EE 238

Power Engineering - II

Power Electronics

Lecture 8

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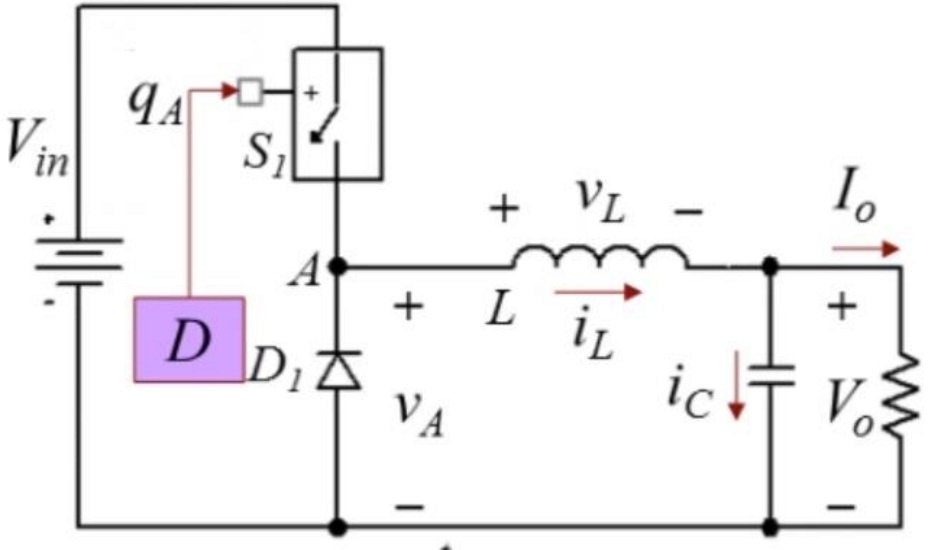
Buck Converter Waveforms

$$\frac{V_o}{V_{in}} = D$$



$$i_L(t) = i_L(t_o) + \int_{t_o}^{t} v_L(\tau)\,d\tau$$

1. <u>ON interval</u>

$v_L(t) = V_{in} - V_o$ Slope of i_L : $m_1 = \dfrac{V_{in} - V_o}{L}$

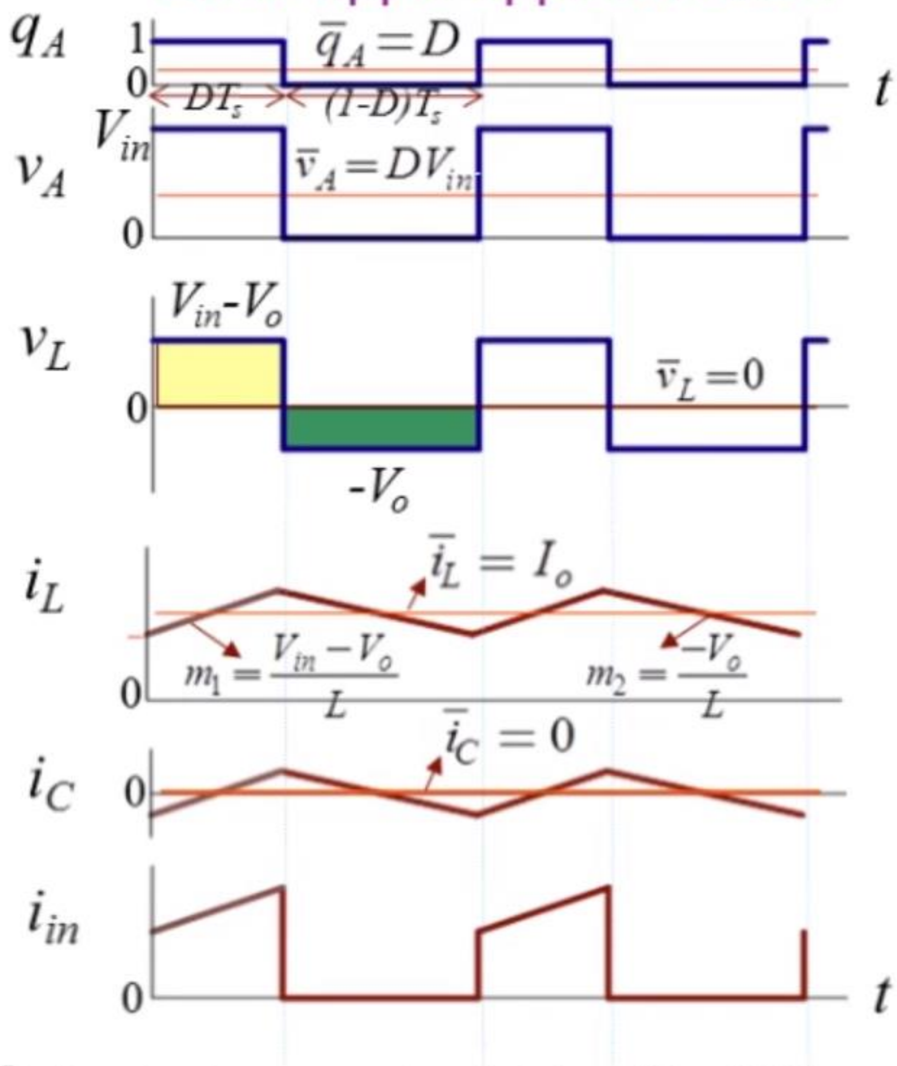
2. <u>OFF interval</u>

$v_L(t) = -V_o$ Slope of i_L : $m_2 = \dfrac{-V_o}{L}$

3. <u>Average of i_L</u> obtained by KCL at output node

$\bar{i}_L = I_o + \bar{i}_c = I_o$ (since $\bar{i}_c = 0$)

Small ripple approximation

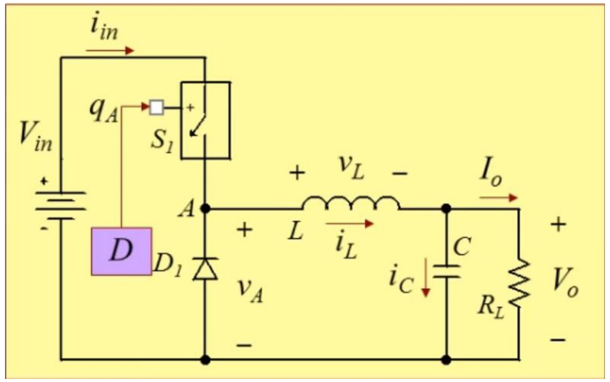


Instantaneous i_C obtained by KCL at output node

$i_c(t) = i_L(t) - I_o$

Selection of Output Filter Inductor, L

- L and C together determine output voltage ripple
- L selected to limit the inductor current ripple to a chosen value
  - e.g. 10-20% of its average current (I_o)
  - trade-off explained in next slide
  - CCM considerations
- **Worst case design**
  - minimum D for fixed output buck



$$L\frac{di}{dt}=v_L$$

Consider the T_{OFF} interval

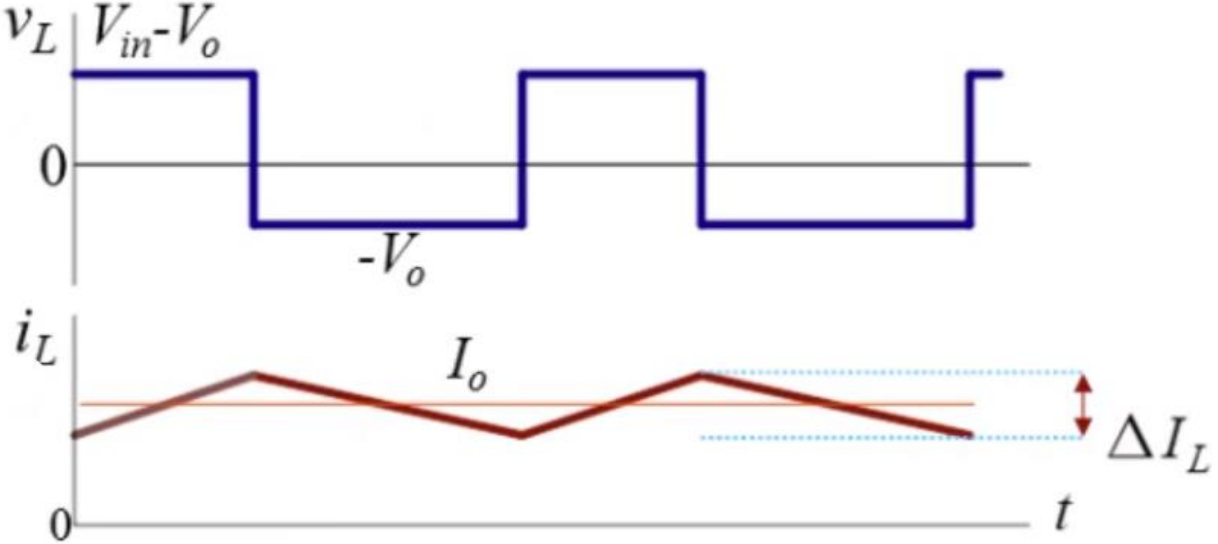
$$L\frac{\Delta I_L}{(1-D)T_S}=V_o$$

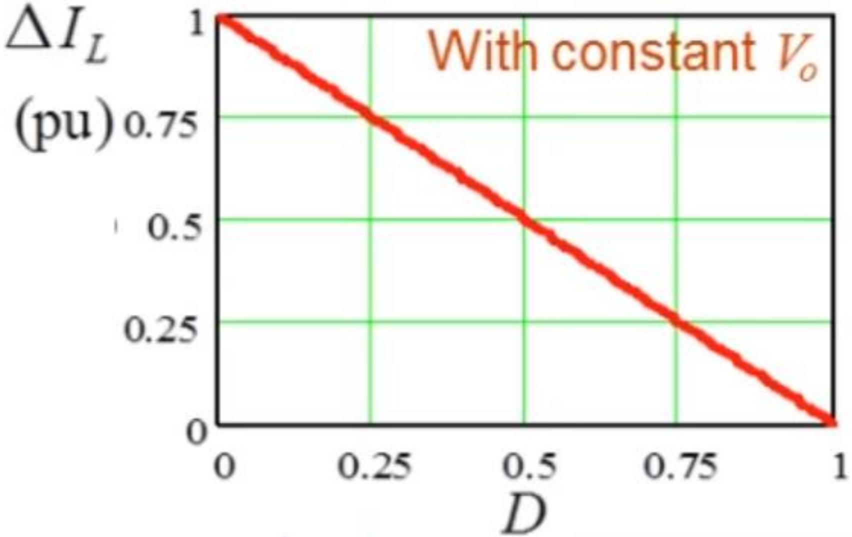
ΔI_L - Peak-peak ripple

For constant V_o and variable V_{in}

$$\left(\frac{V_o}{V_{in,max}}\right)\le D\le\left(\frac{V_o}{V_{in,min}}\right)$$

$$L=\frac{V_o(1-D)T_S}{\Delta I_L}$$





Trade-off in Selection of Inductor Current Ripple

Larger L (small current ripple)

- Lower RMS current in switch, capacitor and inductor, hence lower conduction loss
- Smaller C is enough for same output voltage ripple

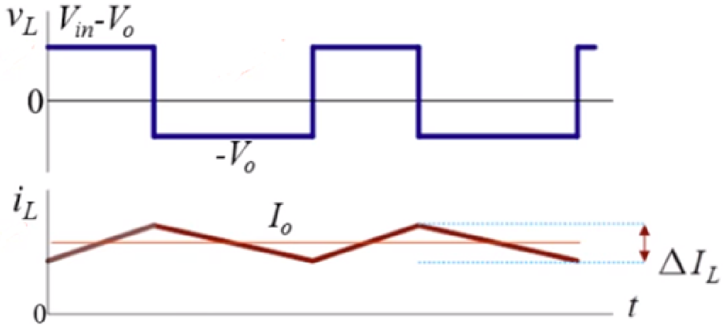
- Poor dynamic response to step loads (ramp rate of i_L)
- Bulky inductor
- Usually higher inductor resistance

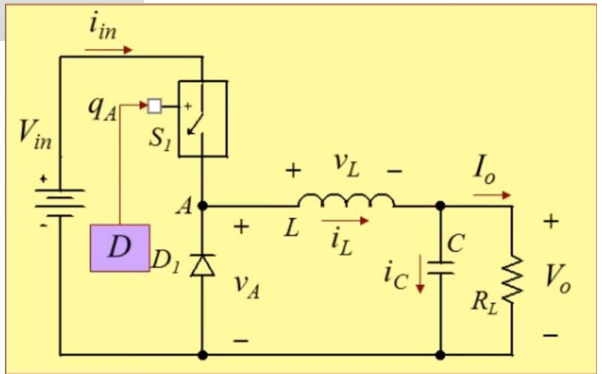
Smaller L (high current ripple)

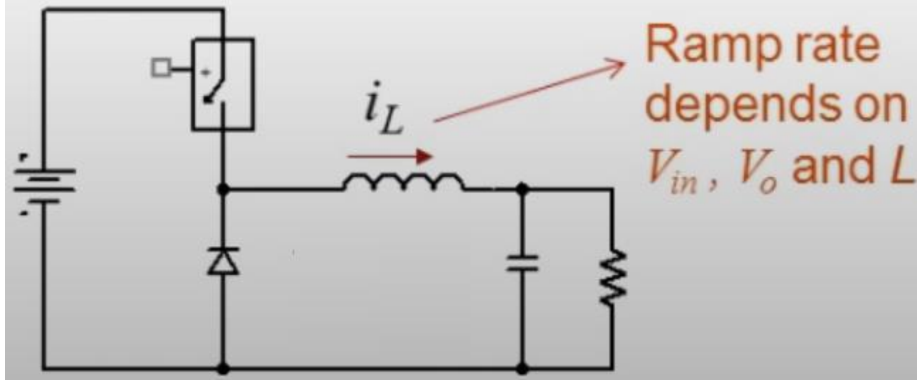
- Good dynamic response to step loads due to higher slew rate of inductor current
- Smaller size inductor, higher power density

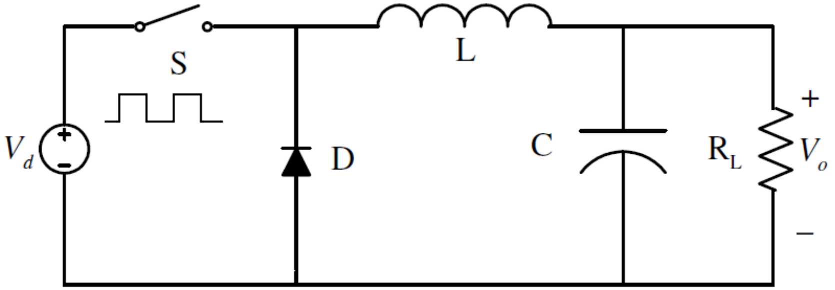
- Larger RMS current in switch, inductor and capacitor, hence higher conduction loss
- Larger flux swing at high frequency

CCM Considerations









CCM

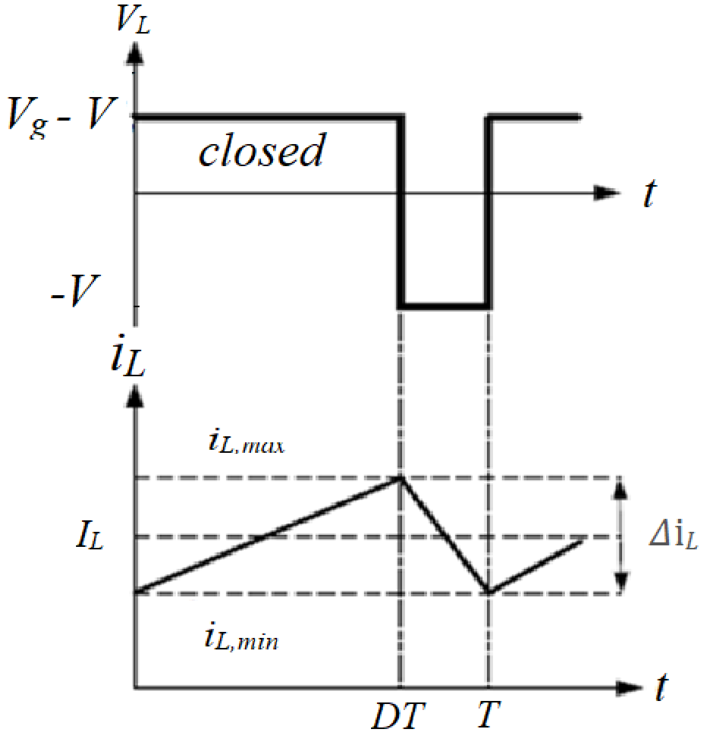
Continuous Conduction Mode.

(wrt i thru L)

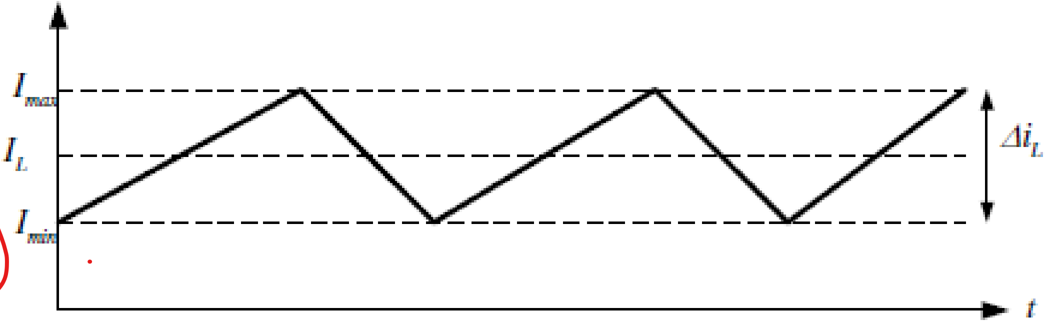
$$(\Delta i_L)_{closed} + (\Delta i_L)_{opened} = 0$$

$$\left(\frac{V_d - V_o}{L}\right) \cdot DT_s - \left(\frac{-V_o}{L}\right) \cdot (1-D)T_s = 0$$

$$\Rightarrow V_o = DV_d$$



Average, Maximum and Minimum Inductor Current



Average inductor current = Average current in R_L

$$\Rightarrow I_L = I_R = \frac{V_o}{R}$$

Maximum current :

$$I_{max} = I_L + \frac{\Delta i_L}{2} = \frac{V_o}{R} + \frac{1}{2}\left(\frac{V_o}{L}(1-D)T\right)$$

$$= V_o\left(\frac{1}{R} + \frac{(1-D)}{2Lf}\right)$$

Minimum current :

$$I_{min} = I_L - \frac{\Delta i_L}{2} = V_o\left(\frac{1}{R} - \frac{(1-D)}{2Lf}\right)$$

Inductor current ripple :

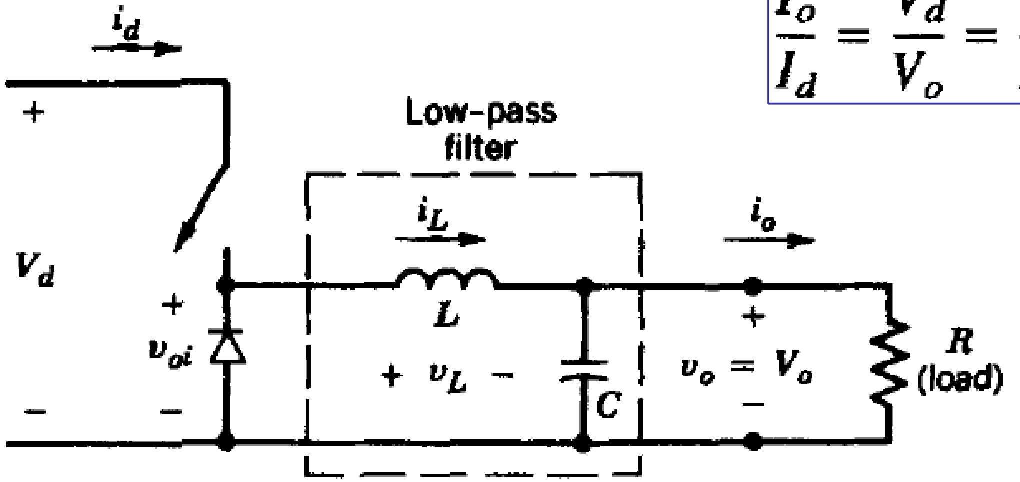
$$\Delta i_L = I_{max} - I_{min}$$

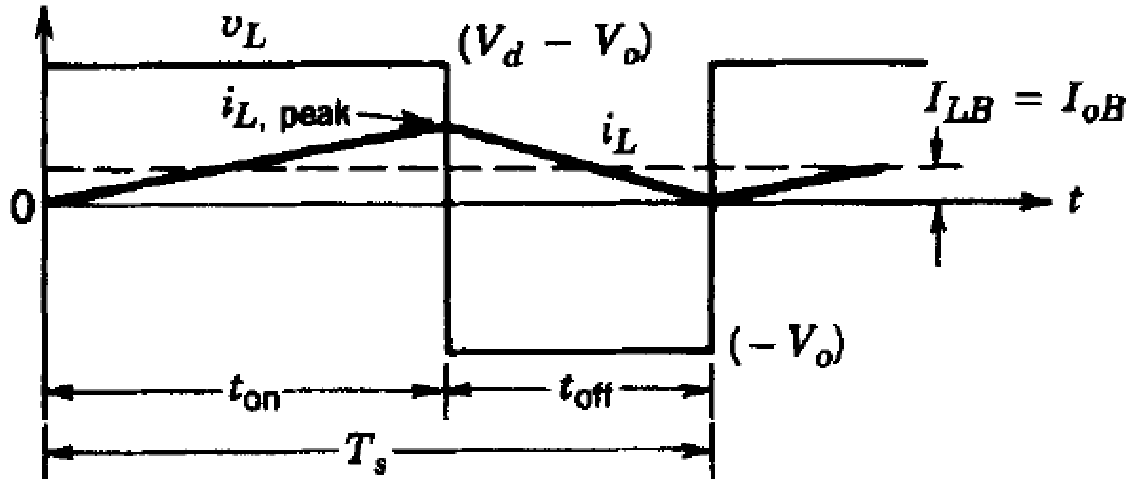
STEP-DOWN (BUCK) CONVERTER

BOUNDARY BETWEEN CONTINUOUS AND DISCONTINUOUS CONDUCTION

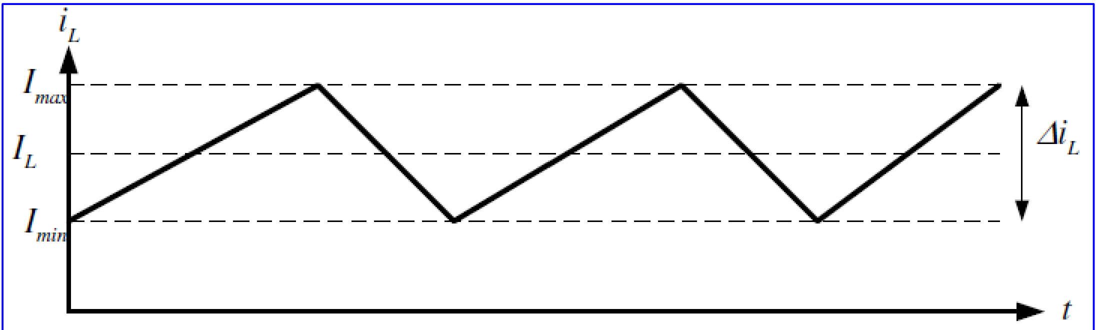
Equations that show the influence of various circuit parameters on the conduction mode of i_L .

$$\frac{I_o}{I_d} = \frac{V_d}{V_o} = \frac{1}{D}$$





BOUNDARY BETWEEN CONTINUOUS AND DISCONTINUOUS CONDUCTION



$$\text{Average inductor current} = \text{Average current in } R_L$$

$$\Rightarrow I_L = I_R = \frac{V_o}{R}$$

Maximum current :

$$I_{\max} = I_L + \frac{\Delta i_L}{2} = \frac{V_o}{R} + \frac{1}{2}\left(\frac{V_o}{L}(1-D)T\right)$$

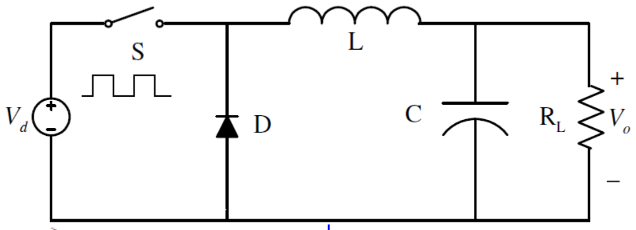
$$= V_o\left(\frac{1}{R} + \frac{(1-D)}{2Lf}\right)$$

Minimum current :

$$I_{\min} = I_L - \frac{\Delta i_L}{2} = V_o\left(\frac{1}{R} - \frac{(1-D)}{2Lf}\right)$$

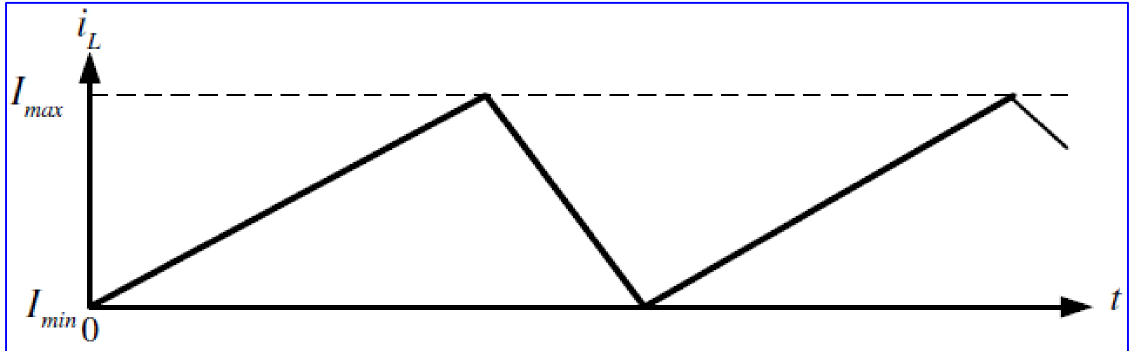
Inductor current ripple :

$$\Delta i_L = I_{\max} - I_{\min}$$



For constant V_o and variable V_{in}

$$\left(\frac{V_o}{V_{in,max}}\right) \le D \le \left(\frac{V_o}{V_{in,min}}\right)$$



From previous analysis,

$$I_{\min} = I_L - \frac{\Delta i_L}{2} = V_o\left(\frac{1}{R} - \frac{(1-D)}{2Lf}\right)$$

For continuous operation, $I_{\min} \ge 0$,

$$V_o\left(\frac{1}{R} - \frac{(1-D)}{2Lf}\right) \ge 0$$

$$\Rightarrow L \ge L_{\min} = \frac{(1-D)}{2f} \cdot R$$

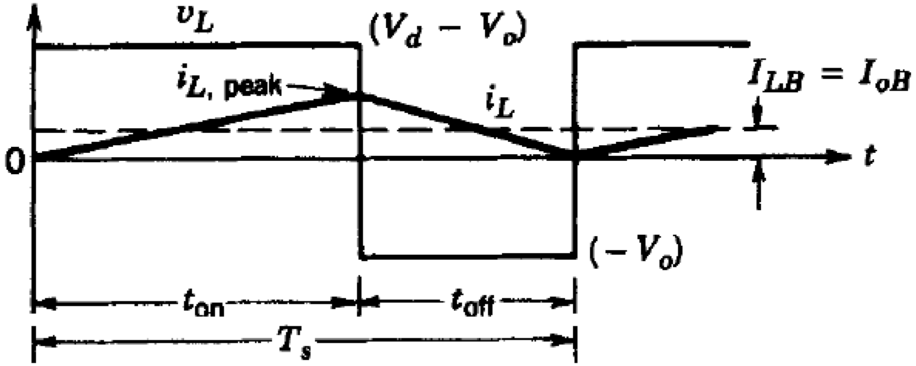
At the boundary,

***Rcritical* = ??**

This is the minimum inductor current to ensure continous mode of operation.

Normally L is chosen b be $>> L_{\min}$

BOUNDARY BETWEEN CONTINUOUS AND DISCONTINUOUS CONDUCTION



$$I_{max} = I_L + \frac{\Delta i_L}{2}$$

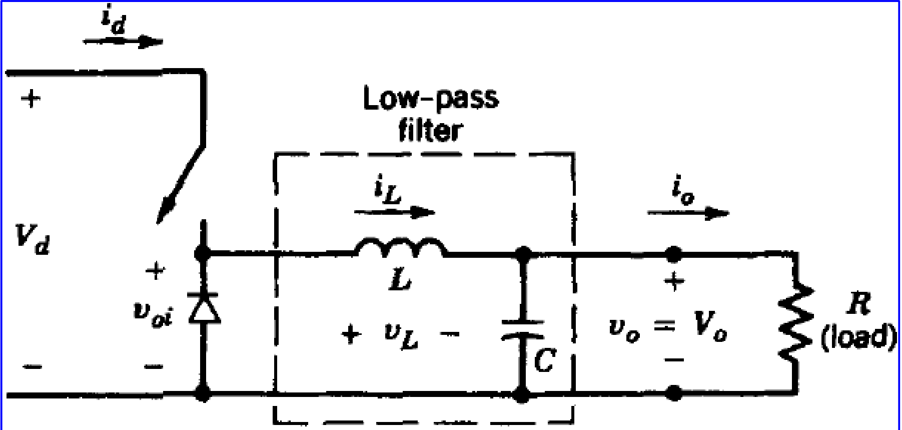
$$I_{min} = I_L - \frac{\Delta i_L}{2}$$

$$(\Delta i_L)_{closed} = \left(\frac{V_d - V_o}{L}\right) \cdot DT$$

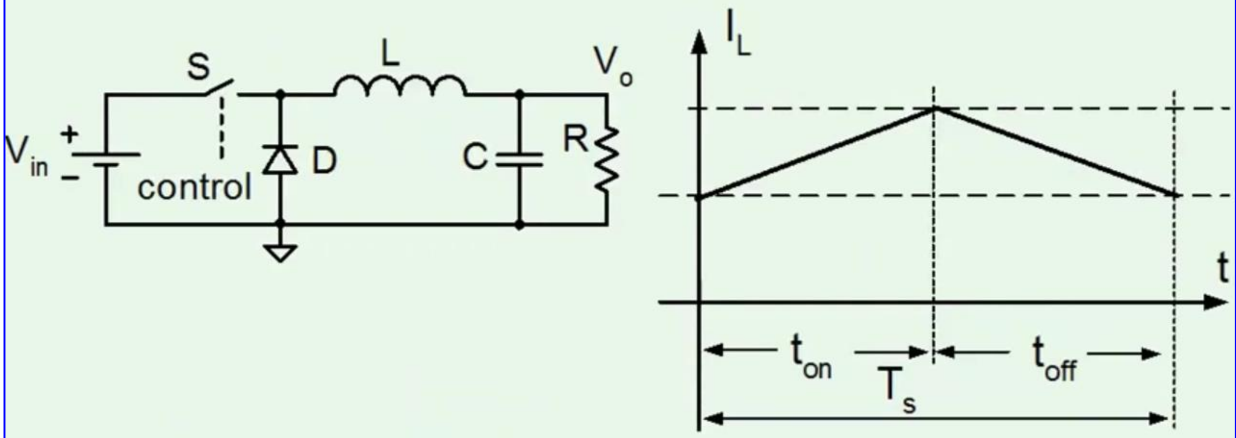
At the boundary, the average inductor current is

$$I_{LB} = \frac{1}{2} i_{L,\text{peak}} = \frac{t_{on}}{2L}(V_d - V_o) = \frac{DT_s}{2L}(V_d - V_o) = I_{oB}$$

Therefore, during an operating condition (with a given set of values for T_s, V_d, V_o, L, and D), if the average output current (and, hence, the average inductor current) becomes less than I_{LB}, then I_L will become discontinuous.

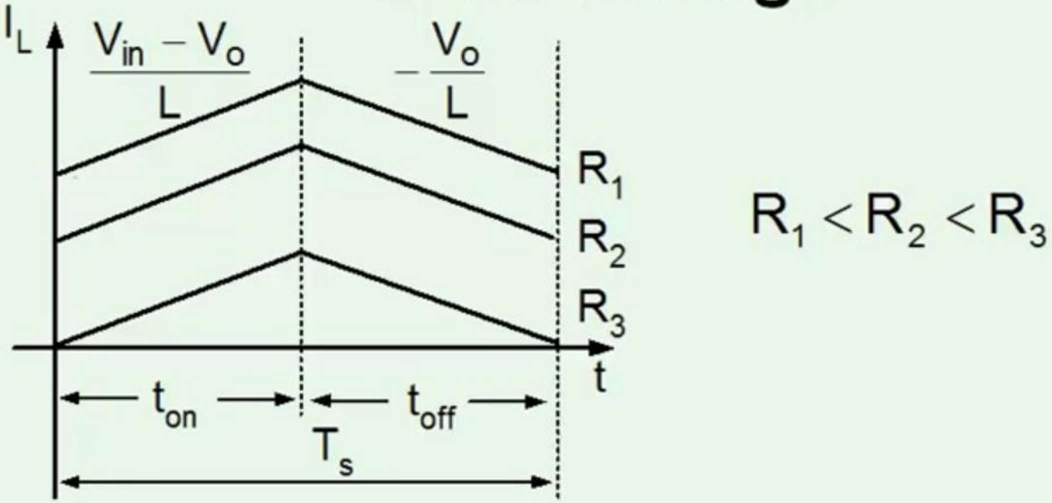


Load Change with Fixed D

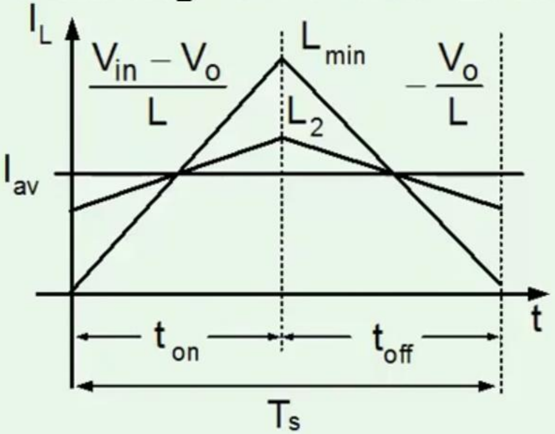


How will I_L change if R is getting smaller?

Load Change

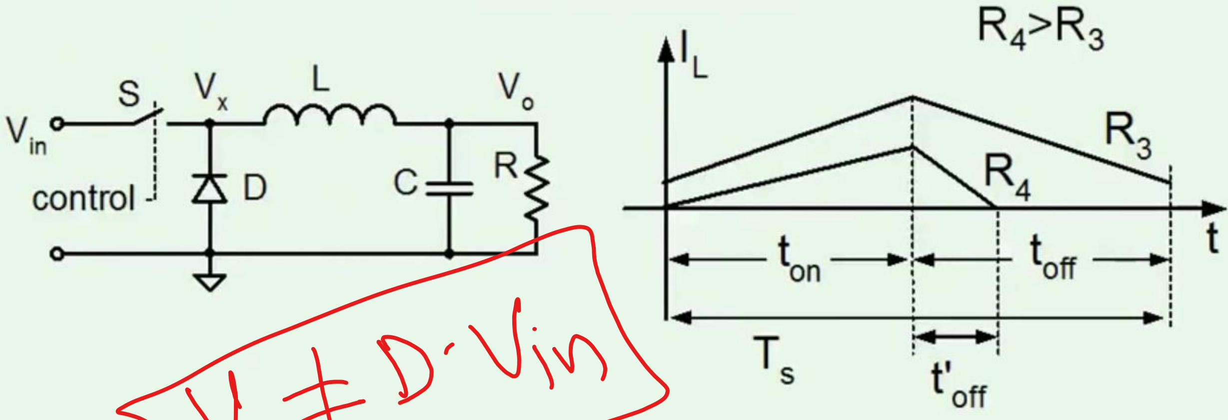


Boundary of CCM and DCM



- For CCM $\quad L > L_{min}$
- In Buck $\quad \frac{V_o}{L_{min}} t_{off} = I_{pk} = 2I_{av} \qquad L_{min} = \frac{V_o D_{off}}{2I_{av} f_s} = \frac{R D_{off}}{2f_s}$

Discontinuous Inductor Current Mode (DCM)



$\boxed{V_o \neq D \cdot V_{in}}$

- Different voltage transfer ratio $\neq D_{on}$
- Higher ripple current

STEP-DOWN (BUCK) CONVERTER

Depending on application, either V_d or V_0 remains constant.

Discontinuous-Conduction Mode with Constant *Vd*

In many applications (e.g., dc motor speed control), V_d remains constant and V_0 is controlled by adjusting *D.*

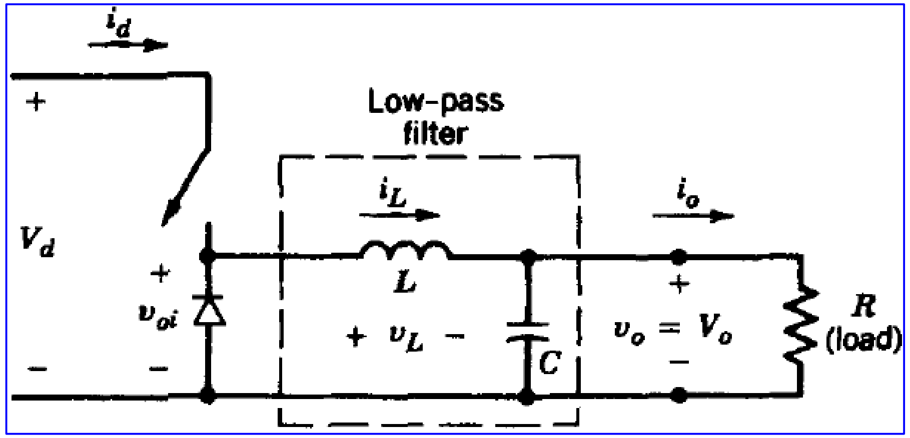
At the edge, $I_{LB} = \frac{DT_s}{2L}(V_d - V_o) = I_{oB}$ Since $V_0 = DV_d$, $I_{LB} = \frac{T_sV_d}{2L}D(1 - D)$

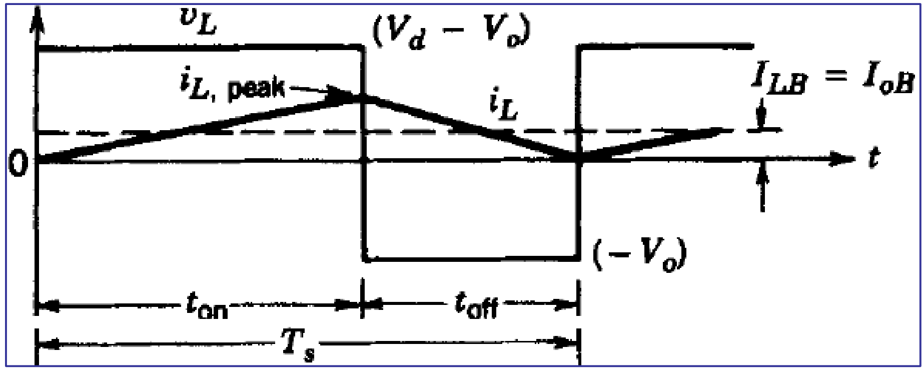
Output current required for CCM is maximum at D = 0.5:

$I_{LB,\max} = \frac{T_sV_d}{8L}$ => $I_{LB} = 4I_{LB,\max}D(1 - D)$

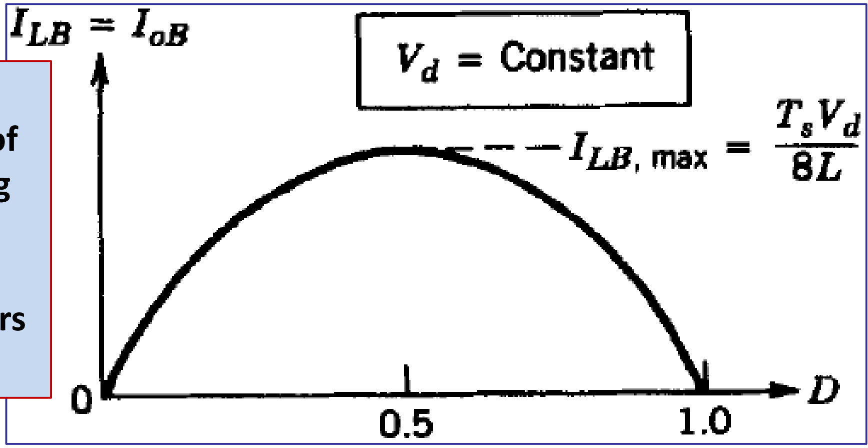
Assuming the converter is operating at the edge for given values of Ts L, *Vd* , and *D.* If these are kept constant and the output load power is decreased (i.e., the load resistance goes up), then the average inductor current will decrease.

Discontinuous-Conduction Mode





I_{LB} as a function of *D,* keeping V_d and all other parameters constant.

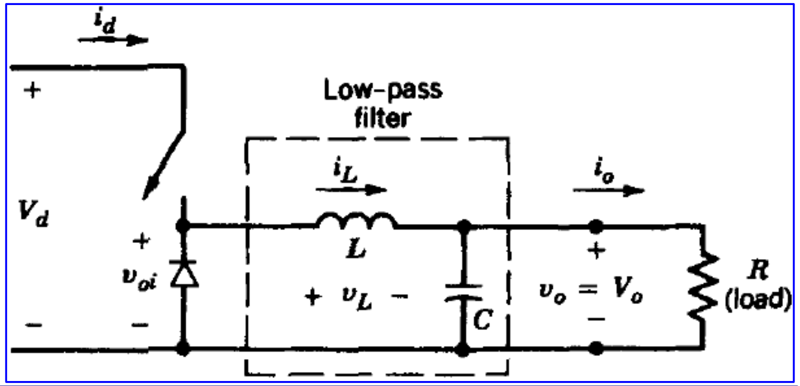


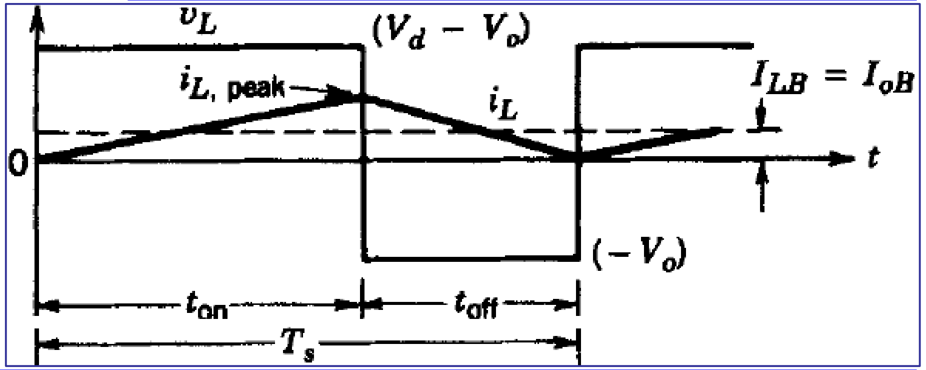
STEP-DOWN (BUCK) CONVERTER

Discontinuous-Conduction Mode

Assumption: converter is operating at the edge for given values of T, L, *Vd* , and *D,* which are kept constant
The output load power is decreased (i.e., the load resistance goes up), then the average inductor current will decrease.

During $\Delta_2 T_s$, power to R is supplied by C alone and *vL* is zero.



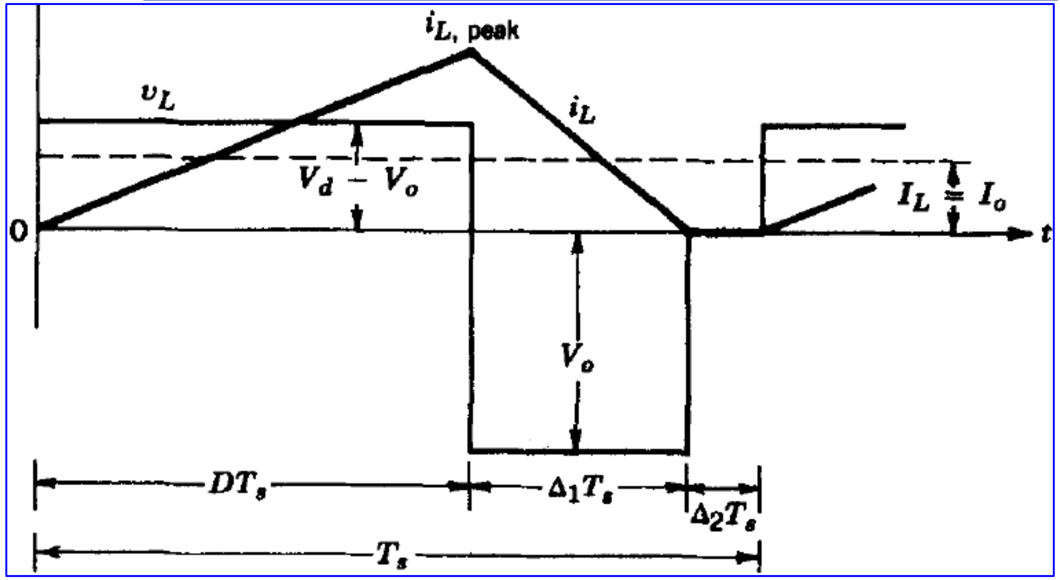


Again, equating the integral of *vL* over one time period to zero yields:

$$\boxed{(V_d - V_o)\, DT_s + (-V_o)\Delta_1 T_s = 0}$$

$$\boxed{\therefore \frac{V_o}{V_d} = \frac{D}{D + \Delta_1}}$$

$\boxed{\text{where } D + \Delta_1 < 1.0.}$



Hence, for same D, V0 in DCM > V0 in CCM.

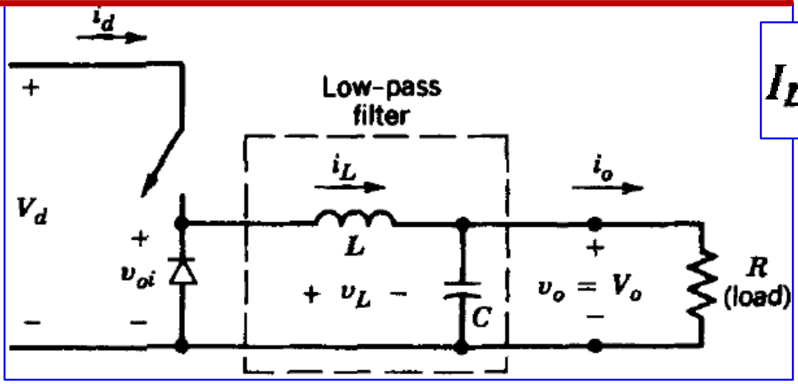
STEP-DOWN (BUCK) CONVERTER

Discontinuous-Conduction Mode

$$-v_0 = L\frac{di_L}{dt} \Rightarrow L\int_{i_{Lpeak}}^{0} di_L = -V_0\int_{0}^{\Delta_1 T_s} dt$$

$$\Rightarrow i_{Lpeak} = \frac{V_0}{L}\Delta_1 T_s$$

$$\therefore \frac{V_o}{V_d} = \frac{D}{D+\Delta_1}$$



$$I_{LB,\max} = \frac{T_s V_d}{8L}$$

$$I_o = i_{L,\text{peak}}\frac{D+\Delta_1}{2} = \frac{V_o T_s}{2L}(D+\Delta_1)\,\Delta_1$$

$$= \frac{V_d T_s}{2L}D\Delta_1 = 4I_{LB,\max}D\Delta_1 \qquad \therefore \Delta_1 = \frac{I_o}{4I_{LB,\max}D}$$

$$\therefore \frac{V_o}{V_d} = \frac{D}{D+\Delta_1} = \frac{D^2}{D^2 + \frac{1}{4}\left(I_o/I_{LB,\max}\right)}$$

The step-down converter characteristic in both modes of operation for a constant *Vd*. *V0/Vd* is plotted as a function of *I0/ILBmax* for various values of *D*. The boundary between CCM and DCM is shown by the dashed curve.