

Smooth Animations to Visualize Gaussian Uncertainty

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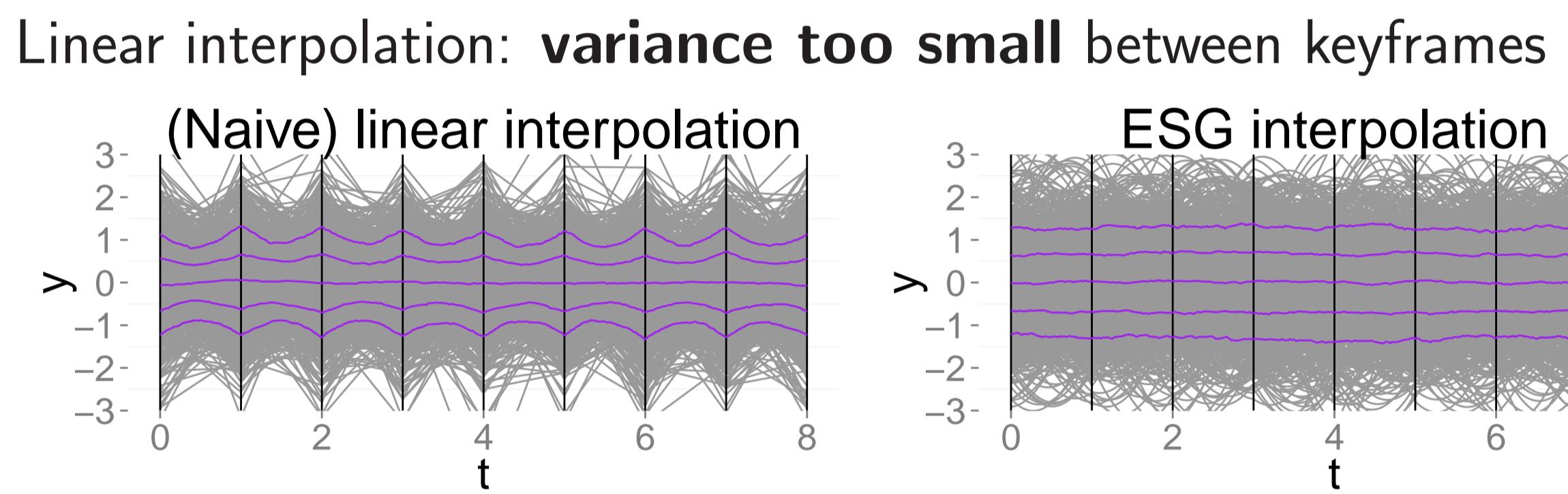
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Introduction

- **Goal:** Visualize uncertainty in *curves and surfaces*
- Specifically: using **Gaussian processes** (see refresher at bottom)
- **Approach:** animations
- Each frame shows one draw from posterior
- Consecutive frames show similar curves (i.e., *continuous* animations)
- **Reducible:** find **single “Gaussian oscillator”**; use copies as needed
- **New Results:**
 - Smooth, keyframe-free animations
 - New framework for all future work in Gaussian animations

Existing approach: interpolate between I.I.D. Gaussian draws



- Ehlschlaeger, Shortridge, Goodchild (**ESG**) solved in 1997 (see right figure)
- Problem with *both* approaches: keyframes are ‘special’
 - Motion changes discontinuously
 - Even at $\Delta t = 1$, correlation can be surprisingly high (up to 0.5)

New approach: eliminate keyframes entirely

- Still use I.I.D. normals, $\{\epsilon_i\}$, but *de-localize* rather than interpolate
- $$f(t) = \frac{1}{\sqrt{N}} \sum_{i=1}^N \left[\epsilon_{2i-1} \sin\left(\frac{\pi i t}{N}\right) + \epsilon_{2i} \cos\left(\frac{\pi i t}{N}\right) \right]$$

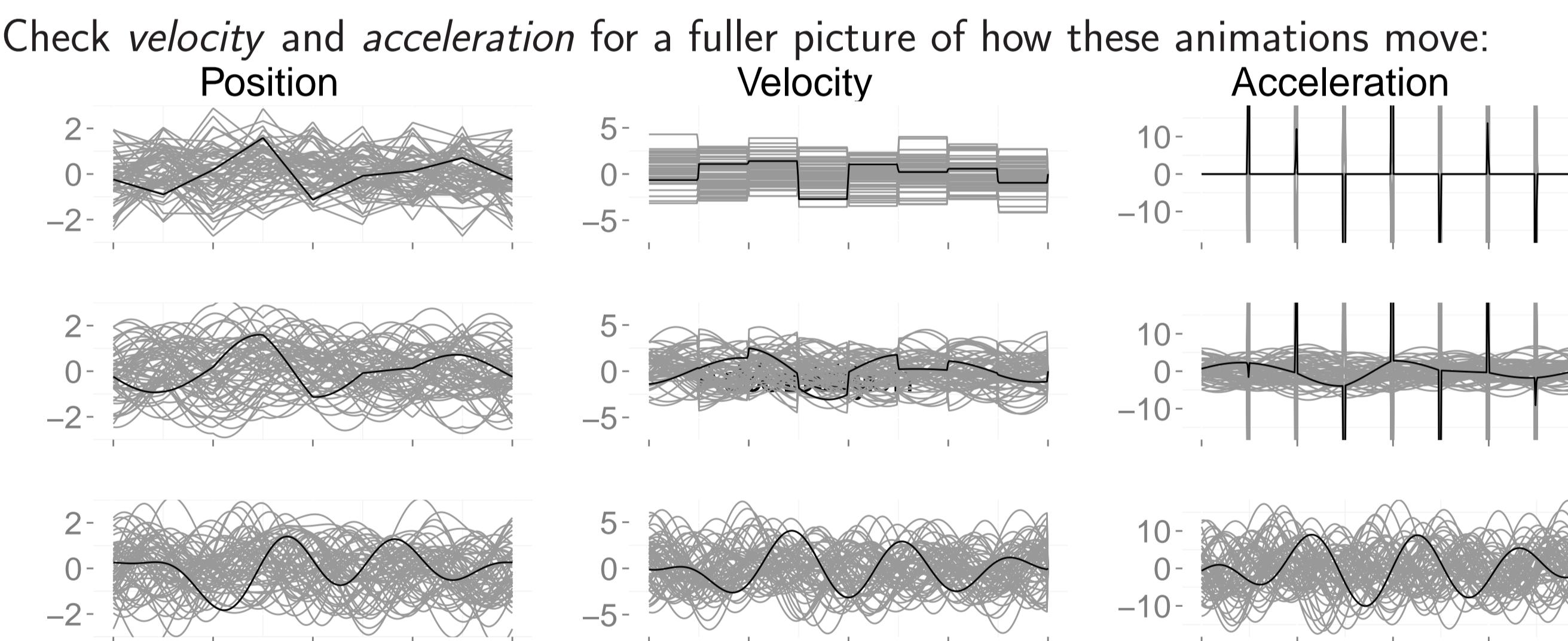
- Correct statistical properties: $\langle f(t) \rangle = 0; \langle f(t)^2 \rangle = 1 \quad \forall t$

Basis function view

$$f(t) = \sum_{i=1}^N \epsilon_i b_i(t)$$

Animation Method	Statistically Correct	Stationary	Smooth
Naive linear interpolation	✗	✗	✗
ESG interpolation	✓	✗	✗
Smooth timetraces	✓	✓	✓

Physical motion: basic kinematics



Motion is *not* different at the keyframes because they do not exist.
(Also: add the dots, in the plots!)

The true nature of $f(t)$

- Observations about $f(t)$:
 - Infinite set of Gaussian random variables
 - Indexed by continuous variable, t
 - Well-defined covariance between every pair of points:

$$\langle f(t)f(t+\tau) \rangle = \frac{1}{N} \sum_{i=1}^N \left[\cos\left(\frac{\pi i \tau}{N}\right) \right]$$
- **Implication:** $f(t)$ is *itself* a Gaussian process
 - Specifically: time-domain GP rather than space-domain
- **Benefit:** Gaussian animations *revealed to belong to a well-studied framework*
 - Future animations: take advantage of Gaussian Processes (e.g., try new covariance functions)

R implementation

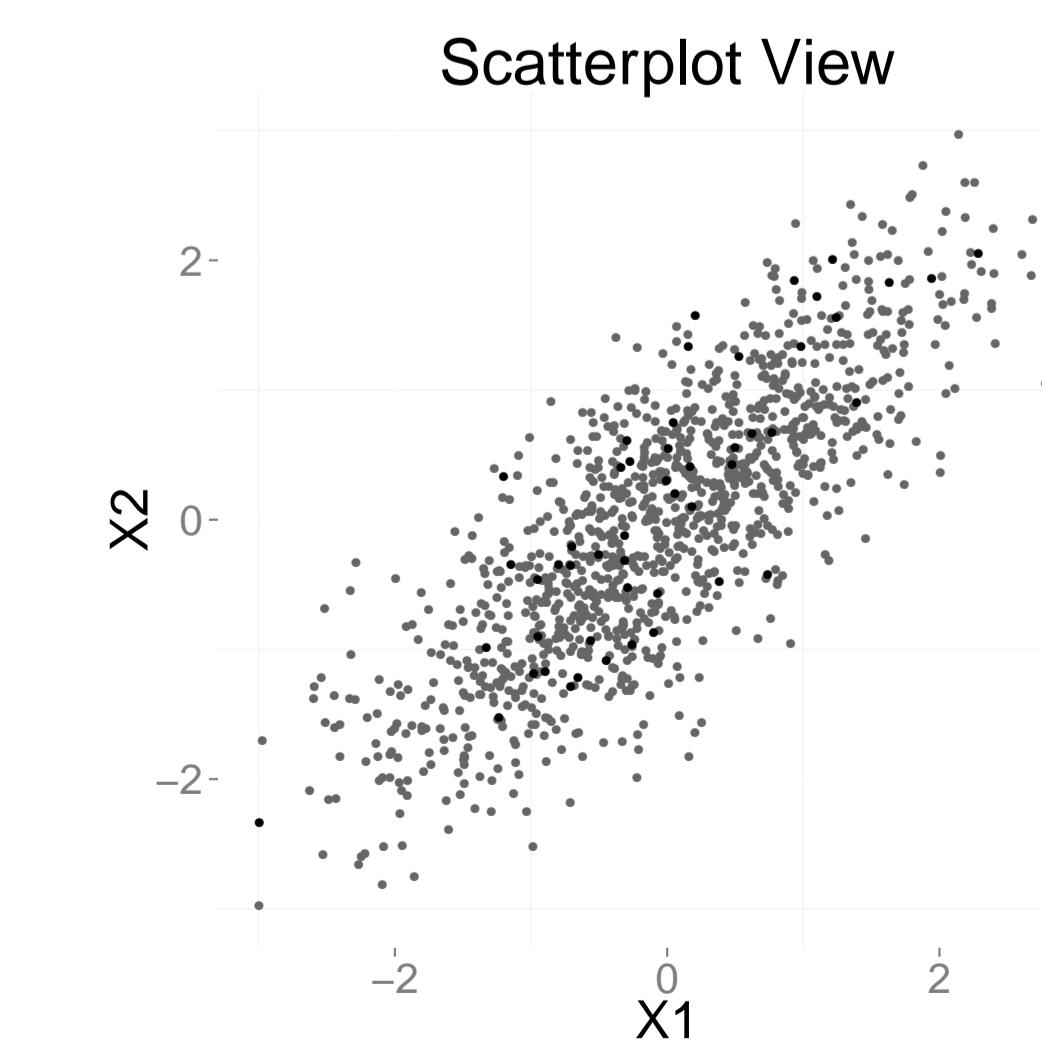
```
# Matrix to turn 2N random values into Gaussian oscillator.
GaussianOscillatorMatrix <- function(N, t) {
  cbind(outer(t, 1:N, function(x, y) cos(pi * x * y / N)),
        outer(t, N:1, function(x, y) sin(pi * x * y / N)))
}
```

Conclusions

- First *statistically correct* Gaussian animations with **smooth and natural motion**
- Moving beyond interpolation: **keyframes entirely eliminated**
- **Time-domain Gaussian Processes** enable *animated visualization of space-domain Gaussian Processes*
 - Stationary covariance function → no keyframes

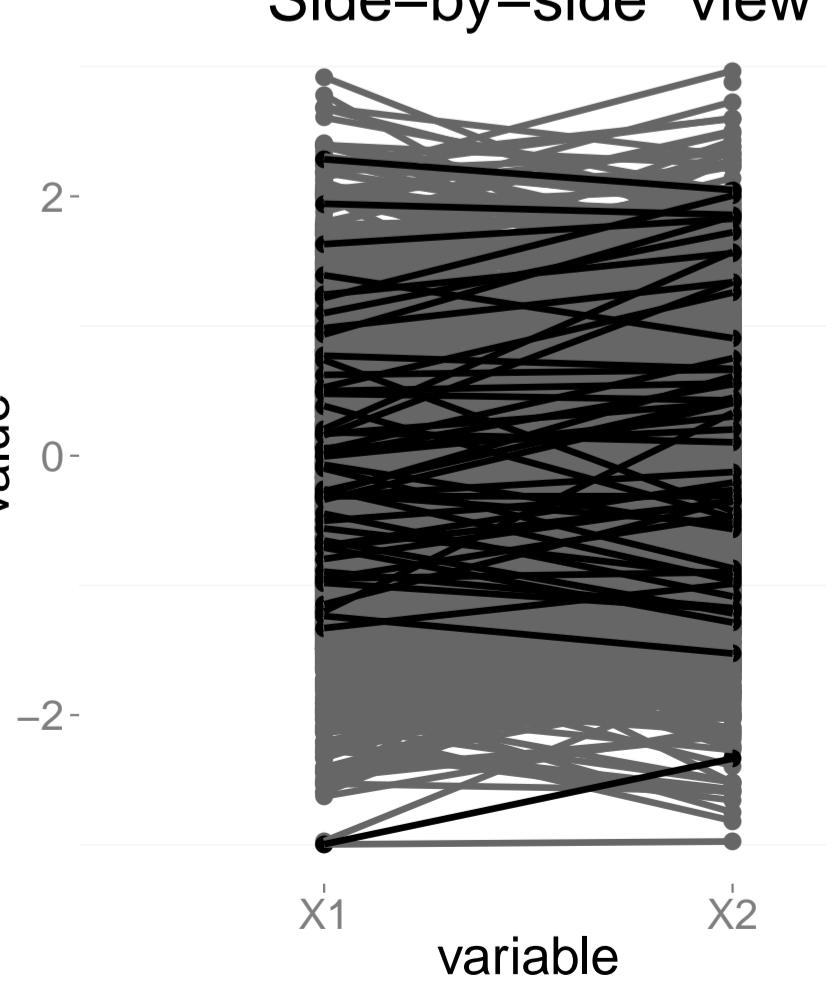
Gaussian Processes refresher: Probabilities for Functions

- Random curves and surfaces: *infinitely many* random variables!



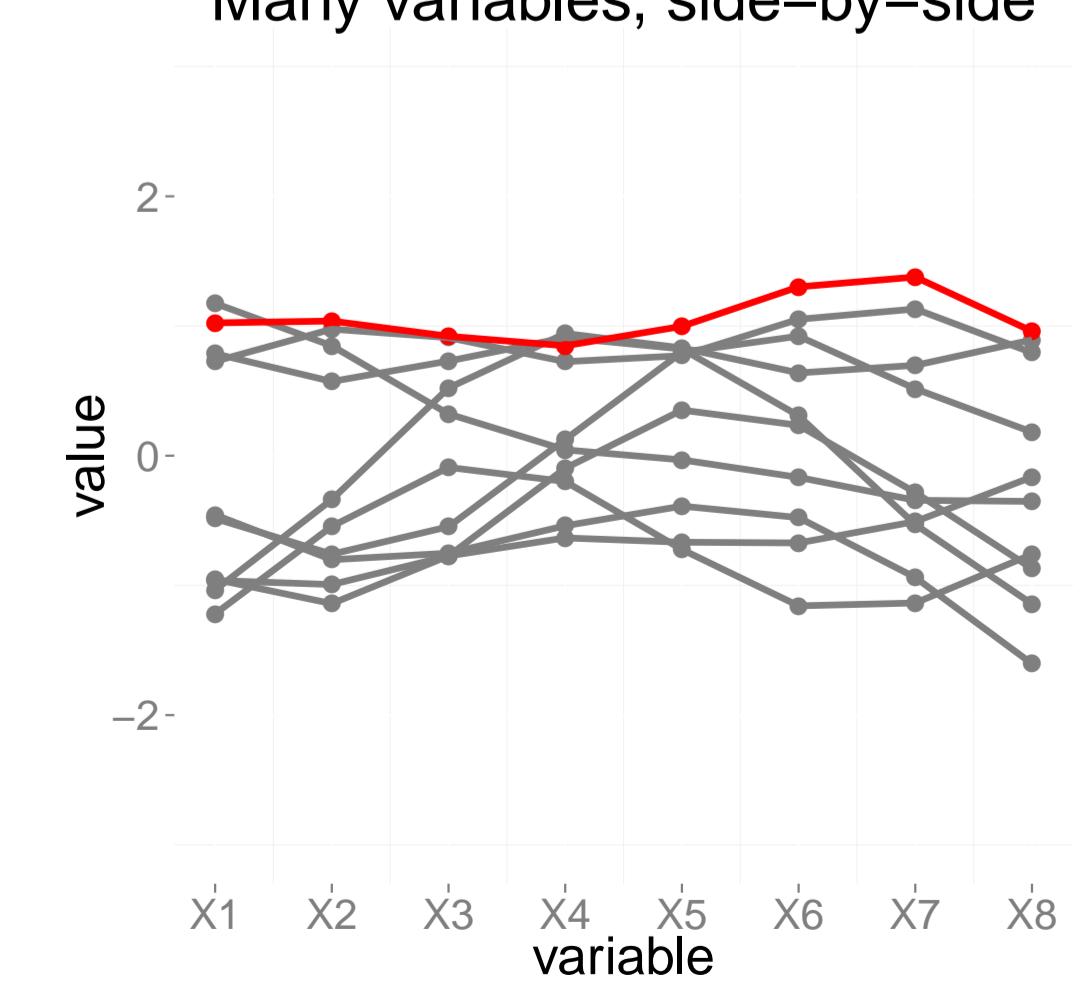
- Highly correlated → close to diagonal
- Works well for two variables

“Side-by-side” view



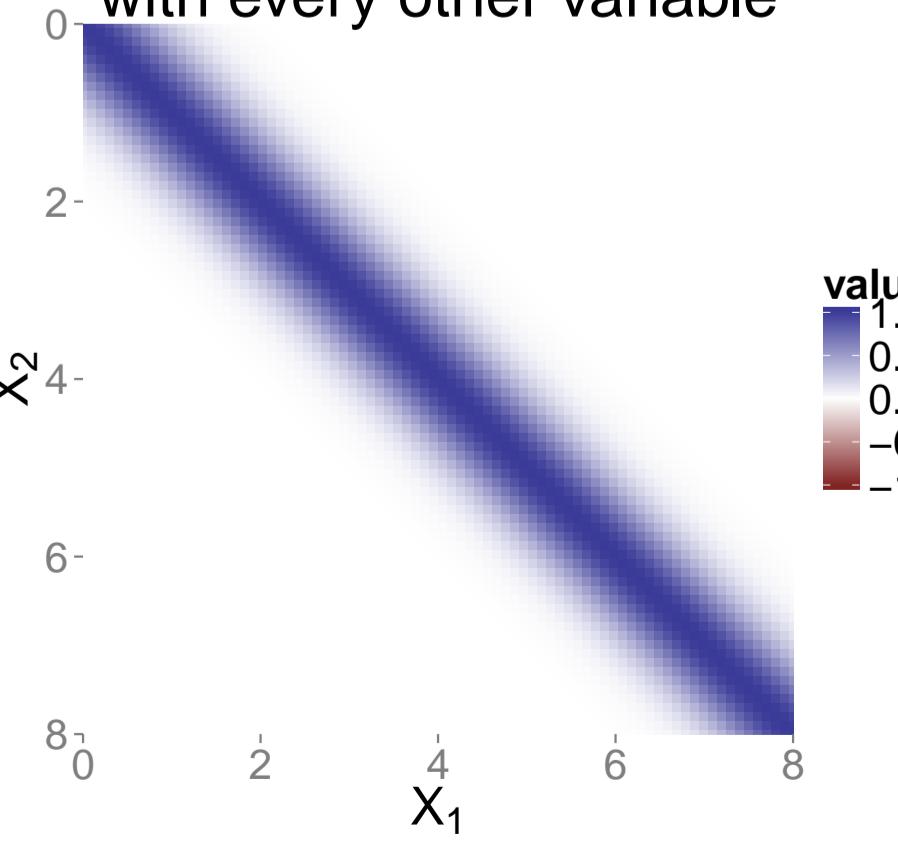
- Highly correlated → horizontal lines
- Works well for more variables...

Many variables, side-by-side



- Variables indexed by *position*

Specify covariance of every variable with every other variable



Get *continuous* random function from *I.I.D.* normal draws:

