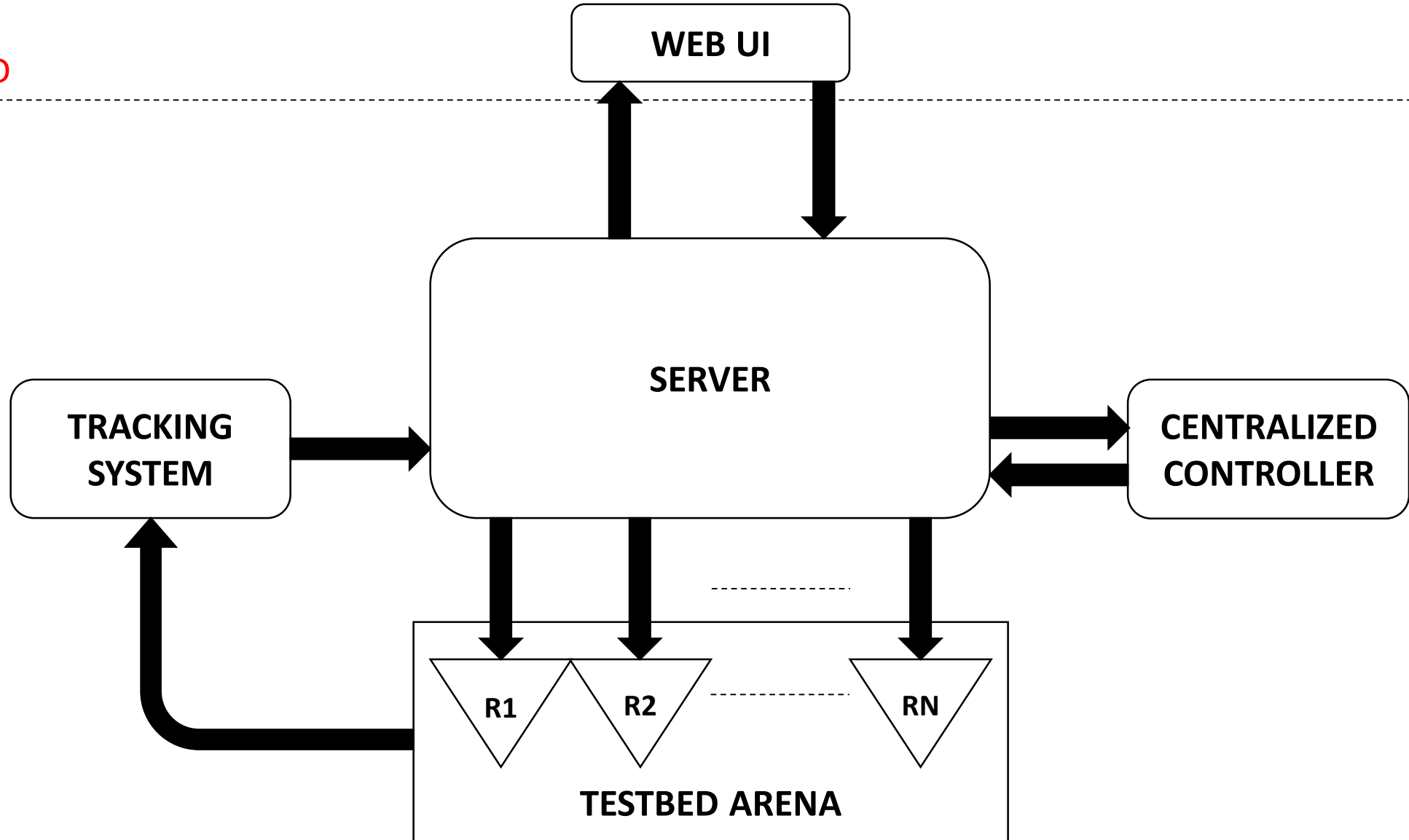


# MOPAT ARCHITECTURE MK I

FRONT-END

BACK-END



# WEB UI

**DYNAMIC FORMATION  
CONTROLLER (Input)**

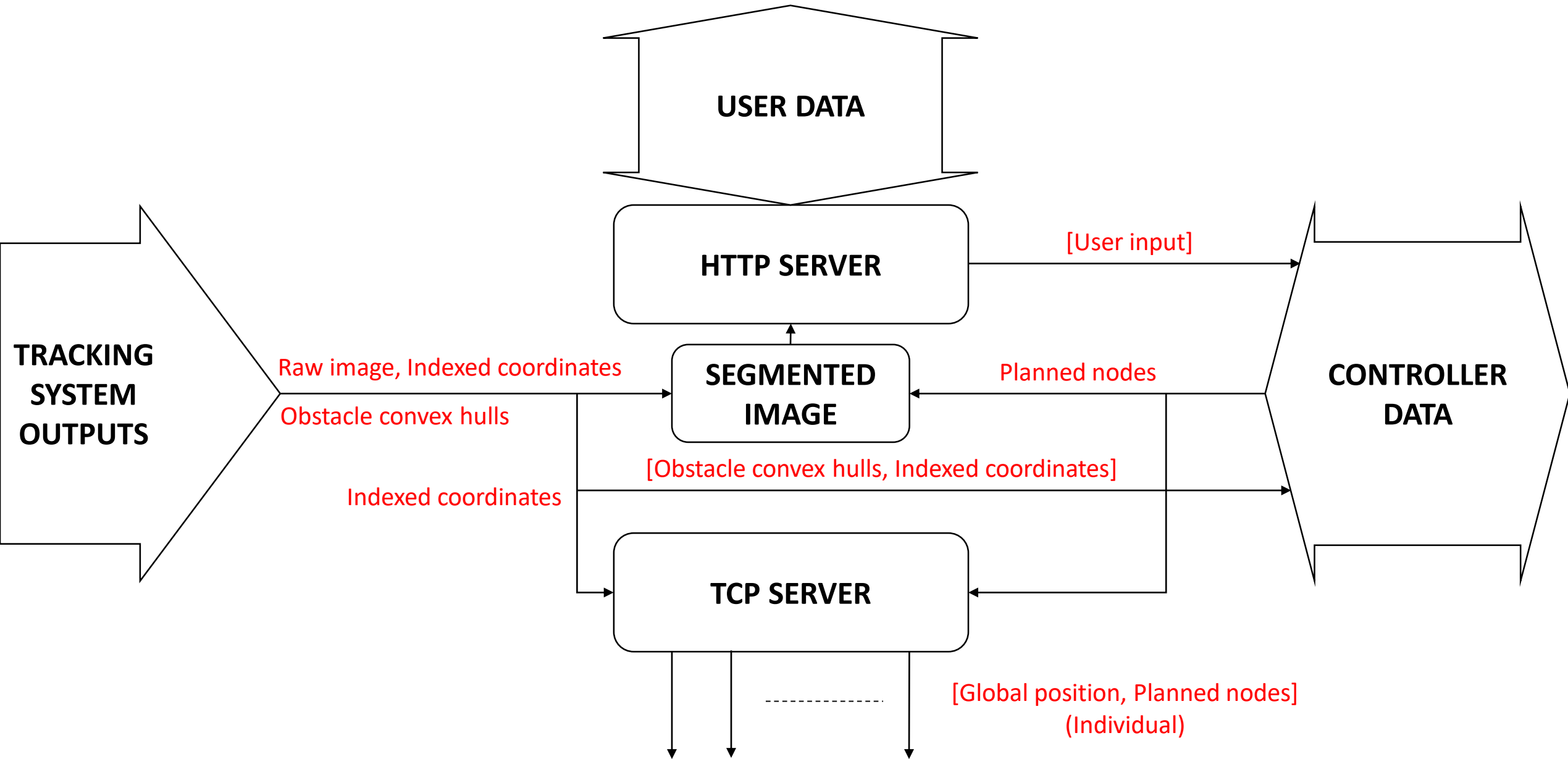
**SYSTEM  
GOAL  
CONTROL  
OPTIONS**

**RAW IMAGE,  
VIRTUAL OBSTACLES (Input),  
GOAL CONTROLLER (Input)**

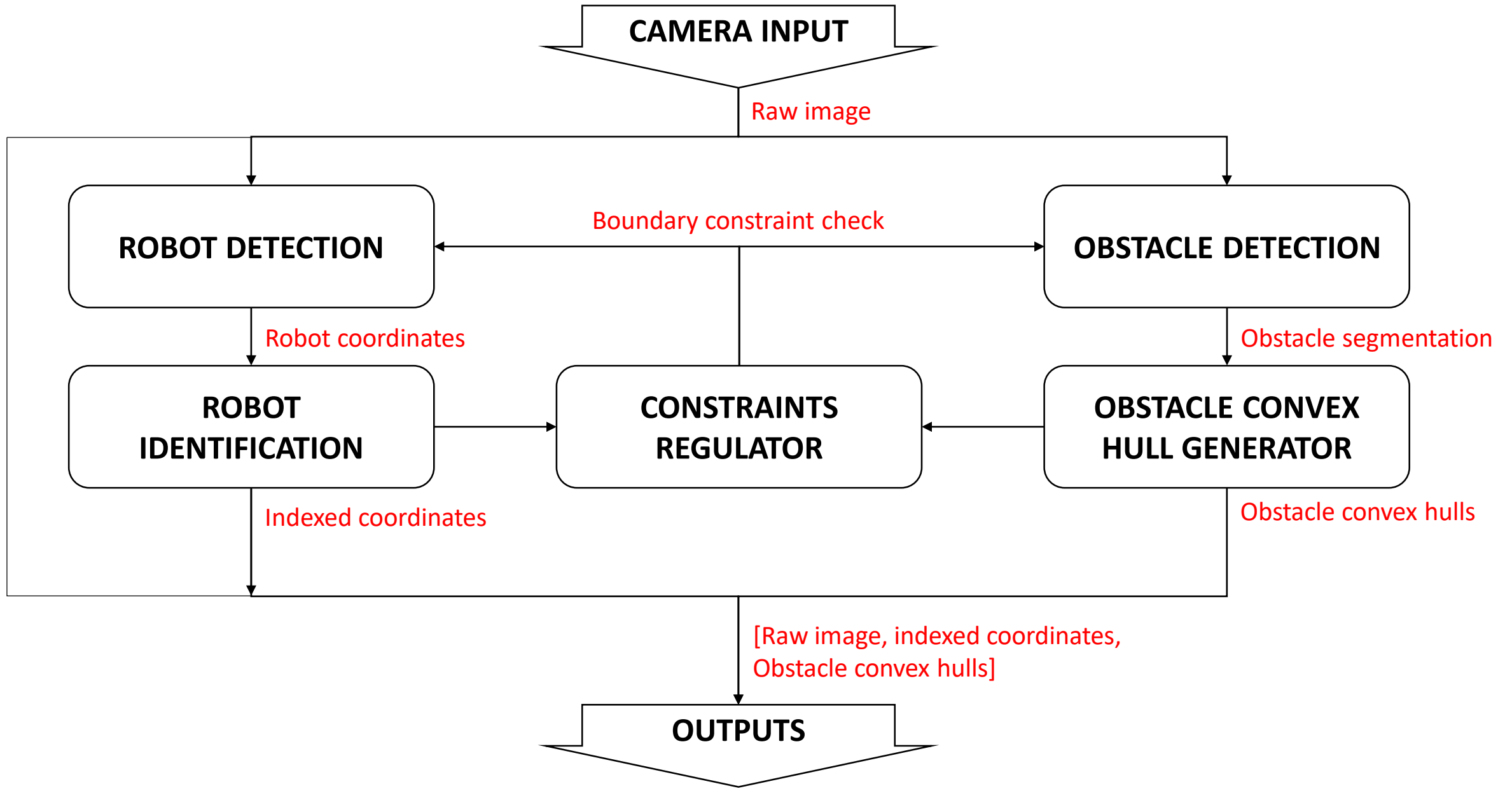
**EXPERIMENT DATA**

**SEGMENTED IMAGE,  
PLANNED PATHS**

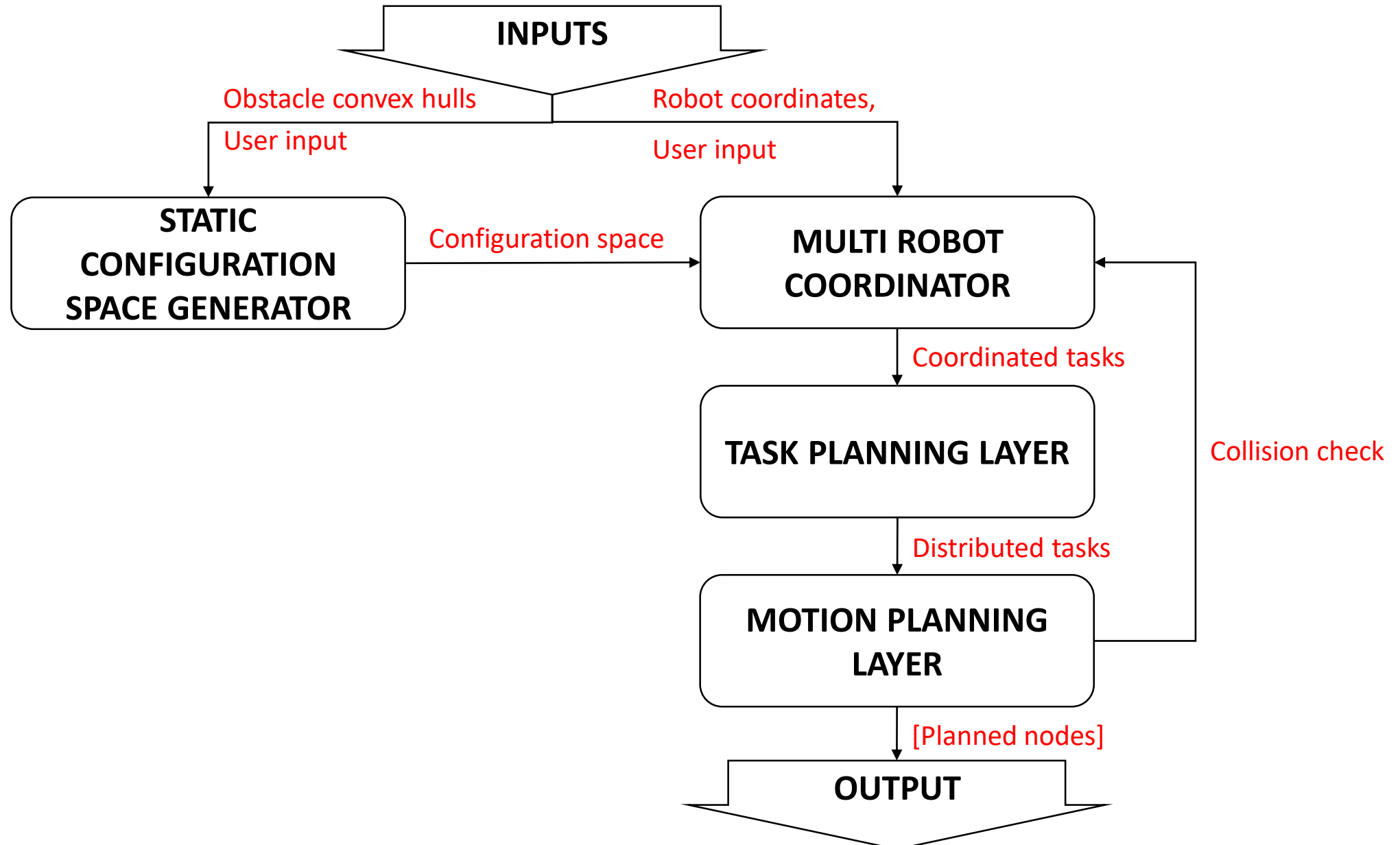
# SERVER



# TRACKING SYSTEM



# CENTRALIZED CONTROLLER



# INDIVIDUAL ROBOTS

