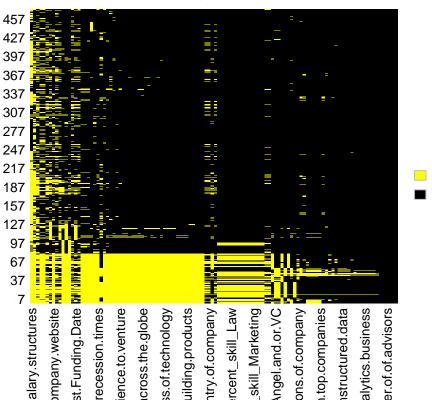
Missingness Map



Missing (15%)

■ Observed (85%