Chirag Parikh

INTERESTS

Computer Vision · Video Understanding · Video-Language Modeling · Multimodal Learning · Explainability · Visual Grounding · Deep Learning · Advanced Driver Assistance Systems (ADAS)

EDUCATION

• International Institute of Information Technology, Hyderabad

2022 - Present

Ph.D. in Computer Science and Engineering

CGPA: 9.33/10

o Advisor: Prof. Ravi Kiran Sarvadevabhatla

Birla Institute of Technology, Mesra

2013 - 2017

Bachelor of Engineering in CET

CGPA: 7.34/10

- o Conducted undergraduate research on Computer Vision in Friction Stir Welding (FSW), Advisor: Prof. Surjya K. Pal
- Winner of MathWorks Prize (ABU Robocon 2015) and 1st Place at Vertechx 2014 (robotics)
- Organized workshops/competitions as Robotics Club executive

EXPERIENCE

• IIIT-H, Center for Visual Information Technology (CVIT) Lab [

2022 - Present

PhD Researcher

- Research in video question answering, driver behavior modeling and explanation, and road scene understanding.
- Contributed to papers in CVPR 2025, ICRA 2024 on road event understanding and driving behavior explanation in dense and unstructured traffic.

• The Hi-Tech Robotic Systemz Ltd. [#]

2019 - 2022

Senior Research Engineer (ADAS)

- Designed HydraNet for Driver State Monitoring (DMS) with real-time inference on embedded platforms.
- $\circ \ A chieved > \! 95\% \ accuracy \ across \ multiple \ subtasks \ in \ DMS \ (eye-closure, smoking, yawning, phone \ activity).$
- Optimized CNNs, created custom datasets, and deployed models on resource-constrained ARM devices.

• FarmGuide [�] 2017 - 2019

Computer Vision Engineer (Remote Sensing)

- Developed CV + geospatial models for cropland detection from satellite imagery.
- Built cloud-scalable pipelines using AWS (EC2, Lambda, S3).
- Applied deep edge detection (HED), clustering, and time-series analysis to remote sensing data.

• Prakshep [�]

Jan - May 2017

Data Science Intern

• Analyzed raster image data and embedded R-code in MySQL to enable real-time GIS queries from SAP HANA DB for agricultural applications.

• IIT Kharagpur, FSW Lab (Machine Vision) [

Summer of 2015 & 2016

Research Intern

- Developed novel image-based methods to detect FSW defects from 3D reconstructions and time-series signals.
- Co-invented and co-authored a patent and 2 journal papers for computer vision application in manufacturing processes.

PUBLICATIONS

C=CONFERENCE, J=JOURNAL, P=PATENT, A=ARXIV, T=THESIS

- [C.1] Chirag Parikh, Deepti Rawat, Rakshitha R. T., Tathagata Ghosh, Ravi Sarvadevabhatla. RoadSocial: A
 Diverse VideoQA Dataset and Benchmark for Road Event Understanding from Social Video Narratives. In
 proc. of IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 2025 [Paper], [Project Page]
- [C.2] Ravi Shankar Mishra, Chirag Parikh, Anbumani Subramanian, C.V.Jawahar, Ravi Kiran Sarvadevabhatla.
 IDD-CRS: A Comprehensive Video Dataset for Critical Road Scenarios in Unstructured Environments. In proc. of IEEE Intelligent Vehicles Symposium (IV), 2025 [Paper]
- [C.3] Chirag Parikh, Rohit Saluja, CV Jawahar, Ravi Sarvadevabhatla. IDD-X: A Multi-View Dataset for Ego-relative Important Object Localization and Explanation in Dense and Unstructured Traffic. In proc. of IEEE International Conference on Robotics and Automation (ICRA), 2024 [Paper], [Project Page]
- [A.1] Chirag Parikh, Ravi Shankar Mishra, Rohan Chandra, Ravi Sarvadevabhatla. Transfer-LMR: Heavy-Tail Driving Behavior Recognition in Diverse Traffic Scenarios. Submitted for publication in MTA Journal, 2024 [Paper], [Code]

- [C.4] Prafful Kumar Khoba, Chirag Parikh, Rohit Saluja, Ravi Kiran Sarvadevabhatla, C.V. Jawahar. A Fine-Grained Vehicle Detection (FGVD) Dataset for Unconstrained Roads. In proc. of Thirteenth Indian Conference on Computer Vision, Graphics and Image Processing (ICVGIP), 2022 [Paper], [Code]
- [P.1] Surjya Kanta Pal, Aaquib Reza Khan, Ravi Ranjan, Chirag Parikh, Srikanta Pal, Debashish Chakravarty, Abhik Maiti. Real-Time Surface Defect Analysis and Correction in Friction Stir Welding Process by Image Processing. IN, Patent No. 514971. File Date: 20/09/2018, Grant Date: 26/02/2024. [Grant Certificate]
- [J.1] Chirag Parikh, Ravi Ranjan, Aaquib Reza Khan, Rahul Jain, Raju Prasad Mahto, Debashish Chakravarty, Srikanta Pal, Surjya K. Pal. Volumetric defect analysis in friction stir welding based on three dimensional reconstructed images. Journal of Manufacturing Processes, Elsevier, 2017 [Paper]
- [J.2] Ravi Ranjan, Aaquib Reza Khan, Chirag Parikh, Rahul Jain, Raju Prasad Mahto, Srikanta Pal, Surjya K. Pal, Debashish Chakravarty. Classification and identification of surface defects in friction stir welding: An image processing approach. Journal of Manufacturing Processes, Elsevier, 2016 [Paper]

PROJECTS

• Differential Attention Networks for Visual Question Answering

2023

IIIT-H Computer Vision course project advised by: Prof. Avinash Sharma

• [Report], [Code]

Integrating storage manager (TASM) and query optimizer (FiGO) in Video-DBMS

2025

IIIT-H Data Systems course project advised by: Prof. Kamal Karlapalem

• [Report], [Code], [Video]

• Driver Activity Recognition for Driver State Monitoring from Infrared Videos

2019-2022

- Sr. Research Engineer at The Hi-Tech Robotic Systemz Ltd.
- Designed a multi-task HydraNet-style architecture with BlazeFace as the shared backbone and task-specific heads for face detection, 3D 68-landmark prediction, eye state classification for drowsiness detection, and activity detection (smoking, yawning, phone usage).
- Curated a 100K+ Infrared Camera Face Detection and 3D Landmark Prediction dataset using RetinaFace and 3DDFA-v2.
- Built end-to-end TensorFlow pipelines with TFRecord-optimized loading, custom loss functions, and advanced data augmentation strategies.
- Deployed quantized TFLite models on resource-constrained ARM devices with a custom C++ inference engine, achieving real-time performance (28 FPS) and 2× speedup over MediaPipe.
- Improved model robustness via pose-conditioned face synthesis (Conditional-BEGAN), fine-tuned HOG+SVM detectors for masked faces, and boosted eye state classification accuracy to 96% through targeted augmentations.

• Cropland Detection from Satellite Imagery

2019-2022

Computer Vision Engineer at FarmGuide

- Achieved 85% accuracy in cropland detection by segmenting farm boundaries on high-resolution satellite imagery using a transfer-learned Holistically-nested Edge Detection (HED) model.
- Created a farm boundaries training dataset via unsupervised Graph Cut segmentation refined through contour analysis and morphological processing.

Real-time Shuttlecock Tracking and Trajectory Estimation for Badminton Playing Robot

2015

BIT Mesra Robotics Club project for ABU Robocon 2015 supported by: Prof. Arun Dayal Udai

• [Report], [Code], [Video]

SKILLS

- Languages: Python, C++, R, MATLAB
- Frameworks: PyTorch, TensorFlow, Keras, OpenCV, dlib
- Tools: Git, Docker, Conda, TFDS, AWS (EC2, S3, Lambda)
- Embedded Platforms: Snapdragon Dragonboard, Odroid XU4, Raspberry Pi, Atmega16/32