D_{t+1}
- Make $E_{in}^{(D_{t+1})}(g_t) = 0.5$
- So g_t and g_{t+1} are "diverse"

How to weighted aggregation
- More weights on better g_t
- Lower ϵ_t: proxy for better g_t

- Given $D = \{(\vec{x}_1, y_1), \ldots, (\vec{x}_N, y_N)\}$
- Initialize $D_1(n) = 1/N$ for all $n = 1, \ldots, N$
- For $t = 1, \ldots, T$
  - Learn g_t from D_t (using decision stumps)
  - Calculate $\epsilon_t = E_{in}^{(D_t)}(g_t)$
  - Set $\alpha_t = \frac{1}{2} \ln\left(\frac{1-\epsilon_t}{\epsilon_t}\right)$
  - Update $D_{t+1}(n) = \frac{1}{Z_t} D_t(n) e^{-\alpha_t y_n g_t(\vec{x}_n)}$
- Output $G(\vec{x}) = sign(\sum_{t=1}^{T} \alpha_t g_t(\vec{x}))$

Theoretical Properties of AdaBoost

- See [Freund & Schapire's Tutorial](#) for more discussion

- The training error of AdaBoost converges fast
  - Let $\gamma_t = \frac{1}{2} - \epsilon_t$ (how good each weak learner is better than random guessing)
  - $E_{in} \le e^{-2\sum_{t=1}^{T}\gamma_t^2}$

- Generalization error
  - VC analysis gives us $E_{out} \le E_{in} + \tilde{O}\left(\sqrt{\dfrac{Td_{vc}}{m}}\right)$

    d_{vc} is the VC dimension of the weak learner

  - It seems as T goes large, overfitting could happen
  - Empirically, AdaBoost is relatively robust to overfitting
  - There are some more delicate analysis using the idea of **margins** to explain why

Lecture Notes Today

The notes are not intended to be comprehensive. They should be accompanied by lectures and/or textbook. Let me know if you spot errors.

Similarity-Based Method: Nearest Neighbor

Movie Rating Prediction

- Below is the historical movie ratings from users (5 is the highest)

	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5	Movie 6
Alice	5	4	3	1	5	2
Bob	4	5	3	2	5	
Charlie	1	2	4	4	2	3
David	2	3	2	4	4	4
…						

- What do you think Bob's rating will be for Movie 6?
  - Maybe 2, since Bob's taste seems to be similar with Alice's

Movie Recommendation

- Below is the historical movie ratings from users (5 is the highest)

	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5	Movie 6
Alice	5	4		1		
Bob	4			2	5	
Charlie	1		4		2	
David		3	2			4
…						

- Which movie will you recommend to Alice, why?
  - Maybe Movie 5, since Bob's taste seems to be similar with Alice's

Nearest Neighbor

- Predict the label of $\vec{x}$ according to its nearest neighbor in D

  - Given $D = \{(\vec{x}_1, y_1), (\vec{x}_2, y_2), \dots, (\vec{x}_N, y_N)\}$; $y_n \in \{+1, -1\}$

  - Let $\vec{x}_{[1]}$ be $\vec{x}$'s nearest neighbor in D, i.e., the closest point to $\vec{x}$ in D

  - Similarly, let $\vec{x}_{[i]}$ be the ith closest point to $\vec{x}$ in D

    - With some distance measure $d(\vec{x}, \vec{x}')$

      - $d(\vec{x}, \vec{x}_{[1]}) \leq d(\vec{x}, \vec{x}_{[2]}) \leq \dots \leq d(\vec{x}, \vec{x}_{[N]})$

  - Let $y_{[i]}(\vec{x})$ or $y_{[i]}$ be the label of $\vec{x}_{[i]}$

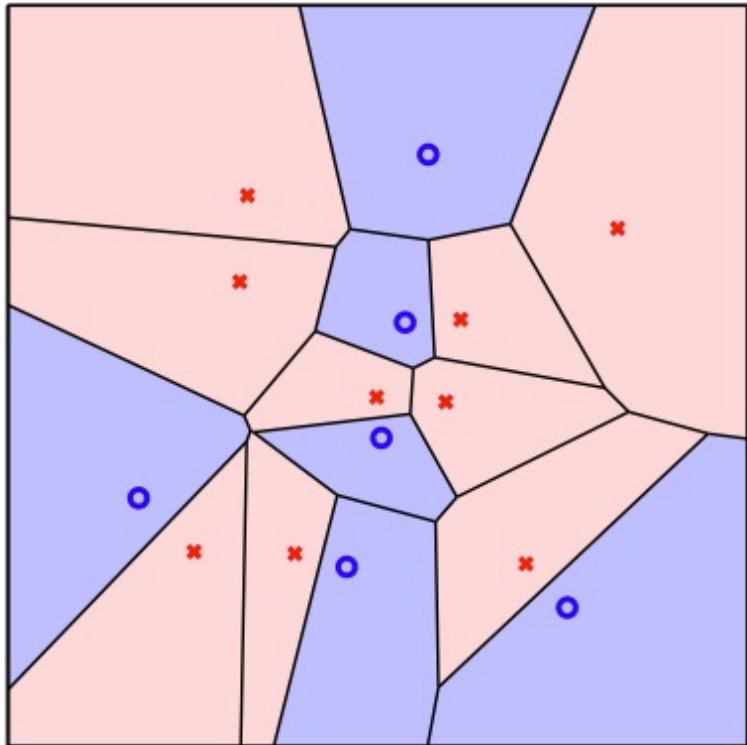- Nearest neighbor hypothesis

  $$g(\vec{x}) = y_{[1]}(\vec{x})$$

Common distance measures:
- Euclidean distance: $d(\vec{x}, \vec{x}') = \|\vec{x} - \vec{x}'\|$
- Cosine similarity: $d(\vec{x}, \vec{x}') = \dfrac{\vec{x} \cdot \vec{x}'}{\|\vec{x}\|\|\vec{x}'\|}$
- And others…

Nearest Neighbor

Decision boundary of $g(\vec{x})$

- Properties of Nearest Neighbor (NN)
  - No training is needed
  - Good interpretability
  - In-sample error $E_{in} = 0$
  - VC dimension is ∞

- This seems to imply bad learning models from what we talked about so far? Why we care?

- What we really care about is E_{out}
  - VC analysis: $E_{out} \leq E_{in} +$ Generalization error
    - We can infer E_{out} through E_{in} and model complexity
  - NN has nice guarantees outside of VC analysis

Nearest Neighbor is 2-Optimal

- Given mild conditions, for nearest neighbor, when $N \to \infty$, with high probability,

$$E_{out} \leq 2E_{out}^*$$

- That is, we can not infer E_{out} from E_{in}, but we know that it cannot be much worse than the best anyone can do.

Proof Sketch of 2-Optimality $(E_{out} \leq 2E^*_{out})$

- Setup
  - The target function is noisy: $\pi(\vec{x}) = \Pr[y = +1|\vec{x}]$
  - The noisy target π is continuous in $\vec{x}$
    - Similar $\vec{x}$ should have similar label distributions
    - It is the underlying assumption for nearest neighbor to work

- Let $g^*(\vec{x})$ be the optimal hypothesis (output a binary prediction)
  - $g^*(\vec{x}) = \begin{cases} +1 & \text{if } \pi(\vec{x}) \geq \frac{1}{2} \\ -1 & \text{otherwise} \end{cases}$
  - Pointwise-error $e(g^*(\vec{x}), y) = \min\{\pi(\vec{x}), 1 - \pi(x)\}$

- $E^*_{out} = \mathbb{E}_{\vec{x}}[e(g^*(\vec{x}), y)] = \mathbb{E}_{\vec{x}}[\min\{\pi(\vec{x}), 1 - \pi(x)\}]$

Proof Sketch of 2-Optimality

- $E_{out}^* = \mathbb{E}_{\vec{x}}[e(g^*(\vec{x}), y)] = \mathbb{E}_{\vec{x}}[\min\{\pi(\vec{x}), 1 - \pi(x)\}]$

- Proof sketch:
  - For a new point $(\vec{x}, y)$, let $(\vec{x}_{[1]}, y_{[1]})$ be its nearest neighbor in D
  - Consider the case when $N \to \infty$
    - A new point is "very close" to its nearest neighbor in D
    - $\pi(\vec{x}) \approx \pi(\vec{x}_{[1]})$
  - The error of nearest neighbor hypothesis on a new point is

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    - $\pi(\vec{x}) \approx \pi(\vec{x}_{[1]})$

  - The error of nearest neighbor hypothesis on a new point is
    $$\Pr[y \neq y_{[1]}] = \Pr[y = +1, y_{[1]} = -1] + \Pr[y = -1, y_{[1]} = +1]$$
    $$= \pi(\vec{x})\left(1 - \pi(\vec{x}_{[1]})\right) + (1 - \pi(\vec{x}))\pi(\vec{x}_{[1]})$$
    $$\approx 2\,\pi(\vec{x})(1 - \pi(\vec{x}))$$
    $$\leq 2\min\{\pi(\vec{x}), 1 - \pi(\vec{x})\}$$

Informal intuitions to summarize the proof:

Assumption for nearest neighbor:
- Target function is continuous
- That is, nearby points have similar label distributions

As N goes large, there are "close enough" points for prediction

Nearest Neighbor is Self-Regularizing

- Intuition of regularization:
  - Use simpler hypothesis if we don't have enough data

- Nearest neighbor hypothesis
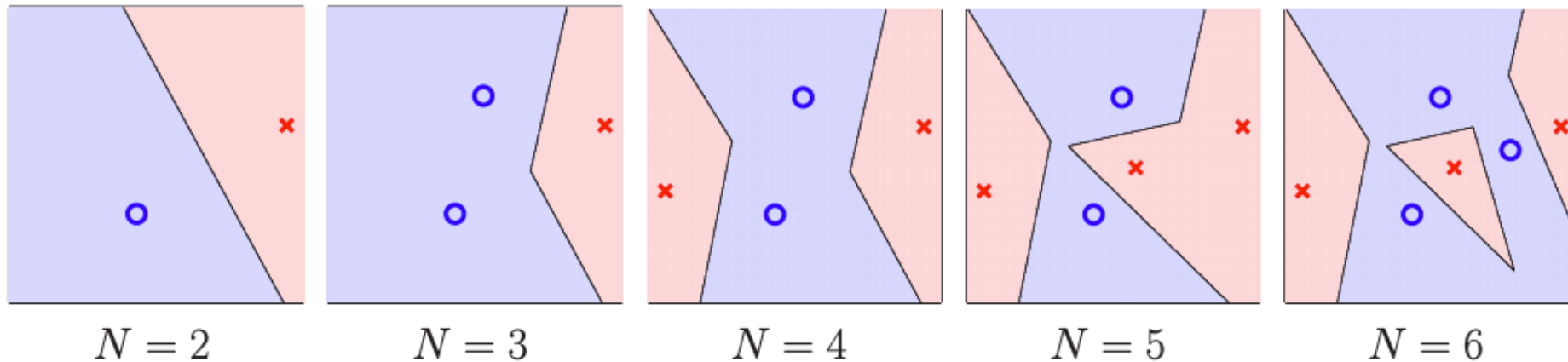
The complexity of hypothesis grows with the number of data points

k-Nearest Neighbor

"Stabilize" the Hypothesis

- Instead of a "single" nearest neighbor
    - Making predictions according to k nearest neighbors

- k-nearest neighbor (K-NN)
    - $g(\vec{x}) = sign\left(\sum_{i=1}^{k} y_{[i]}(\vec{x})\right)$
    - (k is often chosen to be an odd number for binary classification)

Impacts of k

- $k = 1$: the nearest neighbor hypothesis
  - many, complicated decision boundaries
  - may overfit

- $k = N$, g predicts the most common label in the training dataset
  - no decision boundaries
  - may underfit

- k controls the complexity of the hypothesis set
  - k affects how well the learned hypothesis will generalize

How to Choose k

- Making the choice of k a function of N, denoted by $k(N)$
  - Theorem:
    - If $k(N) \to \infty$ as $N \to \infty$ and $\dfrac{k(N)}{N} \to 0$ as $N \to \infty$
    - Then $E_{in}(g) \to E_{out}(g)$ and $E_{out}(g) \to E_{out}(g^*)$

  - Example: $k(N) = \sqrt{N}$ satisfies the condition

- Practical rule of thumb:
  - $k = 3$ is often a good enough choice
  - Using validation to choose k

Summary of k-NN So Far

- Pros
  - Simple algorithm
  - Good interpretations
  - Nice theoretical guarantee
  - Easy to adapt to regression (average of nearest neighbors) and multi-class classification (majority voting)

- Cons
  - Computational issue
    - each prediction requires $O(N)$ computation
  - Curse of dimensionality