# EE 238

# Power Engineering - II

# Power Electronics

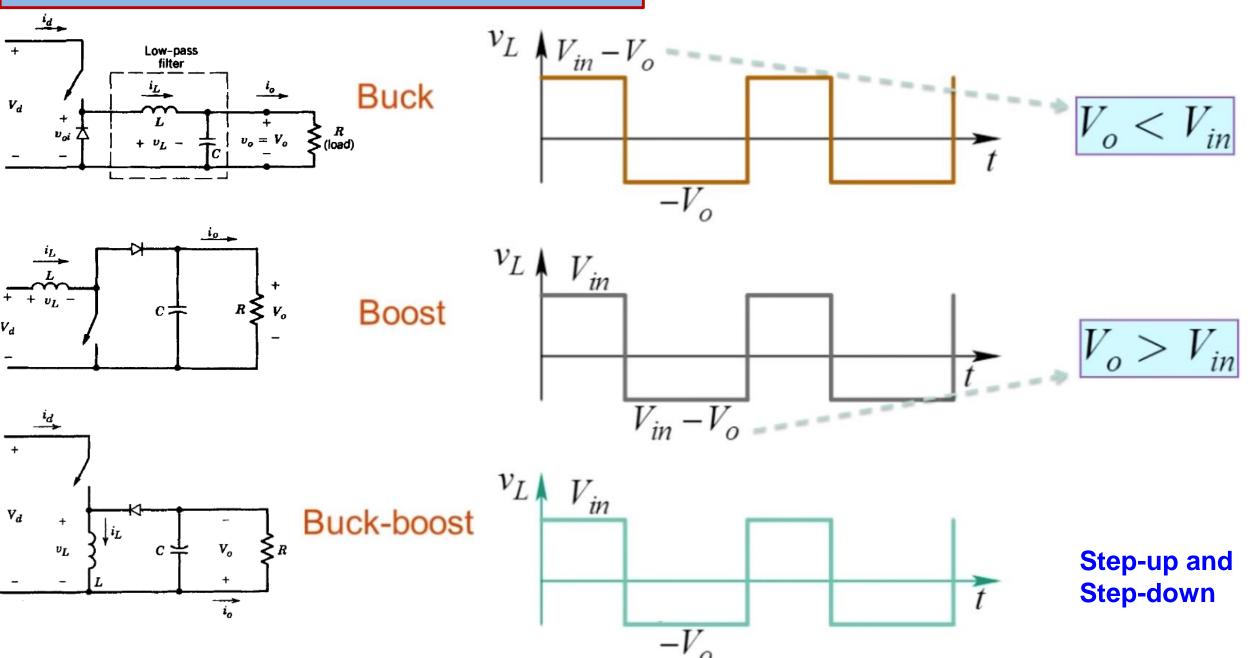


Lecture 13

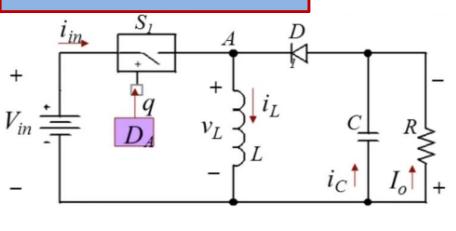
Instructor: Prof. Anshuman Shukla

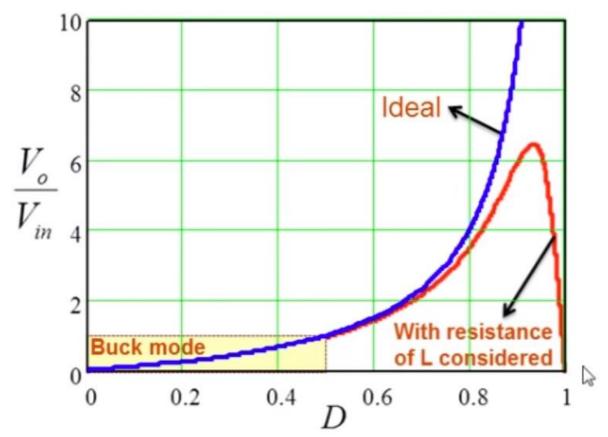
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# Comparison of v₁ in Buck, Boost and Buck-Boost



#### **Effect of non-idealities**



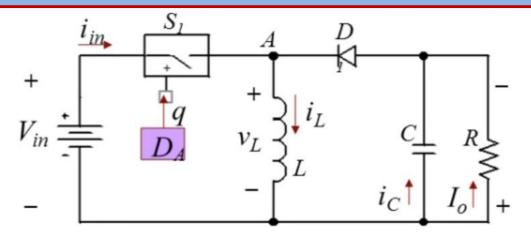


$$\frac{V_o}{V_{in}} = \frac{D}{1 - D}$$

Ideal input-output relationship

- Resistances of inductor and MOSFET, and voltage drop across diode affect voltage conversion ratio
- Effect is dominant at high D
- Difficult to achieve large conversion ratios ( > 10)
- No power transfer at D = 1

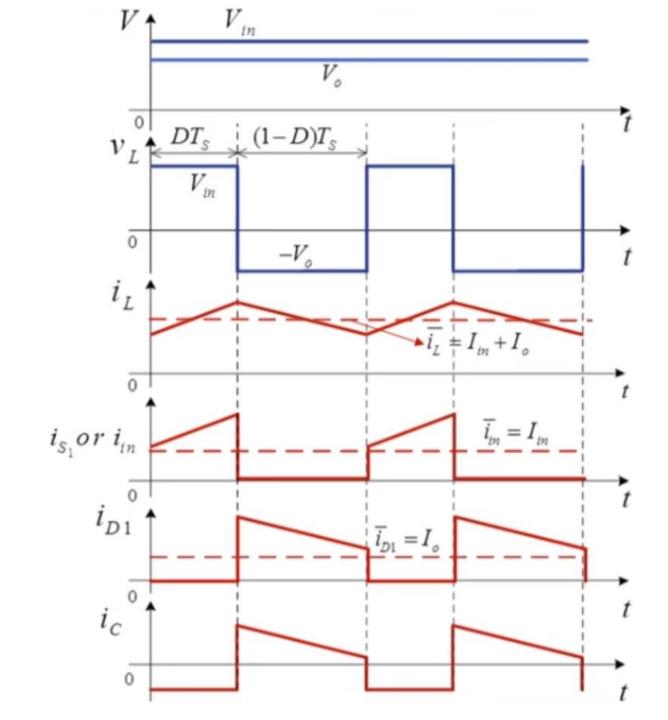
# **Buck-Boost Waveforms and Relationships**



$$\frac{V_o}{V_{in}} = \frac{D}{1 - D} \Rightarrow D = \frac{V_o}{V_o + V_{in}}$$

# For constant output voltage and variable input voltage applications

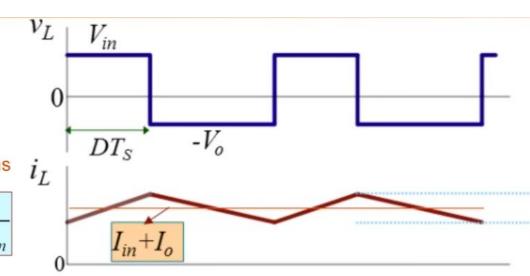
$$\frac{V_o}{V_o + V_{in,max}} \leq D \leq \frac{V_o}{V_o + V_{in,min}}$$

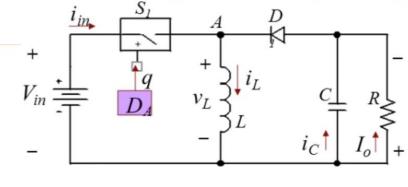


#### **Selection of L**

For constant output voltage and variable input voltage applications

$$\frac{V_o}{V_o + V_{in,max}} \leq D \leq \frac{V_o}{V_o + V_{in,min}}$$





Peak-peak ripple  $\Delta I_{\mathcal{L}}$  in inductor current

- L selected to limit peak-peak inductor current ripple to a chosen value
  - For example, 10-20% of max  $(I_{in} + I_o)$
  - CCM considerations
- ullet Worst-case condition is minimum D
- Choice of L does not significantly affect capacitor selection

# Consider the T<sub>OFF</sub> interval

$$L\frac{\Delta I_L}{(1-D)T_S} = V_o$$

$$L = \frac{V_o \left(1 - D\right) T_S}{\Delta I_L}$$

Assuming no power loss in the converter, power absorbed by the load must equal power supplied the by source, i.e.

$$P_o = P_s$$

$$\frac{V_o^2}{R} = V_d I_s$$

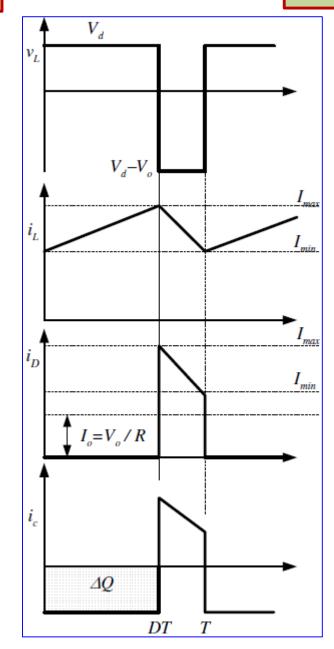
But average source current is related to average inductor current as:

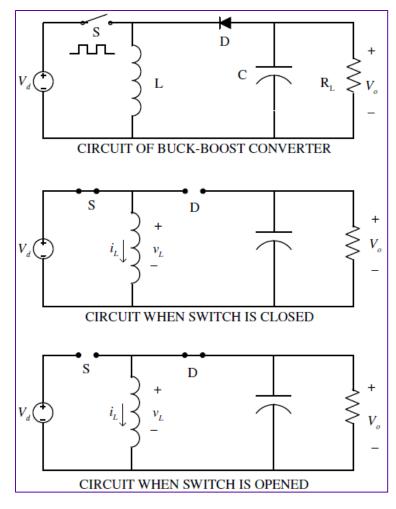
$$I_{s} = I_{L}D$$

$$\Rightarrow \frac{V_{o}^{2}}{R} = V_{d}I_{L}D$$

Substituting for 
$$V_o$$
,  

$$\Rightarrow I_L = \frac{V_o^2}{V_d RD} = \frac{P_o}{V_d D} = \frac{V_d D}{R(1-D)^2}$$





# **Buck-boost analysis**

Max and min inductor current,

$$\Rightarrow I_{\text{max}} = I_L + \frac{\Delta i_L}{2} = \frac{V_d D}{R(1-D)^2} + \frac{V_d DT}{2L}$$

$$\Rightarrow I_{\min} = I_L - \frac{\Delta i_L}{2} = \frac{V_d D}{R(1 - D)^2} - \frac{V_d DT}{2L}$$

For CCM  $\frac{V_{d}D}{R(1-D)^{2}} + \frac{V_{d}DT}{2L} = 0$   $\Rightarrow L_{\min} = \frac{(1-D)^{2}R}{2f}$ 

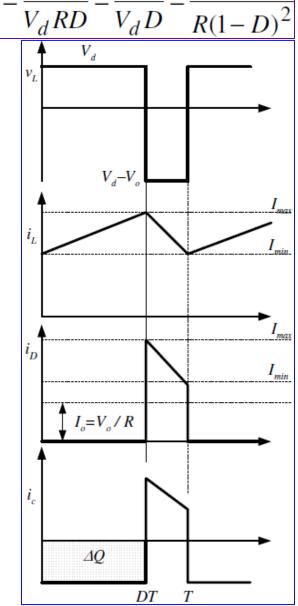
For constant output voltage and variable input voltage applications

$$\frac{V_o}{V_o + V_{in,max}} \leq D \leq \frac{V_o}{V_o + V_{in,min}}$$

#### L and C values

Substituting for  $V_o$ ,

$$\Rightarrow I_L = \frac{V_o^2}{V_d RD} = \frac{P_o}{V_d D} = \frac{V_d D}{R(1-D)^2}$$



## **Buck-boost analysis**

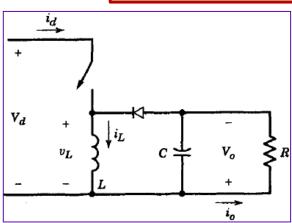
#### **Boundary between Cont. and Discont. Conduction**

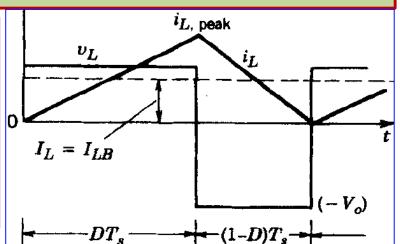
$$I_{LB} = \frac{1}{2} i_{L,\text{peak}} = \frac{T_s V_d}{2L} D$$

$$I_L = I_L - I_L$$

Since the average capacitor current is zero.

$$\frac{V_o}{V_d} = \frac{D}{1 - D} \frac{I_o}{I_d} = \frac{1 - D}{D}$$





The average inductor current and the output current at the border of the continuous and

conduction in terms of 
$$V_{0}$$
,  $I_{LB} = \frac{T_s V_o}{2L} (1 - D)$ 

$$I_{oB} = \frac{T_s V_o}{2L} (1 - D)^2$$

Most applications in which a buck-boost converter may be used require that V<sub>0</sub> be kept constant, though  $V_d$  (and, hence, D) may vary.

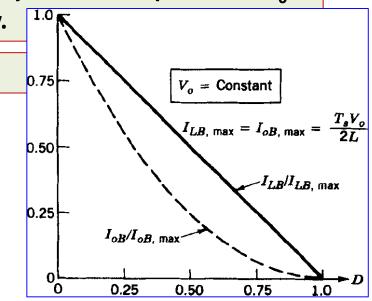
Both  $I_{1B}$  and  $I_{0B}$  result in their maximum values at D=0.

$$I_{LB,\max} = \frac{T_s V_o}{2L}$$
 and  $I_{oB,\max} = \frac{T_s V_o}{2L}$ 

$$I_{LB} = I_{LB,\max}(1-D) \quad I_{oB} = I_{oB}$$

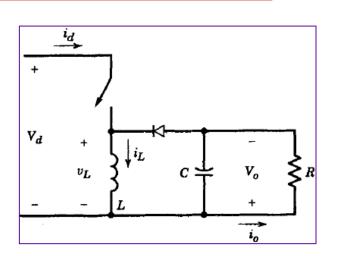
$$I_{oB} = I_{oB,\max}(1-D)^2$$

Figure shows ILB and IoB as a function of D, keeping V0 = const.



## **Buck-boost analysis**

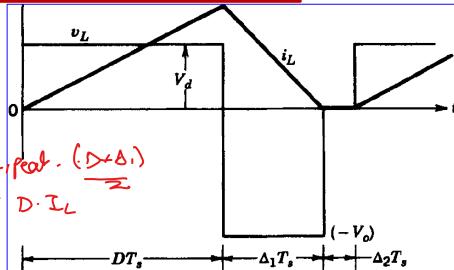
#### **DISCONTINUOUS-CONDUCTION MODE**



If we equate the integral of the inductor voltage over one time period to zero,

$$\begin{aligned} & V_d D T_s + (-V_o) \Delta_1 T_s = 0 \\ & \text{and} \quad \frac{I_o}{I_d} = \frac{\Delta_1}{D} \quad (\text{since } P_d = P_o) \\ & \text{From Fig.} I_L = \frac{V_d}{2L} \, D T_s (D + \Delta_1) \end{aligned}$$

From Fig. 
$$I_L = \frac{V_d}{2L} DT_s (D + \Delta_1)$$

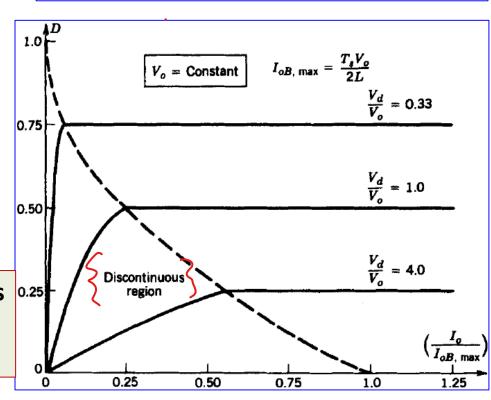


Since  $V_0$  is kept constant, it is useful to obtain D as a function of the output load current  $I_0$  for various values of  $V_0/V_d$ .

Using the equations derived earlier, we find that

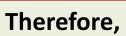
$$D = \frac{V_o}{V_d} \sqrt{\frac{I_o}{I_{oB,\text{max}}}} \frac{I_o = I_L - I_d}{I_o}$$

Figure shows the plot of D as a function of  $I_0/I_{0B,max}$  for various 0.25 values of Vd/V0. The boundary between the continuous and the discontinuous mode is shown by the dashed curve.



## **OUTPUT VOLTAGE RIPPLE**

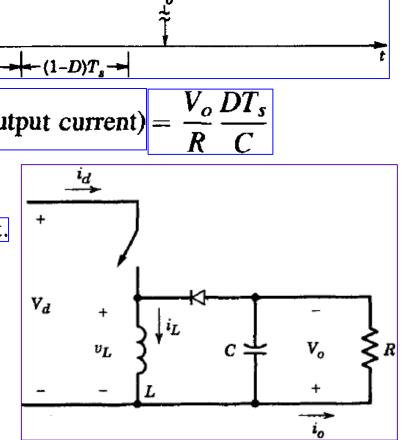
Assuming that all the ripple current component of  $i_D$  flows through the capacitor and its average value flows through the load resistor, the shaded area represents charge  $\Delta Q$ .



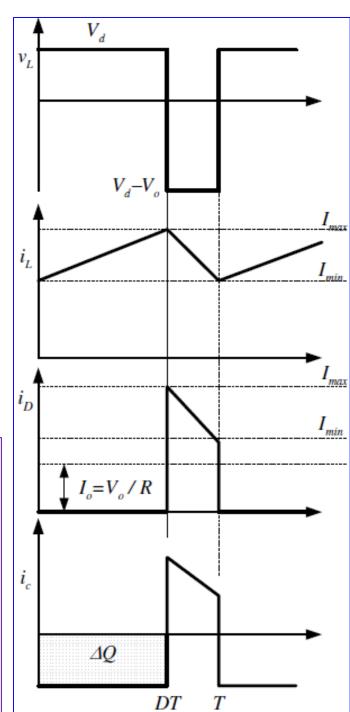
$$\overline{\Delta V_o = \frac{\Delta Q}{C}} = \frac{I_o D T_s}{C}$$
 (assuming a constant output current) =  $\frac{V_o}{R} \frac{D T_s}{C}$ 

$$\frac{\Delta V_o}{V_o} = \frac{DT_s}{RC} = D\frac{T_s}{\tau}$$
 where  $\tau = RC$  time constant.

A similar analysis can be performed for the discontinuous mode of operation.

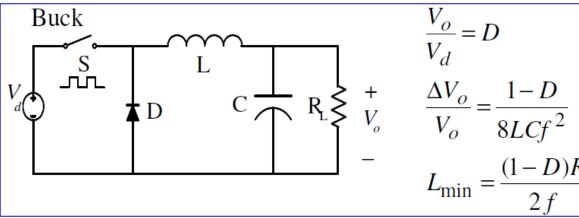


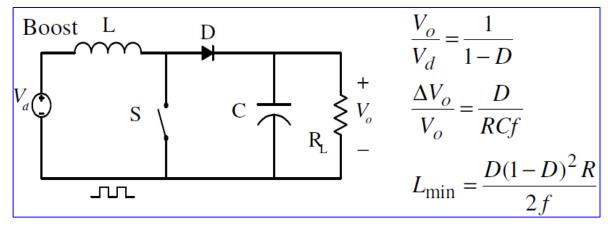
 $I_D = I_o$ 

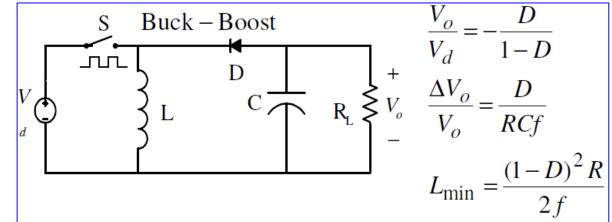


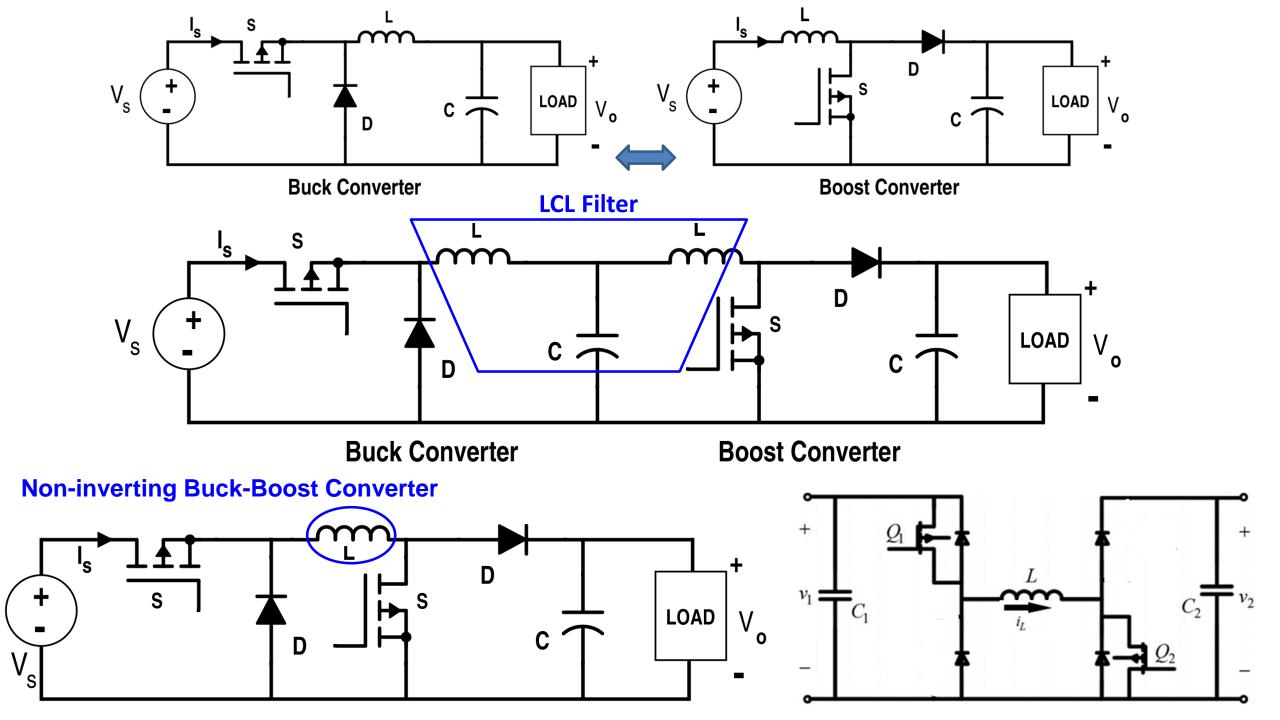
## **Converters in CCM: Summary**

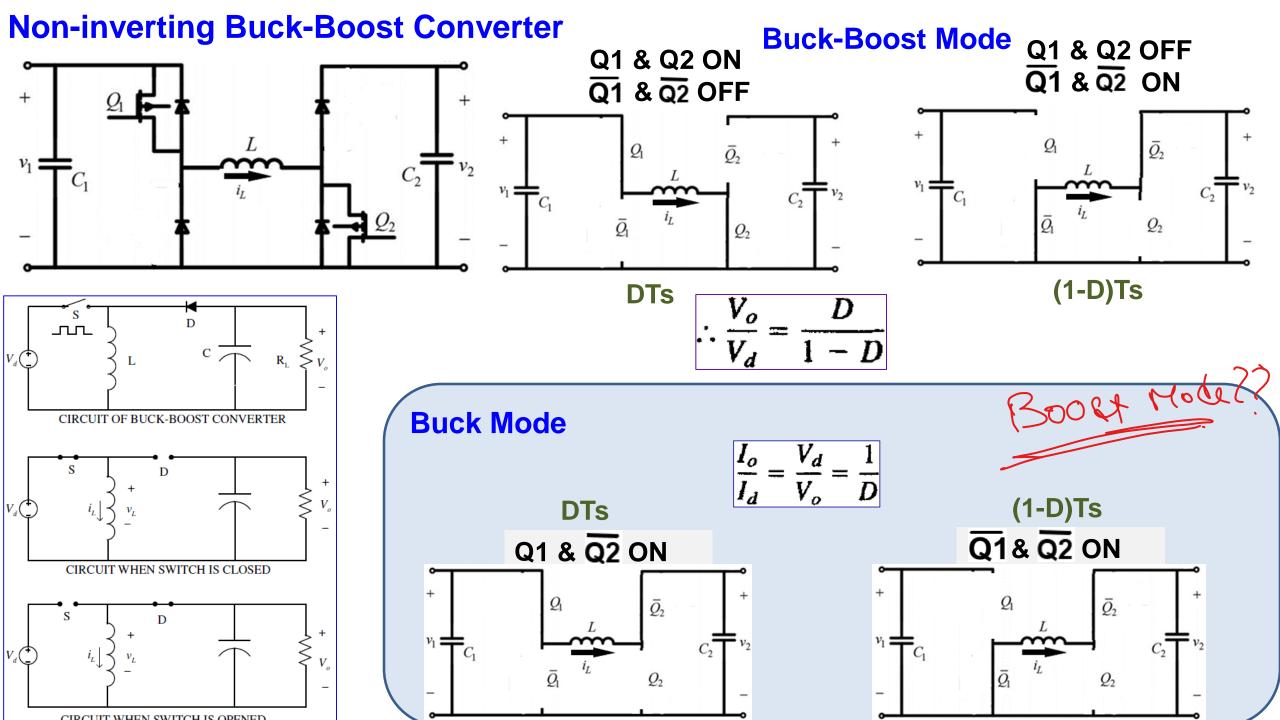












# **Inverters**

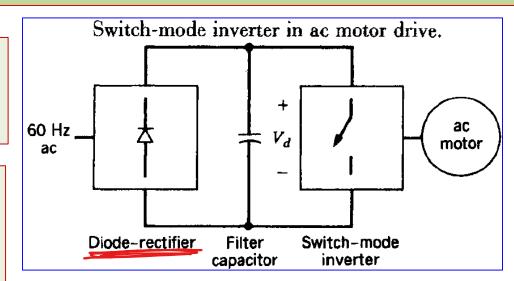
# Converting dc to ac

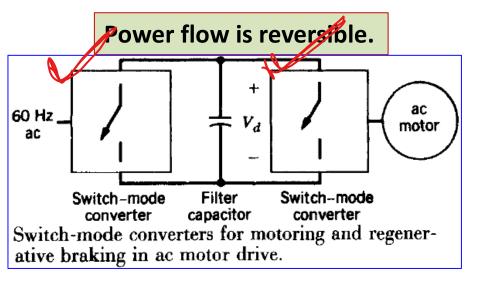
- Inverters convert dc power into ac power at desired output voltage and frequency.
- Applications: variable frequency ac drives, induction heating, standby aircraft, UPS, HVDC, FACTS, and custom power devices, etc.

The voltage at the machine terminals is desired to be sinusoidal and adjustable in its magnitude and frequency. This is accomplished by means of the switch-mode dc-to-ac inverter.

To slow down the ac motor, the kinetic energy associated with the inertia of the motor and its load is recovered and the ac motor acts as a generator. During the so-called braking of the motor, the power flows from the ac side to the dc side of the switch-mode converter and it operates in a rectifier mode.

Regenerative braking may be performed where the energy recovered from the motor load inertia is fed back to the utility grid.



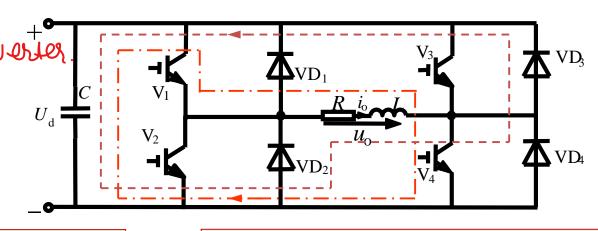


## **Inverters Classification**

VSI > Voltage Source Inc

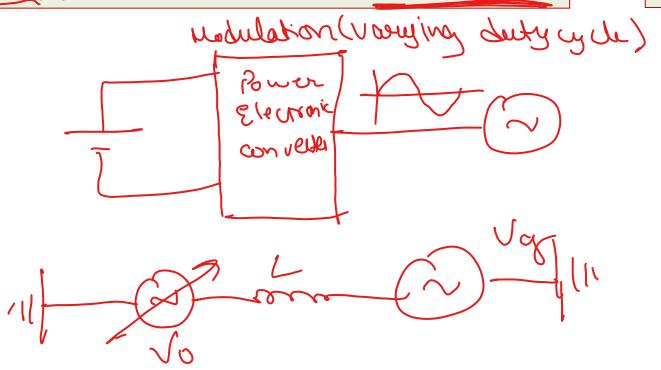
Most commonly used topology.

The input is from a dc source and the ac output functions as a voltage source.



The input dc voltage may be from the rectified output of an ac power supply, in which case it is called a 'dc link' inverter.

Alternatively, the input dc may be from an independent source such as a battery.



Not to