# LIFTLINE Manual

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#### 1 Introduction

LIFTLINE is a collection of MATLAB scripts and functions that implement lifting-line theory.

### 2 Concept of Operations

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## 3 Definition of Inputs and Outputs

#### 3.1 Basic Configuration Geometry Inputs

N panels compose the semi-span. For each row of clalp, alpzl, and clmax, the inboard value applies immediately outboard of the panel's inboard breakpoint.

Variable Name	Dimension	Description	Units
ybp	1 x (N+1)	Spanwise coordinates of breakpoints $[0, y_1, y_2,, b/2]$	m
cbp	1 x (N+1)	Chord at breakpoints $[c_r, c_1, c_2,, c_t]$	m
sweepa	1 x N	Sweep angle $(c/4)$ of each panel	deg
twista	1 x N	Twist angle at tip of each panel	deg
clalp	N x 2	Airfoil section lift-curve slope, $C_{l_{\alpha}}$ . Each row corresponds	1/deg
		to a panel. Column 1 is the inboard value. Column 2 is	
		the outboard value.	
alpzl	N x 2	Airfoil section zero lift angle of attack, $\alpha_{0l}$ . Each row corre-	deg
		sponds to a panel. Column 1 is the inboard value. Column	
		2 is the outboard value.	
clmax	N x 2	Airfoil section maximum lift coefficient, $C_{l_{max}}$ . Each row	-
		corresponds to a panel. Column 1 is the inboard value.	
		Column 2 is the outboard value.	
b	Scalar	Span	m
S	Scalar	Reference wing area	m^2
W	Scalar	Weight	N

#### 3.2 MPEGRID, MPESOLVE, and MPERESULT

In addition to subsets of the basic configuration geometry inputs, the functions MPEGRID, MPESOLVE, and MPERESULT use inputs/outputs as defined below. N is the number of Fourier sine series coefficients.

Variable Name	Dimension	Description	Units
alpha_r	Scalar	Angle of attack (root)	deg
ncoef	Scalar	Number of Fourier sine series coefficients	-
theta	1 x N	Transformed spanwise coordinate	rad
У	1 x N	Spanwise coordinate	m
С	1 x N	Chord	m
a0	1 x N	Section lift-curve slope	1/rad
alpha	1 x N	Section angle of attack	rad
alpha_zl	1 x N	Section zero lift angle of attack	rad
clmax_vec	1 x N	Section maximum lift coefficient	-
An	1 x N	Fourier coefficients $[A_1, A_3,, A_{2N-1}]$	-
U	Scalar	Free-stream velocity	m/s
Gamma	1 x N	Circulation	$m^2/s$
CL	Scalar	Wing lift coefficient	-
CDv	Scalar	Wing vortex-induced drag coefficient	-
cl	1 x N	Section lift coefficient	-

## 3.3 SPAREQ

The function SPAREQ (Spar Equilibrium Shear and Bending Moment) optionally uses the inputs ploads and uloads, as defined below. Other inputs/outputs are also defined below.

Variable Name	Dimension	Description	Units
ploads	R x 2	Point loads applied along the wing. Each row specifies a	N
		point load. Column 1, y-values (meters). Column 2, loads.	
		Negative loads values apply in the downward direction.	
		For example, a store would be input as a negative load.	
		Example: $\begin{bmatrix} 1.2 & -50 \\ 2.1 & -25 \end{bmatrix}$	
uloads	R x 3	Uniform distributed loads applied along the wing. Column	N/m
		1, inboard y-values (meters). Column 2, outboard y-values	
		(meters). Column 3, load per unit span. Negative loads	
		values apply in the downward direction. For example, a	
		fuel tank would be input as a negative load. Example:	
		$   1.1 \ 2.2 \ -10   $	
		$\begin{bmatrix} 2.0 & 4.0 & -20 \end{bmatrix}$	
rho	Scalar	Density	$kg/m^3$
V	1 X N	Shear	N
M	1 X N	Bending Moment	N*m
M_root	1 X N	Root Bending Moment	N*m