

# CHIH-HUI HO

1(619)630-7447 || [chh279@ucsd.edu](mailto:chh279@ucsd.edu) || [Website](#) || [LinkedIn](#) || [Google Scholar](#)

## EDUCATION

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| <b>University of California San Diego, La Jolla, CA</b><br>PhD Candidate in Electrical and Computer Engineering (Advisor: Prof. Vasconcelos) | Sep. 2019 - Now       |
| <b>University of California San Diego, La Jolla, CA</b><br>M.S. in Computer Science, GPA: 3.87/4.0   | Sep. 2017 - Jun. 2019 |
| <b>University of Illinois at Urbana-Champaign, Champaign, IL</b><br>Exchange student in Computer Science, GPA: 3.71/4.0                      | Jan. 2016 - May 2016  |
| <b>National Chiao Tung University, Hsinchu, Taiwan</b><br>B.S. in EECS Honor Program, GPA: 4.15/4.3  | Sep. 2012 - Jun. 2016 |

## RESEARCH INTEREST

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**Deep Learning & Computer Vision:** Metric learning, Adversarial attack, Self-supervised learning, Recognition, Multiview object classification, 3D understanding

## SELECTED PUBLICATION

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- **Chih-Hui Ho**, Nuno Vasconcelos, "DISCO: Adversarial Defense with Local Implicit Functions", *NeurIPS*, 2022
- **Chih-Hui Ho**, Srikar Appalaraju, Bhavan Jasani, R. Manmatha, Nuno Vasconcelos, "YORO - Lightweight End to End Visual Grounding", *ECCV Workshop*, 2022.
- Brandon Leung, **Chih-Hui Ho**, Nuno Vasconcelos, "Black-Box Test-Time Shape REFINement for Single View 3D Reconstruction", *CVPR Workshop*, 2022.
- **Chih-Hui Ho**, Nuno Vasconcelos, "Contrastive Learning with Adversarial Examples", *NeurIPS*, 2020.
- Tz-Ying Wu, Pedro Morgado, Pei Wang, **Chih-Hui Ho**, Nuno Vasconcelos, "Solving Long-tailed Recognition with Deep Realistic Taxonomic Classifier", *ECCV*, 2020.
- **Chih-Hui Ho**, Bo Liu, Tz-Ying Wu, Nuno Vasconcelos, "Exploit Clues from Views: Self-Supervised and Regularized Learning for Multiview Object Recognition", *CVPR*, 2020.
- **Chih-Hui Ho**, Pedro Morgado, Amir Persekian, Nuno Vasconcelos, "PIEs: Pose Invariant Embeddings", *CVPR*, 2019.
- **Chih-Hui Ho**<sup>\*</sup>, Brandon Leung<sup>\*</sup>, Erik Sandstrom, Yen Chang, Nuno Vasconcelos, "Catastrophic Child's Play: Easy to Perform, Hard to Defend Adversarial Attacks", *CVPR*, 2019.
- Jen-Hui Chuang, **Chih-Hui Ho**, Ardian Umam, HsinYi Chen, Mu-Tien Lu, Jenq-Neng Hwang, Tai-An Chen, "Geometry-based Camera Calibration Using Closed-form Solution of Principal Line", *TIP*, 2019.

## PROFESSIONAL EXPERIENCE

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| <b>Graduate Student Researcher, Statistical Visual Computing Lab, UCSD</b><br>• Working on multiview recognition, self-supervised learning, adversarial attack, defect detection   | Jan. 2018 - Now        |
| <b>Amazon AWS Applied Scientist Intern</b><br>• Published a visual grounding transformer paper with 1.3x smaller size and 3x faster speed  | Jun. 2021 - Sept. 2021 |
| <b>Research Assistant, NCTU Computer Vision Research Center</b><br>• Designed bill serial number recognition system with more than 99 % accuracy<br>• Developed camera calibration algorithm and implemented the algorithm into prototype          | Nov. 2016 - Jun. 2017  |
| <b>Software Engineer Internship, Industrial Technology Research Institute</b><br>• Developed a prototype to calibrate robotic arm with an industrial camera<br>• Received Mechanical and Systems Research Lab Prospective Project Excellence Award | Jan. - Dec. 2015       |

## ACADEMIC SERVICES AND AWARD

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- **Reviewer:** NeurIPS, CVPR(outstanding award), ECCV, ICCV, TPAMI, ICML, ICLR, ACCV, WACV, ICIP
- **UCSD Teaching Assistant:** ECE 271A/B Statistical Learning I/II, ECE 271C Deep Learning and Applications
- **Fellowship:** 2022 Amazon Post-Internship Fellowship, 2021 Qualcomm Innovation Fellowship Finalist

## SKILLS

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**Languages & Library:** Python, C/C++ , MATLAB, Pytorch, OpenCV, Keras, Kubernetes, L<sup>A</sup>T<sub>E</sub>X