



Indian Institute of Space Science and Technology

AE-224 MACHINING AND PRECISION MANUFACTURING

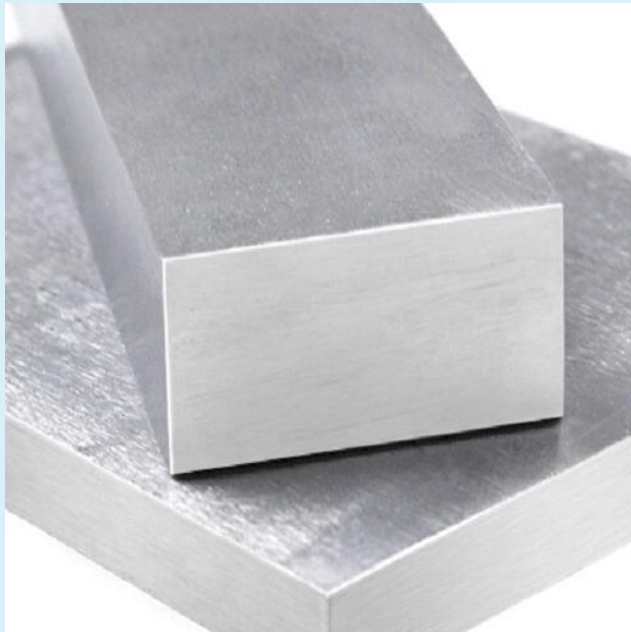
Task I : Designing and Manufacturing of a
Mechanical Housing

Presented by –
Chinmay Gourkhede
SC19B012

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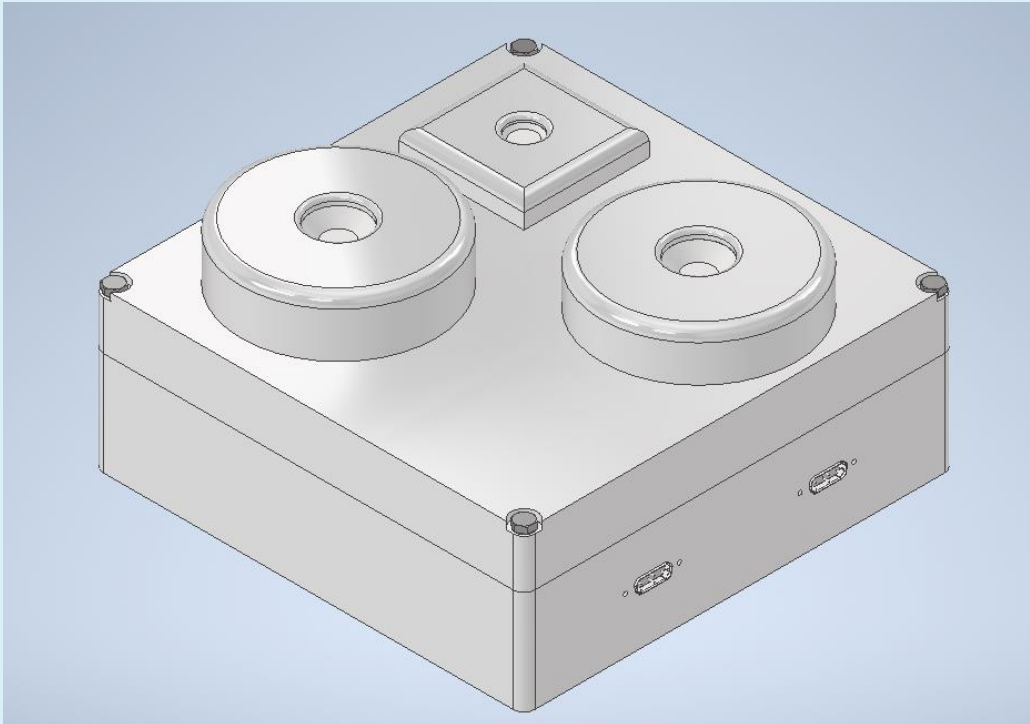
1. Raw Material Selection
2. Finished Product
3. Fabrication of Bottom
4. Fabrication of Top
5. Assembly
6. Measuring Methods for Verification

Raw Material : *Aluminium*



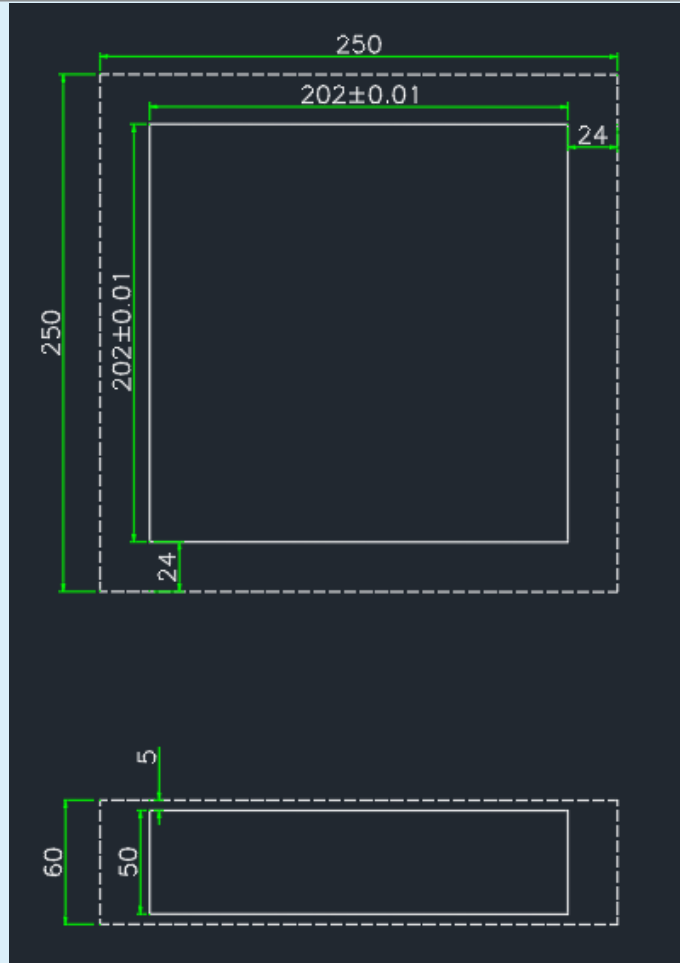
- Aluminium has high strength-to-weight ratio which varies from 0.7 – 1.8
- It is Easily Available and Machinable
- Being a light weight metal , Aluminium is widely used in Aviation Industry
- The Dimensions of the Metal Blank provided is 250x250x60 mm , 2 nos.

Finished Product :



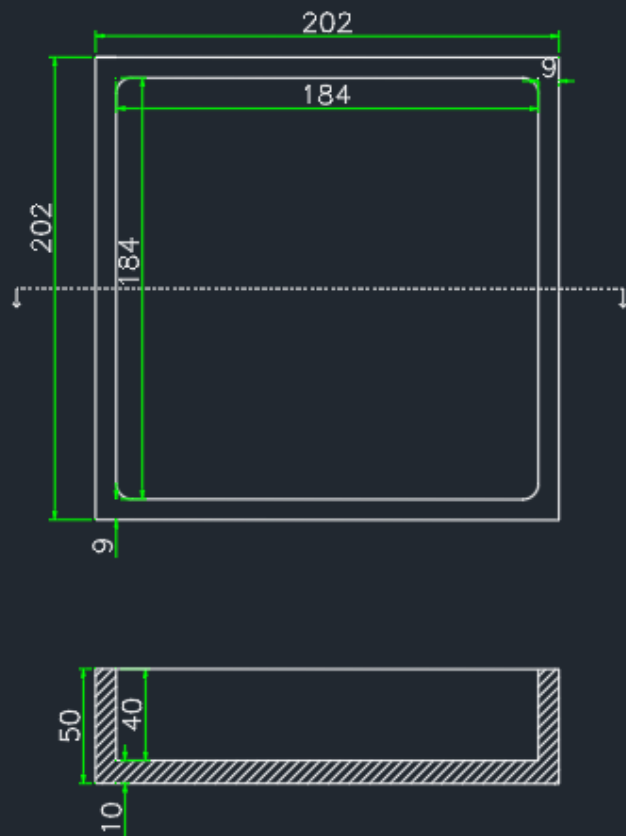
- Dimensions : $200 \pm 0.1\text{mm} \times 200 \pm 0.1\text{mm} \times 100 \pm 0.1\text{mm}$
- Overall Weight : $2.485 + 0.300 = 2.785\text{kg}$

Fabrication of Bottom:



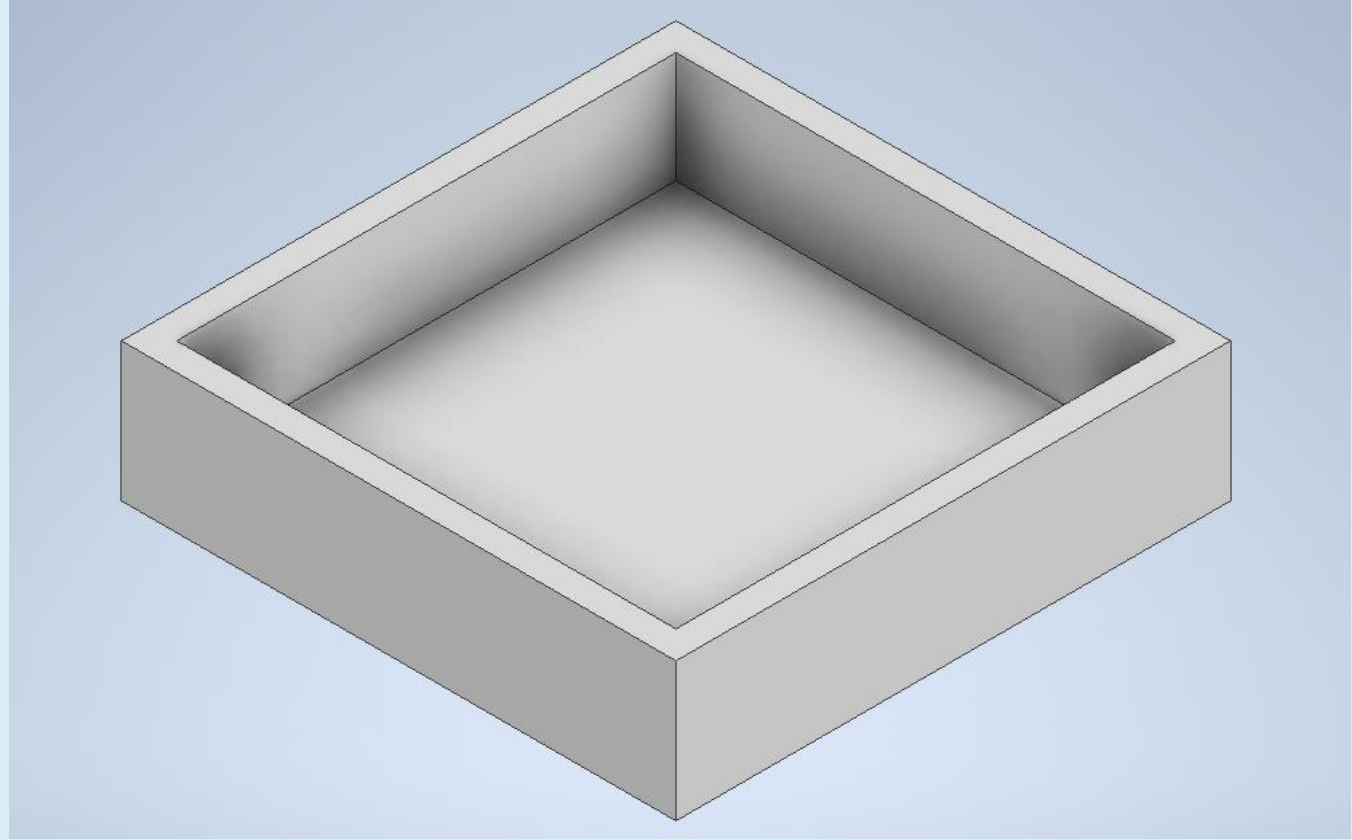
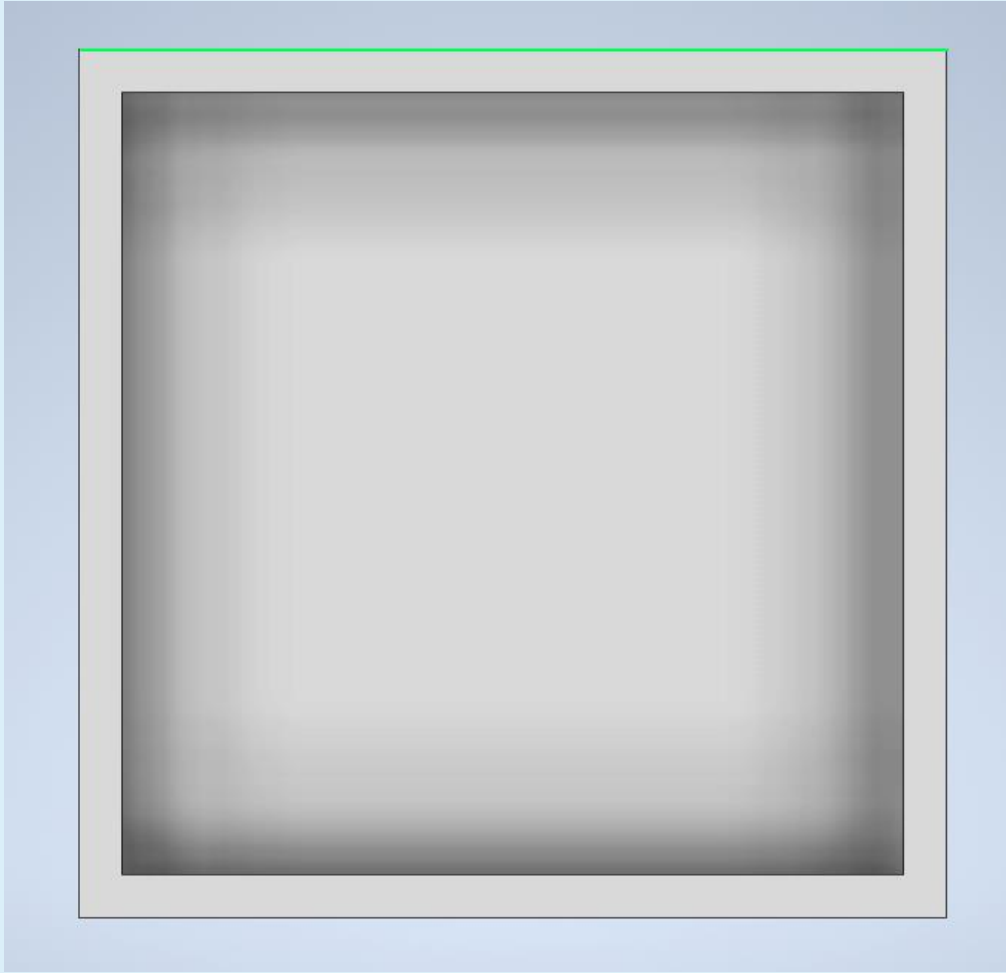
1. Face & End Milling

- to reduce plate dimension from 250x250x60 to 202x202x50
- Milling Tool required of dim $\varnothing 50$ mm
- Extra 2 mm is for Grinding 1 mm from each side for a better finish.

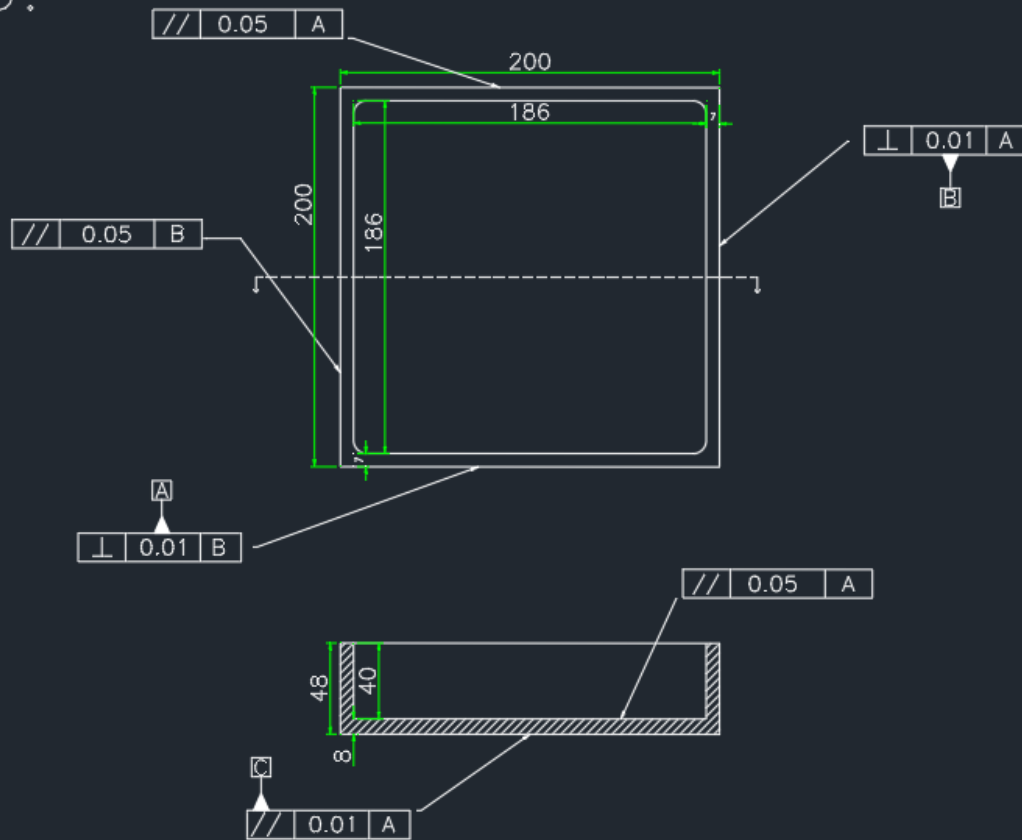


2. Square Pocket Milling

- Starting 11 mm from the edges to make a cavity of dimension 184x184x40 mm.
- Milling Tool $\varnothing 30$ -50mm

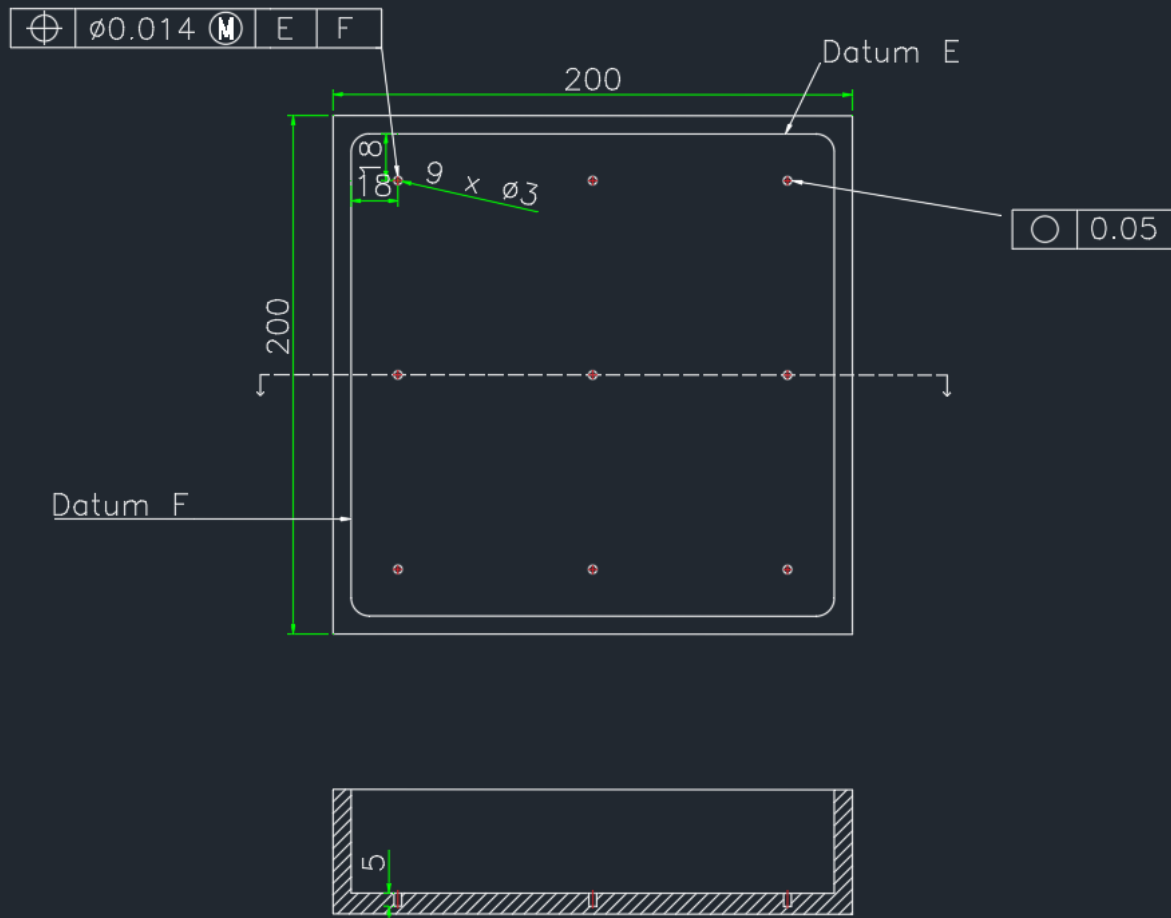


3.



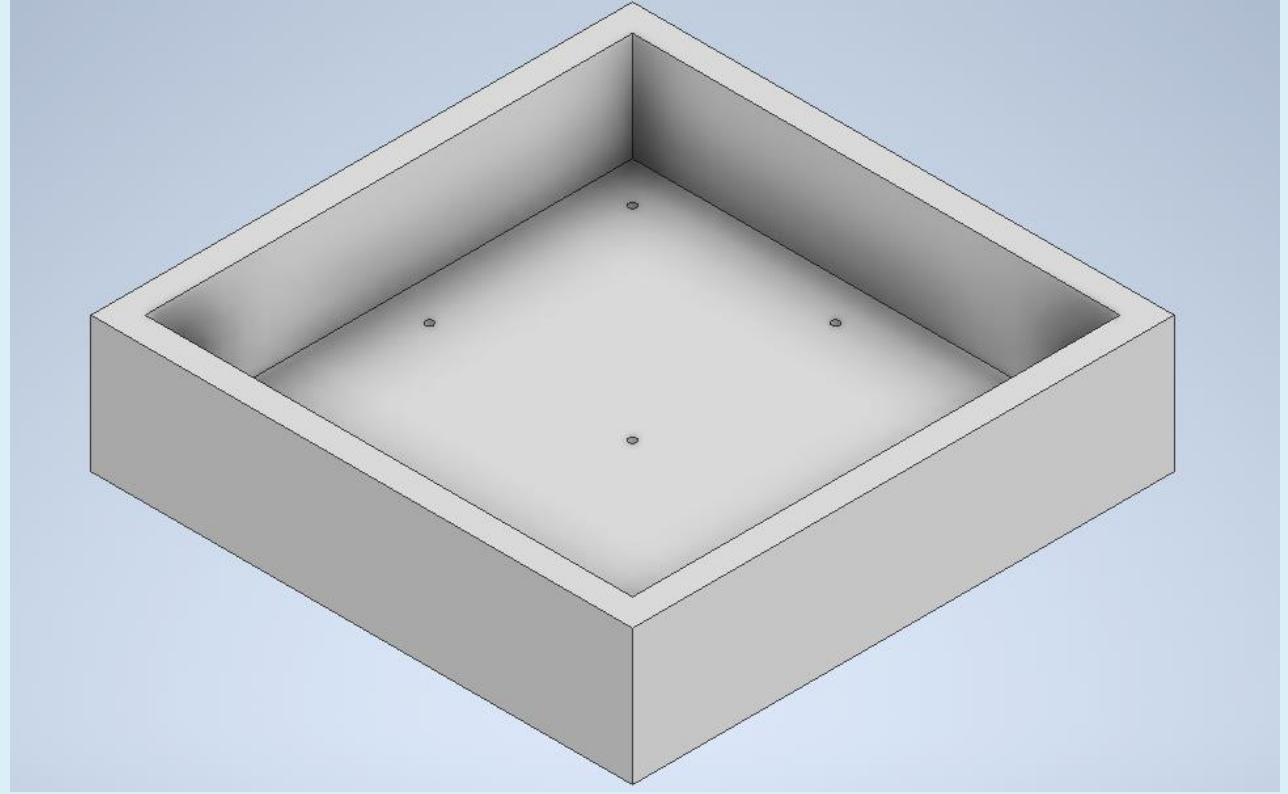
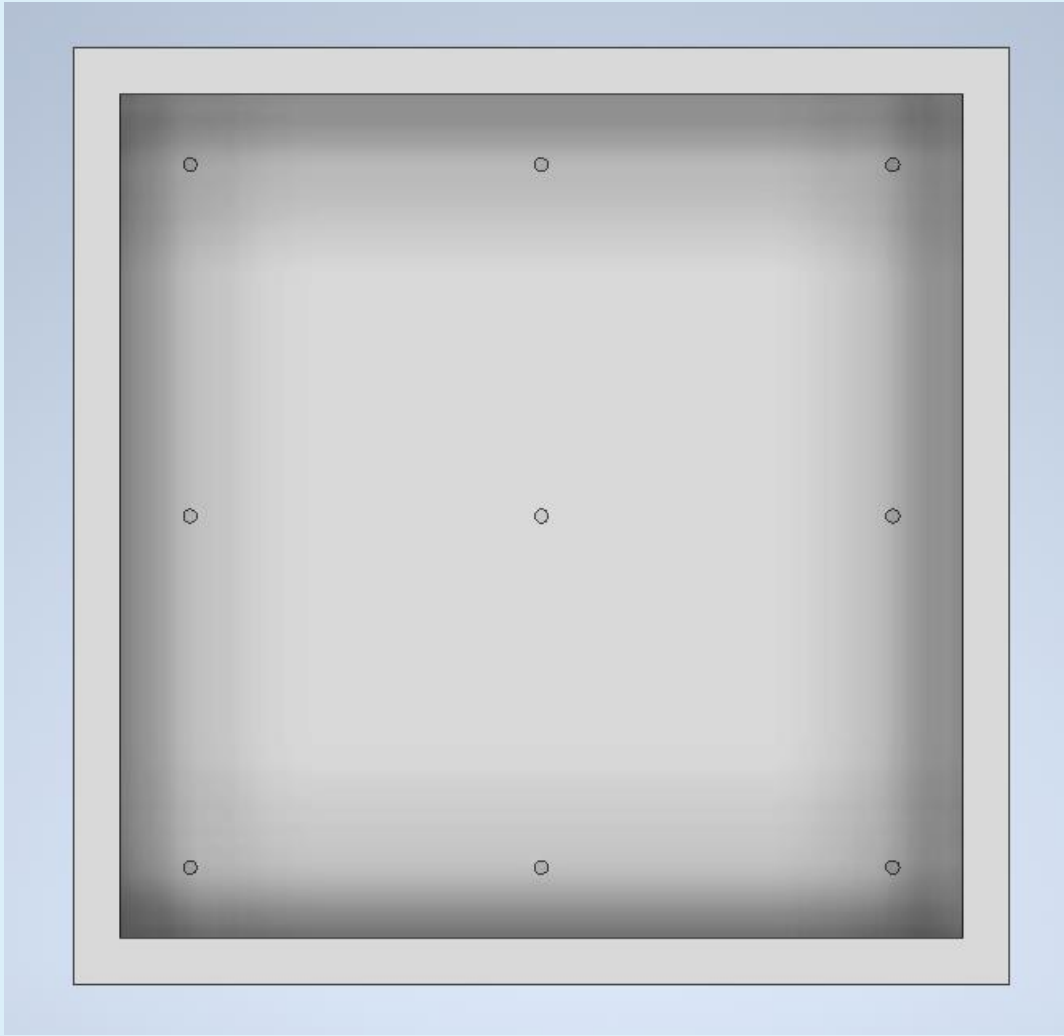
3. Grinding

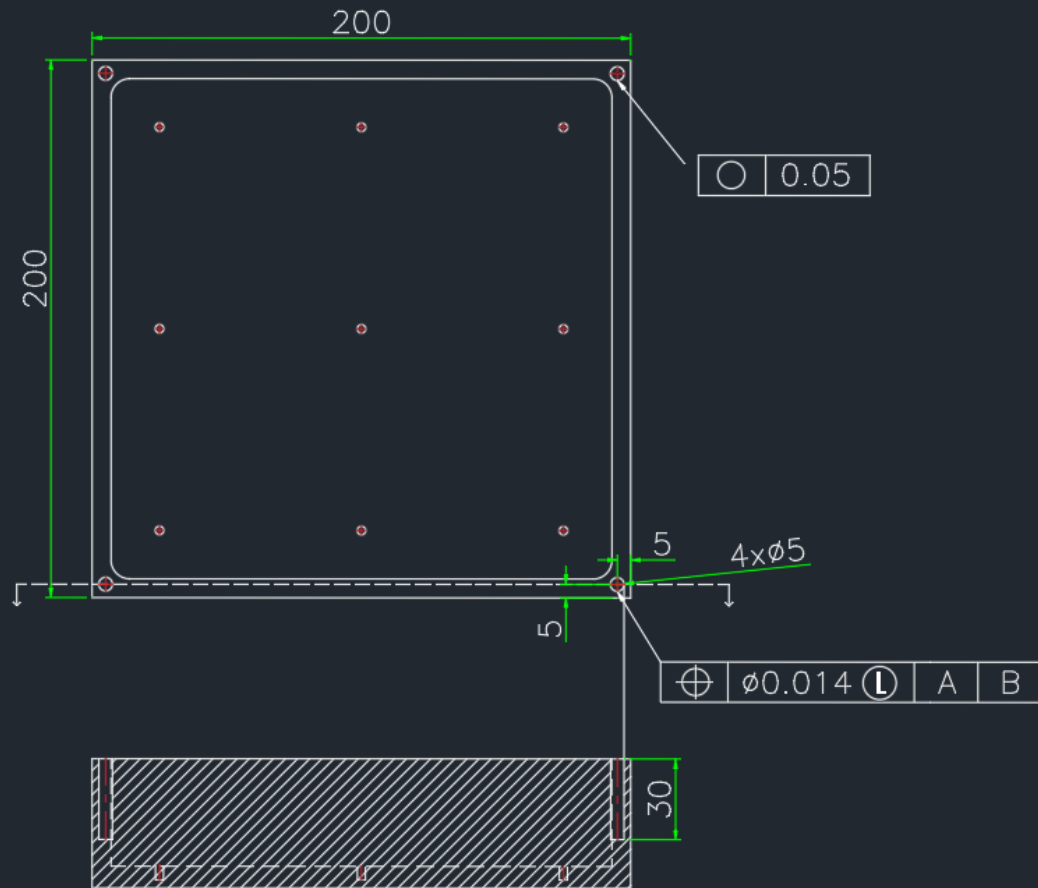
- With the Help of Grinding wheel , we remove the additional 1 mm from the work-piece
- Grinding wheel , Open structure with Soft wheel



4a. Drilling

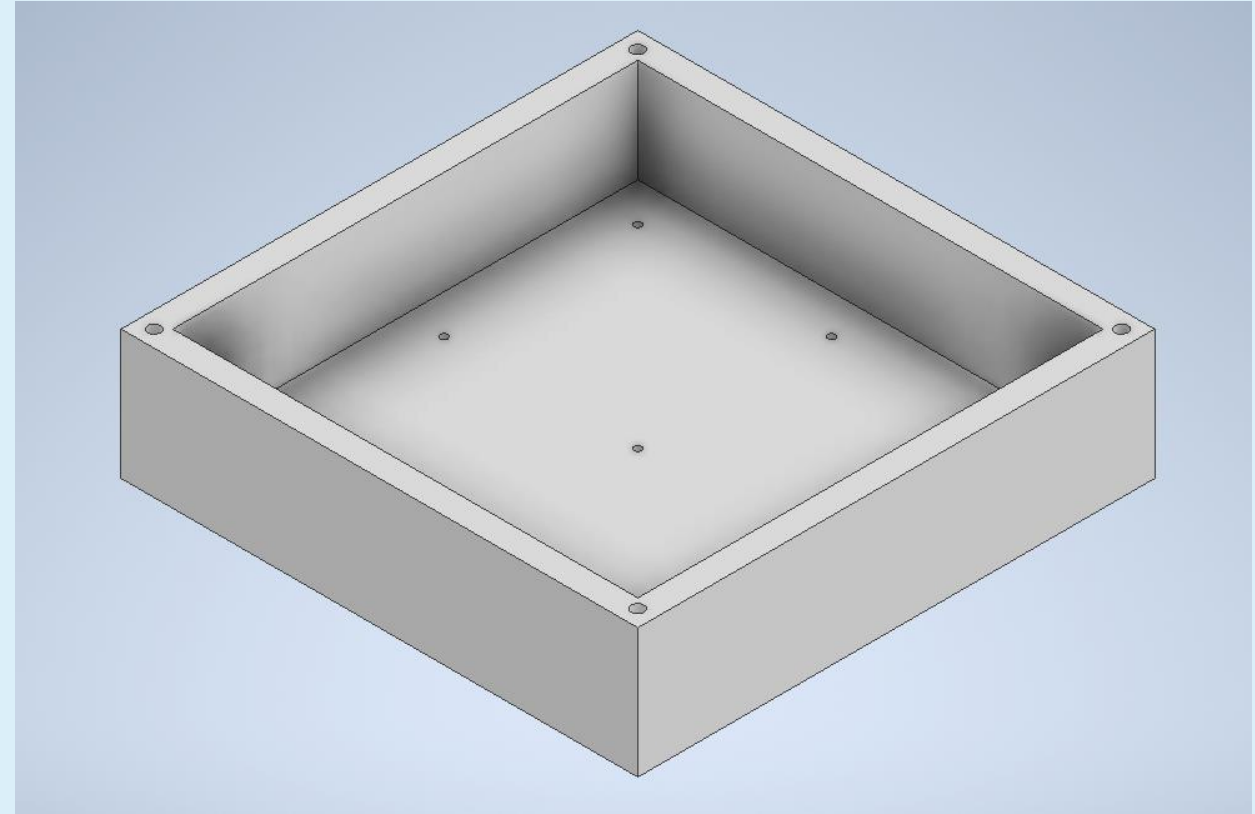
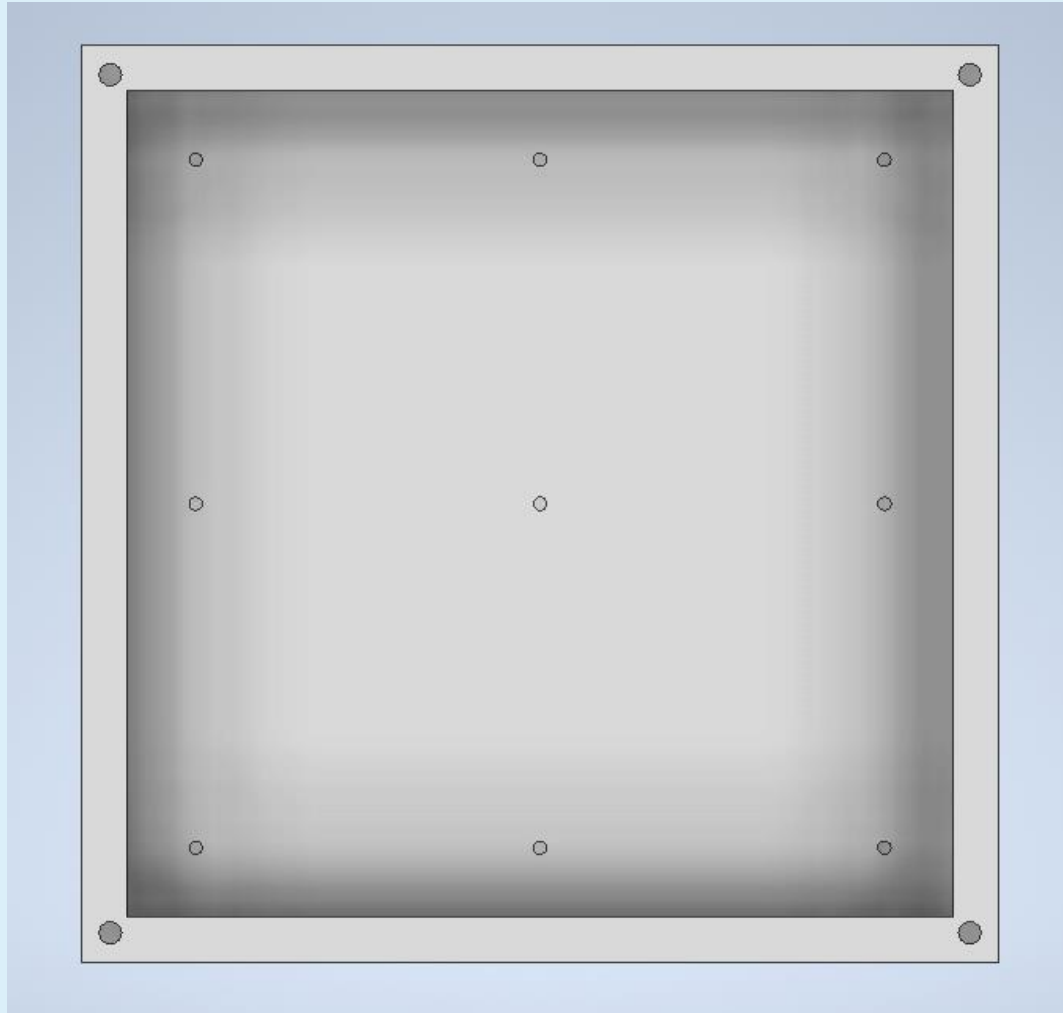
- Performing Drilling operation with the help of a Drilling Machine to construct blind drill holes inside the cavity , on the base
- Dimension – 9 x (M3 , 5mm)
- Drill bit $\varnothing 3$ mm
- These drill holes will help to secure the circuit board 10mm above the base.
- A Jig can be used for convenience in drilling

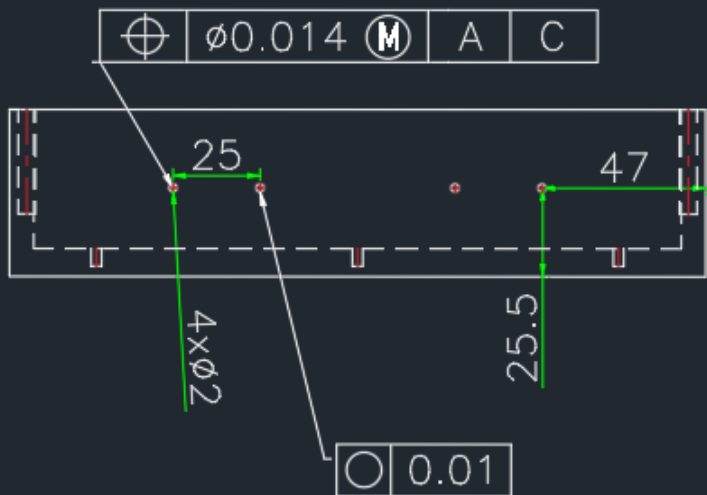
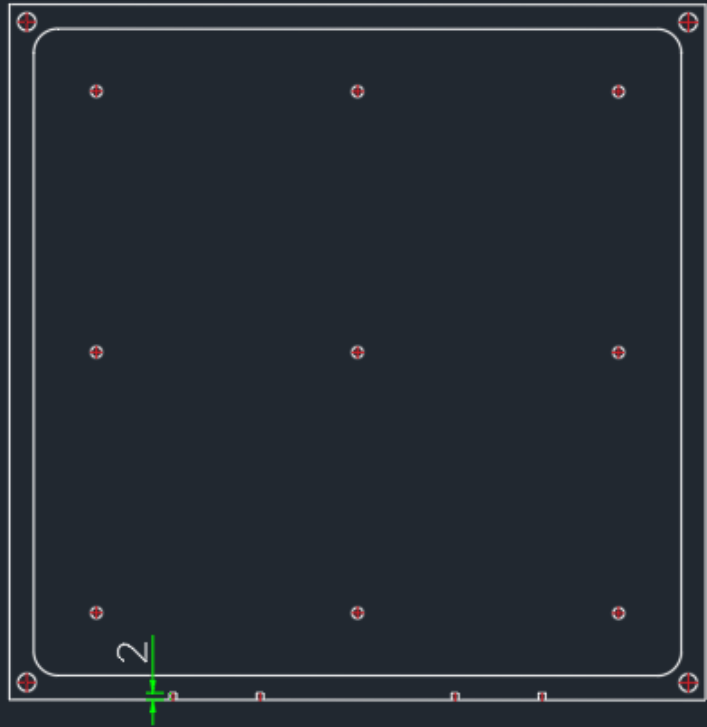




4b. Drilling

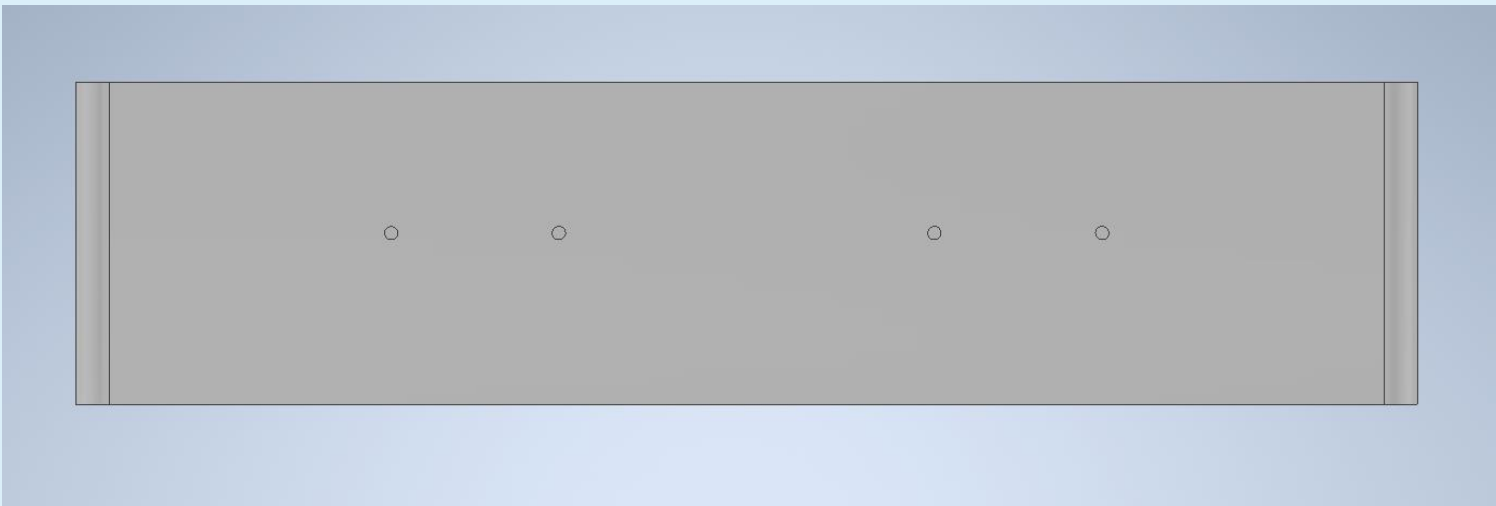
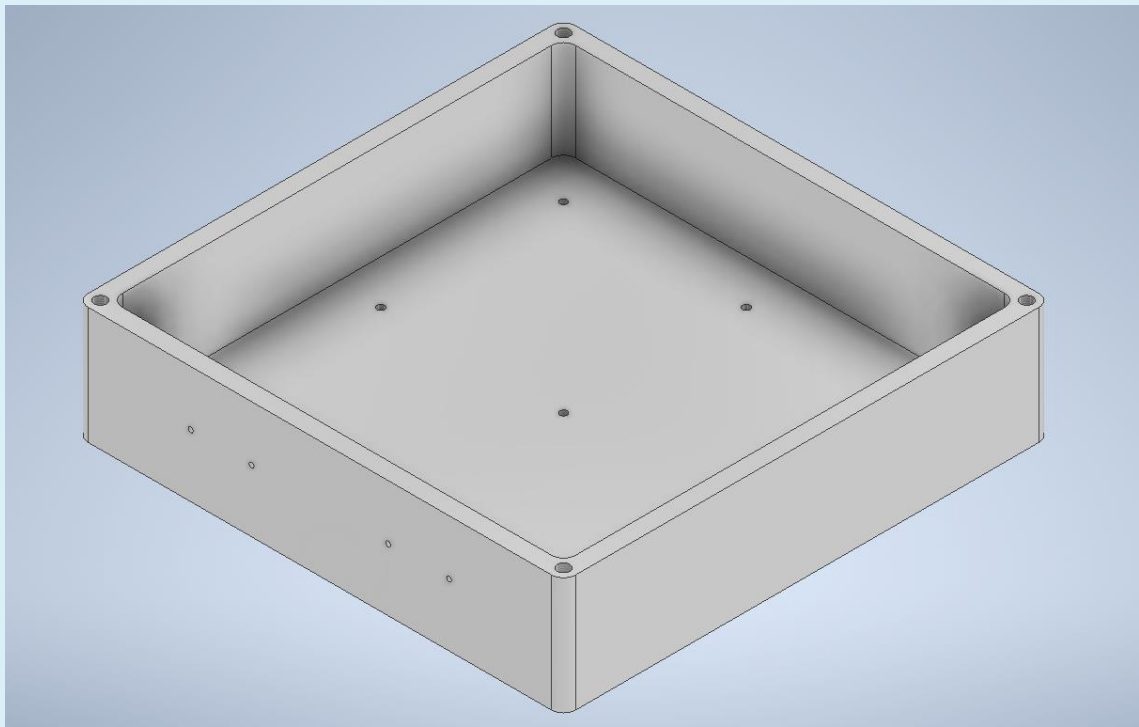
- Using Drilling Operation to construct 4 blind drill holes at the corners of the wall on the Top.
- Dimensions : $\varnothing 5$ mm , 30mm
- These holes will be useful to attach the Top to the Bottom
- Drill bit $\varnothing 5$ mm

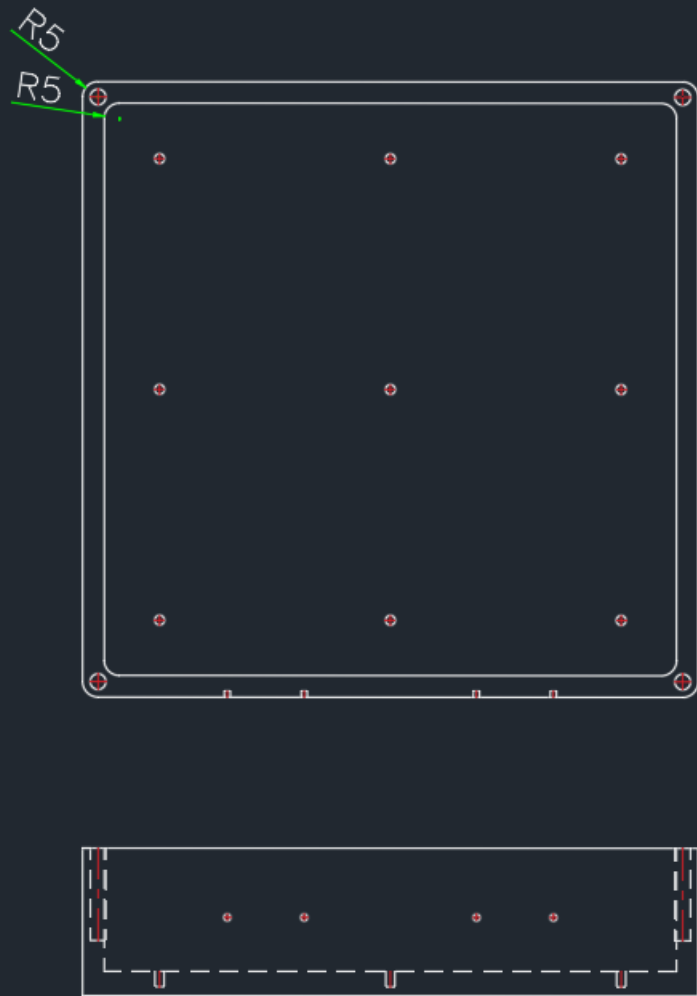




4c. Drilling

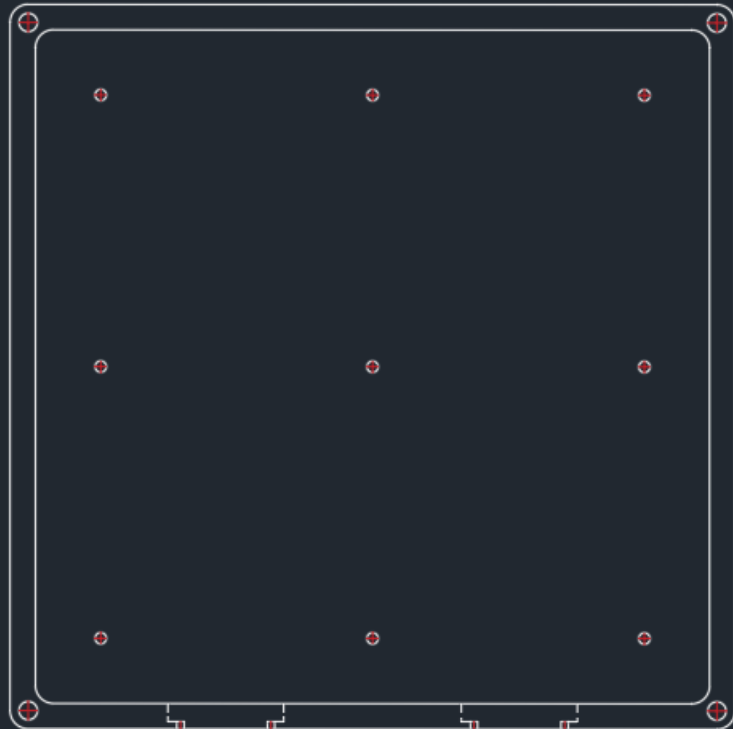
- Drilling 4 blind holes on any one of the outer of the walls. This face will be called the 'Front Face' of the box.
- They will be useful to attach the D-Pin connectors to the interior of the 'Front Wall'
- They will also help to use Wire EDM to make slot for D-Pin.
- Dimension: 4 x ($\varnothing 2$ mm , 2mm)
- Drill bit $\varnothing 2$ mm





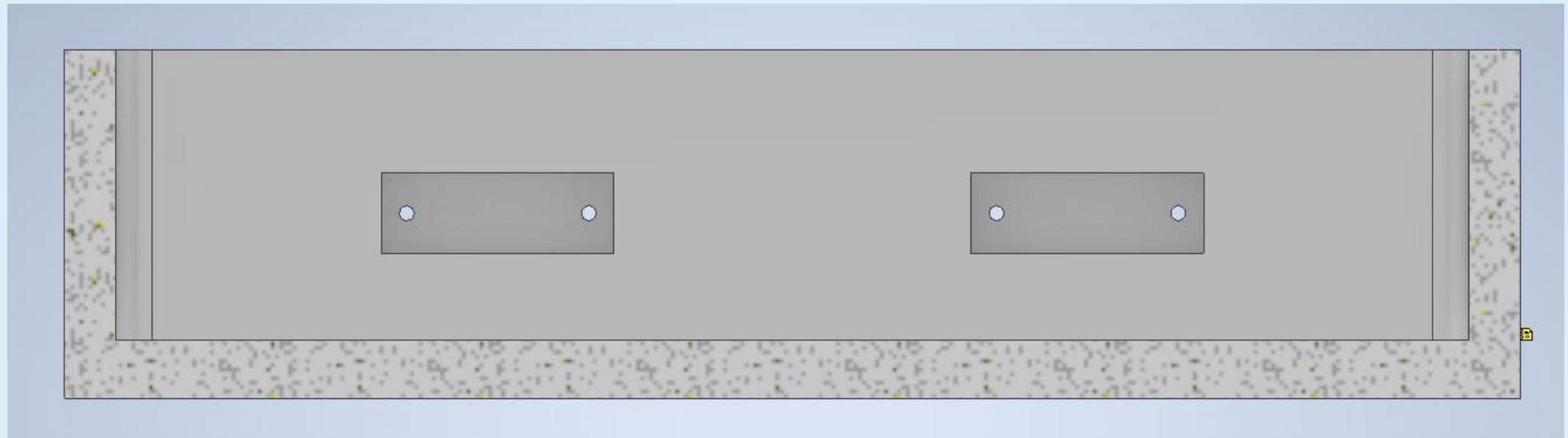
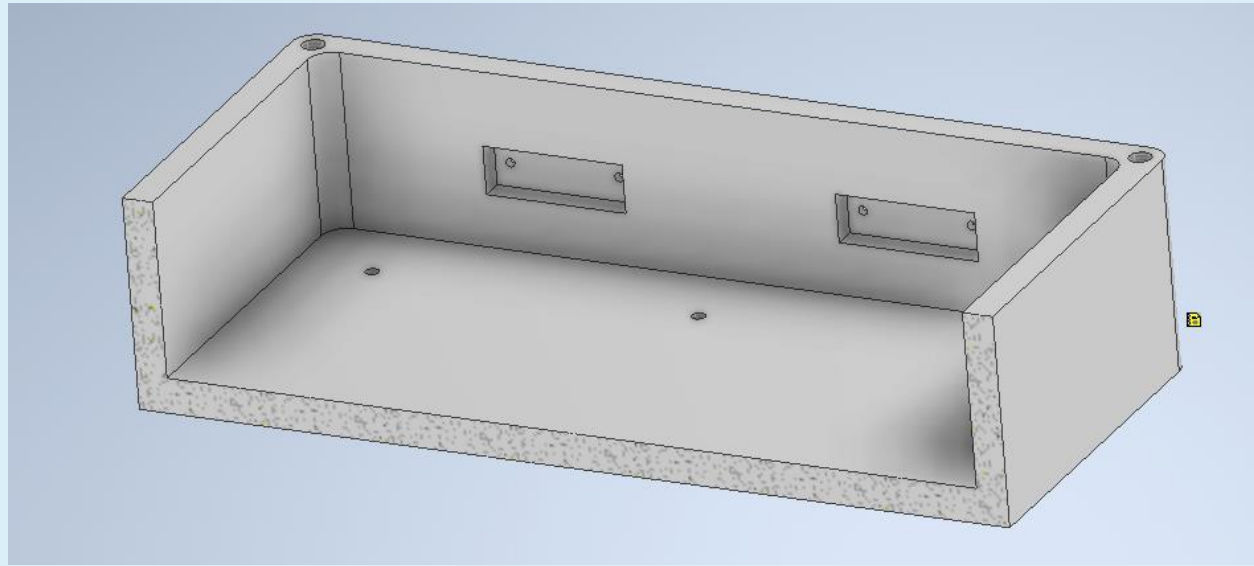
5.Fillet

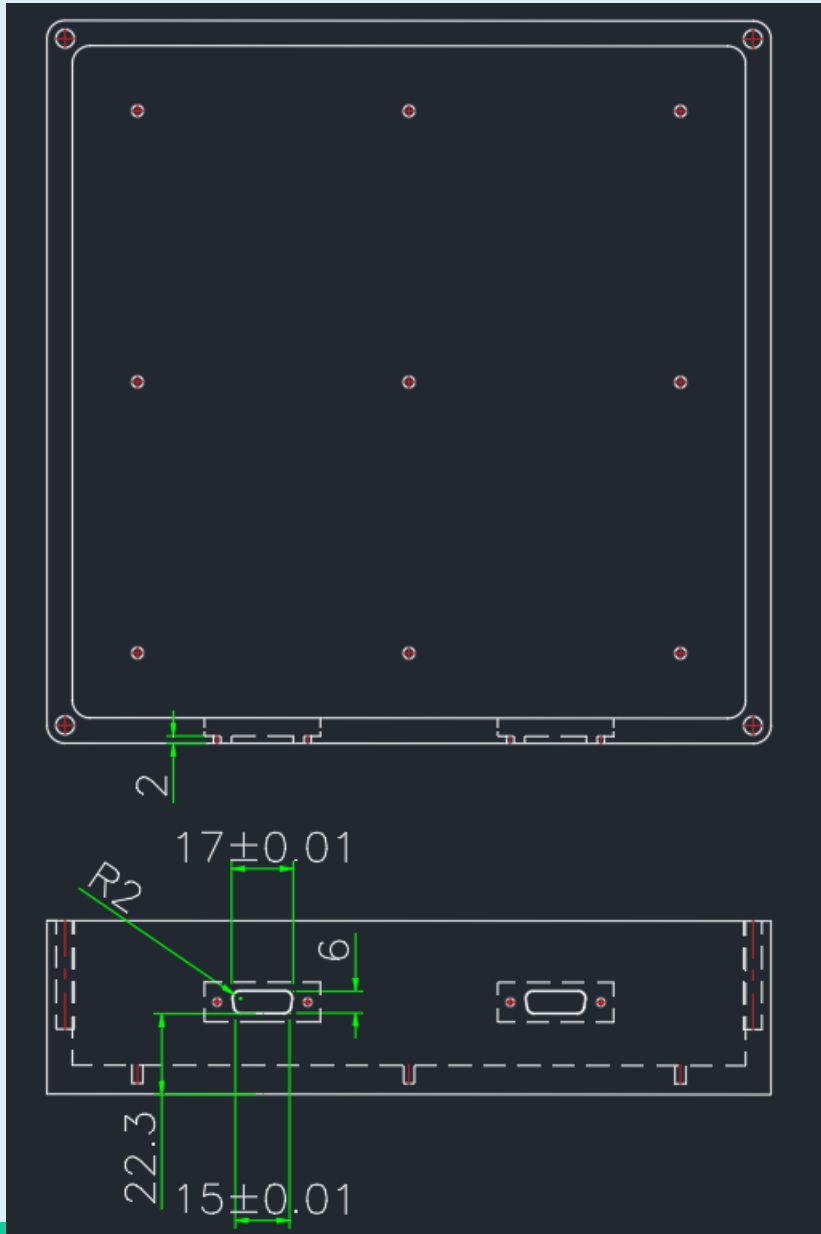
- Adding fillets on Radius 5mm on the interior and Exterior corners of the Bottom Assembly
- Fillets help in reducing stress concentration as they can distribute stress uniformly



6. Square Pocket Milling

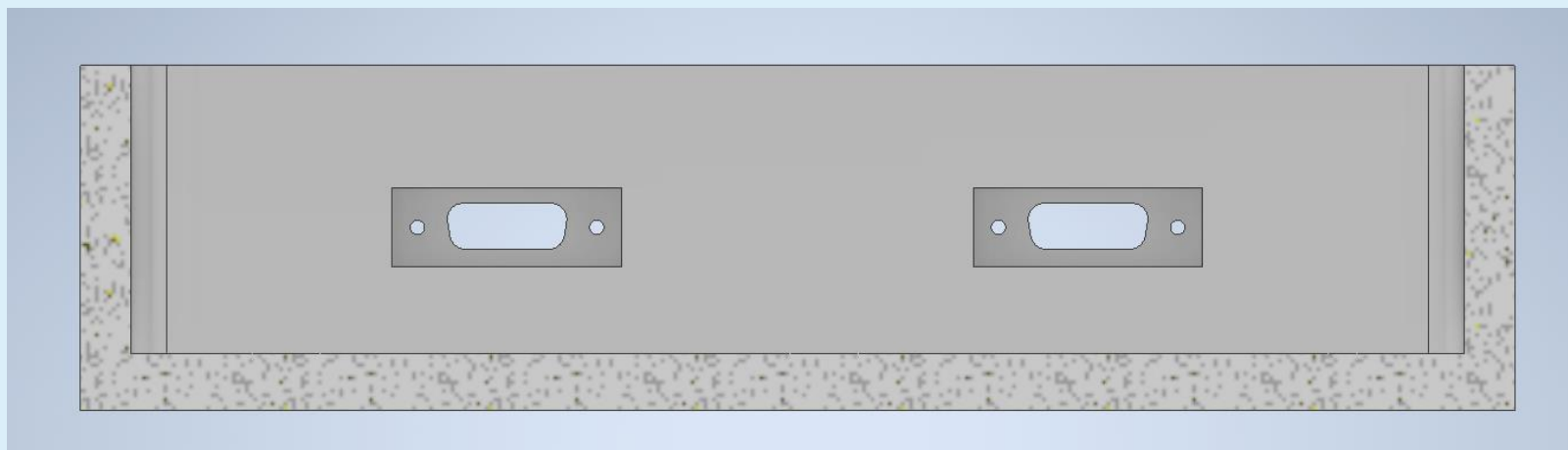
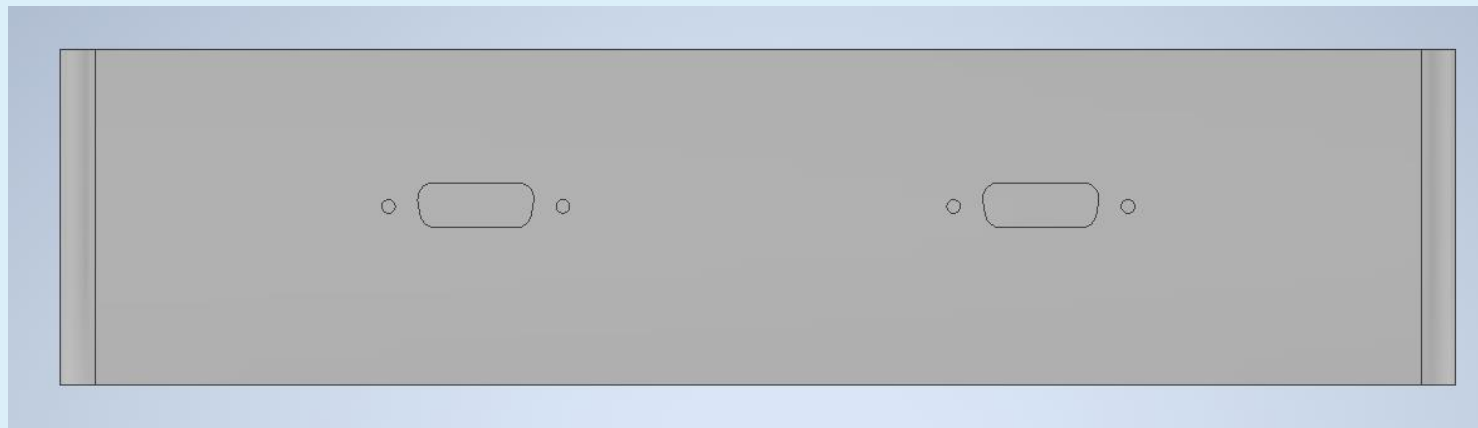
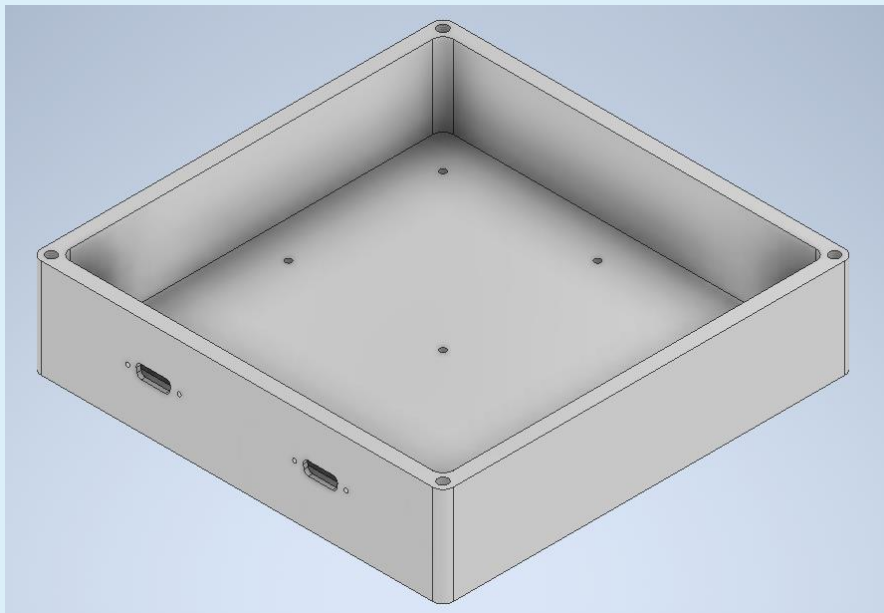
- Constructing a rectangular cavity inside the front wall to fit the D-Pins
- Dimension 32x11 mm
- Milling tool $\varnothing 5\text{mm}$

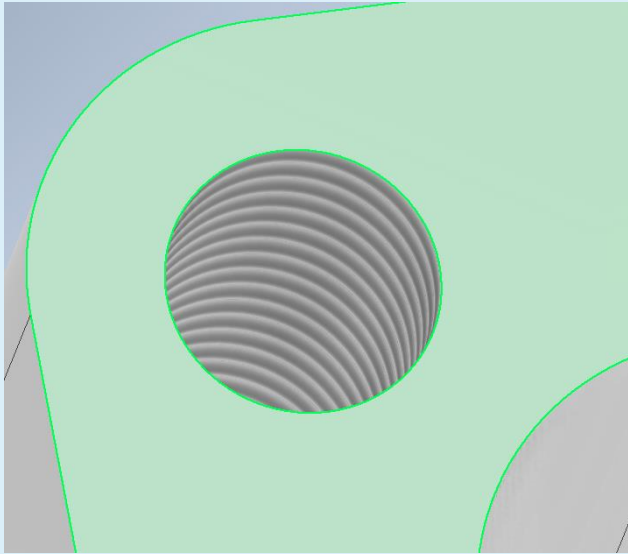




7. Wire EDM

- Slot for D pin to be exposed out.
- Using the Drill holes

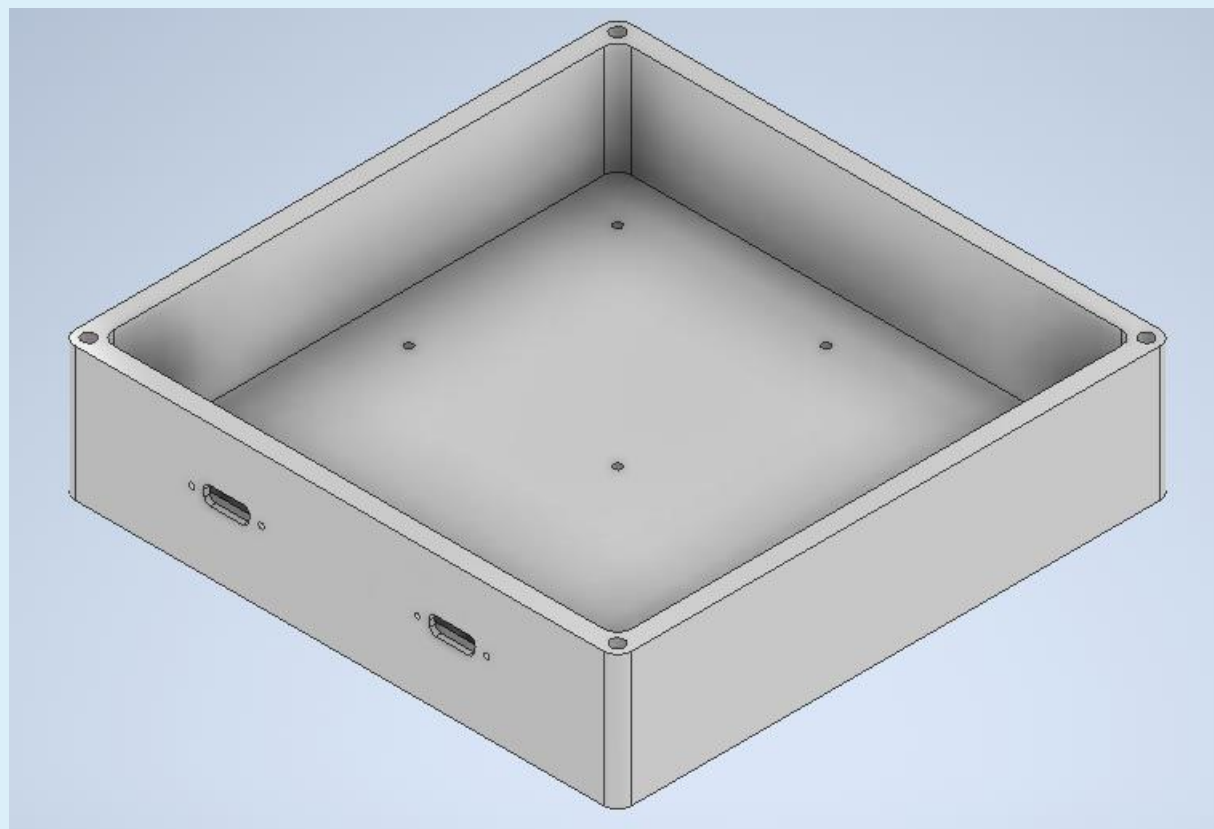
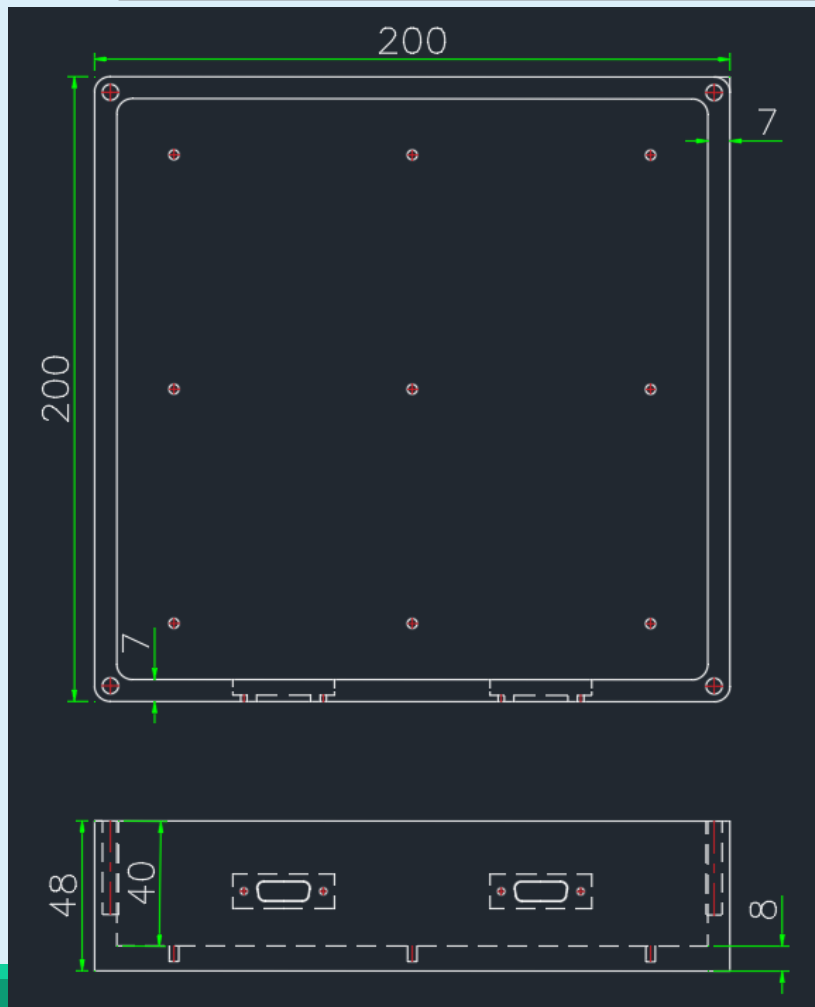


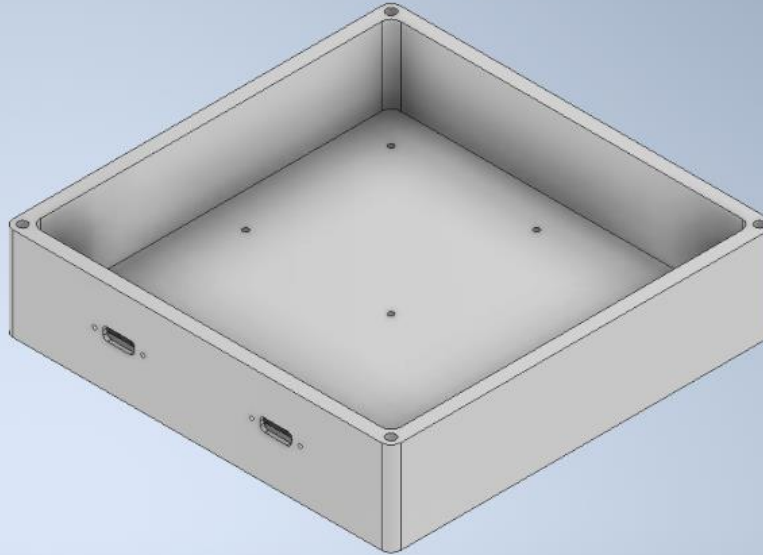
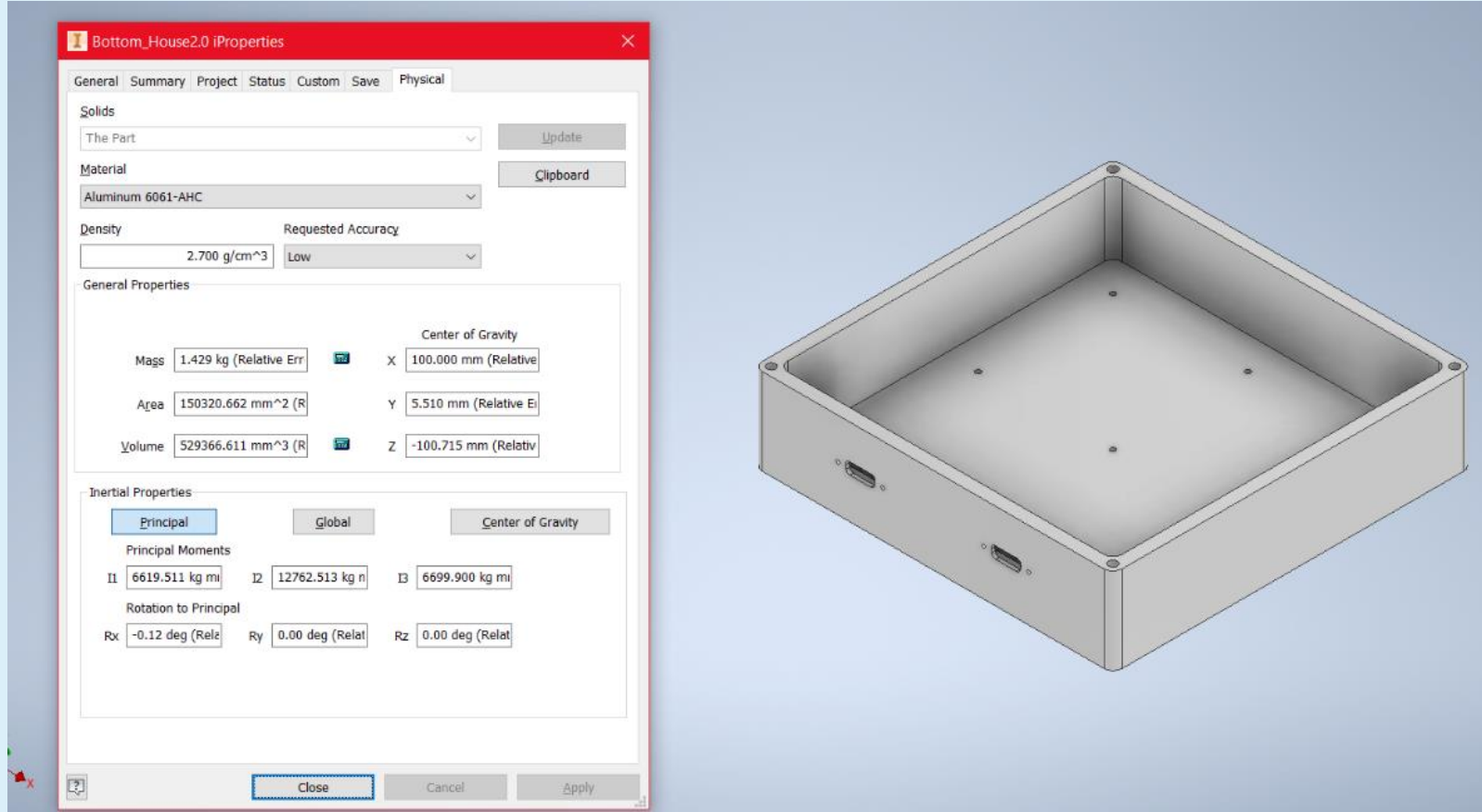


8. Tapping

- To add internal threads to the drilled holes on the base and on the Corners of the Work piece

Final Bottom



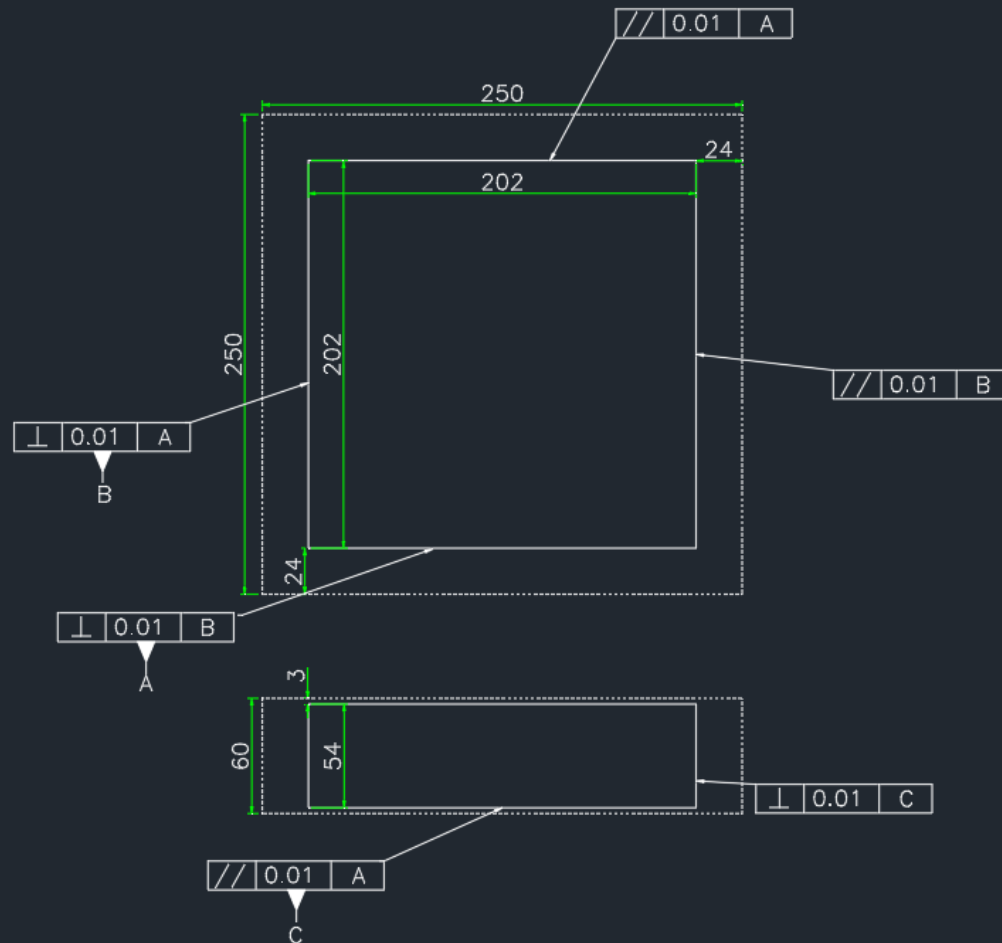


Weight of Bottom

Mass = 1.429kg

Fabrication of Top:

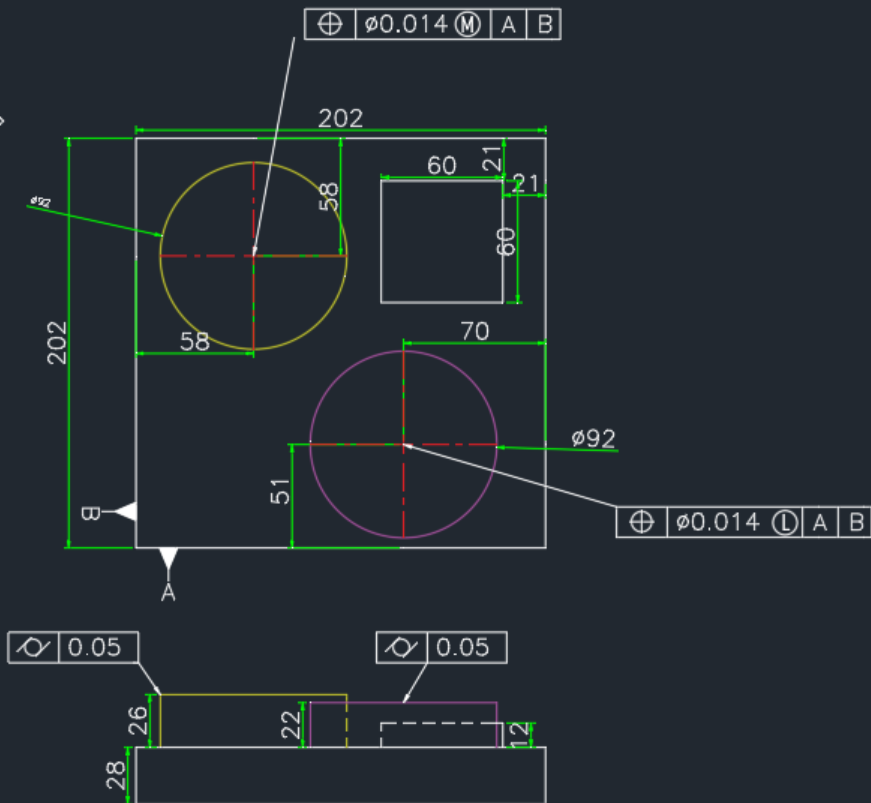
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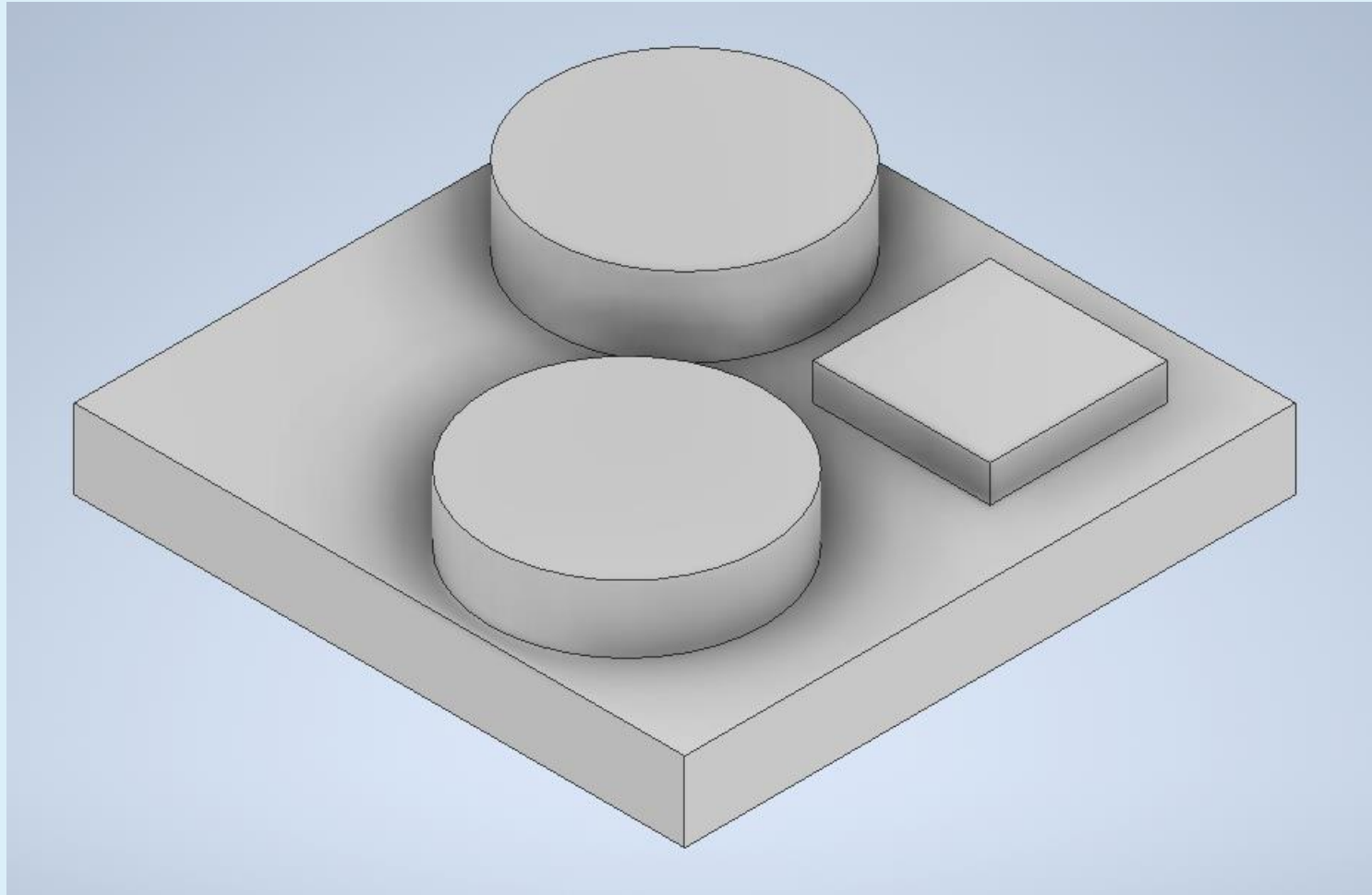
1. Face Milling

- End milling to reduce the dimension of the blank from 250x250x60 mm to 202x202x54 mm
- Milling tool of dim $\varnothing 50\text{mm}$
- Extra 2mm for grinding

2. ♦

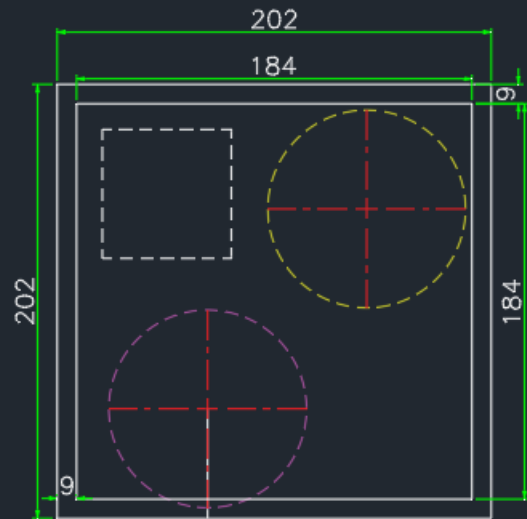


- End milling on Top face to obtain Required profile.
- Milling tool of dim $\varnothing 30\text{mm}$ and $\varnothing 10\text{mm}$



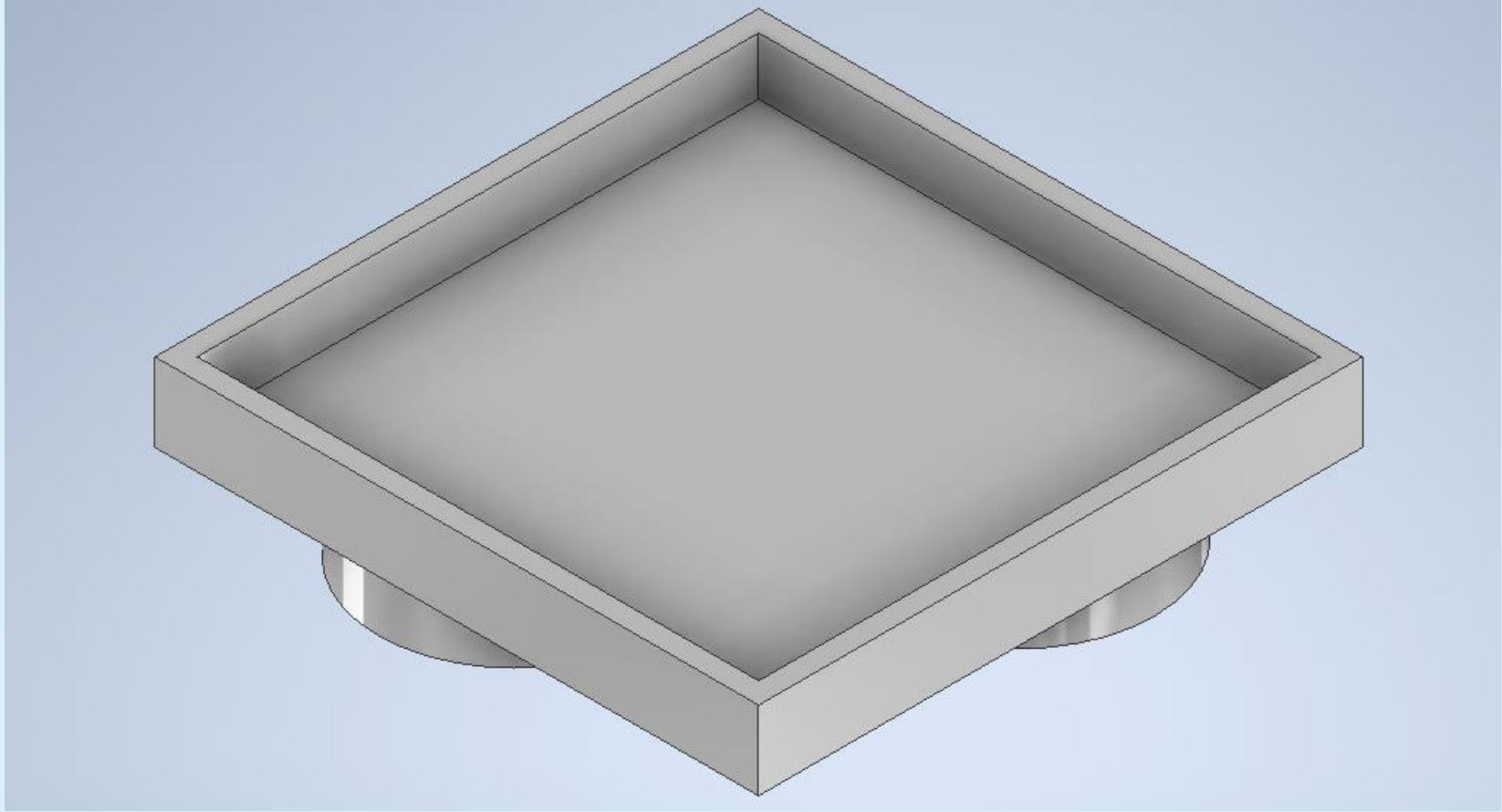
3.

BOTTOM

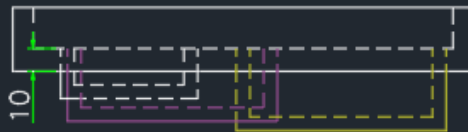
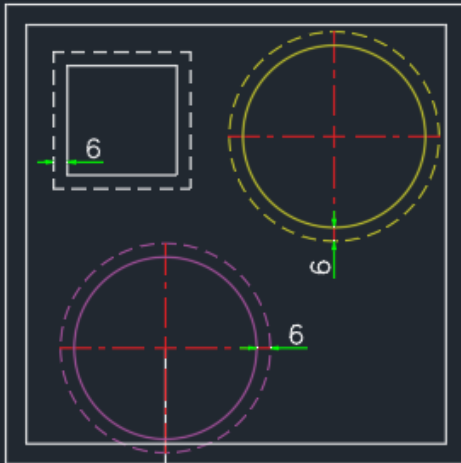


2b. End Milling

- End milling on the bottom surface to create a cavity of dimension 184x184x18mm
- Mill tool $\varnothing 30$ -50mm

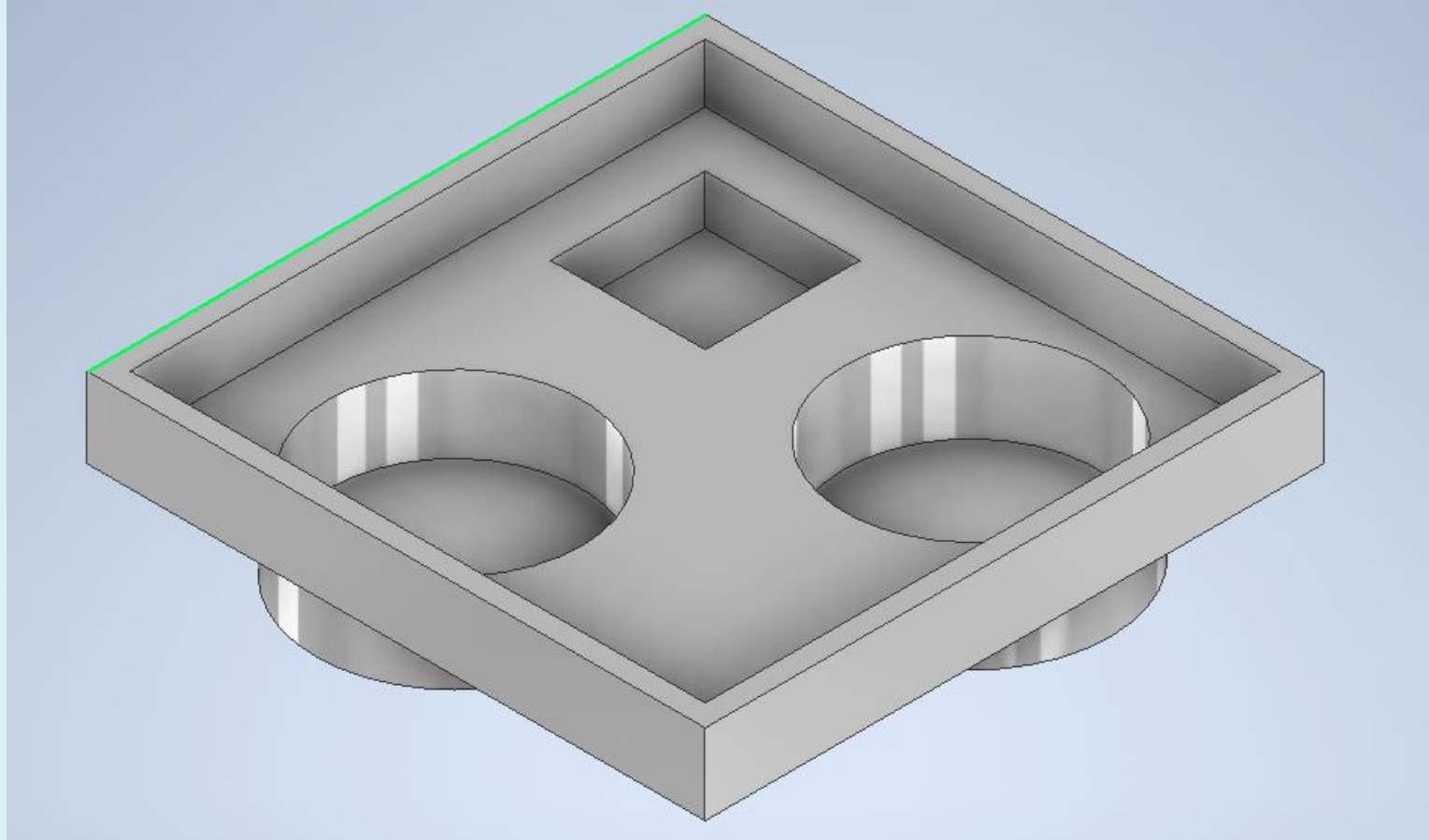


BOTTOM

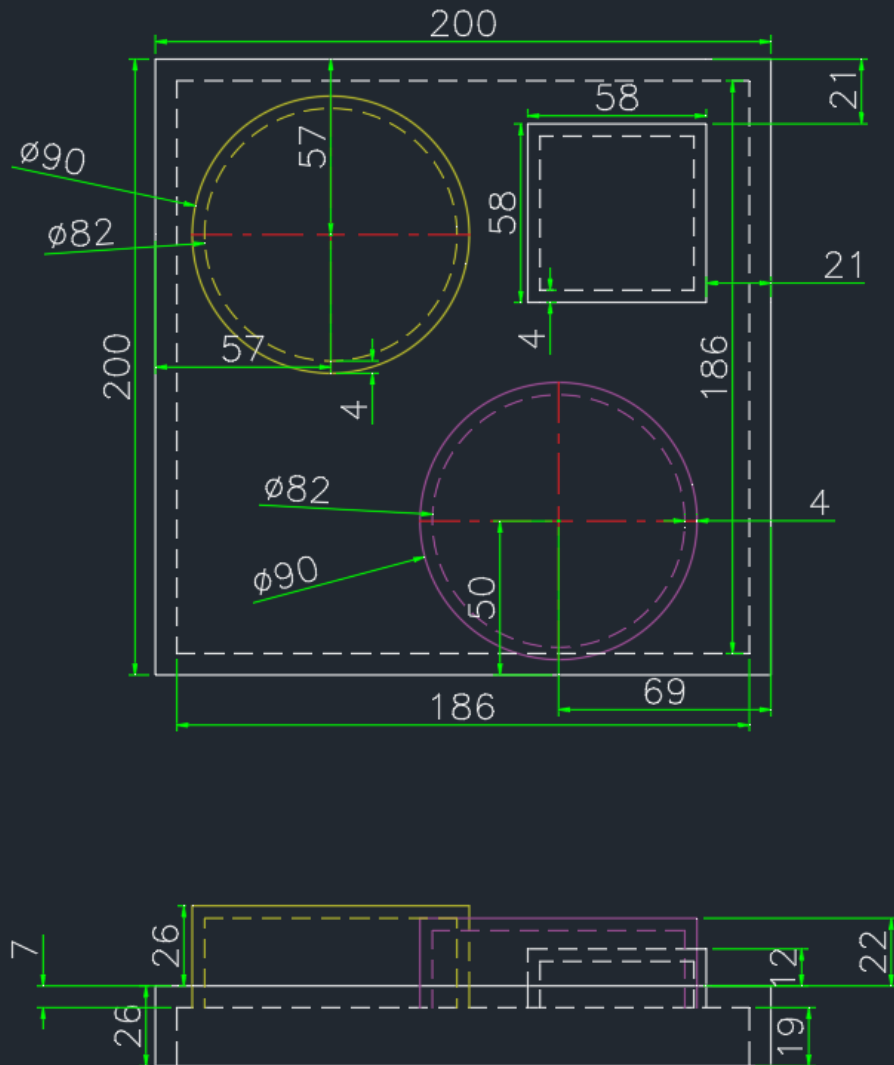


2c. End milling

- using end mill to create holes for the Sensor 1 , 2 and 3.
- Milling tool , $\varnothing 30\text{mm}$



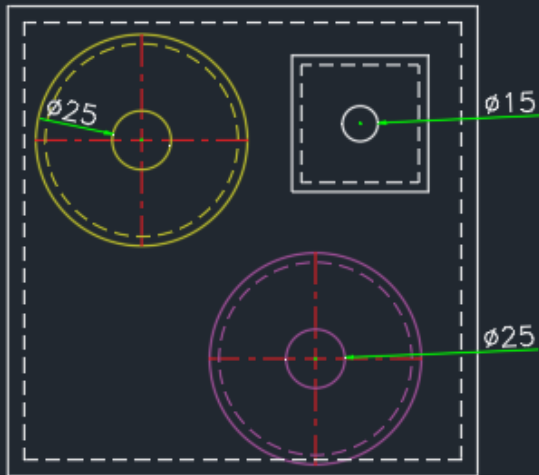
5.



3.Grinding

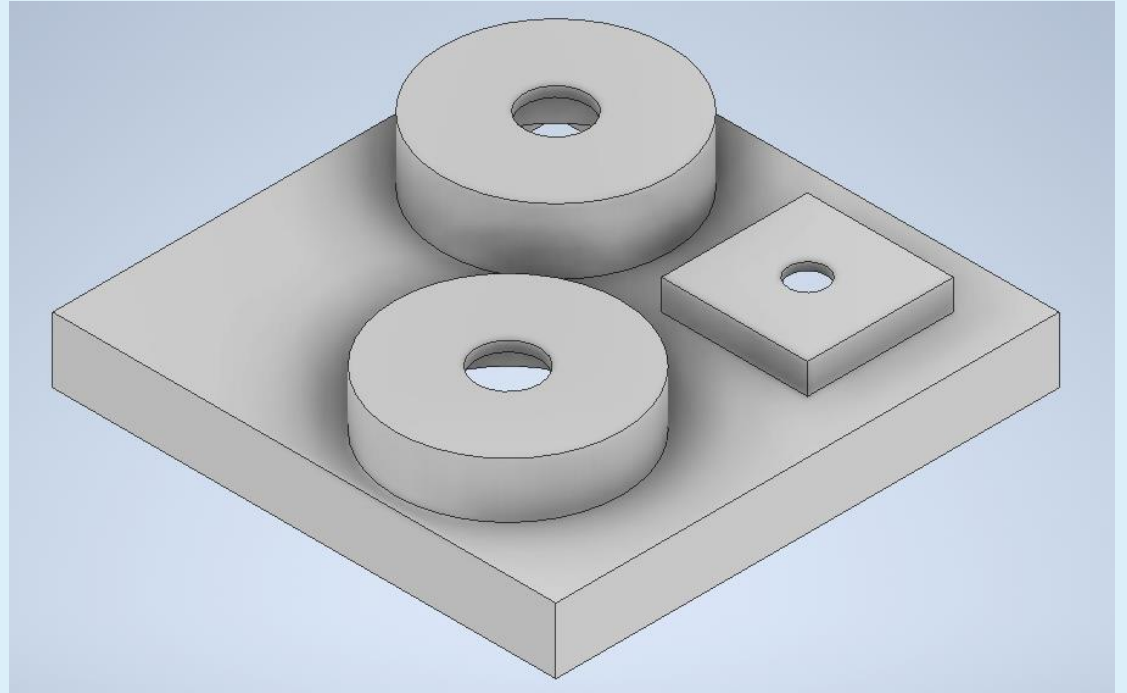
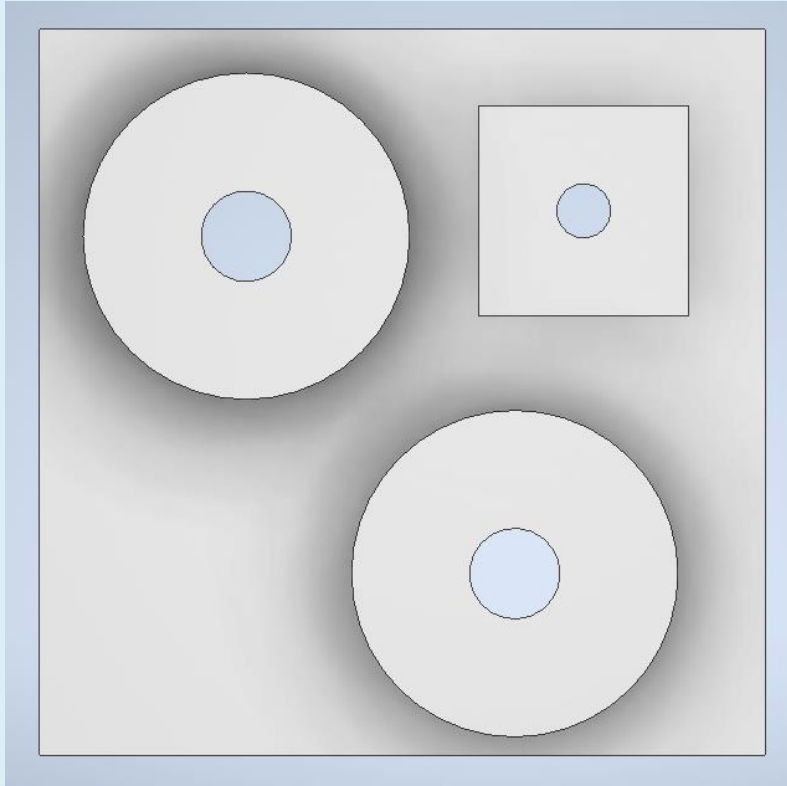
- Grinding the extra 1mm from all the faces for better surface finish
- Grinding wheel , Open structure with Soft wheel

6.

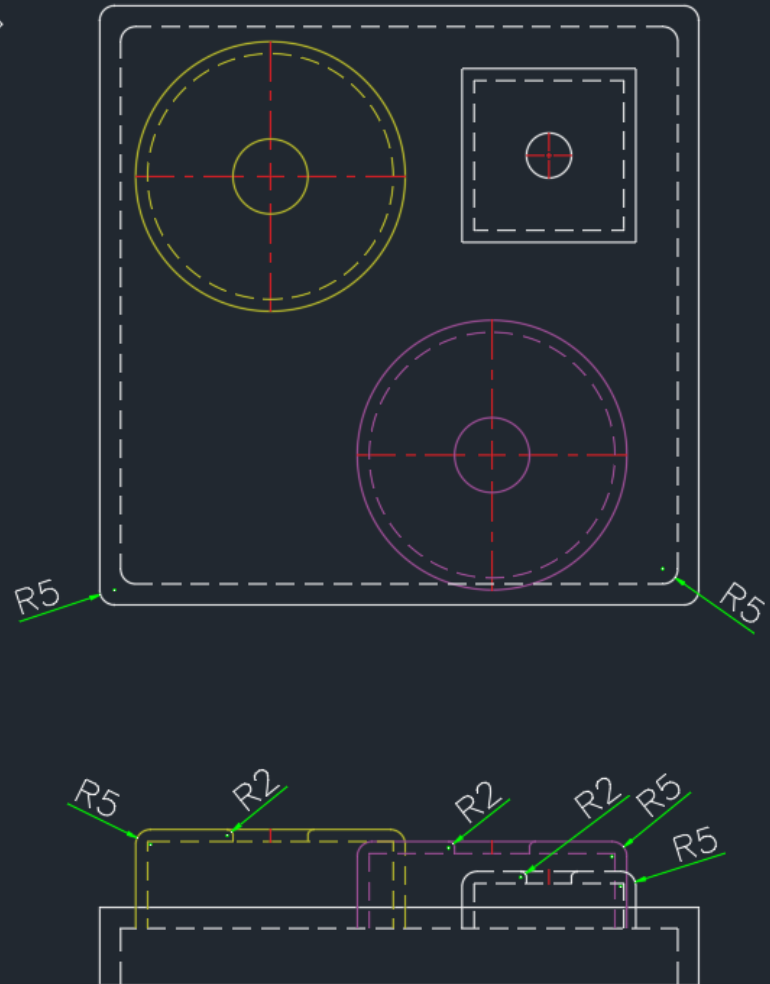


4.Trespanning

- To create opening on the top face of the respective cylindrical holes of the sensors
- Tool with Ø25 and Ø15mm

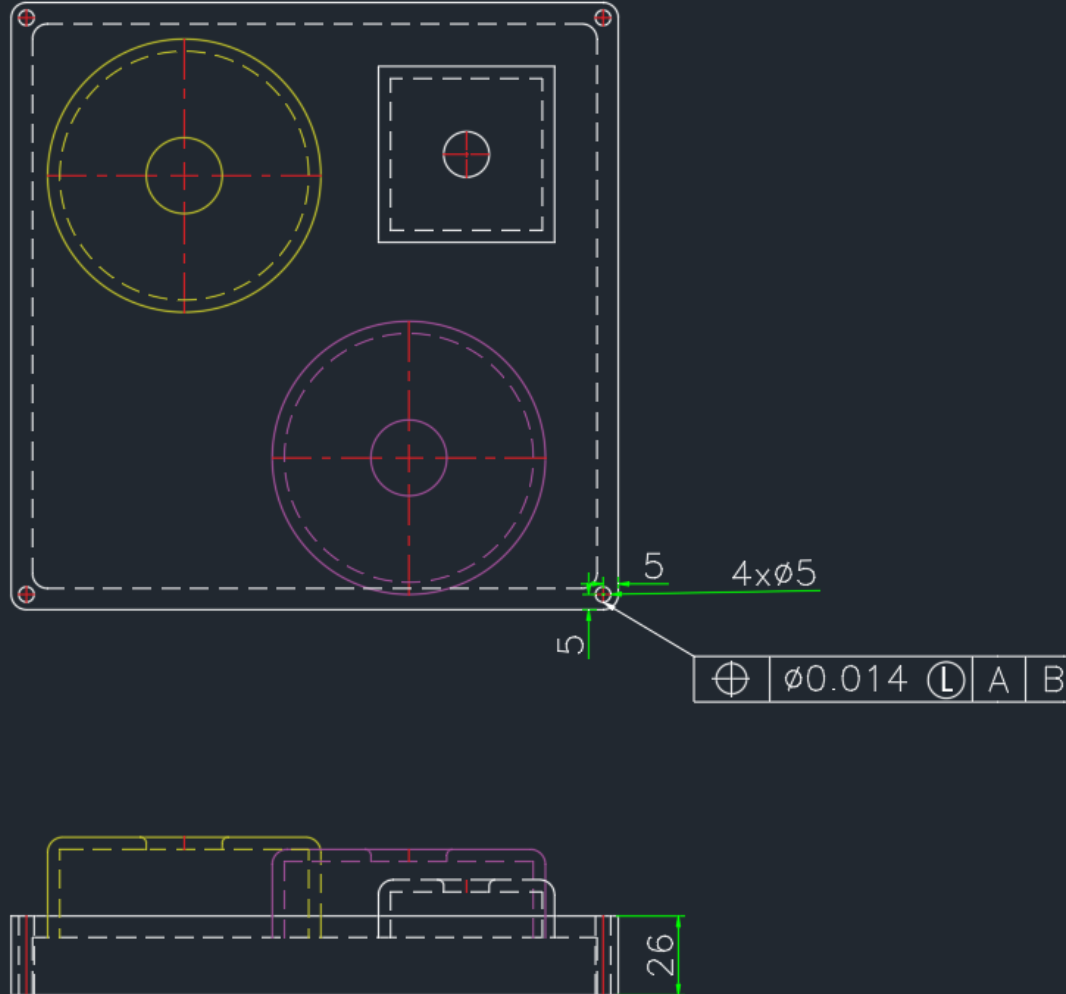


7.



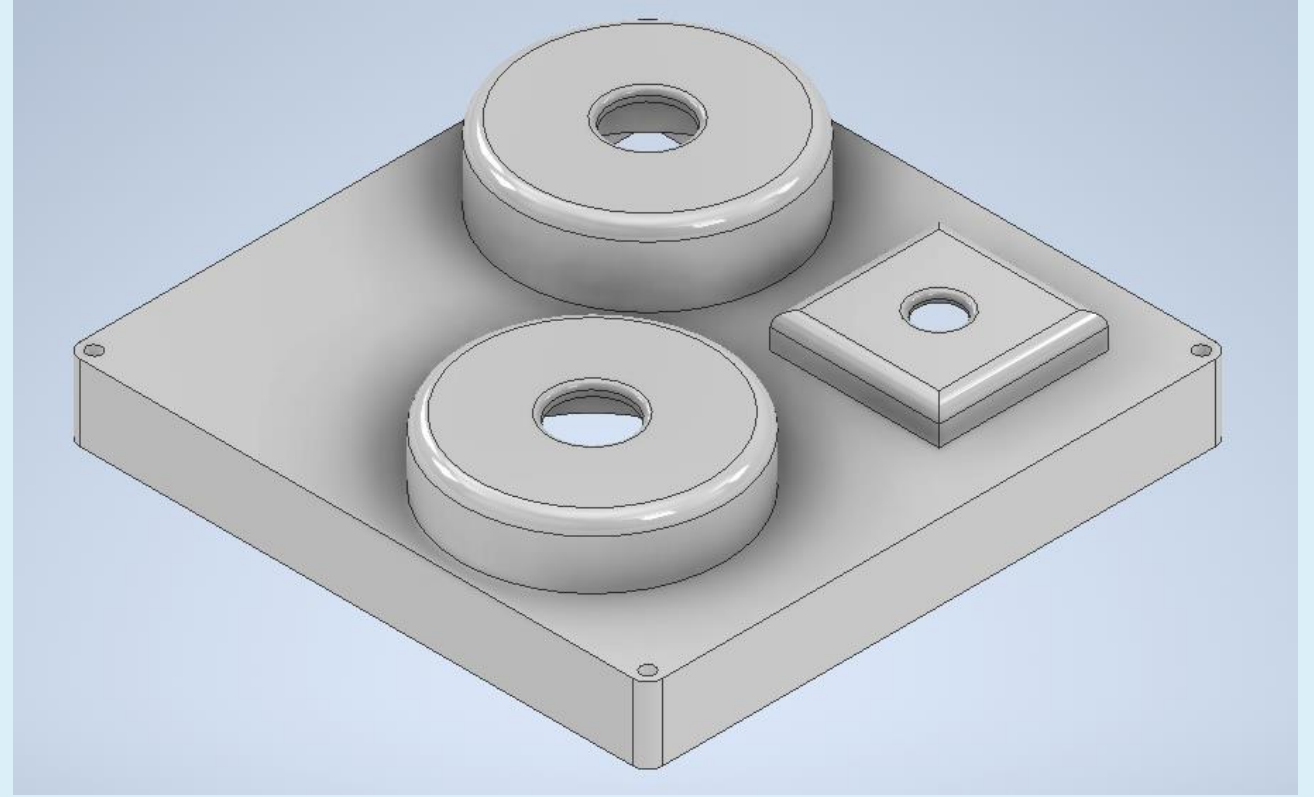
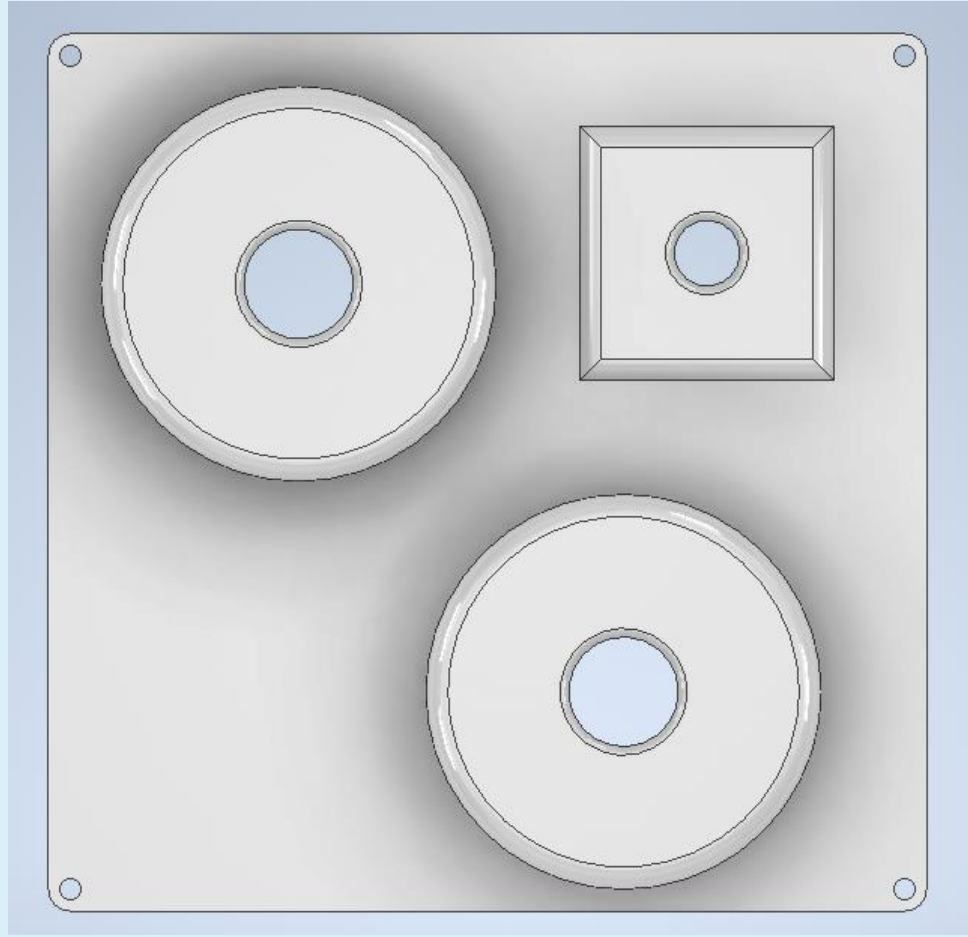
5. Fillet

- Adding 5mm fillet to the interior and exterior corners of the Work piece and to the edges of the Cylinders
- 2mm Fillet on the holes of the Cylinder

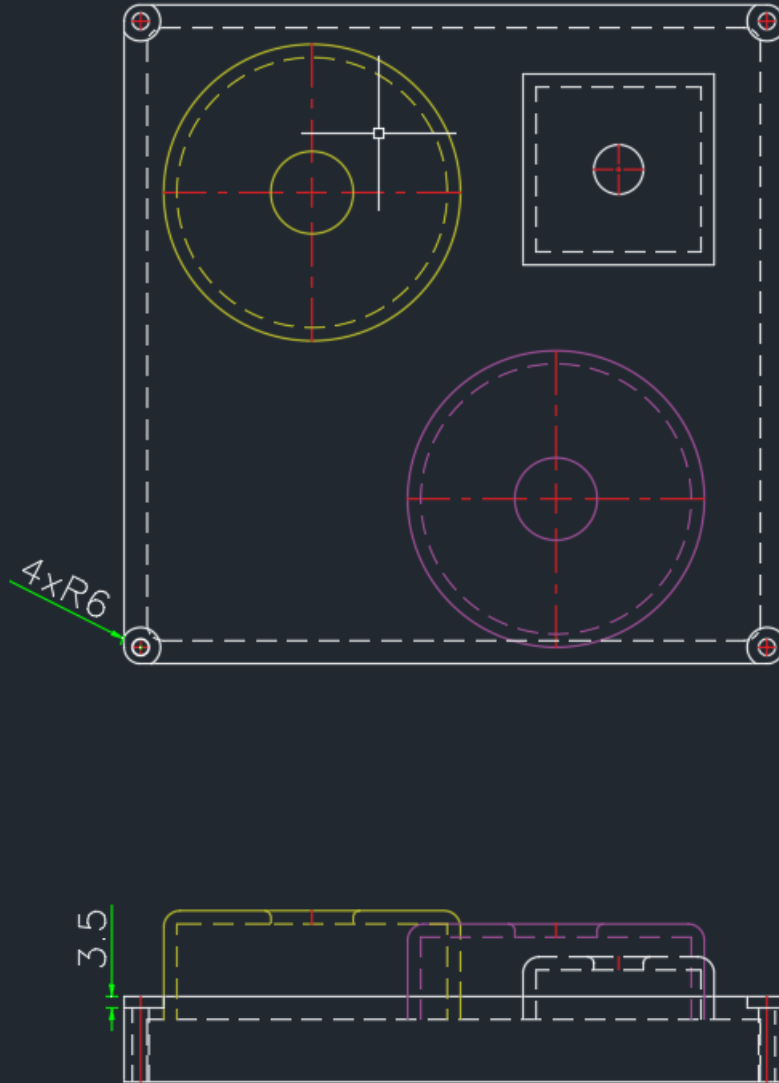


6.Drilling

- Drilling holes at the corner of the Work piece with the help of a Drilling Machine
- Dimensions : 4 x (Ø5mm , 26mm)
- Drill bit Ø5mm

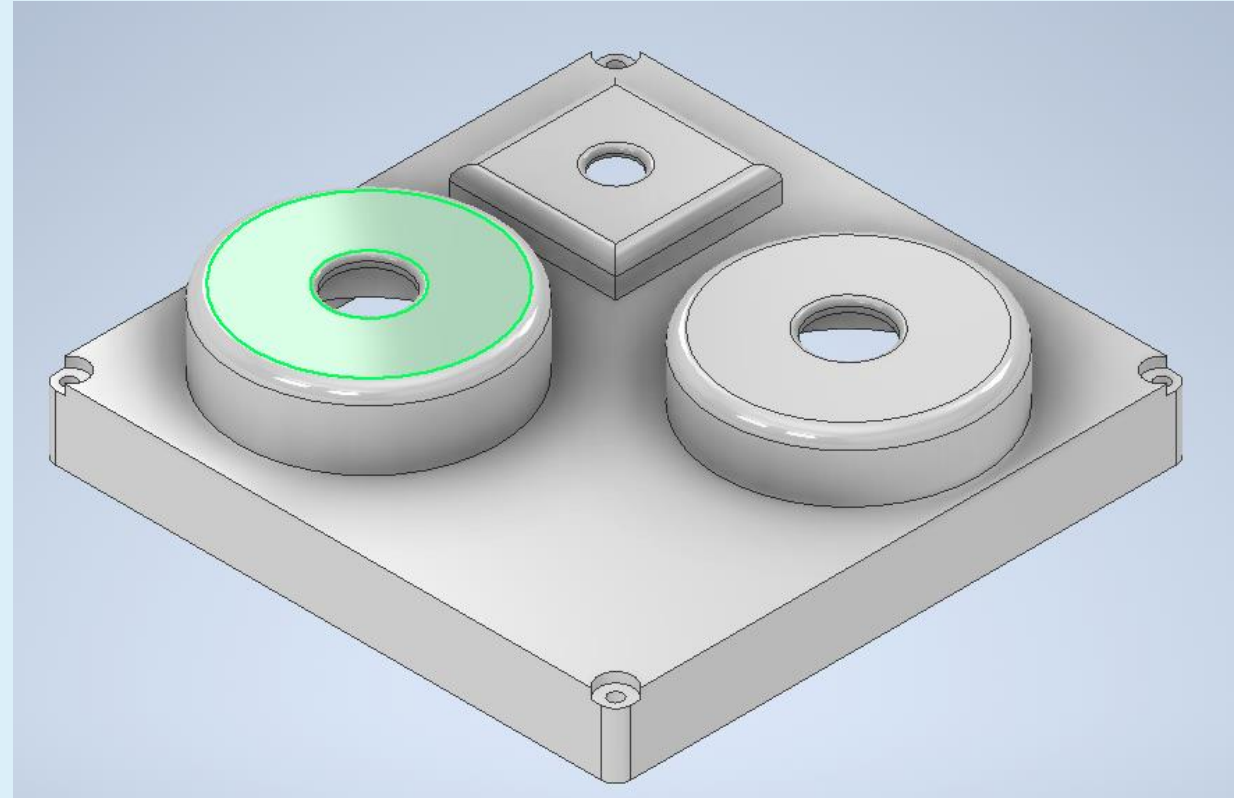
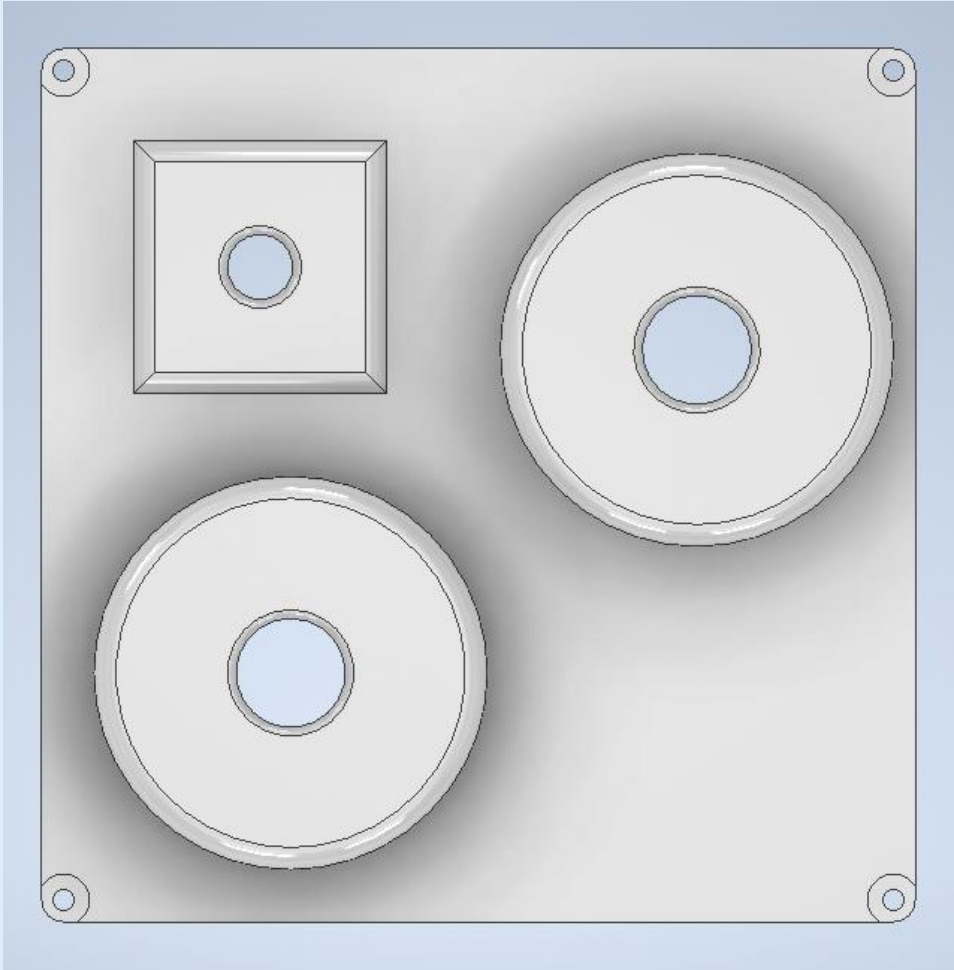


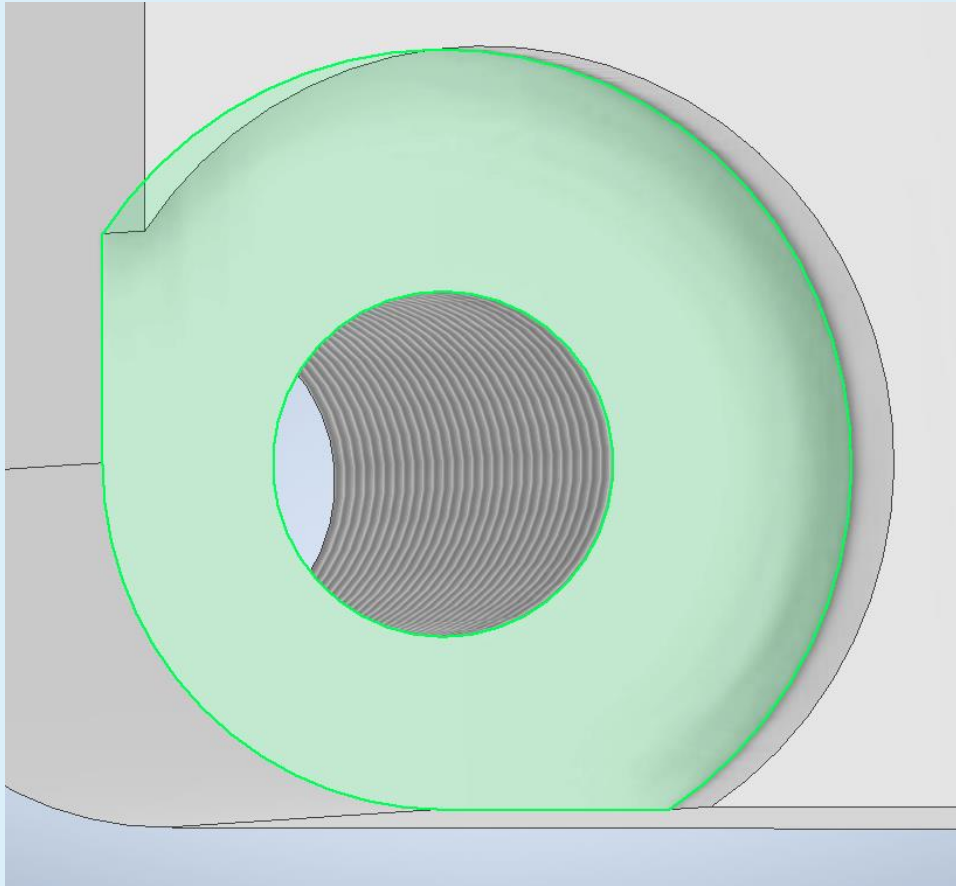
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7. Counter-boring

- Counter-Boring 3.5mm on the drilled holes
- Counterbore with $\varnothing 12\text{mm}$

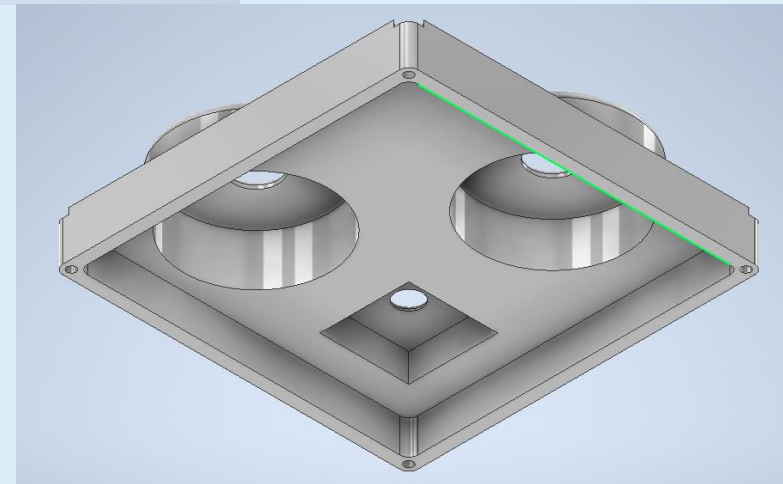
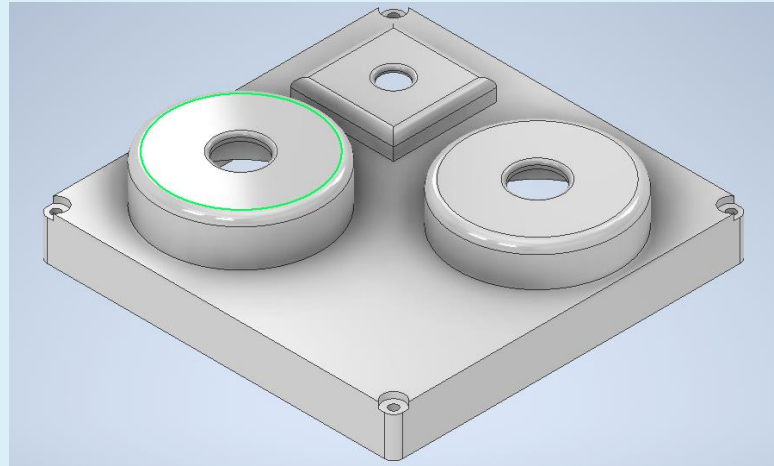
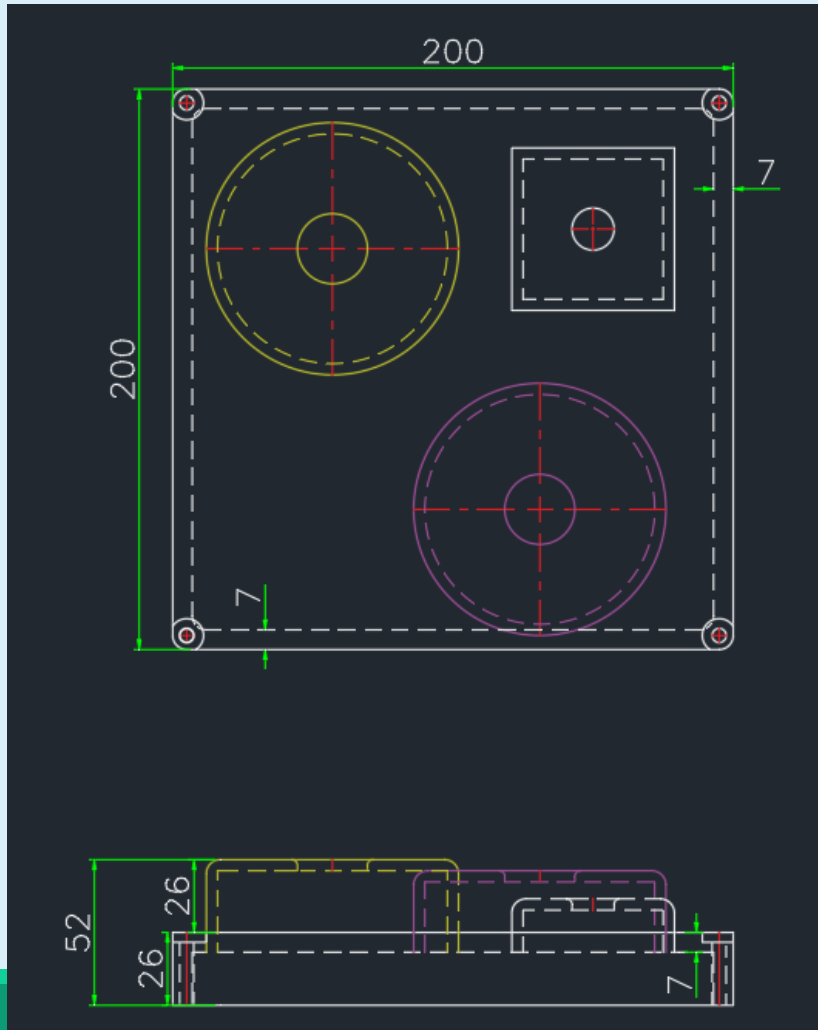




8.Tapping

- To add Internal threads to the Drilled Holes

Final Top



New_Top iProperties

General Summary Project Status Custom Save Physical

Solids
The Part Update

Material
Aluminum 6061-AHC Clipboard

Density 2.700 g/cm³ Requested Accuracy Low

General Properties

Center of Gravity

Mass 1.056 kg (Relative Err) X 99.210 mm (Relative I

Area 145859.702 mm² (R) Y 23.944 mm (Relative I

Volume 391120.144 mm³ (R) Z -100.217 mm (Relativ

Inertial Properties

Principal Global Center of Gravity

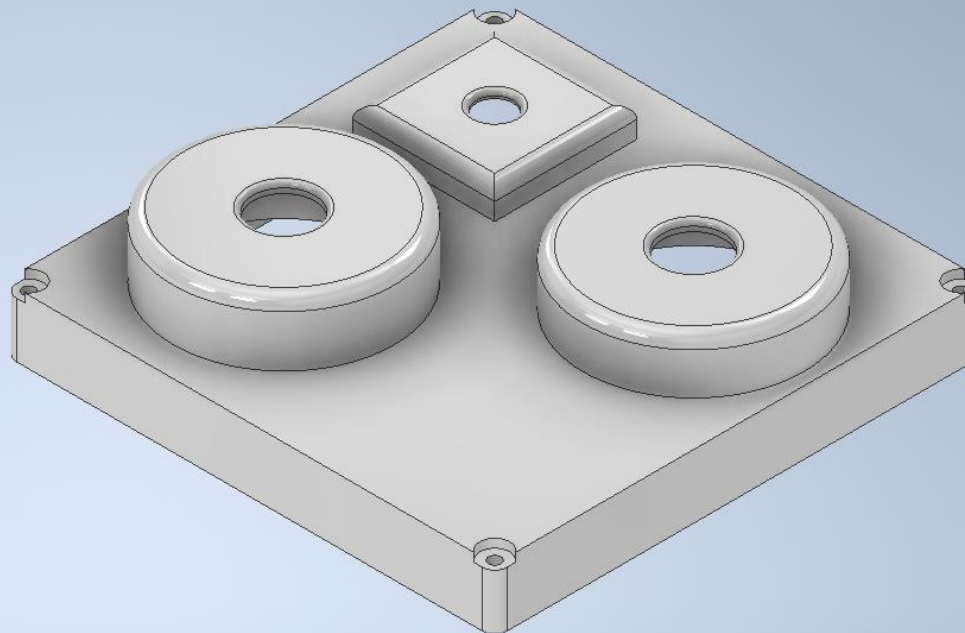
Principal Moments

I1 4542.606 kg m² I2 8615.281 kg m² I3 4398.171 kg m²

Rotation to Principal

Rx -0.68 deg (Relz) Ry -41.20 deg (Re Rz 0.38 deg (Relat

Close Cancel Apply

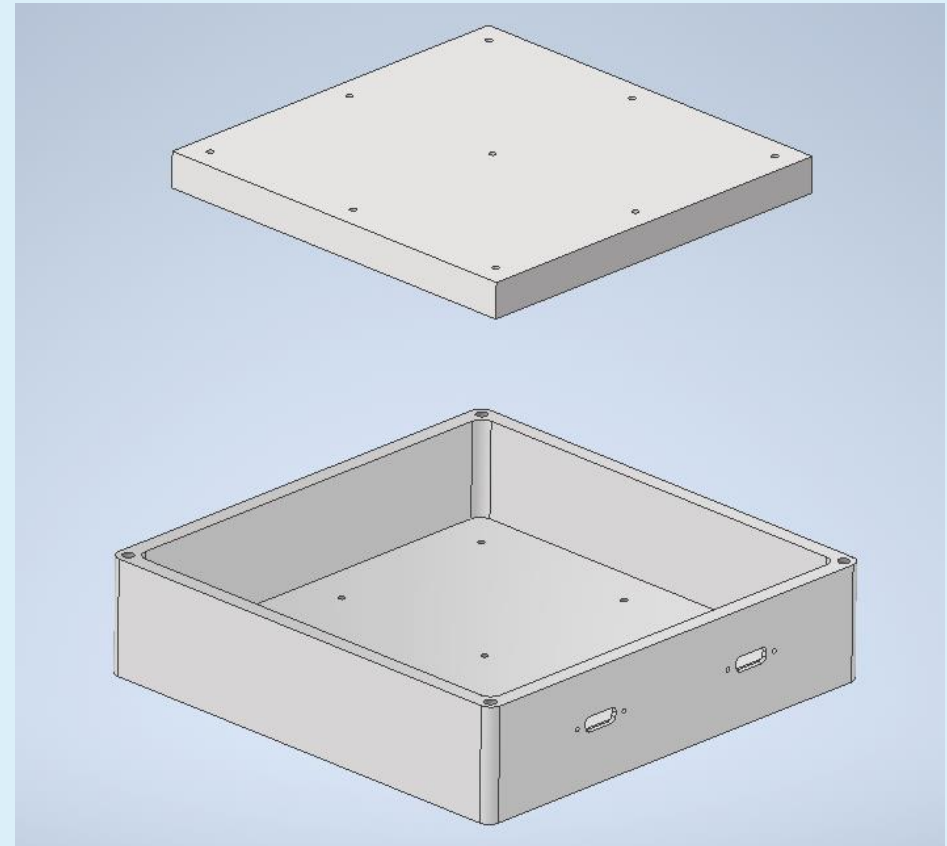


Weight of Top

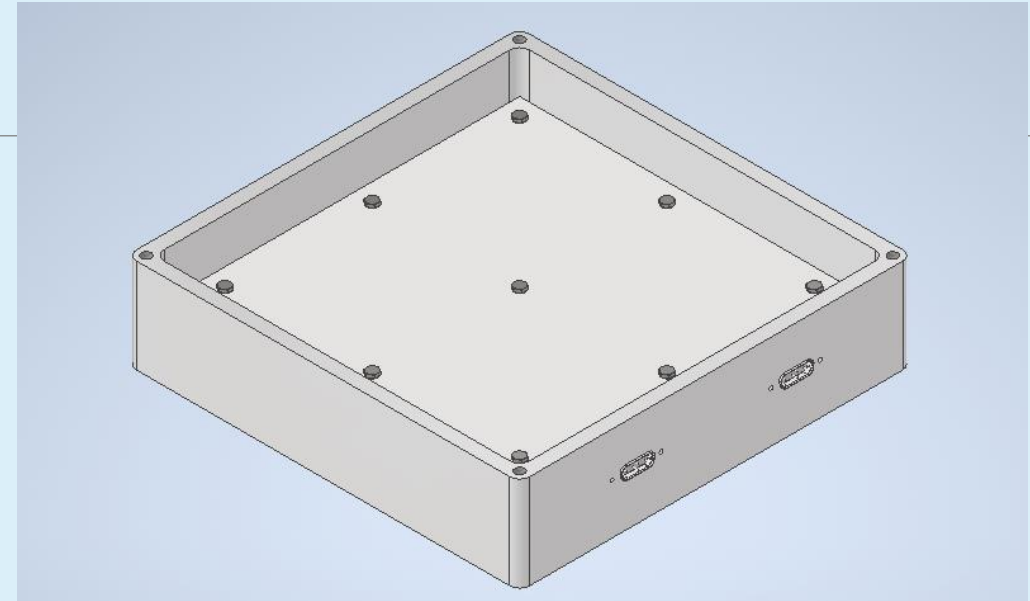
Mass = 1.056 kg

Assembly:

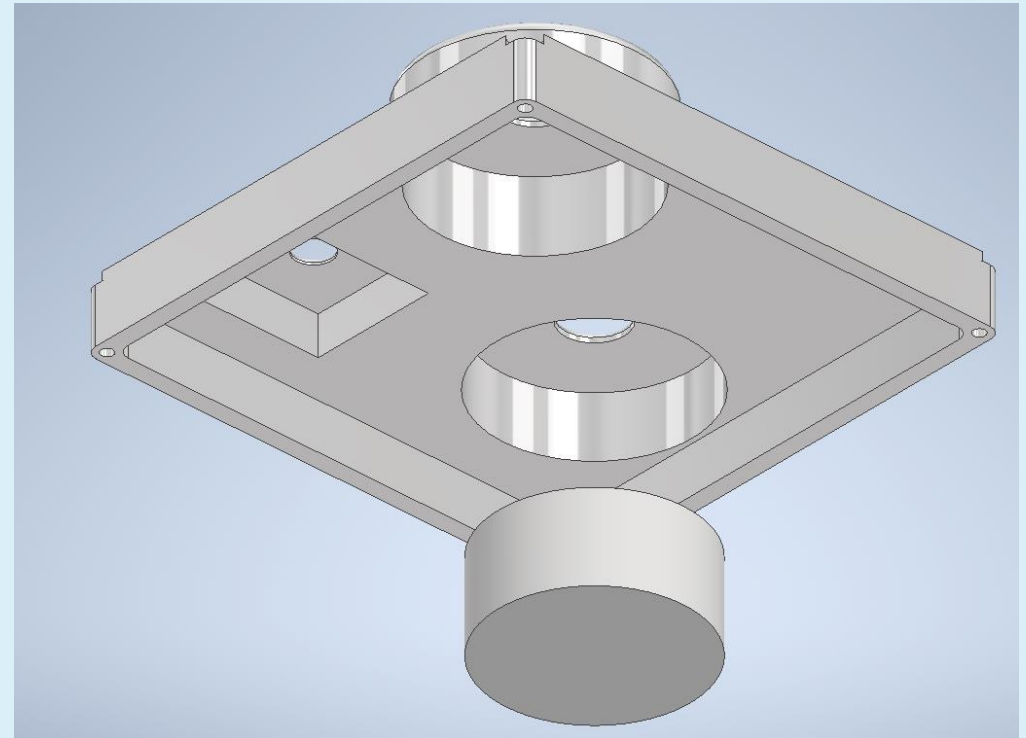
1. Insertion of Circuit Board(Sensor 4 in Documents) inside the Bottom Housing.



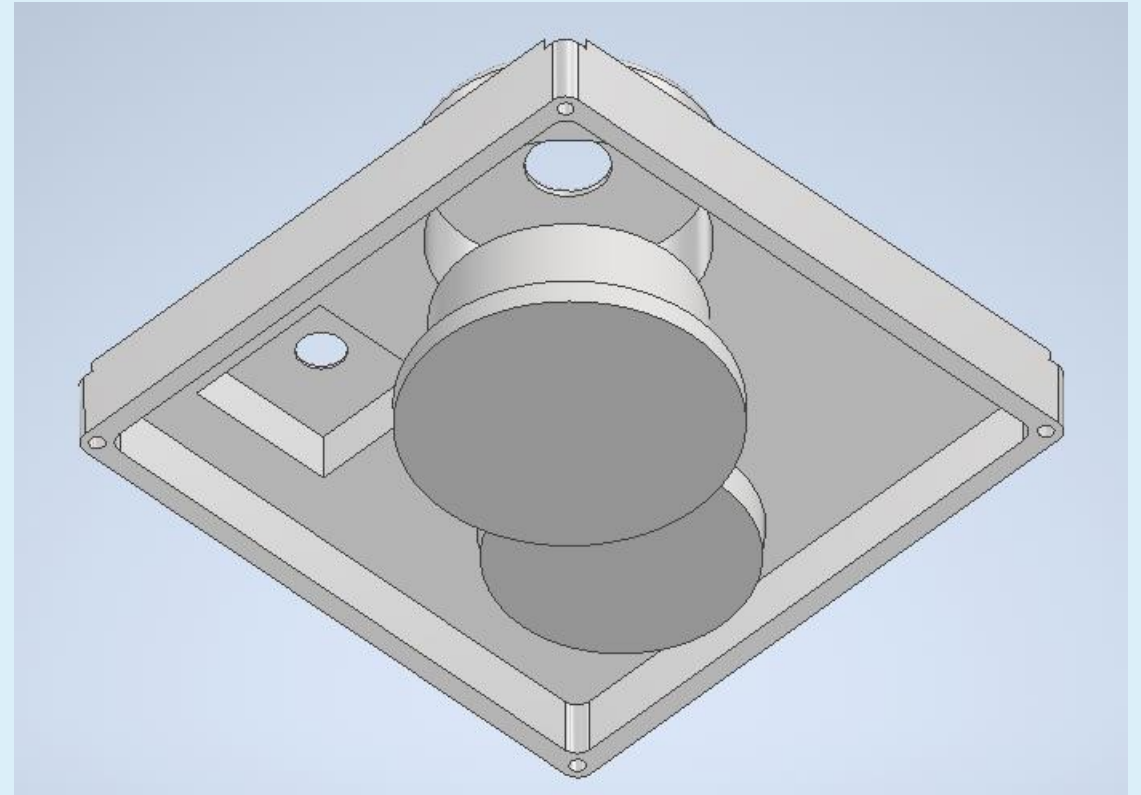
2. Attaching the Circuit Board 10mm above the Base with the help of M3x30mm screws. The D-Pins automatically fit in the slots and are Exposed out.



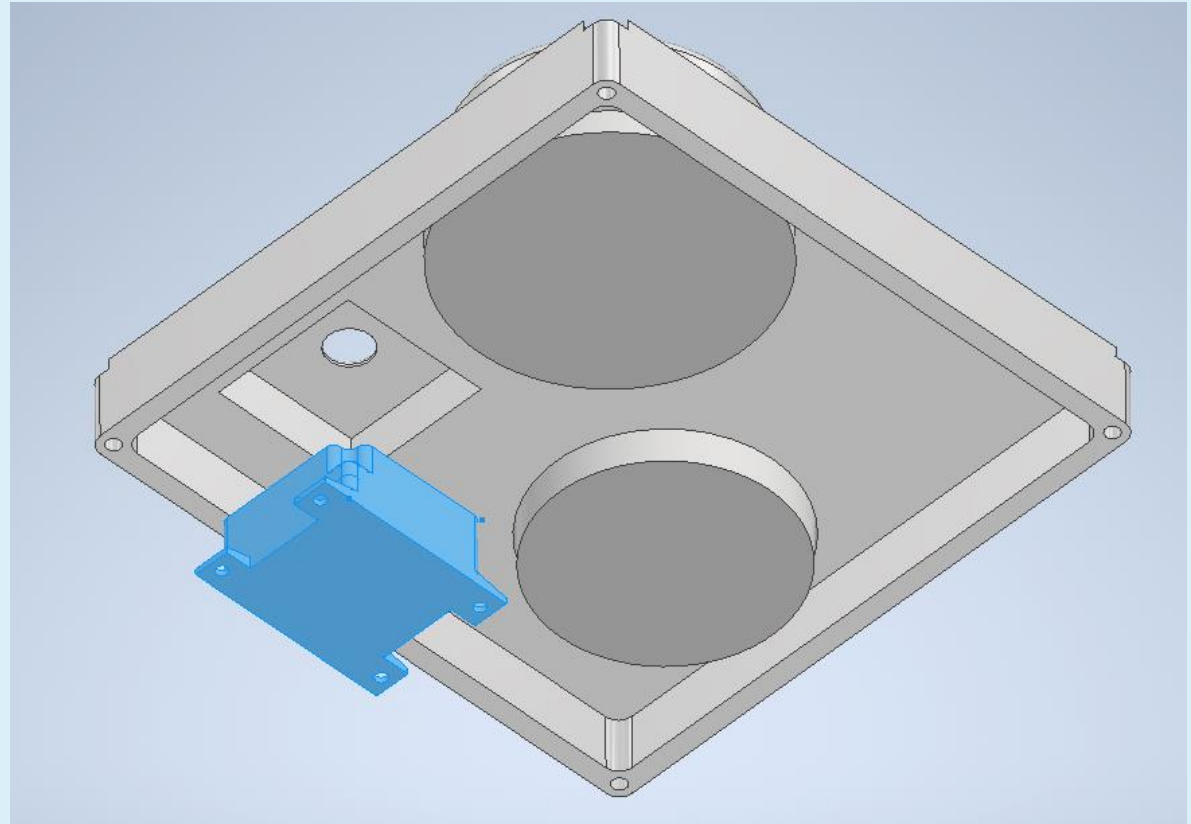
3. Inserting Sensor 1 in the Top Housing. The Sensor will be fixed with the help of L joints



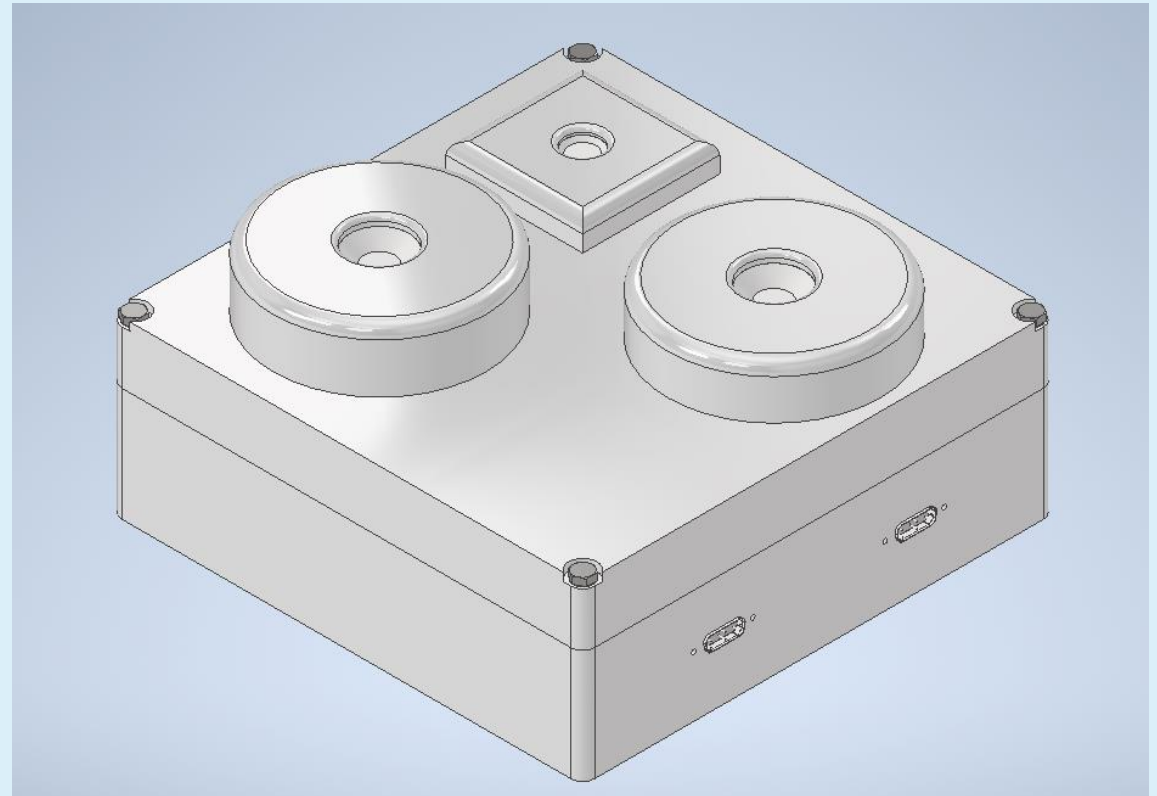
4. Inserting Sensor 2 inside the Top Housing and attaching it with L Joints.



5. Inserting Sensor 3 into its Slot in Top Housing and screwing it to the top.



6. Fixing Top Housing to Bottom with
M5x50 mm screws.



Measuring Methods for Verification

- Perpendicularity : It can be Measured with Height Gauge and a Datum Perpendicular to the Gauge.
- Parallelism : Dial Indicator mounted on a clamped.
- Position Tolerance : Co-ordinate Measuring Machine (CMM) or Computer Vision System are appropriate instruments for obtaining positioning of various parts.
- Circularity : A Dial Indicator mounted on a clamped with the subject revolving on V-Block.
- Cylindricity : Similar Method to Circularity

End