(1) 演算法公式 (LaTeX)

```
\textbf{Epsilon-Greedy Algorithm}
```

```
 \begin\{align*\} \& \text\{Initialize: \} Q(a) = 0, \ N(a) = 0 \quad \forall a \in \{1, \dots, k\} \ \& \text\{For each time step \} t = 1 \text\{ to \} T: \ & \quad \text\{With probability \} \varepsilon, \text\{ choose a random action \} a_t \in \{1, \dots, k\} & \quad \text\{With probability \} 1 - \varepsilon, \text\{ choose \} a_t = \arg\max_a Q(a) \ & \quad \text\{Receive reward \} r_t \sim \mathcal\{N\}(\mu_{a_t}, 1) \ & \quad \N(a_t) \leftarrow \N(a_t) + 1 \ & \quad \Q(a_t) \leftarrow \Q(a_t) + \frac\{1\}\{N(a_t)\} \left(r_t - Q(a_t)\right) \end\{align*\}
```

(2) ChatGPT 提示語

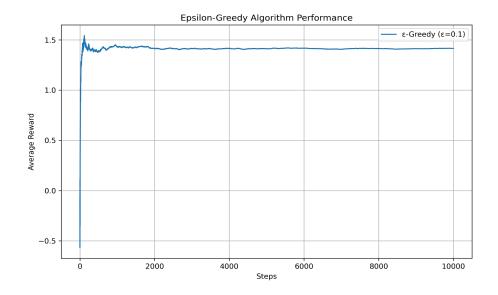
請實作 epsilon-greedy

多臂拉霸演算法,需包含探索與利用的邏輯,並用遞增平均更新動作價值,繪製報酬曲線。

(3) Python 程式碼

```
import numpy as np
import matplotlib.pyplot as plt
np.random.seed(42)
k = 10
steps = 10000
epsilon = 0.1
true_rewards = np.random.normal(0, 1, k)
Q = np.zeros(k)
N = np.zeros(k)
rewards = np.zeros(steps)
for t in range(steps):
    if np.random.rand() < epsilon:</pre>
        a = np.random.randint(k)
    else:
        a = np.argmax(Q)
    reward = np.random.normal(true_rewards[a], 1)
    N[a] += 1
    Q[a] += (reward - Q[a]) / N[a]
    rewards[t] = reward
cumulative_average = np.cumsum(rewards) / (np.arange(steps) + 1)
plt.figure(figsize=(10, 6))
plt.plot(cumulative_average, label=f"\epsilon-Greedy (\epsilon={epsilon})")
plt.xlabel("Steps")
plt.ylabel("Average Reward")
plt.title("Epsilon-Greedy Algorithm Performance")
plt.legend()
plt.grid(True)
plt.savefig("epsilon_greedy_result.png", dpi=300)
plt.show()
```

(3-1) 圖表



(4) 結果分析

時間複雜度: O(T*k) 空間複雜度: O(k+T)

說明:

- 結構簡單, 易於實作
- 探索與利用比依賴 epsilon 參數
- 適合靜態環境但對 epsilon 選擇較敏感