CS599 (Deep Learning)

Homework – 09

1. **Python Code:**

```
import torch
import pandas as pd
import matplotlib
import numpy as np
import math
matplotlib.use("agg")

from sklearn.model_selection import KFold, GridSearchCV, ParameterGrid
from sklearn.neighbors import KNeighborsRegressor
from sklearn.linear_model import LassoCV
from sklearn.pipeline import make_pipeline
from sklearn.preprocessing import StandardScaler
from sklearn.metrics import mean_squared_error
from collections import Counter


data_set_dict = {"forest_fires": ("forestfires.csv", ",", True),
            "air_foil": ("airfoil_self_noise.tsv", "\t", False)}
data_dict = {}
hist_df_list = []


for data_name, (file_name, sep, log_trans) in data_set_dict.items():
   data_df = pd.read_csv(file_name, sep = sep, header = 0)
   data_nrow, data_ncol = data_df.shape
   label_col_num = data_ncol - 1
   data_label_vec = data_df.iloc[:, label_col_num]
   if log_trans:
      data_label_vec = np.log(data_label_vec + 1)
   label_sd = math.sqrt(data_label_vec.var())
   standard_label_vec = (
      data_label_vec - data_label_vec.mean()
   )/ label_sd
   is_feature_col = (
            np.arange(data_ncol) != label_col_num
            ) & (
               data_df.dtypes != "object"
            )
   data_features = data_df.loc[:, is_feature_col]
   feature_nrow, feature_ncol = data_features.shape
```

```
    feature_mean = data_features.mean().to_numpy().reshape(1, feature_ncol)
    feature_std = data_features.std().to_numpy().reshape(1, feature_ncol)
    feature_scaled = (data_features - feature_mean)/feature_std
    print("%s %s" %(data_name, data_features.shape))
    input_tensor = torch.from_numpy(
      feature_scaled.to_numpy()
    ).float()
    output_tensor = torch.from_numpy(
      standard_label_vec.to_numpy()
    ).float().reshape(data_nrow, 1)
    data_dict[data_name] = (feature_scaled, standard_label_vec)
    hist_df_list.append(pd.DataFrame({
            "data_name": data_name,
            "label": standard_label_vec})
            )
hist_df = pd.concat(hist_df_list)

class TorchModel(torch.nn.Module):
    def __init__(self, units_per_layer):
      super(TorchModel, self).__init__()
      seq_args = []
      second_to_last = len(units_per_layer)-1
      for layer_i in range(second_to_last):
        next_i = layer_i+1
        layer_units = units_per_layer[layer_i]
        next_units = units_per_layer[next_i]
        seq_args.append(torch.nn.Linear(layer_units, next_units))
        if layer_i < second_to_last-1:
          seq_args.append(torch.nn.ReLU())
      self.stack = torch.nn.Sequential(*seq_args)
    def forward(self, features):
      return self.stack(features)

class CSV(torch.utils.data.Dataset):
    def __init__(self, features, labels):
      self.features = features
      self.labels = labels
    def __getitem__(self, item):
      return self.features[item,:], self.labels[item]
    def __len__(self):
      return len(self.labels)

class TorchLearner:
    def __init__(
        self, units_per_layer, step_size=0.1,
        batch_size=20, max_epochs=50):
      self.max_epochs = max_epochs
      self.batch_size=batch_size
```

```
        self.model = TorchModel(units_per_layer)
        self.loss_fun = torch.nn.MSELoss()
        self.optimizer = torch.optim.SGD(
            self.model.parameters(), lr=step_size)
    def fit(self, split_data_dict):
        ds = CSV(
            split_data_dict["subtrain"]["X"],
            split_data_dict["subtrain"]["y"])
        dl = torch.utils.data.DataLoader(
            ds, batch_size=self.batch_size, shuffle=True)
        train_df_list = []
        for epoch_number in range(self.max_epochs):
            #print(epoch_number)
            for batch_features, batch_labels in dl:
                self.optimizer.zero_grad()
                loss_value = self.loss_fun(
                    self.model(batch_features), batch_labels)
                loss_value.backward()
                self.optimizer.step()
            for set_name, set_data in split_data_dict.items():
                pred_vec = self.model(set_data["X"])
                set_loss_value = self.loss_fun(pred_vec, set_data["y"])
                train_df_list.append(pd.DataFrame({
                    "set_name":[set_name],
                    "loss":float(set_loss_value),
                    "epoch":[epoch_number]
                }))
        self.train_df = pd.concat(train_df_list)
    def decision_function(self, test_features):
        with torch.no_grad():
            pred_vec = self.model(test_features)
        return pred_vec.numpy()

    def predict(self, test_features):
        pred_scores = self.decision_function(test_features)
        return pred_scores


class TorchLearnerCV:
    def __init__(self, n_folds, units_per_layer=[data_ncol,1]):
        self.units_per_layer = units_per_layer
        self.n_folds = n_folds
    def fit(self, train_features, train_labels):
        train_nrow, train_ncol = train_features.shape
        times_to_repeat=int(math.ceil(train_nrow/self.n_folds))
        fold_id_vec = np.tile(torch.arange(self.n_folds), times_to_repeat)[:train_nrow]
        np.random.shuffle(fold_id_vec)
        cv_data_list = []
```

```
        for validation_fold in range(self.n_folds):
            is_split = {
                "subtrain":fold_id_vec != validation_fold,
                "validation":fold_id_vec == validation_fold
                }
            split_data_dict = {}
            for set_name, is_set in is_split.items():
                set_y = train_labels[is_set]
                split_data_dict[set_name] = {
                    "X":train_features[is_set,:],
                    "y":set_y}
            learner = TorchLearner(self.units_per_layer)
            learner.fit(split_data_dict)
            cv_data_list.append(learner.train_df)
        self.cv_data = pd.concat(cv_data_list)
        self.train_df = self.cv_data.groupby(["set_name","epoch"]).mean().reset_index()
        #print(self.train_df)
        valid_df = self.train_df.query("set_name=='validation'")
        #print(valid_df)
        best_epochs = valid_df["loss"].argmin()
        self.min_df = valid_df.query("epoch==%s"%(best_epochs))
        print("Best Epoch: ", best_epochs)
        self.final_learner = TorchLearner(self.units_per_layer, max_epochs=(best_epochs + 1))
        self.final_learner.fit({"subtrain":{"X":train_features,"y":train_labels}})
        return self.cv_data
    def predict(self, test_features):
        return self.final_learner.predict(test_features)



test_loss_data_frames = []
loss_data_dict = {}
min_df_dict = {}
for data_name, (data_features, data_labels) in data_dict.items():
    kf = KFold(n_splits=3, shuffle=True, random_state=3)
    enum_obj = enumerate(kf.split(data_features))
    for fold_num, index_tup in enum_obj:
        zip_obj = zip(["train", "test"], index_tup)
        split_data = {}
        for set_name, set_indices in zip_obj:
            split_data[set_name] = (torch.from_numpy(data_features.iloc[set_indices,
:].to_numpy()).float(),
                                    torch.from_numpy(np.ravel(data_labels.iloc[set_indices])).float())
        #x = {data_name:X.shape for data_name, (X,y) in split_data.items()}
        #print(f"{data_name}: ", x)
        train_features, train_labels = split_data["train"]
        nrow, ncol = train_features.shape
        #print(f"{data_name}: ", nrow, ncol)
```

```
test_features, test_labels = split_data["test"]

#kneighbors
knn = KNeighborsRegressor()
hp_parameters = {"n_neighbors": list(range(1, 21))}
grid = GridSearchCV(knn, hp_parameters, cv=3)
grid.fit(train_features, train_labels)
best_n_neighbors = grid.best_params_['n_neighbors']
print("Best N-Neighbors = ", best_n_neighbors)
knn = KNeighborsRegressor(n_neighbors=best_n_neighbors)
knn.fit(train_features, train_labels)
knn_pred = knn.predict(test_features)
#print(test_labels)
#print(knn_pred)
#loss = mean_squared_error(test_labels, knn_pred)
#print(f"Knn Loss {data_name} : ", loss)

#linear model
pipe = make_pipeline(StandardScaler(), LassoCV(cv=3, max_iter=2000))
pipe.fit(train_features, train_labels)
lr_pred = pipe.predict(test_features)

#loss_linear = mean_squared_error(test_labels, lr_pred)
#print(f"Linear_loss {data_name} : ", loss_linear)

#Featureless
y_train_series = pd.Series(train_labels)
mean_train_label = y_train_series.mean()
print("Mean Train Label = ", mean_train_label)

# create a featureless baseline
featureless_pred = np.repeat(mean_train_label, len(test_features))
#featureless_loss = mean_squared_error(test_labels, featureless_pred)
#print(f"Featureless Loss {data_name} : ", featureless_loss)

#TorchLearnerCV
linear_learner = TorchLearnerCV(3, [ncol, 1])
#print("ncol:", ncol)
linear_loss = linear_learner.fit(train_features, train_labels.reshape(nrow,1))
ll_pred = linear_learner.predict(test_features)
#print(ll_pred)
#loss_torchlinear = mean_squared_error(test_labels, ll_pred)
#print(f"Torch Linear_loss {data_name} : ", loss_torchlinear)

#TorchLearnerCV + Deep
deep_learner = TorchLearnerCV(3, [ncol, 100, 10, 1])
deep_loss = deep_learner.fit(train_features, train_labels.reshape(nrow, 1))
dl_pred = deep_learner.predict(test_features)
```

```
        #loss_deeplearner = mean_squared_error(test_labels, dl_pred)
        #print(f"Torch Deep_loss {data_name} : ", loss_deeplearner)

        linear_loss = linear_loss.groupby(['set_name', 'epoch']).mean().reset_index()
        deep_loss = deep_loss.groupby(['set_name', 'epoch']).mean().reset_index()

        valid_df = linear_loss.query("set_name=='validation'")
        index_min = valid_df["loss"].argmin()
        min_df = valid_df.query("epoch==%s" % index_min)

        valid_df_deep = deep_loss.query("set_name=='validation'")
        index_min_deep = valid_df_deep["loss"].argmin()
        min_df_deep = valid_df_deep.query("epoch==%s" % index_min_deep)

        min_df_dict[data_name] = {'min_df linear': min_df,
                                  'min_df deep': min_df_deep}

        loss_data_dict[data_name] = {'TorchLearnerCV Linear': linear_loss,
                'TorchLearnerCV Deep': deep_loss}

        # store predict data in dict
        pred_dict = {'KNeighborsRegressor + GridSearchCV': knn_pred,
                'LassoCV': lr_pred,
                'TorchLearnerCV Linear': ll_pred,
                'TorchLearnerCV Deep': dl_pred,
                'featureless': featureless_pred}
        test_square_loss = {}
        for algorithm, predictions in pred_dict.items():
          #print(f"{algorithm}:", predictions.shape)
          test_loss = mean_squared_error(test_labels, predictions)
          #accuracy = np.mean(test_labels == predictions)
          test_square_loss[algorithm] = test_loss

        for algorithm, test_loss in test_square_loss.items():
          print(f"{algorithm} Test Square Loss: {test_loss}")
          test_loss_df = pd.DataFrame({
            "data_set": [data_name],
            "fold_id": [fold_num],
            "algorithm": [algorithm],
            "test square loss": [test_square_loss[algorithm]]})
          test_loss_data_frames.append(test_loss_df)
        print(f"**************************End of
{data_name}({fold_num})**************************")



total_test_loss_df = pd.concat(test_loss_data_frames, ignore_index = True)
print(total_test_loss_df)
```

```
import plotnine as p9
gg = p9.ggplot(total_test_loss_df, p9.aes(x ='test square loss', y = 'algorithm'))+\
      p9.facet_grid('.~data_set') + p9.geom_point()

gg.save("Test_square_loss.png", height = 8, width = 12)


forest_fires_loss = loss_data_dict["forest_fires"]
air_foil_loss = loss_data_dict["air_foil"]
forest_fires_min = min_df_dict["forest_fires"]
air_foil_min = min_df_dict["air_foil"]

gg1 = p9.ggplot() + p9.geom_line(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data =
forest_fires_loss["TorchLearnerCV Linear"])\
 + p9.geom_point(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data =
forest_fires_min["min_df linear"])  #p9.geom_line(p9.aes(fill = 'setname'))

gg1.save("Torch_validation_graph1.png", height = 8, width = 12)

gg2 = p9.ggplot() + p9.geom_line(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data =
forest_fires_loss["TorchLearnerCV Deep"])\
 + p9.geom_point(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data =
forest_fires_min["min_df deep"])  #p9.geom_line(p9.aes(fill = 'setname'))

gg2.save("Torch_validation_graph2.png", height = 8, width = 12)

gg3 = p9.ggplot() + p9.geom_line(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data =
air_foil_loss["TorchLearnerCV Linear"])\
 + p9.geom_point(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data =
air_foil_min["min_df linear"])  #p9.geom_line(p9.aes(fill = 'setname'))

gg3.save("Torch_validation_graph3.png", height = 8, width = 12)

gg4 = p9.ggplot() + p9.geom_line(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data =
air_foil_loss["TorchLearnerCV Deep"])\
 + p9.geom_point(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data =
air_foil_min["min_df deep"])  #p9.geom_line(p9.aes(fill = 'setname'))

gg4.save("Torch_validation_graph4.png", height = 8, width = 12)
```

2. Output:

```
>>> for data_name, (data_features, data_labels) in data_dict.items():
...     kf = KFold(n_splits=3, shuffle=True, random_state=3)
...     enum_obj = enumerate(kf.split(data_features))
...     for fold_num, index_tup in enum_obj:
```

```
...       zip_obj = zip(["train", "test"], index_tup)
...       split_data = {}
...       for set_name, set_indices in zip_obj:
...          split_data[set_name] = (torch.from_numpy(data_features.iloc[set_indices,
:].to_numpy()).float(),
...                                  torch.from_numpy(np.ravel(data_labels.iloc[set_indices])).float())
...       #x = {data_name:X.shape for data_name, (X,y) in split_data.items()}
... ...
...
...       for algorithm, test_loss in test_square_loss.items():
...          print(f"{algorithm} Test Square Loss: {test_loss}")
...          test_loss_df = pd.DataFrame({
...             "data_set": [data_name],
...             "fold_id": [fold_num],
...             "algorithm": [algorithm],
...             "test square loss": [test_square_loss[algorithm]]})
...          test_loss_data_frames.append(test_loss_df)
...       print(f"**************************End of
{data_name}({fold_num})**************************")

Best N-Neighbors =  19
Mean Train Label =  0.0049645514
Best Epoch:  0
Best Epoch:  2
KNeighborsRegressor + GridSearchCV Test Square Loss: 1.0609387159347534
LassoCV Test Square Loss: 1.0739297224352429
TorchLearnerCV Linear Test Square Loss: 1.2798919677734375
TorchLearnerCV Deep Test Square Loss: 1.073811411857605
featureless Test Square Loss: 1.0739296674728394
**************************End of forest_fires(0)**************************
Best N-Neighbors =  20
Mean Train Label =  -0.019172536
Best Epoch:  0
Best Epoch:  3
KNeighborsRegressor + GridSearchCV Test Square Loss: 0.988243818283081
LassoCV Test Square Loss: 0.9922808202492903
TorchLearnerCV Linear Test Square Loss: 1.0052711963653564
TorchLearnerCV Deep Test Square Loss: 0.989805281162262
featureless Test Square Loss: 0.9922808408737183
**************************End of forest_fires(1)**************************
Best N-Neighbors =  17
Mean Train Label =  0.014222353
Best Epoch:  10
Best Epoch:  0
KNeighborsRegressor + GridSearchCV Test Square Loss: 1.0026485919952393
LassoCV Test Square Loss: 0.9305249905775753
TorchLearnerCV Linear Test Square Loss: 1.1973176002502441
TorchLearnerCV Deep Test Square Loss: 0.9264524579048157
```

```
featureless Test Square Loss: 0.9305248856544495
**************************End of forest_fires(2)**************************
Best N-Neighbors =  13
Mean Train Label =  -0.034039237
Best Epoch:  42
Best Epoch:  44
KNeighborsRegressor + GridSearchCV Test Square Loss: 0.31644493341445923
LassoCV Test Square Loss: 0.47843713543411764
TorchLearnerCV Linear Test Square Loss: 0.5696210265159607
TorchLearnerCV Deep Test Square Loss: 0.1302846521139145
featureless Test Square Loss: 0.9787271022796631
**************************End of air_foil(0)**************************
Best N-Neighbors =  9
Mean Train Label =  0.00056366913
Best Epoch:  44
Best Epoch:  49
KNeighborsRegressor + GridSearchCV Test Square Loss: 0.2813766300678253
LassoCV Test Square Loss: 0.48135759164756325
TorchLearnerCV Linear Test Square Loss: 0.6965237259864807
TorchLearnerCV Deep Test Square Loss: 0.2059951275587082
featureless Test Square Loss: 0.9960943460464478
**************************End of air_foil(1)**************************
Best N-Neighbors =  11
Mean Train Label =  0.033475567
Best Epoch:  42
Best Epoch:  45
KNeighborsRegressor + GridSearchCV Test Square Loss: 0.3124180734157562
LassoCV Test Square Loss: 0.5237005567324898
TorchLearnerCV Linear Test Square Loss: 0.5518736839294434
TorchLearnerCV Deep Test Square Loss: 0.3650369644165039
featureless Test Square Loss: 1.0345804691314697
**************************End of air_foil(2)**************************
```

>>> total_test_loss_df = pd.concat(test_loss_data_frames, ignore_index = True)

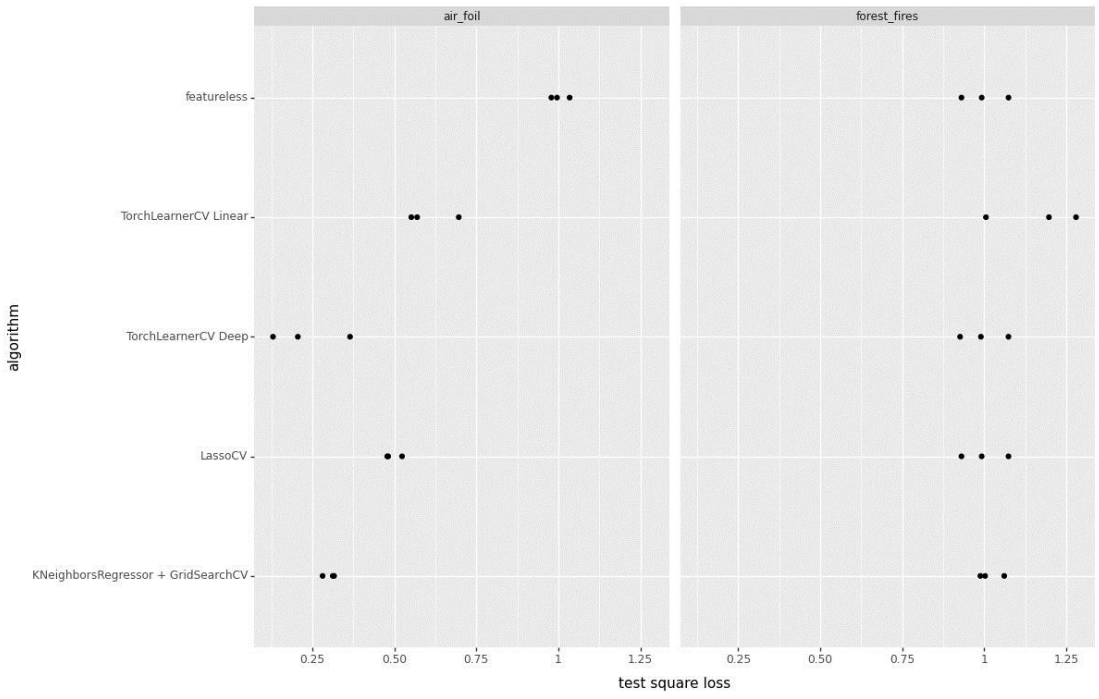
>>> print(total_test_loss_df)

	data_set	fold_id	algorithm	test square loss
0	forest_fires	0	KNeighborsRegressor + GridSearchCV	1.060939
1	forest_fires	0	LassoCV	1.073930
2	forest_fires	0	TorchLearnerCV Linear	1.279892
3	forest_fires	0	TorchLearnerCV Deep	1.073811
4	forest_fires	0	featureless	1.073930
5	forest_fires	1	KNeighborsRegressor + GridSearchCV	0.988244
6	forest_fires	1	LassoCV	0.992281
7	forest_fires	1	TorchLearnerCV Linear	1.005271
8	forest_fires	1	TorchLearnerCV Deep	0.989805
9	forest_fires	1	featureless	0.992281

10	forest_fires	2	KNeighborsRegressor + GridSearchCV	1.002649
11	forest_fires	2	LassoCV	0.930525
12	forest_fires	2	TorchLearnerCV Linear	1.197318
13	forest_fires	2	TorchLearnerCV Deep	0.926452
14	forest_fires	2	featureless	0.930525
15	air_foil	0	KNeighborsRegressor + GridSearchCV	0.316445
16	air_foil	0	LassoCV	0.478437
17	air_foil	0	TorchLearnerCV Linear	0.569621
18	air_foil	0	TorchLearnerCV Deep	0.130285
19	air_foil	0	featureless	0.978727
20	air_foil	1	KNeighborsRegressor + GridSearchCV	0.281377
21	air_foil	1	LassoCV	0.481358
22	air_foil	1	TorchLearnerCV Linear	0.696524
23	air_foil	1	TorchLearnerCV Deep	0.205995
24	air_foil	1	featureless	0.996094
25	air_foil	2	KNeighborsRegressor + GridSearchCV	0.312418
26	air_foil	2	LassoCV	0.523701
27	air_foil	2	TorchLearnerCV Linear	0.551874
28	air_foil	2	TorchLearnerCV Deep	0.365037
29	air_foil	2	featureless	1.034580

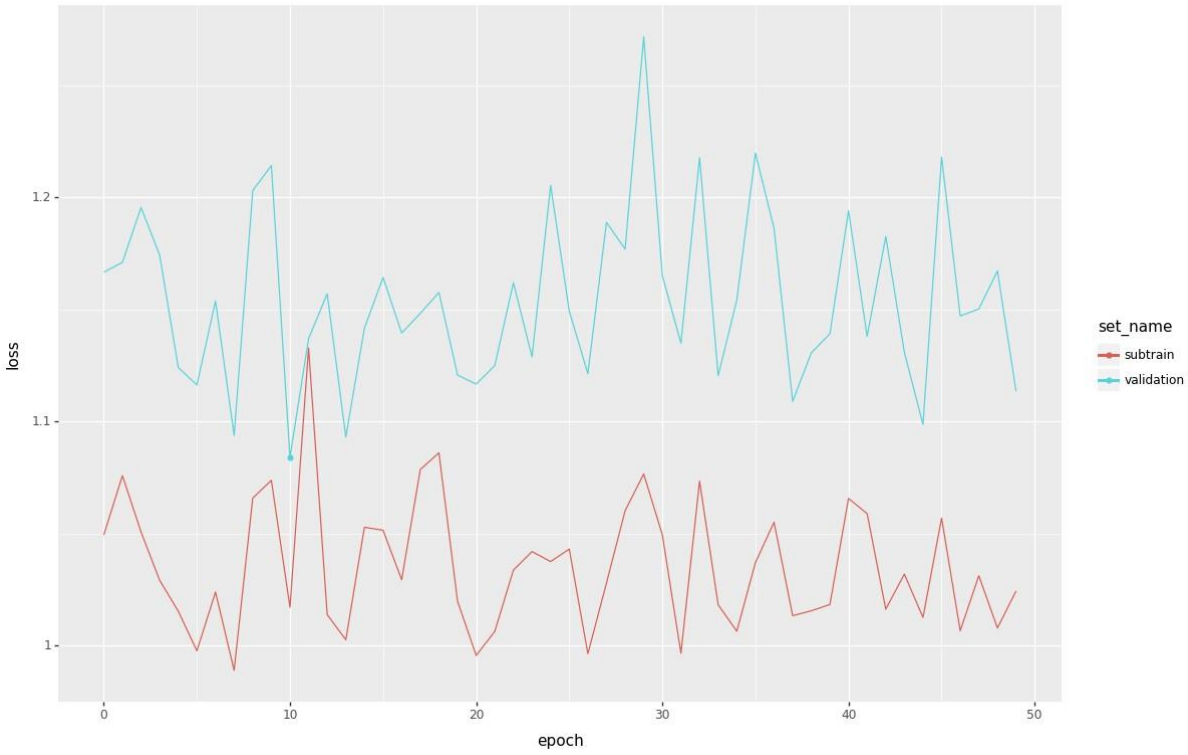
Test Loss Square Graph:

```
>>> gg = p9.ggplot(total_test_loss_df, p9.aes(x ='test square loss', y = 'algorithm'))+\
...       p9.facet_grid('.~data_set') + p9.geom_point()

>>> gg.save("Test_square_loss.png", height = 8, width = 12)
```



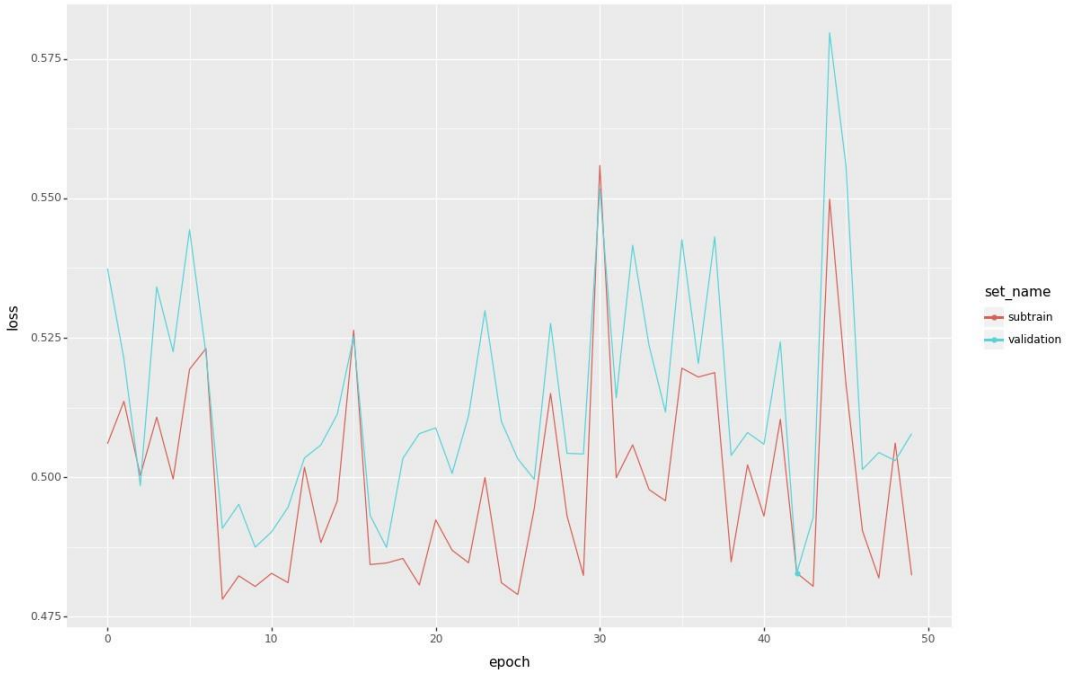
Linear subtrain/validation loss graph (Forest Fires):

```
>>> gg1 = p9.ggplot() + p9.geom_line(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data = forest_fires_loss["TorchLearnerCV Linear"])\
...   + p9.geom_point(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data = forest_fires_min["min_df linear"])  #p9.geom_line(p9.aes(fill = 'setname'))

>>> gg1.save("Torch_validation_graph1.png", height = 8, width = 12)
```



Linear subtrain/validation loss graph (Air Foil):

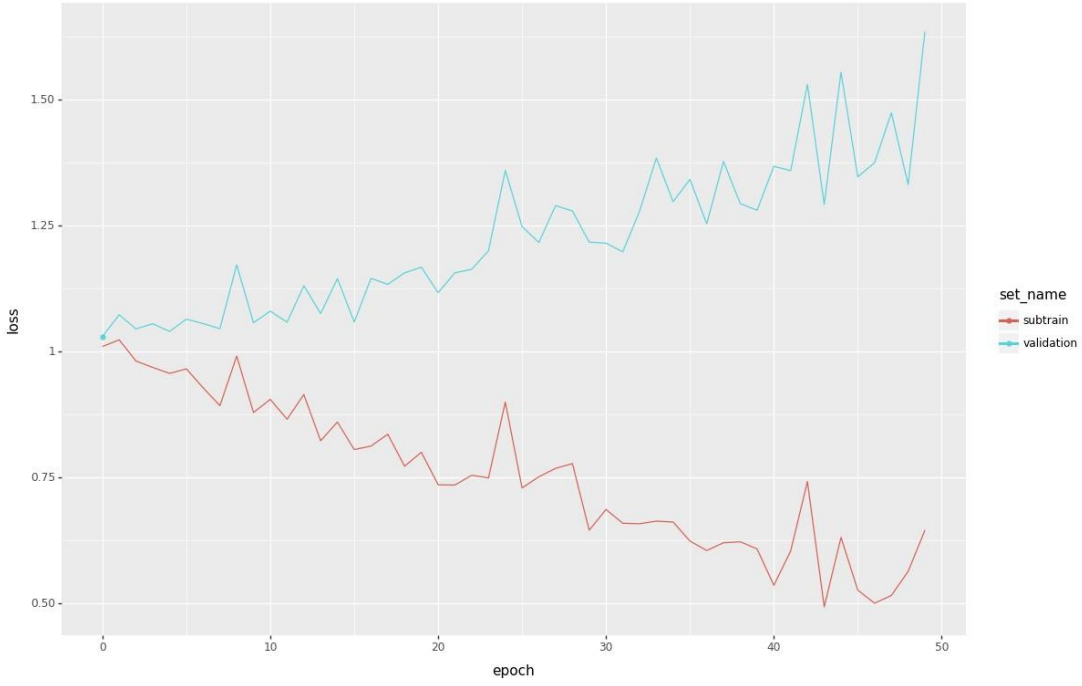
```
>>> gg3 = p9.ggplot() + p9.geom_line(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data = air_foil_loss["TorchLearnerCV Linear"])\
...   + p9.geom_point(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data = air_foil_min["min_df linear"])  #p9.geom_line(p9.aes(fill = 'setname'))

>>> gg3.save("Torch_validation_graph3.png", height = 8, width = 12)
```



Deep subtrain/validation loss graph (Forest Fires):

>>> gg2 = p9.ggplot() + p9.geom_line(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data = forest_fires_loss["TorchLearnerCV Deep"])
... + p9.geom_point(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data = forest_fires_min["min_df deep"]) #p9.geom_line(p9.aes(fill = 'setname'))

>>> gg2.save("Torch_validation_graph2.png", height = 8, width = 12)



Deep subtrain/validation loss graph (Air Foil):

```
>>> gg4 = p9.ggplot() + p9.geom_line(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data = air_foil_loss["TorchLearnerCV Deep"])\
...   + p9.geom_point(p9.aes(x ='epoch', y = 'loss', color = 'set_name'), data = air_foil_min["min_df deep"])  #p9.geom_line(p9.aes(fill = 'setname'))

>>> gg4.save("Torch_validation_graph4.png", height = 8, width = 12)
```