



ESP32 Main Board Connections (NodeMCU-ESP32)

1. Power Connections

- ESP32 5V → Breadboard +5V rail
- ESP32 GND → Breadboard GND rail

Everything else shares this GND and 5V, unless separately powered.

2. IR Eye-Blink Sensor (3-pin module)

Pins on sensor: VCC – GND – OUT

Connect as follows:

Sensor Pin Connects To

VCC ESP32 5V

GND ESP32 GND

OUT ESP32 GPIO 15 (your SENSOR_PIN in code)

3. GPS Module (NEO-6M or similar)

Pins: VCC – GND – TX – RX

GPS
Pin Connects To

VCC ESP32 5V

GND ESP32 GND

TX ESP32 RX2 → GPIO 16 (*or whatever RX pin you are using*)

RX ESP32 TX2 → GPIO 17 (*optional, used only if sending commands*)

(Your diagram shows only TX used, which is okay.)

4. Vibration Motor With Transistor Driver

You are using:

- ✓ NPN Transistor
- ✓ Diode for flyback protection
- ✓ Motor powered by 9V battery

Connections:

Part	Connection
Motor +	9V battery +
Motor –	Transistor Collector
Transistor Emitter GND common with ESP32	
Transistor Base	ESP32 GPIO 19 through 1k Ω resistor

Protection:

- Diode across motor terminals (reverse-biased)
 - Diode Cathode \rightarrow Motor +
 - Diode Anode \rightarrow Motor –

5. Buzzer

Pins: + and –

Pin	Connection
Buzzer +	ESP32 GPIO 5
Buzzer –	GND

ESP32-CAM Module Power & Stream

You are powering the ESP32-CAM from the main ESP32 board.

Power:

ESP32-CAM Pin Connects To

5V ESP32 Main 5V

GND ESP32 Main GND

Streaming:

No additional pins needed; it streams via WiFi on port 82.

Cam on/off happens through HTTP:
http://CAM_IP/on
http://CAM_IP/off

7. Summary of Primary GPIO Usage

Feature	ESP32 GPIO
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IR Eye Sensor	GPIO 15
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Buzzer	GPIO 5
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Motor Driver	GPIO 19
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Camera (separate board)	WiFi + HTTP only
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GPS RX	GPIO 16 (if used)
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GPS TX	GPIO 17 (main data line)
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