Chinmaya **Devara**J

Ph.D. Graduate | Computer Vision | University of Maryland College Park

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I am a Ph.D. candidate in Electrical and Computer Engineering at the University of Maryland College Park, advised by Prof. Yiannis Aloimonos and Dr. Cornelia Fermuller. My broad field of research is Computer vision and Generative AI. I have contributed to pioneering projects in text-image generation, video-text models, and zero-shot action recognition, holding a patent and multiple publications. My research topics include Multimodal language modeling, video representation learning, vision-language models, LLMs, and action recognition. I am seeking full-time roles in the industry to leverage my expertise for transformative advancements in AI and technology.

EDUCATION

Present	Ph.D.	Electrical and Computer Engineering, University of Maryland, College Park
2022	MS	Electrical and Computer Engineering, University of Maryland, College Park
2015	D Tools	Floatrical Engineering National Institute of Taphyalagu Karnataka Curathkal In

2015 B.Tech. | Electrical Engineering, National Institute of Technology, Karnataka, Surathkal India

Publications

- 1. **Chinmaya Devaraj**, Cornelia Fermuller, Yiannis Aloimonos. Diving DeepWith Video-Text Models in Representing Motion . Accepted ACL Findings 2024.
- 2. Chinmaya Devaraj, Cornelia Fermuller, Yiannis Aloimonos. Incorporating Visual Grounding In GCN For Zero-shot Learning Of Human Object Interaction Actions. CVPRW 2023
- 3. Eadom Dessalene*, Chinmaya Devaraj*, Michael Maynord*, Cornelia Fermuller, and Yiannis Aloimonos. Forecasting action through contact representations from first person video. TPAMI 2021 (* Indicates equal contribution) Link..
- 4. Chinmaya Devaraj, Cornelia Fermuller, Yiannis Aloimonos. Introducing Meta-Verbs into Graph Convolutional Networks for Zero-shot Action Recognition. CVPRW 2021
- 5. Eadom Dessalene, Michael Maynord, Chinmaya Devaraj, Cornelia Fermuller, and Yiannis Aloimonos. "Egocentric object manipulation graphs." arXiv preprint.
- 6. Chinmaya Devaraj, Aritra Chowdhury, Arpit Jain, James R. Kubricht, Peter Tu, and Alberto Santamaria-Pang. From Symbols to Signals: Symbolic Variational Autoencoders. ICASSP 2020. Link.
- 7. James Kubricht, Alberto Santamaria-Pang, Chinmaya Devaraj, Aritra Chowdhury, and Peter Tu. Emergent Languages from Pretrained Embeddings Characterize Latent Concepts in Dynamic Imagery. International Journal of Semantic Computing. (2020) Link.
- 8. Alberto Santamaria-Pang, James R. Kubricht, Chinmaya Devaraj, Aritra Chowdhury, and Peter Tu. Towards semantic action analysis via emergent language. IEEE International Conference on Artificial Intelligence and Virtual Reality (AIVR) 2019.
- 9. Chengxi Ye, Chinmaya Devaraj, Michael Maynord, Cornelia Fermüller, Yiannis Aloimonos. "Evenly Cascaded Convolutional Networks." The 1st International Workshop on Big Visual Dataset Construction, Management and Applications, IEEE BigData 2018. Best Student Paper Award. Link.

PATENTS

1. Alberto Santamaria-Pang, Peter Henry Tu, James KUBRICHT, Aritra Chowdhury, Arpit Jain, Chinmaya Devaraj. System and methods for artificial intelligence explainability via symbolic generative modeling. US Patent 2021

SKILLS

Deep Learning frameworks Pytorch, TensorFlow, TFLearn, Keras

> Languages Python, C, MATLAB

Deep Learning Architectures CNNs, RNNs, LSTMs, Transformers, VAE, GANs

> Computer Vision, Machine Learning, Data collection, Multi-model Learning, Generative Al, Domain Skills:

Reinforcement Learning, Vision+Language Models, Natural Language Processing, Generative Pre-trained Transformers (GPT), Graph Neural Networks, Video Understanding, Representation learning, Video-text models, Motion understanding, Zero-shot recognition, Action Recog-

nition, Action anticipation



Research intern June-Aug 2019

GE Research | Computer Vision and Machine learning team, NISKAYUNA, NY

- > Designed and evaluated text-guided image generation to understand emergent languages in videos and images.
- > Developed symbolic variational autoencoder to reconstruct images from symbols.
- > Developed domain adaption methods using symbolic variational autoencoder.

Emergent language | Variational Autoencoders | Text-Image Generation | Al generated Images | Explainable Al

Research intern June-Aug 2017

Honda Research Institute, MOUNTAIN VIEW, CA

- > Designed and evaluated deep neural network to model driver's visual attention and driver's behavior information from driving data.
- > Improved computation speed by 10X by designing efficient methods to process driving data object segmentation Visual attention Efficient deep learning

RESEARCH EXPERIENCE

Aug 2016 -Present

Ph.D. Researcher, Advisors: Prof. Yiannis Aloimonos and Dr Cornelia Fermuller, UMD, MD

- > Developed framework for zero shot action recognition and transfer learning of actions across activity datasets using knowledge graphs and vision language models.
- > Developed framework for representing motion in videos in video-text models.
- > Developed Evenly Cascaded Neural networks an efficient neural network for image classification.
- > Co-developed framework to anticipate future egocentric actions.
- > Co-developed a novel CNN-LSTM architecture to perform multimodal fusion and hallucination of sensor data and video data.

Action recognition | Multimodal Learning | Vision-language models | LLMs | Finetuning |

June -Aug 2016

Visiting Student Researcher, Telluride Neromorphic Workshop, Colorado

> Developed algorithm that uses foreground, background information obtained from event-based signals of dynamic vision sensor (DVS) camera to segment objects in video.

Event based camera video object segmentation

Selected Ph.D. Projects

MAVL: Using Moments in Actions in Vision Language Models.

Jan 2024- Current.

- Prompted off-the-shelf GPT-4 with instructional activity steps to generate finer steps describing the subactions and the characteristic motion involved in fine-grained actions.
- Developed method to perform zero-shot action recognition of fine-grained activities using video-text models.
- We validated our method on two fine-grained action datasets and showed that the network outperforms other baselines.

Leveraging Motoric Information for Recognizing Manipulation Actions.

Sept 2016- March 2017

- Developed an approach for visual recognition and temporal segmentation of fine-grained manipulation actions based on a recurrent neural network architecture.
- During training, a hallucination structure is learned from visual and motoric data, and this mirroring structure helps recognition during the testing phase when only visual data is present.
- We validated our method on two multimodal fine-grained action datasets, and showed that the network outperforms vision-only approaches.

Awards

- 1. Winner of EPIC-kitchens action anticipation challenge CVPR 2020
- 2. Selected among 8 teams globally at Amazon Simbot Challenge 2022 with an award amount of \$250000
- 3. Received NSF Neuropac Fellowship for academic year 2023-2024 with award amount of \$21000

SERVICE AND LEADERSHIP

- 1. Serving as reviewer for major computer vision conferences CVPR[20,21,23], ICCV[21], NLP conferences NAACL[2024], and journals (CVIU, RA-L).
- 2. Founder of SKY at UMD club at UMD dedicated to promoting mental and physical well-being in UMD community. Impacted over 2000 students and faculty through breathwork and meditation programs.