

Chinmay Nandan Samant

Contact Details: 02, Rue du Vieil Armand, 67100, Strasbourg, Les Cattleyas, Studio 026, France

Email: chinmaynsamant@gmail.com Cell: +33 605929227

RESEARCH INTERESTS

Medical Imaging, Machine Learning, Image Processing

EDUCATION

Masters in Computer Vision(Erasmus Mundus Vision & Robotics) **University of Bourgogne**

Le Creusot, France
Sept 2013 - Aug 2015

- Image Processing, Medical Imaging, Scene Segmentation and interpretation, Visual Tracking, Machine Learning, Neural Networks
- Autonomous, Probabilistic Robotics, Self-calibration, Localization, Computer Vision, 3D reconstruction/ registration, Visual Servoing

Masters in Electronic Science **University of Pune**

Pune, India
Aug 2010 - Apr 2012

- Embedded systems design, Digital Signal Processing
- Analog, power electronics design

Bachelors in Electronic Science **University of Pune**

Pune, India
Aug 2007 - Apr 2010

- Minors: Mathematics, Physics, Statistics

WORK EXPERIENCE

ICUBE, University of Strasbourg, France **Intern**

Feb 2015 - Present

Real-time marker segmentation and tracking in MRI

- Intelligent segmentation and robust tracking of the marker
- Evaluating deformity in the shape of the marker
- Physical design of the marker

LE2i, University of Bourgogne, France **Intern**

Jul 2014 – Aug 2014

Wood texture analysis and classification

- Classification of wood material based on the patterns present on the wooden planks.
- Feature Extraction & Machine Learning

Center for Sensor Studies, University of Pune, India **Research Assistant**

Jul 2012 – Jun 2013

- Ultrasonic Transducer Applications: Coal Presence Detection, Runtime mass fluid flow measurement, Ultrasonic Transducer Development, Embedded Systems Development

PROJECT EXPERIENCE

Medical imaging tool for object volume reconstruction

- A MATLAB tool for manual segmentation and volume reconstruction in medical images

Machine learning algorithms for segmentation and classification

- A thorough study of state of art algorithms mainly for medical applications

3D reconstruction simulation tool for pattern projection based active camera systems

- Simulation of a camera and projector system for virtual 3D reconstruction

Visual tracking

- Extensive study of visual tracking algorithms and their applications

FPGA based temperature module

- Temperature signal processing module, VGA display and other controls

Robotics surveillance

- Autonomous robotic surveillance with Turtlebot based of ROS.

Visual servoing

- Study of state of art visual servoing methods

Wavelets based compression and filtering

- Image analysis with wavelets and its applications

Surveys and implementations

- Edge Detection in Color Images
- Compressed Sensing

Single View Metrology tool for Height estimation

- A MATLAB tool for depth and height estimation using a single webcam

Kohonen network learning for classification of patient data

- Implementation in MATLAB to classify complex patient movement data

Computer Vision/Image Processing Toolbox

- Implemented in OpenCV and MATLAB, built with complete user interface for Images, Videos and Live camera feed.

PCA based face recognition

- PCA was implemented to detect faces out of pool of images. Implemented in MATLAB.

Interactive Map Software

- Google maps alike offline map software created for Le Creusot, using OpenCV and MATLAB.

Masters in Electronics Thesis: Non-Contact Liquid Level Measurement using Ultrasonic Sensors

- An Ultrasonic Sensor system was developed to measure liquid level without contact.

SKILLS

- Computer Languages: C/C++ , MATLAB, Assembly, VHDL
- Electronics: Microcontroller Programming, Hardware Design
- Tools: ROS, Qt, Codeblocks, OpenCV, GitHub, Orcad

ADDITIONAL

Fluent in English, Marathi, Hindi. French Basic; Hobbies: Tech gadget analysis & testing, music & sports

REFERENCES

Adlane HABED

Associate Professor
University of Strasbourg
ICube – CNRS 7357
habed@unistra.fr

David FOFI

Professor, Head of Computer Vision Dept
University of Bourgogne
Le2i UMR CNRS 6306
david.fofi@u-bourgogne.fr , +33 3 85 73 11 26