

Linear Algebra Assignment 9

1) Determine diagonalizability. If so, find invertible matrix P and diagonal matrix D such that $A = PDP^{-1}$.

a) $\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ First we find λ_n : $\det(A - \lambda I) = 0$.

$$\begin{vmatrix} 1-\lambda & 2 \\ 0 & 1-\lambda \end{vmatrix} = (1-\lambda)(1-\lambda) - 0 = 0 = \lambda^2 - 2\lambda + 1$$

$$\therefore (\lambda - 1)^2 = 0, \lambda_1 = 1 = \lambda_2$$

✓ There are enough eigenvalues (multiplicity 2).

Now we find eigenvectors:

$$\begin{bmatrix} 1-\lambda & 2 \\ 0 & 1-\lambda \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \begin{array}{l} x_1 = x_1 \\ x_2 = 0 \end{array} \quad \begin{array}{l} v = x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ \text{span}\{e_1\} \end{array}$$

✗ There are not enough eigenvectors to diagonalize.

b) $\begin{bmatrix} 0 & -2 \\ 1 & 3 \end{bmatrix}, \begin{vmatrix} 0-\lambda & -2 \\ 1 & 3-\lambda \end{vmatrix} = (-\lambda)(3-\lambda) + 2 = 0 = \lambda^2 - 3\lambda + 2$
 $(\lambda-1)(\lambda-2) = 0, \lambda_1 = 1, \lambda_2 = 2$

✓ There are enough eigenvalues.

$$\begin{bmatrix} 0-\lambda & -2 \\ 1 & 3-\lambda \end{bmatrix} = \begin{bmatrix} -1 & -2 \\ 1 & 2 \end{bmatrix}, \begin{bmatrix} -1 & -2 & | & 0 \\ 1 & 2 & | & 0 \end{bmatrix} = \begin{bmatrix} 1 & 2 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \quad \begin{array}{l} x_1 = -2x_2 \quad \bar{v}_1 = x_2 \begin{bmatrix} -2 \\ 1 \end{bmatrix} \\ x_2 = x_2 \end{array}$$

$$\begin{bmatrix} 0-\lambda & -2 \\ 1 & 3-\lambda \end{bmatrix} = \begin{bmatrix} -2 & -2 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} -2 & -2 & | & 0 \\ 1 & 1 & | & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \quad \begin{array}{l} x_1 = x_2 \quad \bar{v}_2 = x_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ x_2 = x_2 \end{array}$$

✓ There are enough eigenvectors

✓ $A = PDP^{-1}$ is: $\begin{bmatrix} 0 & -2 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} -1/3 & 1/3 \\ 1/3 & 2/3 \end{bmatrix}$.

c) $\begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix} \cdot \begin{vmatrix} 0-\lambda & 0 & 1 \\ 1 & 0-\lambda & -1 \\ 0 & 1 & 1-\lambda \end{vmatrix} = -\lambda(\lambda^2 - \lambda + 1) - 0 + 1$
 $= -\lambda^3 + \lambda^2 - \lambda + 1$
 ~~$(\lambda-1)(\lambda^2 + 1) = 0$~~
 $\times \lambda = 1$, there are not enough linear factors,
which means there are not enough eigenvalues.

d) $\begin{bmatrix} 3 & 1 & 1 \\ 2 & 4 & 2 \\ -1 & -1 & 1 \end{bmatrix} \cdot \begin{vmatrix} 3-\lambda & 1 & 1 \\ 2 & 4-\lambda & 2 \\ -1 & -1 & 1-\lambda \end{vmatrix} = (3-\lambda)(\lambda^2 - 5\lambda + 6)$
 $- 1(-2\lambda + 4) + 1(2 - \lambda - 4)$

$= -\lambda^3 + 8\lambda^2 - 20\lambda + 16 = -(\lambda - 4)(\lambda - 2)^2 = 0$

✓ $\lambda_1 = 4$, $\lambda_2 = \lambda_3 = 2$, There are enough λ_i .

$\begin{bmatrix} 3-4 & 1 & 1 \\ 2 & 4-4 & 2 \\ -1 & -1 & 1-4 \end{bmatrix} = \begin{bmatrix} -1 & 1 & 1 \\ 2 & 0 & 2 \\ 1 & -1 & -3 \end{bmatrix} = \cancel{\begin{bmatrix} -1 & 1 & 1 & 0 \\ 0 & 2 & 4 & 0 \\ 1 & -1 & -3 & 0 \end{bmatrix}}_{\text{RRREF}} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

calculator used

$x_1 = x_3, x_2 = 2x_3, x_3 = x_3 \quad \bar{V}_1 = x_3 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \quad \bar{V}_2 = x_3 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$
 $\begin{bmatrix} 3-2 & 1 & 1 \\ 2 & 4-2 & 2 \\ -1 & -1 & 1-2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 2 & 2 & 2 & 0 \\ -1 & -1 & -1 & 0 \end{bmatrix} \text{RRREF} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \cancel{x_1 = x_3} \quad \cancel{x_2 = x_2} \quad \cancel{x_3 = x_3}$

✓ There are enough eigenvectors.

✓ $A = PDP^{-1}$ is:

$\begin{bmatrix} 3 & 1 & 1 \\ 2 & 4 & 2 \\ -1 & -1 & 1 \end{bmatrix} = \begin{bmatrix} -1 & -1 & -1 \\ 0 & 1 & -2 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 1/2 & 1/2 & 3/2 \\ -1 & 0 & -1 \\ -1/2 & -1/2 & -1/2 \end{bmatrix}.$

Note: D is always the matrix of the eigenvalues on the diagonal with zeros otherwise, P is always the matrix of eigenvectors placed in the same order.

2) To find the general expression for A^n of matrix $A = \begin{bmatrix} 0 & -2 \\ 1 & 3 \end{bmatrix}$, we put it in the form of $A^n = P D^n P^{-1}$:

$$\begin{bmatrix} 0 & -2 \\ 1 & 3 \end{bmatrix}^n = \begin{bmatrix} -2 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}^n \begin{bmatrix} -1 & -1 \\ 1 & 2 \end{bmatrix}$$

This diagonalization was found previously in part 1)b).

3) As I just stated, the diagonalization of the standard matrix $\begin{bmatrix} 0 & -2 \\ 1 & 3 \end{bmatrix}$ was found in part 1)b). We can use this to find a basis B of \mathbb{R}^2 such that this matrix relative to B is diagonal:

$$D_B = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}, B = \left\{ \begin{bmatrix} -2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\} \dots \text{the eigenvectors.}$$

4) We are given $A = \begin{bmatrix} 1 & -1 \\ 9 & 1 \end{bmatrix}$ and asked to find an invertible matrix P and a rotation matrix C , such that $A = P C P^{-1}$

$$\begin{vmatrix} 1-\lambda & -1 \\ 9 & 1-\lambda \end{vmatrix} = \lambda^2 - 2\lambda + 10 \rightarrow \lambda = \frac{2 \pm \sqrt{-36}}{2} = \frac{2+6i}{2} = 1+3i$$

$$\lambda_1 = 1+3i, \lambda_2 = 1-3i$$

$$\lambda_1: \begin{bmatrix} -3i & -1 & | & 0 \\ 9 & -3i & | & 0 \end{bmatrix} \xrightarrow{\text{RRREF}} \begin{bmatrix} 1 & -\frac{1}{3} & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \quad \begin{aligned} x_1 &= \frac{1}{3}x_2 & \tilde{x}_1 &= x_2 \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} i \\ 3 \end{bmatrix} \\ \text{calculated.} & & x_2 &= x_2 \end{aligned}$$

$$\lambda_2: \begin{bmatrix} 3i & -1 & | & 0 \\ 9 & 3i & | & 0 \end{bmatrix} \xrightarrow{\text{RRREF}} \begin{bmatrix} 1 & \frac{1}{3} & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \quad \begin{aligned} x_1 &= -\frac{1}{3}x_2 & \tilde{x}_2 &= x_2 \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} -i \\ 3 \end{bmatrix} \\ \text{calculated.} & & x_2 &= x_2 \end{aligned}$$

continued →

PB of the form: $[Re \bar{v}, Im \bar{v}]$ and
 C is $\begin{bmatrix} a-b \\ b-a \end{bmatrix}$ where a, b Real and b is Imaginary:
 (parts of an λ)

$$A = PCP^{-1} \text{ is:}$$

$$\begin{bmatrix} 1 & -1 \\ a & 1 \end{bmatrix} = \begin{bmatrix} 3 & 1 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} 1 & -3 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{6} & \frac{1}{6} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$$

C is a complex rotation on a circle made out of A which is a rotation on an orbit. C and A are similar.