

Informed Truthfulness for Multi-Task Peer Prediction

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Let's talk about crowdsourcing











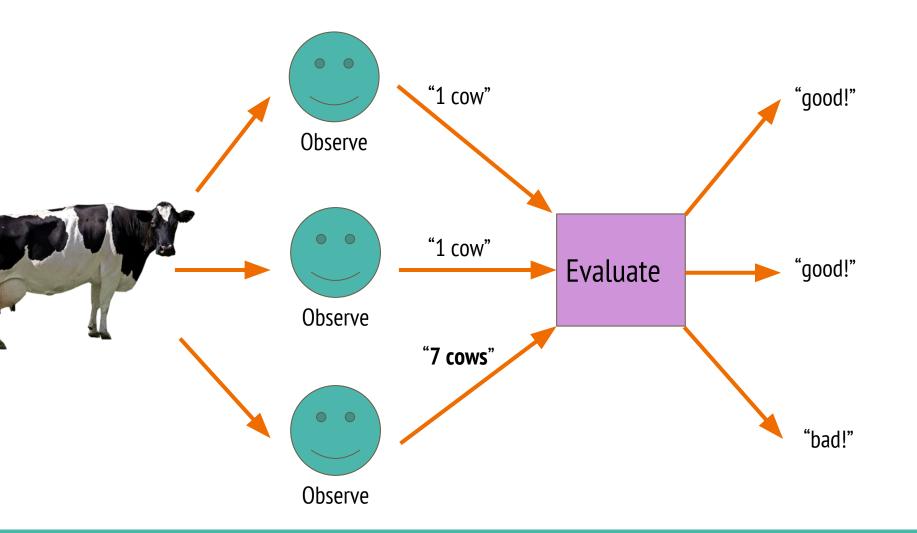












Applications beyond



Gather location-specific info

Image and video labeling

Search result evaluation

Academic peer review

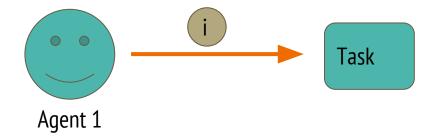
Participatory sensing

Evaluations for peer assessment in massive courses

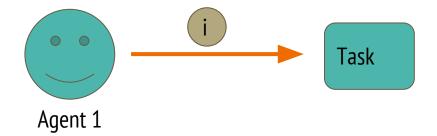
Goals:

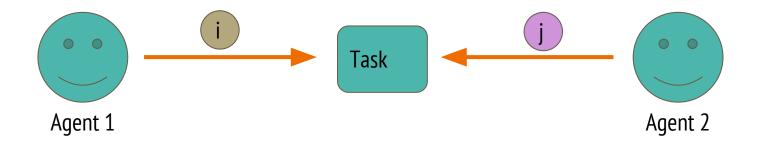
Ensure truthful equilibrium exists and is attractive

Impossibility results

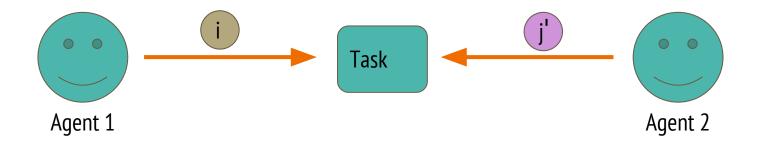


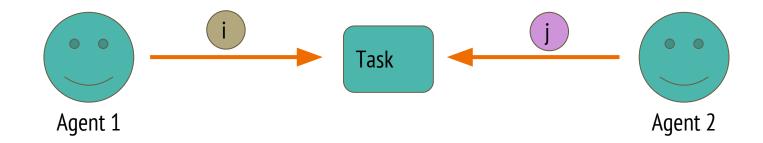
Signal: 1 ... n





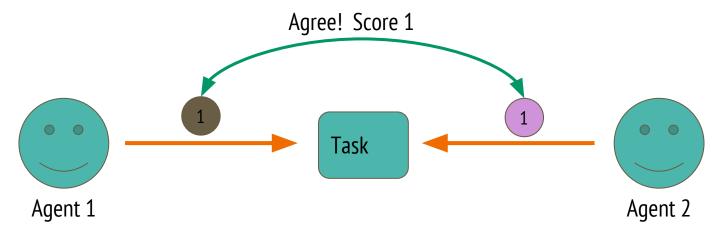
Joint probability: P(i,j)



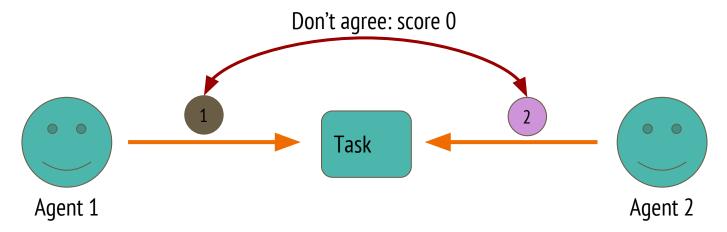


Goal: design scores to encourage effort, truthful reports

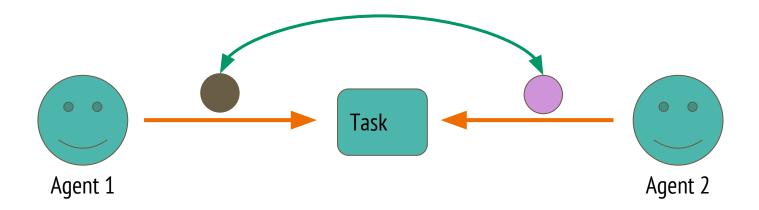
Output agreement (von Ahn, Dabbish '04)



Output agreement

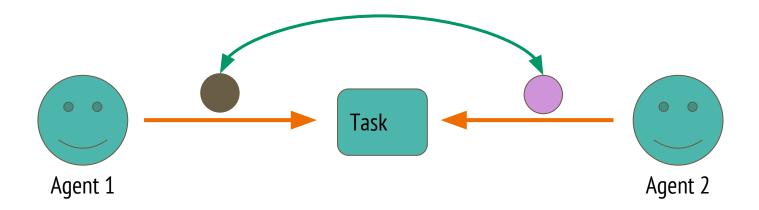


Output agreement



Honest reporting is a correlated equil if my signal predicts yours

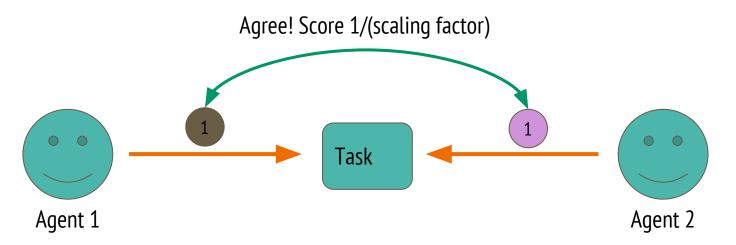
Output agreement



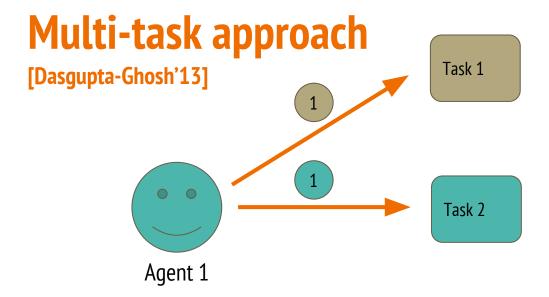
To manipulate: all agents always report same thing

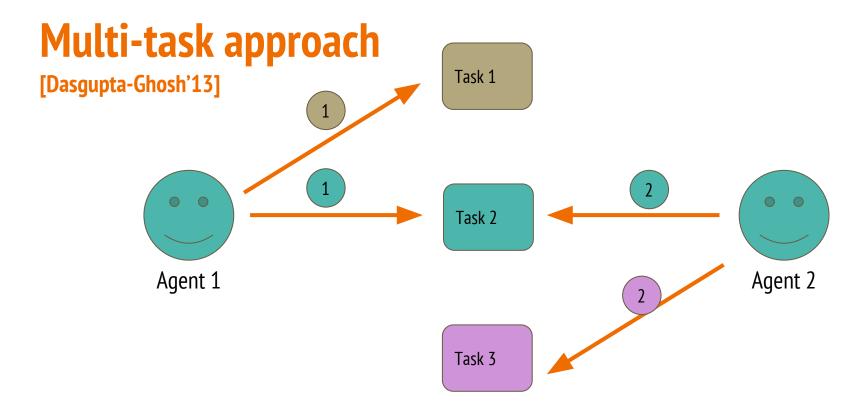
Ensuring truthful reporting is best

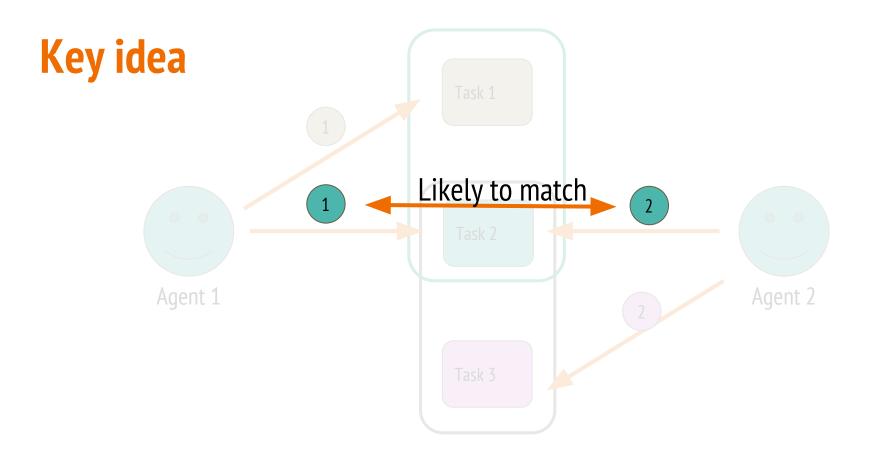
[Kamble et. al. '15, Radanovic et. al. '16]

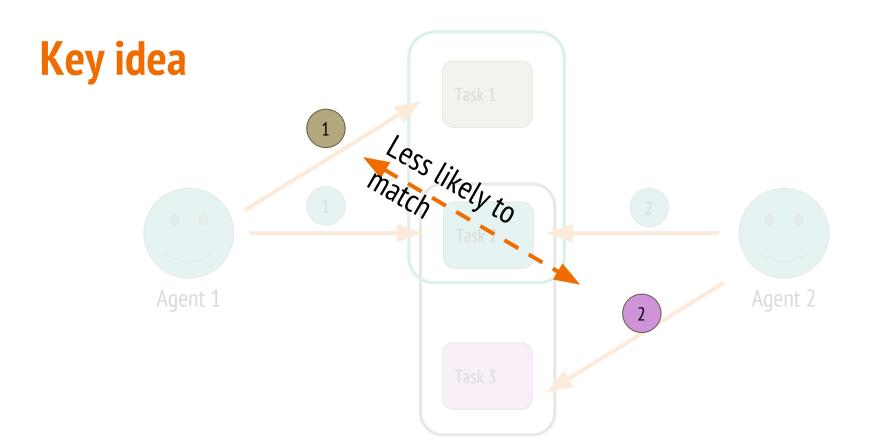


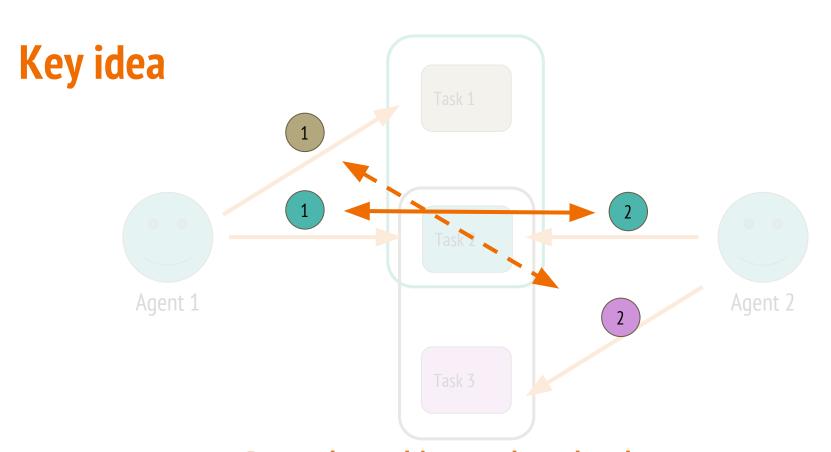
Scaling factor learned from reports on many similar tasks. Truthfulness is an equilibrium, guarantees highest payoff.



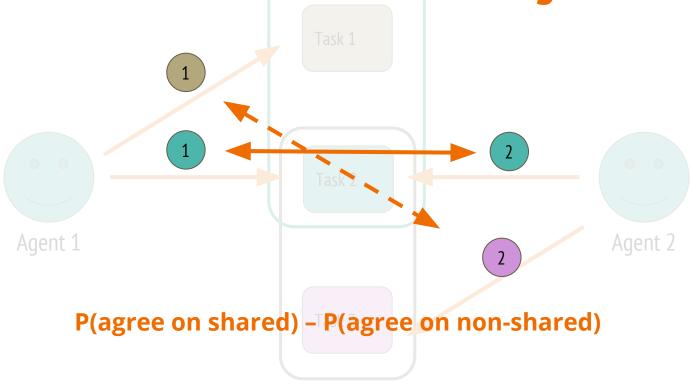








Reward matching on shared tasks. Punish matching on non-shared tasks. Why doesn't this Just Work with >2 signals?



Our multi-signal mechanism: Correlated Agreement

- 1. Split tasks into shared and non-shared.
- 2. Score = (agree on shared) (agree on non-shared)

"Agree" when reports aren't equal, but positively correlated.

The *Correlated Agreement* mechanism

- Informed truthful—being truthful is optimal, better than constant or random reports
- 2. Works with minimal information with few tasks
- 3. Works with no information with many tasks

Connection to information theory

Truthful score ~ $D_{TV}(P(\cdot,\cdot) - P(\cdot)P(\cdot))$

More agreement \Rightarrow higher scores.

Other rules correspond to different distance functions. [Kong-Schoenebeck '16]

Open questions

Is peer prediction practical as primary incentive? When?

Combine peer prediction with other incentive models in a single system?

Heterogeneous agents

Non-binary effort models

Non-random task assignment (e.g. maps)

Unintended correlated "signals"

Thank you!

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Setup

```
Agents 1, 2, tasks k
```

Signals i,j (require effort)

Shared tasks, agent 1 tasks, agent 2 tasks

Signal prior P(i), joint P(i,j)

Strategies: F, G probability of reporting r given signal i.

Informed strategy: depend on the signal somehow

Truthful strategy: F*

Solution concepts

E(F, G): expected payment for a shared task

(Strict) Proper: $E(F^*, G^*) \ge E(F, G^*)$, for all $F := F^*$

Strong-truthful: $E(F^*, G^*) \ge E(F, G)$, for all F, G (if expected payment tied, F and G must be permutations)

Informed-truthful: $E(F^*, G^*) \ge E(F, G)$, for all F, G (if expected payment tied, F and G must be informed)

A useful matrix

$$\Delta_{ij} = P(i,j) - P(i)P(j)$$

If
$$\Delta_{ij} > 0$$
 then $P(j|i) > P(j)$

Example Delta

Prior:
$$P(i):[0.55;0.45]$$

Joint: $P(i,j):\begin{bmatrix}0.4 & 0.15\\0.15 & .3\end{bmatrix}$

Delta: $\Delta \approx \begin{pmatrix}0.1 & -0.1\\-0.1 & 0.1\end{pmatrix}$

Sign(Delta): $\begin{pmatrix}+&-\\-&+\end{pmatrix}$

Scoring matrix

$$\Delta = \begin{pmatrix} + & + & - \\ + & + & - \\ - & - & + \end{pmatrix} \qquad S = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Expected payment

$$E(F,G) = \sum_{i,j} P(i,j)S(F_i,G_j) - P(i)P(j)S(F_i,G_j)$$

$$= \sum_{i,j} (P(i,j) - P(i)P(j))S(F_i,G_j)$$

$$= \sum_{i,j} \Delta_{ij}S(F_i,G_j).$$

(Lemma: can restrict to deterministic strategies)

Key theorem

The Correlated Agreement mechanism is informed truthful for all* models.

Proof sketch

$$E(F,G) = \sum_{i,j} \Delta_{ij} S(F_i, G_j)$$

$$\Delta = \begin{pmatrix} + & + & - \\ + & + & - \\ - & - & + \end{pmatrix} \qquad S = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Other results

Detail-free version of mechanism: learn scoring matrix from reports

Correlated Agreement is maximal among large class of mechanisms that use this scoring structure

Much simpler analysis of Dasgupta-Ghosh'13 mechanism

Binary mechanism (Dasgupta-Ghosh '13):

- 1. Split tasks into shared and non-shared.
- 2. Score: (agree on shared) (agree on non-shared)

Expected score: P(agree on shared) – P(agree on non-shared)

Have to agree based on properties of shared task. Constant or random reporting has expected score = 0