

# Chinmay Talegaonkar

🏠 Website | ✉ ctalegaonkar@ucsd.edu | 🔗 LinkedIn | 🐙 GitHub | 📄 Google Scholar

## EDUCATION

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<b>University of California, San Diego</b> <i>Ph.D. in Electrical and Computer Engineering</i> <b>Advisor:</b> Prof. Nicholas Antipa	San Diego, CA <i>Sept 2022 – Present</i> GPA: 4.0/4.0
<b>University of California, Los Angeles</b> <i>M.S. in Electrical and Computer Engineering</i> <b>Advisor:</b> Prof. Achuta Kadambi	Los Angeles, CA <i>2019 – 2021</i> GPA: 4.0/4.0
<b>Indian Institute of Technology, Bombay</b> <i>B.Tech. in Electrical Engineering</i> <i>Minor in Computer Science</i> <b>Advisor:</b> Prof. Ajit Rajwade	Mumbai, India <i>2015 – 2019</i> GPA: 9.07/10.0

## WORK EXPERIENCE

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<b>Research Intern</b> <i>Qualcomm AI</i>	<i>San Diego, CA</i> <i>June 2023 – Sept 2023</i>
<ul style="list-style-type: none"><li>Developed a memory-efficient generalizable NeRF-like method to create human avatars from monocular videos. Achieved comparable accuracy to existing methods. <i>Patent Pending</i></li><li>Invented a point-based 3D scene representation for human modeling that reduces memory usage by 10x and training time by 100x respectively.</li><li>Engineered an end-to-end pipeline to estimate SMPL mesh, and segmentation masks from videos.</li></ul>	
<b>Senior Deep Learning Engineer</b> <i>Intrinsic.ai</i>	<i>Mountain View, CA</i> <i>May 2022 – Sept 2022</i>
<ul style="list-style-type: none"><li>Led the development of a novel HDR fusion algorithm, resulting in higher pose estimation accuracy for difficult lighting scenarios.</li><li>Implemented a deep learning-based feature extractor to improve stereo matching and point cloud generation from a multi-view camera setup.</li></ul>	
<b>Senior Deep Learning Engineer</b> <i>Akasha Imaging - acquired by Intrinsic.ai (an Alphabet company) in May 2022.</i>	<i>Palo Alto, CA</i> <i>May 2021 – May 2022</i>
<ul style="list-style-type: none"><li>Developed an end-to-end deep learning based multi-view pose estimation pipeline with more than 99% reliability and sub-millimeter accuracy. This led to the company's first product order.</li><li>Engineered a synthetic data generation pipeline to generate training data for segmentation and keypoint estimation algorithms.</li><li>Contributed to tools for ML Ops, CI/CD testing, pose evaluation frameworks, and data collection setups.</li></ul>	
<b>Deep Learning Software Intern</b> <i>NVIDIA</i>	<i>Santa Clara, CA</i> <i>June 2020 – Sept 2020</i>
<ul style="list-style-type: none"><li>Optimized CUDA kernels for backpropagation in 2D and 3D convolution layers in popular CNN architectures, resulting in 30% speedup.</li><li>Implemented a linearized thread launching algorithm resulting in over 30 % speedup for 3D convolutions with low channel counts.</li><li>Enabled complex valued convolution kernels in <i>CUTLASS</i> achieving more than 90% compute resource utilization.</li></ul>	
<b>AI/ML Compute DevTech Intern</b> <i>NVIDIA</i>	<i>Bengaluru, India</i> <i>May 2018 – July 2018</i>
<ul style="list-style-type: none"><li>Developed CUDA kernels for optimizing routing layer and back-propagation in capsule networks resulting in a 2x speedup</li><li>Parallelized end-to-end implementation of <i>DBscan</i> using <i>CUTLASS</i> and <i>thrust</i> libraries for <b>NVIDIA Rapids</b> 🚀 platform</li></ul>	

## PUBLICATIONS

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### Pose Estimation of Buried Deep-Sea Objects using 3D Deep Learning Models

Jerry Yan\*, **Chinmay Talegaonkar\***, Nicholas Antipa, Eric Terrill, Sophia Merrifield  
OCEANS Conference and Expositions, 2024. [Paper](#) [Code](#)

### Visual Physics: Discovering Physical Laws from Videos

Pradyumna Chari\*, **Chinmay Talegaonkar\***, Yunhao Ba\*, Achuta Kadambi  
ICCP 2020 Poster, CVPR 2020 Tutorial. [arXiv PrePrint](#)  
Journal Version: *On learning mechanical laws of motion from video using neural networks*.  
IEEE Access, 2023. [Paper](#)

### Compressive Phase Retrieval Under Poisson Noise

**Chinmay Talegaonkar**, Parthasarathi Khirwadkar, Ajit Rajwade  
IEEE International Conference on Image Processing (ICIP) 2019. [Paper](#)

### Performance Bounds For Tractable Poisson Denoisers With Principled Parameter Tuning

**Chinmay Talegaonkar**, Ajit Rajwade  
IEEE Global Conference on Signal and Information Processing (GlobalSIP) 2018. [Paper](#)

## KEY SKILLS

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**Programming Languages:** C & C++, CUDA, Bash, Python, MATLAB

**Frameworks:** Pytorch, OpenCV, scikit-learn, numpy, scipy, pandas, blender, mitsuba3, Slang.D

**Development Tools:** Github, Jenkins, Google Cloud, Docker

## RESEARCH PROJECTS

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### Exact Volume Rendering of 3D Gaussians

Aug 2024 - Present

*Guide: Prof. Nicholas Antipa and Prof. Ravi Ramamoorthi*

Developed a method for fast, exact volume rendering of 3D Gaussians. Currently exploring potential applications in Computed Tomography.

### Defocus Blur Rendering with 3D Gaussian Splatting

Jan 2024 - Present

*Guide: Prof. Nicholas Antipa and Prof. Ravi Ramamoorthi*

Devised an approach for rendering 3D Gaussians with defocus blur. Demonstrated applications in novel view synthesis from blurry images.

### Monocular Depth Diffusion Models with Defocus Cues

Jan 2024 - Present

*Guide: Prof. Nicholas Antipa*

Developed a test-time optimization method leveraging lens blur to remove depth ambiguities in monocular depth diffusion models. The proposed approach also enables metric depth estimation through these models.

### Novel View Synthesis in the Presence of Phase Optics

Sept 2022 - Dec 2022

*Guide: Prof. Ravi Ramamoorthi*

NeRF-based view synthesis from sparse views captured using a microlens array [Code](#) [Report](#)

## TEACHING ASSISTANT

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|-----------------------------------|-----------------------|
| • Introduction to Quantum Physics | IIT Bombay, Fall 2016 |
| • Software Systems Lab            | UCLA, Winter 2020     |
| • Reinforcement Learning          | UCLA, Spring 2020     |
| • Introduction to Computer Vision | UCLA, Winter 2021     |
| • Computational Imaging           | UCSD, Spring 2024     |