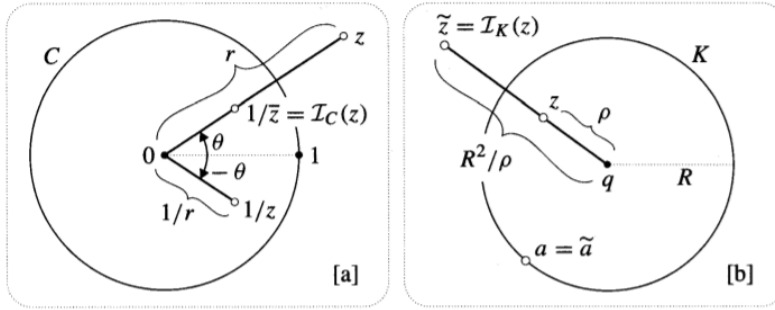


Mobius Transformations and Inversions

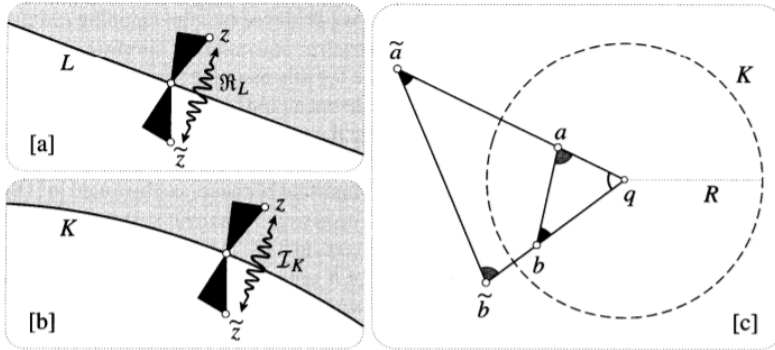
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Complex Analysis

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1. $M(z) = (az + b)/(cz + d)$; $M(z) = -(ad - bc)/(c^2(z + d/c)) + a/c$; Take z , apply translation of d/c , apply complex inversion, apply dilative rotation of $-(ad - bc)/c^2$ and apply translation of a/c , and the resulting complex number would be M.T. of z .
2. Complex inversion comprise of : $z \rightarrow 1/\bar{z}$, $z \rightarrow \bar{z}$; Geometric inversion: $\mathcal{I}_C(z) = 1/\bar{z}$, where C is origin centered unit circle; For geometric inversion in general circle K , $\tilde{z} = \mathcal{I}_K(z)$ is obtained by: $(\tilde{z} - q)(\bar{\tilde{z}} - \bar{q}) = R^2$, $\tilde{z} = (R^2 - |q|^2 + \bar{z}q)/(\bar{z} - \bar{q})$.

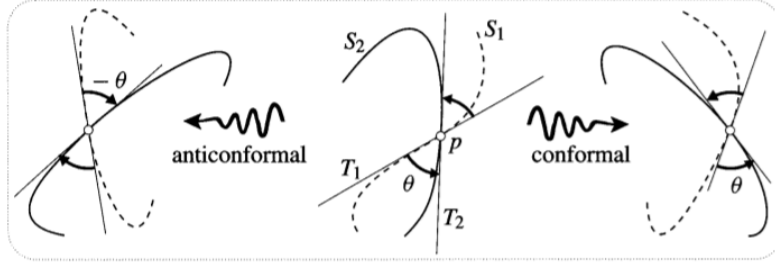


3. Line L divides plane into two parts, \mathcal{R}_L (reflection in L) interchanges those parts, $\mathcal{R}_L(L) = L$, $\mathcal{R}_L(\mathcal{R}_L(z)) = z$; \mathcal{I}_K shares all three properties. As K gets larger or the point to be inverted/reflected comes closer to K , \mathcal{I}_K behaves as \mathcal{R}_K .

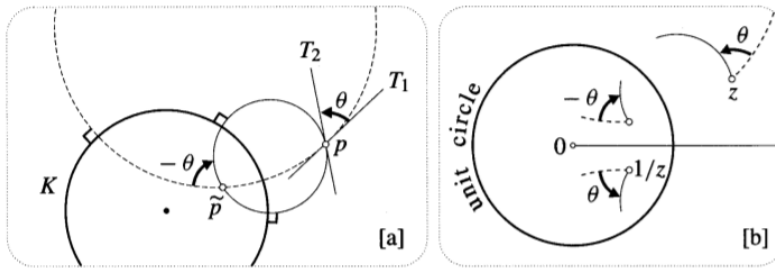
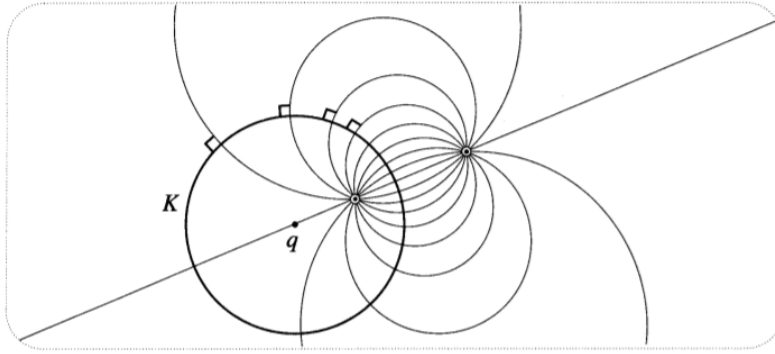


4. $\tilde{a} = \mathcal{I}_K(a)$, $\tilde{b} = \mathcal{I}_K(b)$, $[q\tilde{a}][qa] = R^2 = [qb][q\tilde{b}]$, $aqb \sim \tilde{b}q\tilde{a}$, $[\tilde{a}\tilde{b}]/[ab] = [q\tilde{a}]/[qb]$, $[\tilde{a}\tilde{b}] = ([ab]R^2)/([qa][qb])$.

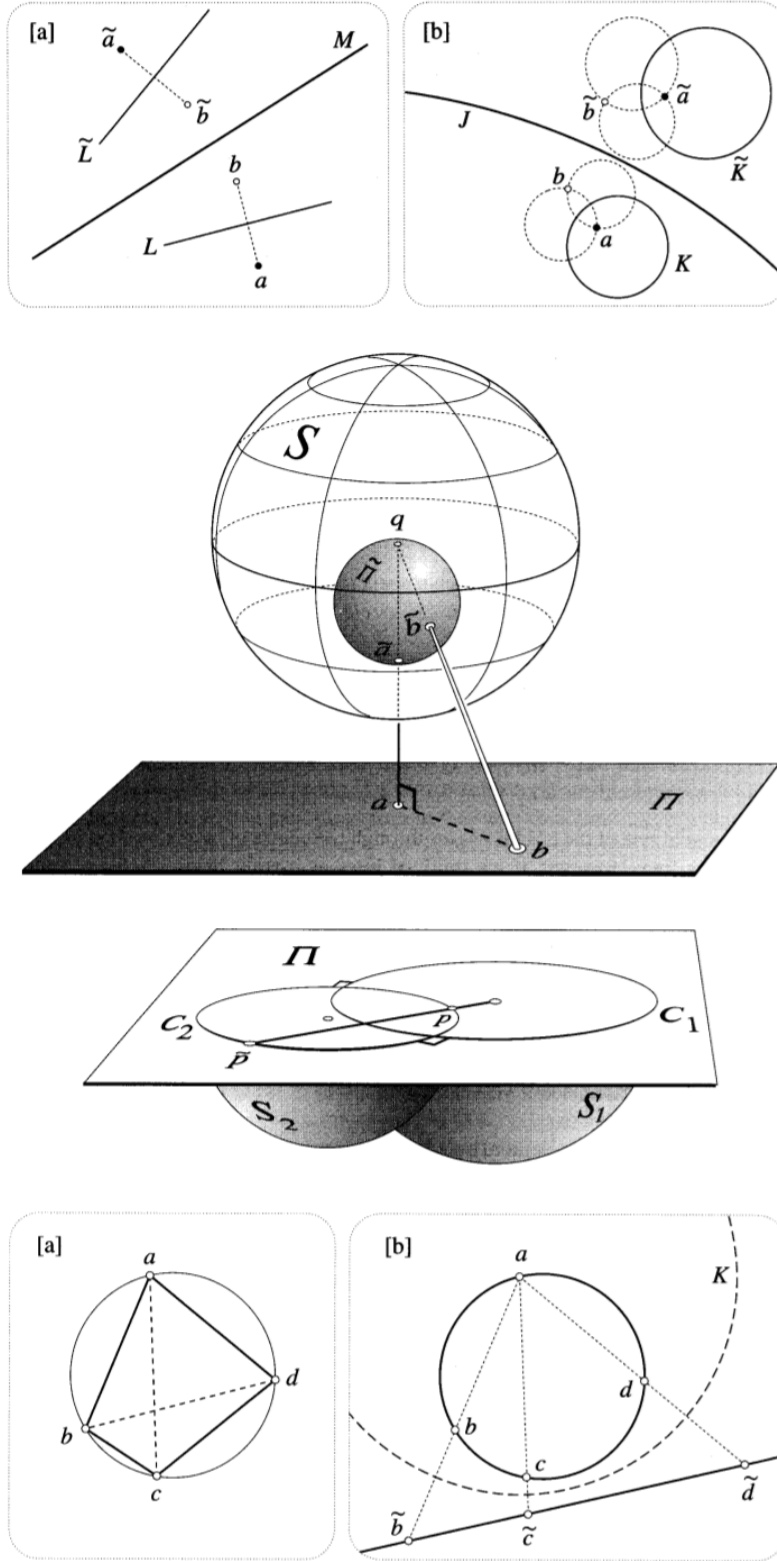
9. Conformal at p : When transformation preserves sign and magnitude of the angle between any two curves sufficiently smooth at p ; Anticonformal at p : Magnitude preserved, sign reversed; Conformal map: Conformal for all p ; Anticonformal map: Anticonformal for all p ; Isogonal map: Magnitude preserved for all p , can't say anything about sign.



10. Geometric inversion is anticonformal (draw \perp circle to K passing through z at a specific angle). Complex inversion is conformal. Even number of reflections (in lines or circles) is conformal, odd is anticonformal.

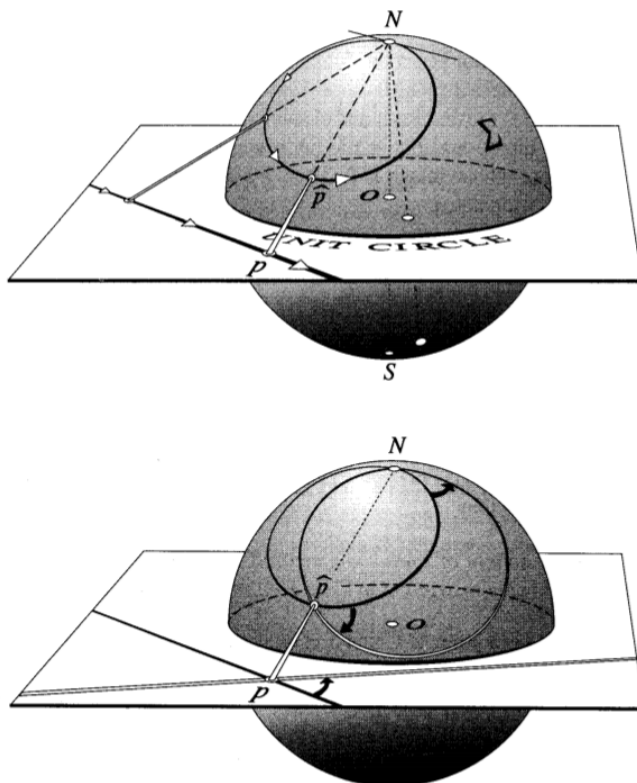


11. Inversion maps any pair of \perp circles to another pair of \perp circles; If a and b are symmetric wrt K then $\tilde{a}, \tilde{b}, \tilde{K} = \mathcal{I}_J(a, b, K)$, \tilde{a} and \tilde{b} are symmetric wrt \tilde{K} .
12. Analogous results for inversion in a sphere; Let S_1 and S_2 be intersecting spheres, and let C_1 and C_2 be the great circles in which these spheres intersect a plane Π passing through their centres. Then $S_1 \perp S_2 \iff C_1 \perp C_2$.
13. Ptolemy's theorem $[ab][cd] + [ad][bc] = [ac][bd]$ where a, b, c, d lie on a circle.

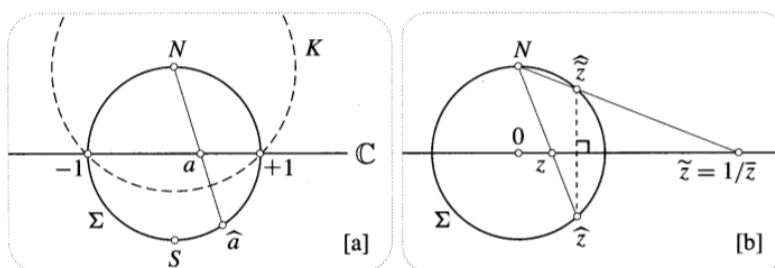


14. Extended complex plane = complex plan with a point ∞ ; Stereographic projection:
Angle preserving (conformal (if sense of angle on Σ by observer inside it)) mapping

from extended complex plane to unit sphere Σ . Stereographic image of a line in the plane is a circle on Σ passing through $N = \infty$. Circles on plane are mapped to circles on Σ .



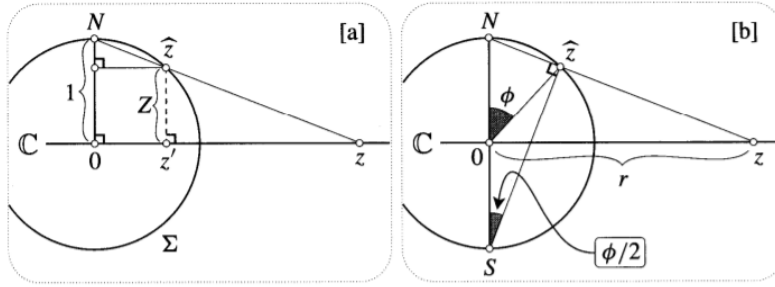
15. If K is sphere of radius $\sqrt{2}$ centred at N then stereographic projection of plane is nothing but its inversion in K ; This is another reason why stereographic projection preserves circles.



16. Transformation on stereographic image of complex plane corresponding to: complex conjugation is reflection of Σ in vertical plane through real axis; geometric inversion is reflection of Σ in its equatorial plane; complex inversion is rotation of Σ with π about real axis.
17. Transferring a function from complex plane to Σ can tell about its behaviour at $\infty \equiv N$; Complex inversion is conformal everywhere; $z \rightarrow z^2$ is conformal everywhere except

at 0 and $N = \infty$; Such points where conformality of an otherwise conformal map breaks down are called critical points; To investigate conformality of $f(z)$ at ∞ , take $F(z) = f(1/z)$ and check its conformality at O .

18. Stereographic formulae: Given Cartesian coordinates of z as $x + iy$, and Cartesian coordinates of its stereographic image on Σ as (X, Y, Z) , we have, $x + iy = (X + iY)/(1 - Z)$ and $X + iY = 2z/(1 + |z|^2)$ where $Z = (|z|^2 - 1)/(|z|^2 + 1)$; Also, if polar coordinates of stereographic image are (ϕ, θ) where θ measures angle around Z -axis and ϕ is the angle subtended at the centre of Σ by points N and \hat{z} , then, $z = e^{i\theta} \cot(\phi/2)$; \hat{p} and \hat{q} are antipodal on Σ then $q = -1/\bar{p}$.



19. M.T. map circles to circles, are conformal, if two points are symmetric wrt a circle then their images are symmetric wrt image circle, maps an oriented circle C to an oriented circle \tilde{C} s.t. region to the left of C is mapped to the region to the left of \tilde{C} .

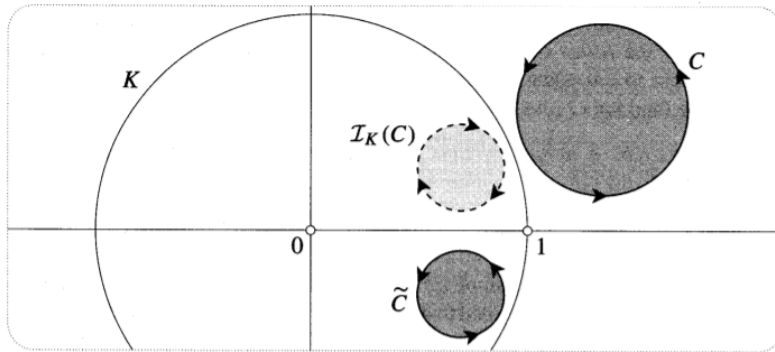
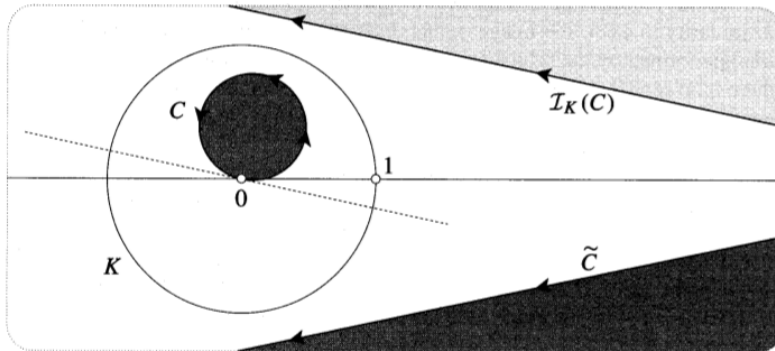
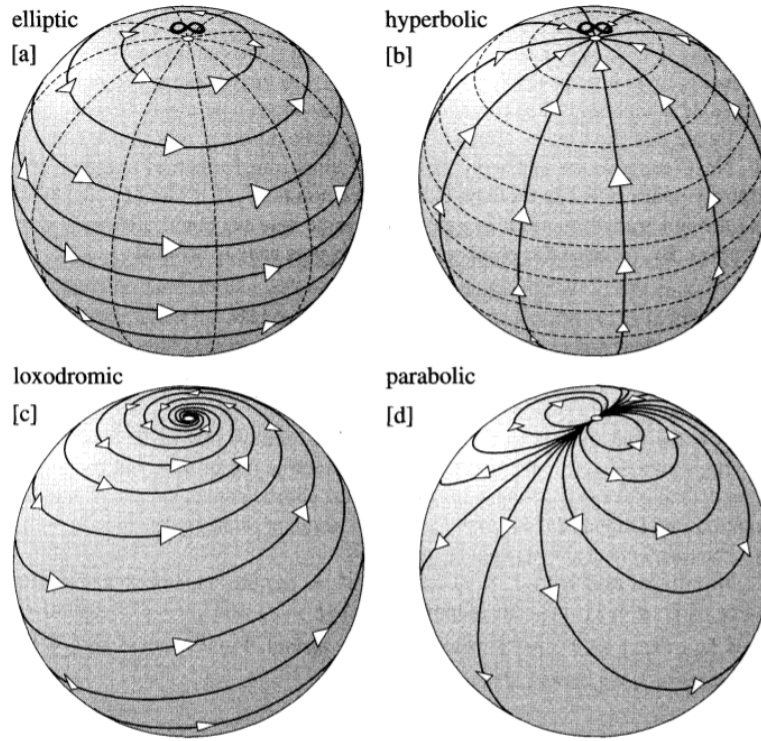


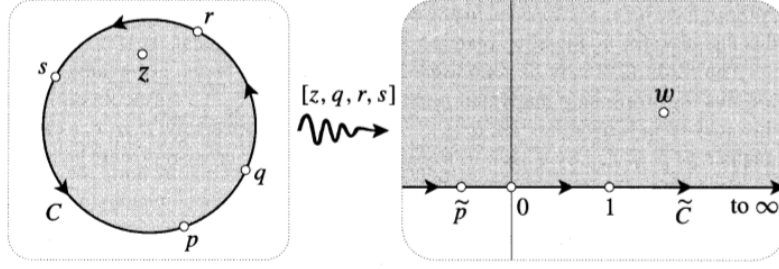
Figure [24]



20. There exist a unique M.T. sending any three points to any other three points; $ad - bc = 1$ then M.T. is normalized; set of M.T. forms a group under composition; $z = M(z)$ is a quadratic in z , so, with exception of identity mapping, a M.T. has atmost two fixed points, this fact is used to prove uniqueness part; if $c \neq 0$ then both fixed points lie on a finite plane; if $c = 0$ then $M(z) = Az + B$, which is a similarity, has a fixed points at ∞ ;
21. Transfer $M(z) = e^{i\theta}z$ on Σ to see that origin centered circles are invariant curves, origin originating rays map to another such ray, and fixed points are 0 and ∞ : Such M.T. is called elliptic M.T.; transfer $M(z) = \rho z$ on Σ to see that origin centered circles map to another such circle, origin originating rays are invariant curves, and fixed points are 0 and ∞ : Such M.T. is called hyperbolic M.T.; Transfer $M(z) = \rho e^{i\theta}z$ to see the combined effect, 0 and ∞ are fixed points: Such M.T. is called loxodromic M.T.; $M(z) = z + b$ has lines parallel to b as invariant curves and only ∞ as its fixed point: Such M.T. is called parabolic M.T.; A M.T. has a fixed point at $\infty \iff$ it is a similarity $M(z) = az + b$; ∞ is the sole fixed point \iff it is a translation $M(z) = z + b$.

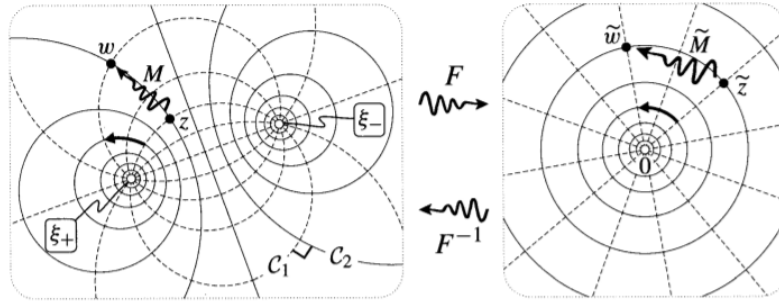


22. M.T. taking q, r, s to q', r', s' is given by $M'(z) = M_{q',r',s'}^{-1} \circ M_{q,r,s}(z)$ where $M_{q,r,s} = [z, q, r, s] = ((z - q)(r - s))/((z - s)(r - q))$ is a M.T. mapping $q \rightarrow 0, r \rightarrow 1, s \rightarrow \infty$; $[z, q, r, s]$ is called cross-ratio; A point p lies on the circle through $q, r, s \iff \text{Im}[p, q, r, s] = 0$; if q, r, s induce positive orientation to circle then z lies outside $\iff \text{Im}[p, q, r, s] < 0$ and inside if $\text{Im}[p, q, r, s] > 0$.
23. M.T. in matrix form $[a, b; c, d]$ which is non-unique; if M.T. is normalized then matrix

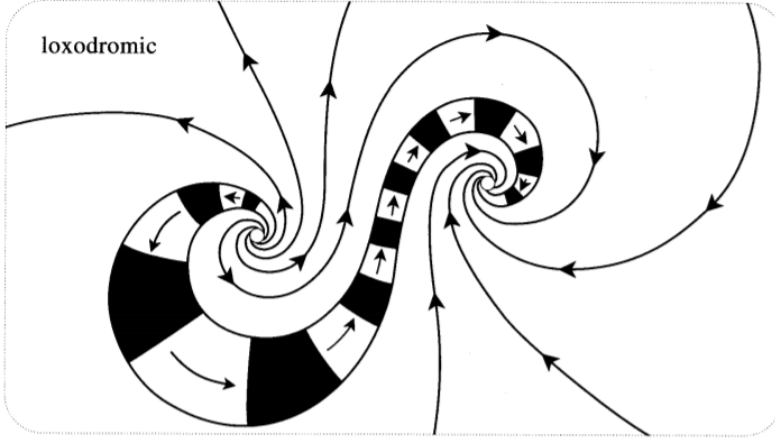
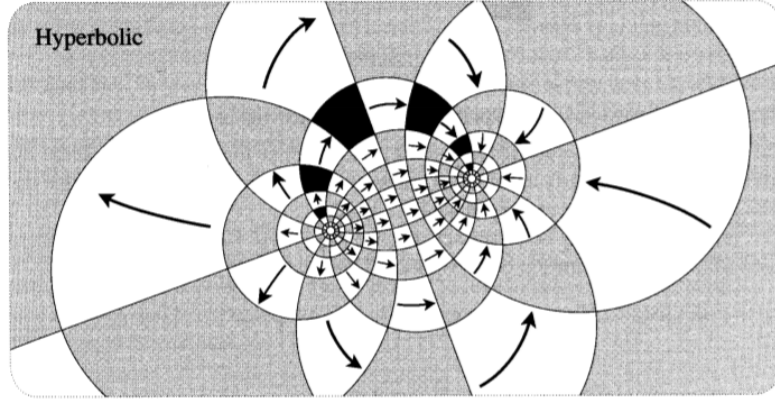
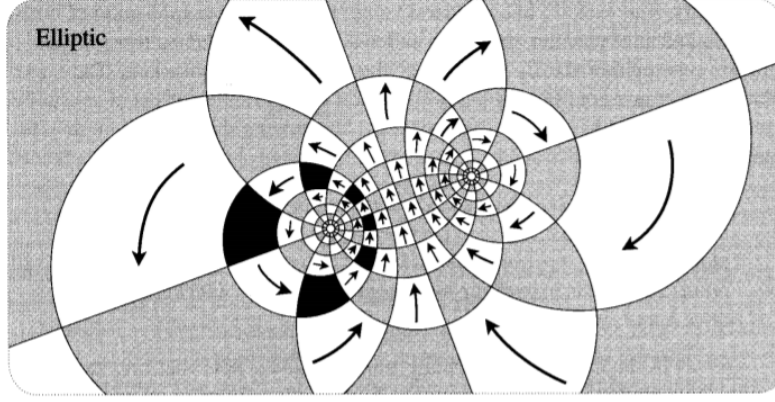


form is unique upto sign; check following in matrix form: Identity M.T., normalization coefficient as determinant, normalized \times normalized = normalized, composition of M.T., inverse of M.T.; M.T. are linear transformations, only they act on homogeneous coordinates in \mathbb{C}^2 ; $z = \zeta_1/\zeta_2$ is a fixed point of $M(z) \iff [\zeta_1, \zeta_2]^T$ is evec of $[M]$; Check with matrix form that if ∞ is a fixed point then $c = 0$; Suppose $M(z)$ is normalized then $\det([M]) = 1$, so, $\det([M] - \lambda I) = \lambda^2 - (a+d)\lambda + 1 = 0$; $\lambda_1\lambda_2 = 1$ and $\lambda_1 + \lambda_2 = a + d$.

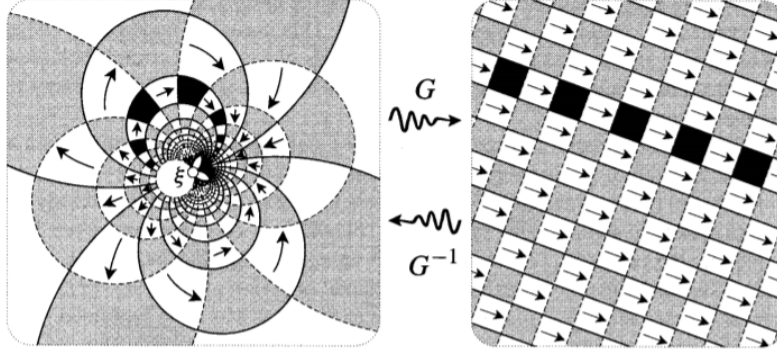
24. Two vectors in \mathbb{C}^2 are $\perp \iff$ they are homogeneous coordinates of antipodal points on Σ ; A linear transformation $[R]$ analogous to a rotation must preserve inner product: $\langle [R]p, [R]q \rangle = \langle p, q \rangle$, so, $[R]^*[R] = I$; We get form of $[R] = [a, b; -\bar{b}, \bar{a}]$ and therefore the most general rotation of Σ can be expressed as $R(z) = (az+b)/(-\bar{b}z+\bar{a})$.
25. M.T. $M(z)$ with two fixed points ξ_+ and ξ_- ; Consider family of circles through them as C_1 and family of circles s.t. each circle is \perp all circles of C_1 as C_2 ; Note that ξ_+ and ξ_- are symmetric wrt to a circle in C_2 ; $F(z) = (z - \xi_+)/(z - \xi_-)$ sends $\xi_+ \rightarrow 0$ and $\xi_- \rightarrow \infty$; C_1 circles become straight lines from origin and C_2 circles become concentric origin centred circles; $w = M(z)$ in z -plane and in w -plane $\tilde{w} = \tilde{M}(\tilde{z})$ so that $\tilde{M}(\tilde{z}) = F(M(F^{-1}(\tilde{z})))$; Two fixed points, so, $\tilde{M}(z) = mz$ where $m = \rho w^{i\alpha}$; m is the multiplier of $M(z)$; $M(z)$ is elliptic if $m = e^{i\alpha}$ - C_1 circles permute among themselves and C_2 circles are invariant, $\alpha = (m/n)2\pi$ then period of M is n .



26. $M(z)$ is hyperbolic if $m = \rho$: C_1 circles are invariant and C_2 circles permute, $\rho < 1$ is contraction and movement is from ξ_- to ξ_+ and analogously with $\rho > 1$.
27. $M(z)$ is loxodromic if $m = \rho e^{i\alpha}$; m is the multiplier associated with ξ_+ and $1/m$ is the multiplier associated with ξ_- ; Locally, i.e. near ξ_+ the effect of $M(z)$ is just dilative rotation m and near ξ_- the effect of $M(z)$ is again dilative rotation $1/m$.

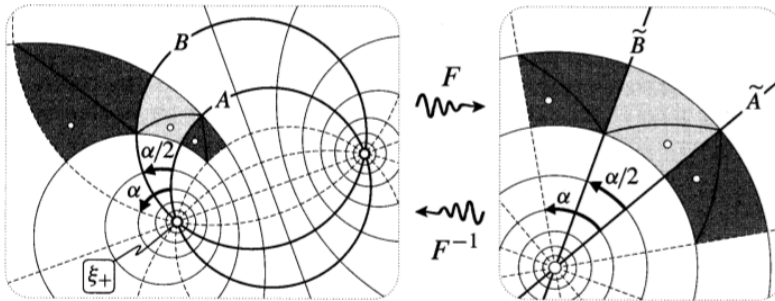


28. M.T. $M(z)$ with one fixed point ξ ; C_1 and C_2 be two \perp families of circle passing through ξ , so, \perp at the second point of intersections too; $G(z) = 1/(z - \xi)$ sends $\xi \rightarrow \infty$; C_1 and C_2 are mapped to two \perp families of lines; $\tilde{M}(\tilde{z}) = G(M(G^{-1}(\tilde{z})))$; ∞ is only fixed point, so, $\tilde{M}(\tilde{z}) = \tilde{z} + T$; C_1 circles permute and C_2 circles permute; $M(z)$ is said to be parabolic in such case; Also, normalized $M(z)$ is parabolic $\iff (a + d) = \pm 2$ so $\xi = (a - d)/2c$ and we get $T = \pm c$.
29. Since $M(z)$ maps $z = \infty$ to $w = a/c$ the multiplier can be computed by $(a/c - \xi_+)/ (a/c - \xi_-) = m(z - \xi_+)/ (z - \xi_-) = m$; Using $\det([\tilde{M}]) = \det([F][M][F^{-1}]) =$

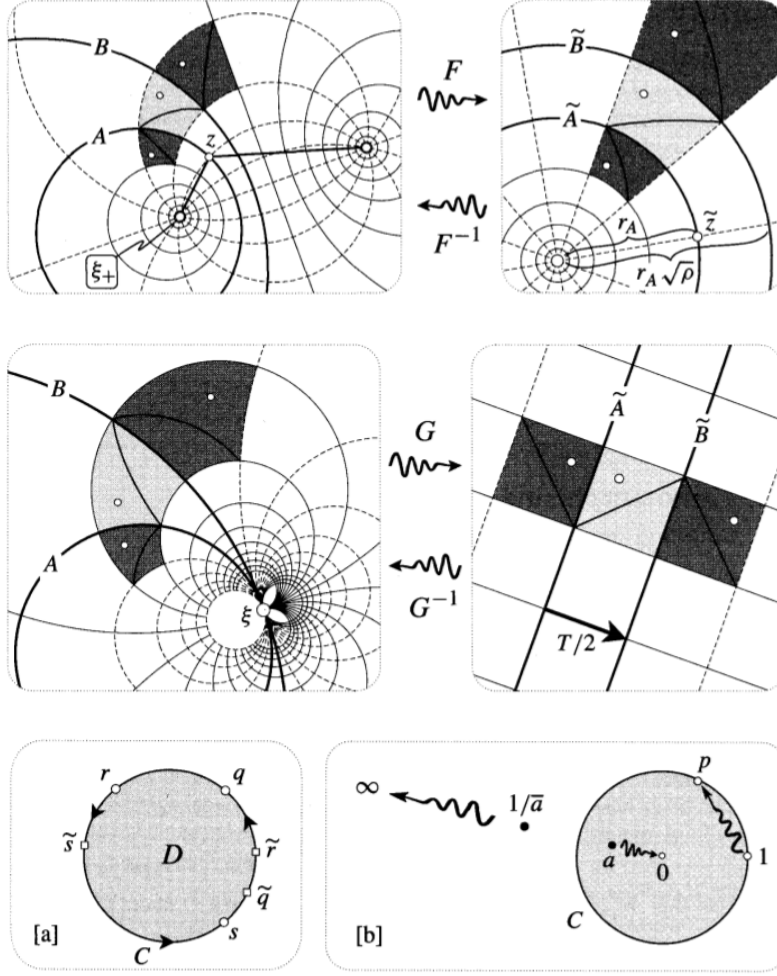


$\det([M])$, $\tilde{M}(\tilde{z}) = m\tilde{z}$ and normalized form of $[\tilde{M}] = [\sqrt{m}, 0; 0, 1/\sqrt{m}]$ we get $\text{tr}([\tilde{M}]) = \text{tr}([F][M][F^{-1}]) = \text{tr}([M]) = a + d$, so, $\sqrt{m} + 1/\sqrt{m} = a + d$; $M(z)$ is elliptic $\iff a + d$ is real and $|a + d| < 2$; $M(z)$ is parabolic $\iff (a + d) = \pm 2$; $M(z)$ is hyperbolic $\iff a + d$ is real and $|a + d| > 2$; $M(z)$ is loxodromic $\iff a + d$ is complex.

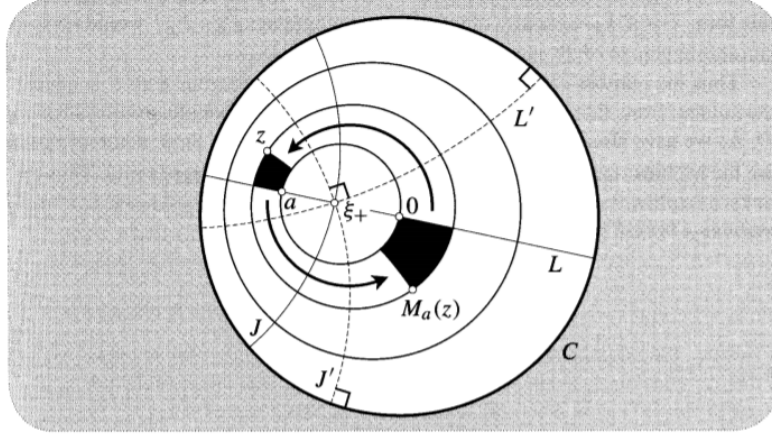
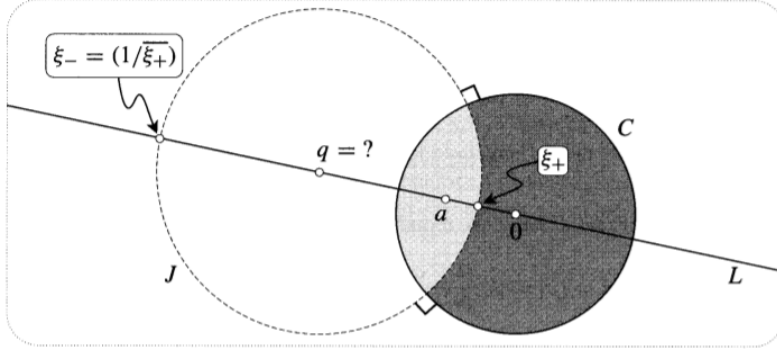
30. If a fixed points of $M(z)$ is represented as an evect with eval λ of a normalized matrix $[M]$ then the multiplier associated with the fixed point is given by $m = 1/\lambda^2$. The two reciprocal values of m equal to the two reciprocal values of λ^2 . Easy exercise to show that $m_+ = 1/\lambda_+^2$ where λ_+ is the eval corresponding to evect/fixed point ξ_+ .
31. Composition of any two reflections is a M.T.; Composition of 2 reflections is a non-loxodromic M.T. and composition of 4 reflections is a loxodromic M.T.; Elliptic case - $m = e^{i\alpha}$ then $M(z) = \mathcal{I}_B(\mathcal{I}_A(z))$ where A and B are two circles from C_1 s.t. angle from A to B is $\alpha/2$; Hyperbolic case - $m = \rho$ then $M(z) = \mathcal{I}_B(\mathcal{I}_A(z))$ where A and B are two circles of Apollonius with limit points ξ_{\pm} s.t. $r_B/r_A = \sqrt{\rho}$ - if a point moves s.t. ratio of its distance from ξ_+ and ξ_- is constant then the point moves on a circle, $r_A = |\tilde{z}| = |F(z)| = |(z - \xi_+)/(z - \xi_-)|$; Parabolic case - $M(z) = \mathcal{I}_B(\mathcal{I}_A(z))$ where A and B are circles that touch each other at ξ s.t. the distance between parallel line $G(A)$ and $G(B)$ is $T/2$.



32. Automorphisms of unit disc. An automorphism of a region R of the complex plane is a one-to-one, conformal mapping of R to itself. A M.T. has six degrees of freedom (need image of 3 fixed complex numbers to specify). M.A. of unit disc D have three degrees of freedom (need three angles to specify images of three fixed points on the boundary of disc). Another way to fill up 3 degrees of freedom: specify which point a inside D is to be mapped to origin and which point p on C is image of the point 1.



33. If two M.A. M and N map two interior points to the same image points, then $M = N$; Since C is mapped to itself by M , the symmetry principle tells us that if a pair of points are symmetric wrt to C then so are their images. Since a is mapped to 0 , $1/\bar{a}$ will map to ∞ . Thus, form of M is $M = k(z - a)/(\bar{a}z - 1)$ where k is a constant. Also, $p = M(1)$. So, $1 = |p| = |k|(|1 - a|)/(|\bar{a} - 1|) = |k|$. So $k = e^{i\phi}$. Choice of p is equivalent to choice of ϕ . $M_0^\phi = e^{-i\phi}$ which rotates D about origin by $\pi + \phi$. $M_a^\phi = R_0^\phi \circ M_a^0$. $M_a^0 \equiv M_a$; M_a swaps 0 and a . This is the only M.A. with this property. $M_a = R_L \circ I_J$ where J is the circle orthogonal to C which swaps a and 0 and has $1/\bar{a}$ as centre, and L is the line passing through 0 and a (and so through $1/\bar{a}$). Fixed points ξ_\pm are intersection points of J and L , and so they are symmetric with respect to C . Since reflections occur in orthogonal circles through these points, M_a is elliptic and $m = e^{i\pi}$ associated with both ξ_{pm} . So, M_a is involutory and any pair of points z , $M_a(z)$ is swapped by M_a . M_a can also be expressed as $I_{L'} \circ I_{J'}$ where J' and L' are any two circles through ξ_+ that are orthogonal to C . If $\Phi \equiv 2 \cos^{-1} |a|$, then M_a^ϕ is elliptic if $|\phi| < \Phi$, parabolic if $|\phi| = \Phi$ and hyperbolic if $|\phi| > \Phi$.
34. Riemann's Mapping Theorem: Any simply connected region R (other than the entire plane) may be mapped one-to-one and conformally to any other such region S . It is



sufficient to establish this in case of S being D , for if, F_R is a one-to-one conformal mapping from R to D , and F_S is a one-to-one mapping of S to D , then $F_S^{-1} \circ F_R$ is a one-to-one conformal mapping of R to S . $\tilde{F}_R \circ F_R^{-1}$ would always be some automorphism M of D so that $\tilde{F}_R = M \circ F_R$. Number of one-to-one conformal mappings from R to S is equal to the number from R to D , which in turn is equal to the number of automorphisms of D . We will show that these automorphisms are M_a^ϕ which form a 3 parameter family. This implies that there exist a 3-parameter family of one-to-one conformal mappings from R to S .