

EE 238

Power Engineering - II

Power Electronics



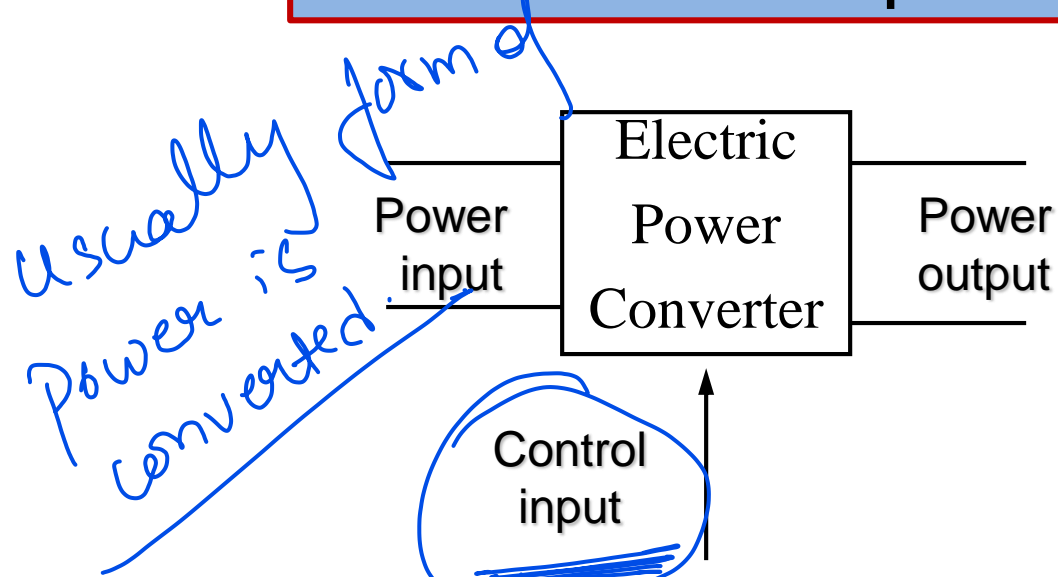
Lecture 2

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Conversion of electric power

Power Electronics Converters



Other names for electric power converter:

- Power converter
- Converter
- Switching converter
- Power electronic circuit
- Power electronic converter

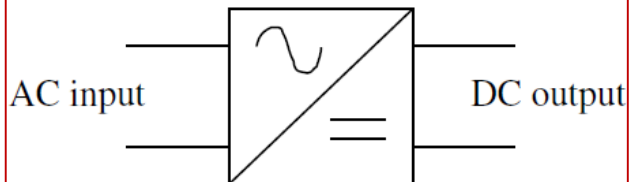
eg: In IM we can control voltage & freq. to change the rotor speed.

Two types of electric power		Changeable properties in conversion	
DC(Direct Current)		Magnitude	
AC (Alternating Current)		Frequency, magnitude, <u>number of phases</u>	

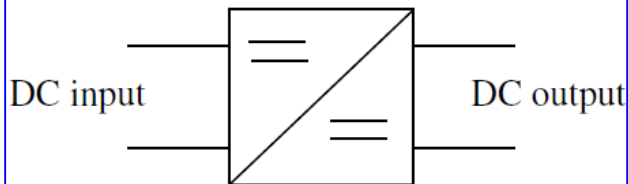
Classification of power converters

Power input \ Power output	DC	AC
	DC	AC
AC	AC to DC converter (<u>Rectifier</u>)	AC to AC converter (Fixed frequency : <u>AC controller</u> Variable frequency: <u>Cycloconverter</u> or <u>frequency converter</u>)
DC	DC to DC converter (<u>Chopper</u>)	DC to AC converter (<u>Inverter</u>)

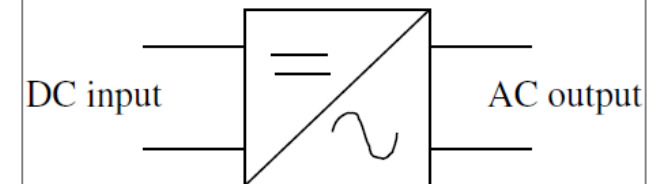
AC to DC: RECTIFIER



DC to DC: CHOPPER

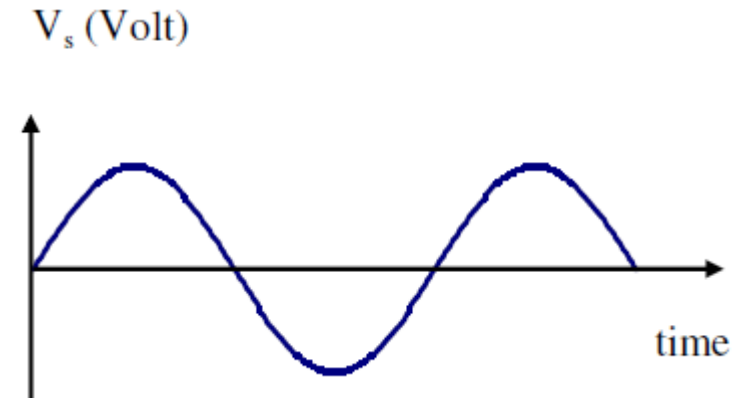


DC to AC: INVERTER

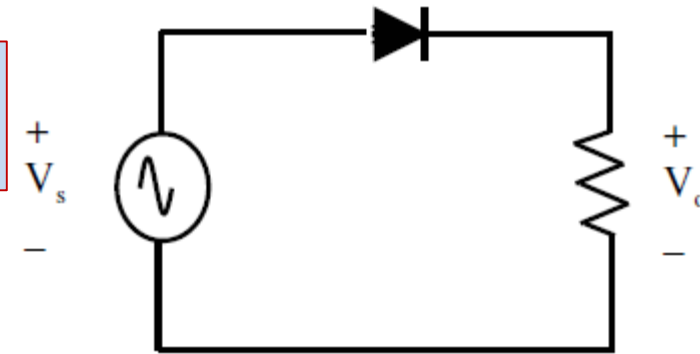


Power Conversion concept: example #1

- Supply: 50Hz, 240V RMS (340V peak).
Customer needs DC voltage for welding purpose, say.
- The sine-wave supply gives zero DC component!

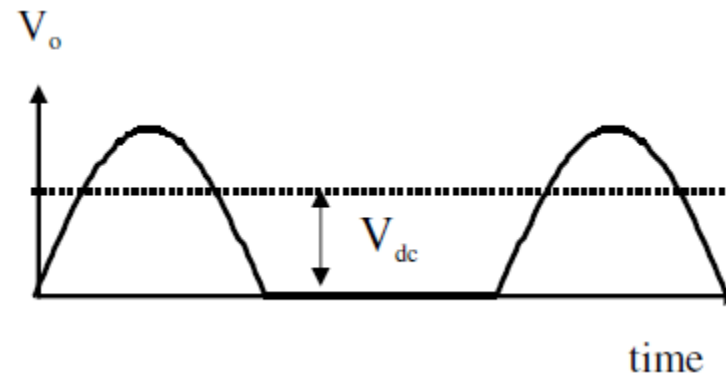


- We can use simple half-wave rectifier. A fixed DC voltage is now obtained. This is a simple PE system.



Average output voltage :

$$V_o = \frac{V_m}{\pi}$$



Conversion Concept

How if customer wants variable DC voltage?

More complex circuit using SCR is required.

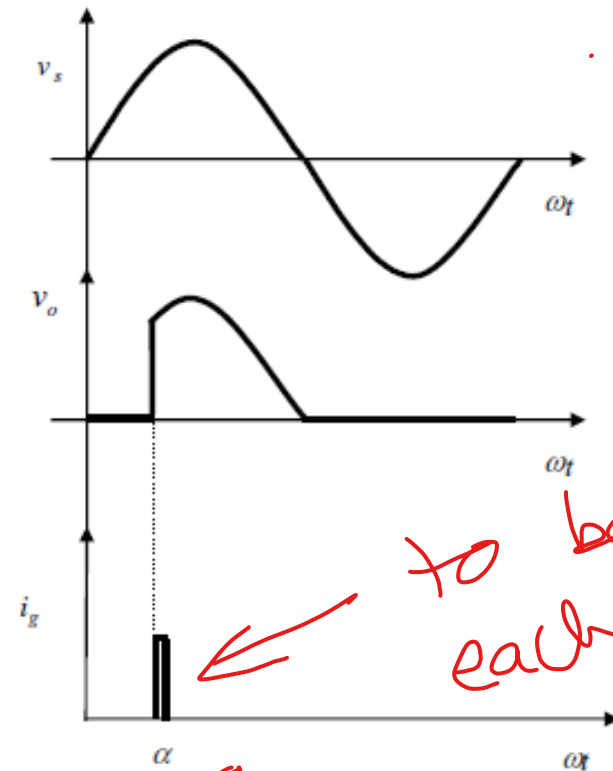
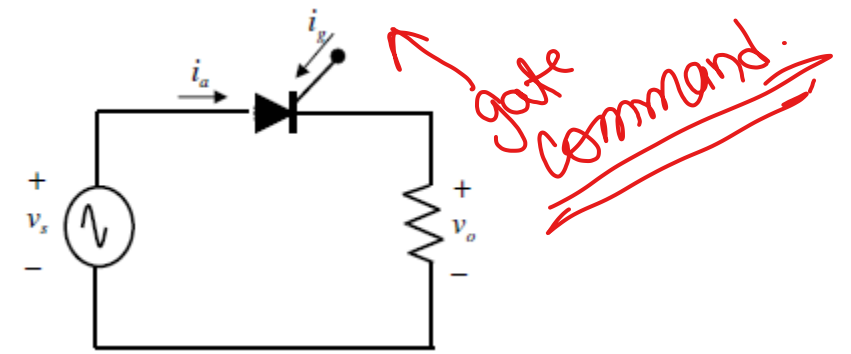
SCR: Silicon Controlled Rectifier
Thyristor.

Average output voltage :

$$V_o = \frac{1}{2\pi} \int_{\alpha}^{\pi} V_m \sin(\omega t) d\omega t = \frac{V_m}{2\pi} [1 + \cos \alpha]$$

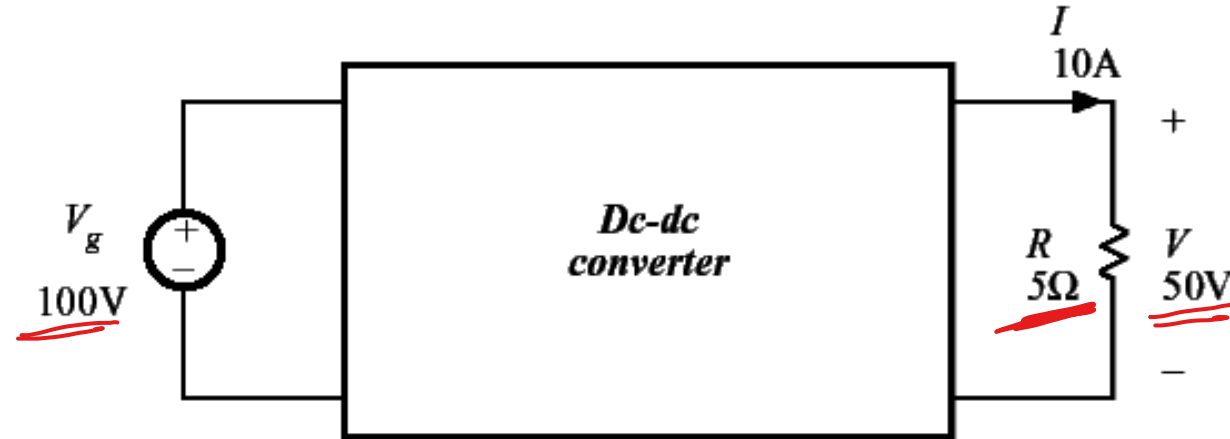
By controlling the firing angle, α , the output DC voltage (after conversion) can be varied.

Obviously this needs a complicated electronic system to set the firing current pulses for the SCR.



A simple example #2

A dc-dc converter example



Input source: 100V

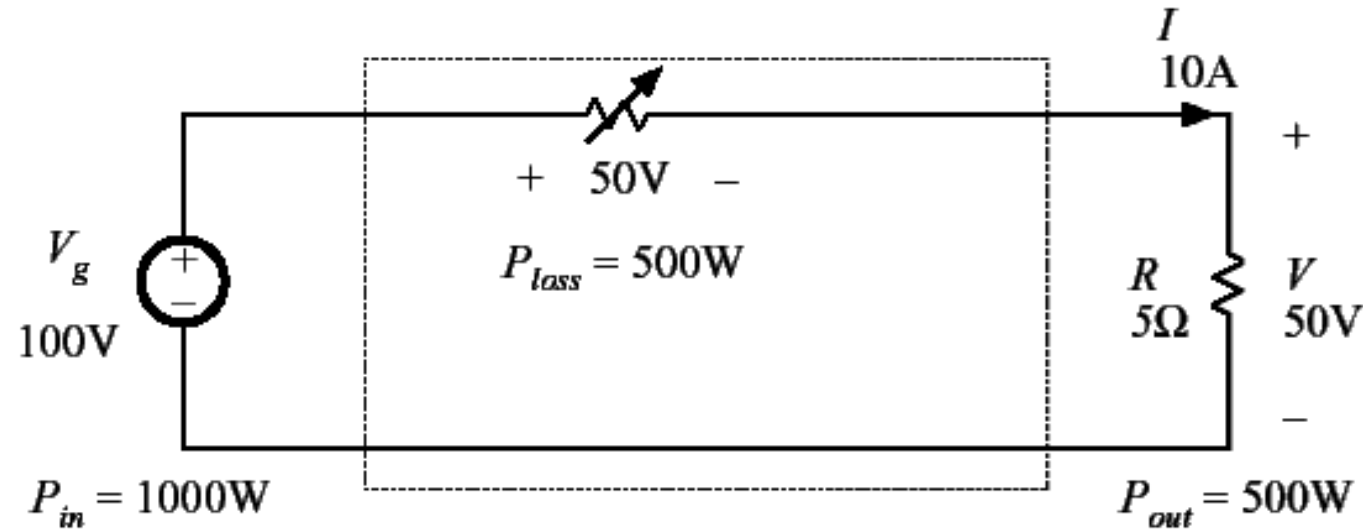
Output load: 50V, 10A, 500W

How can this converter be realized?

Dissipative realization

- Resistive voltage divider

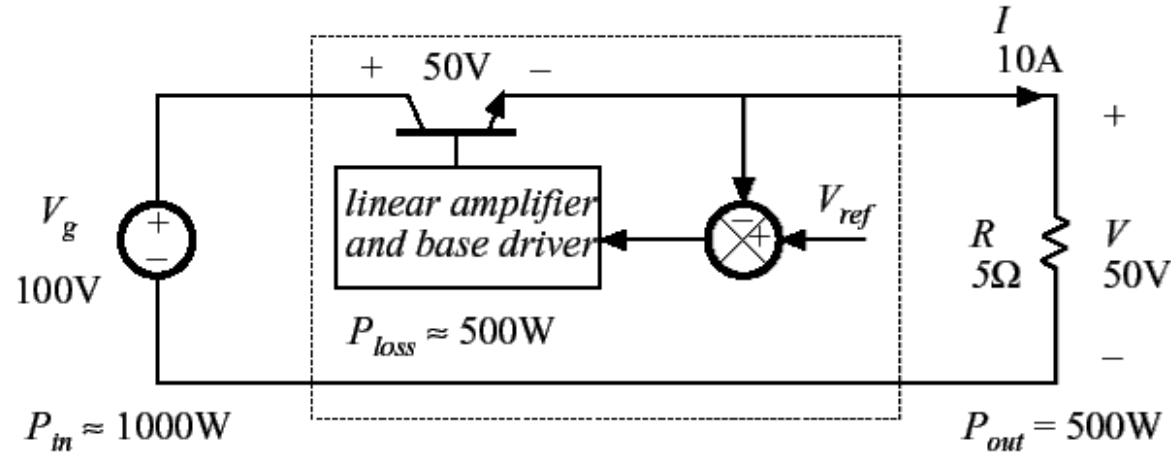
500W power loss



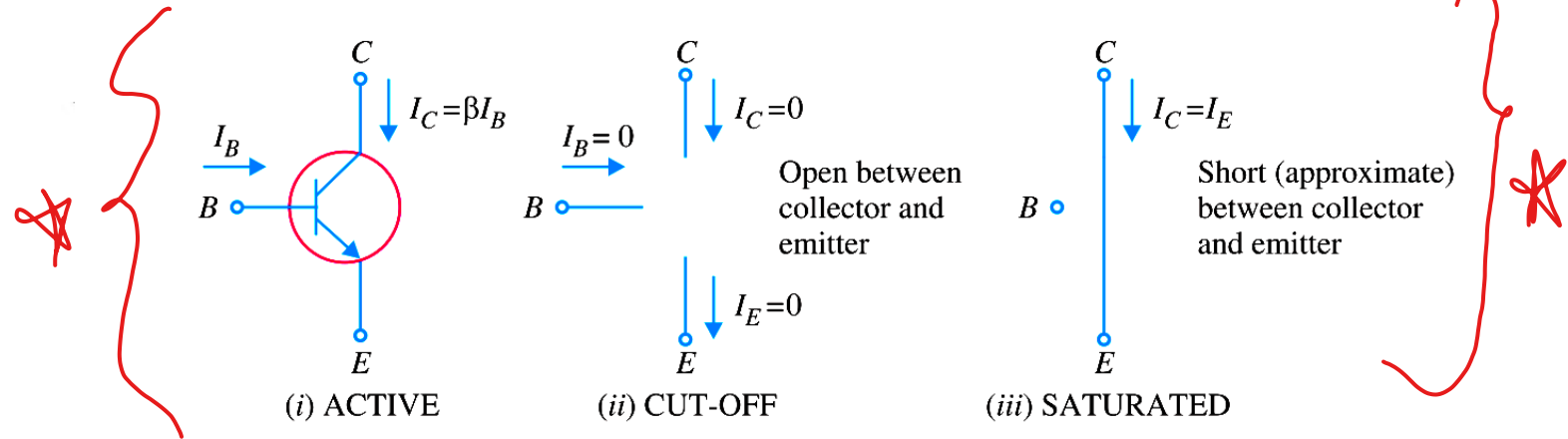
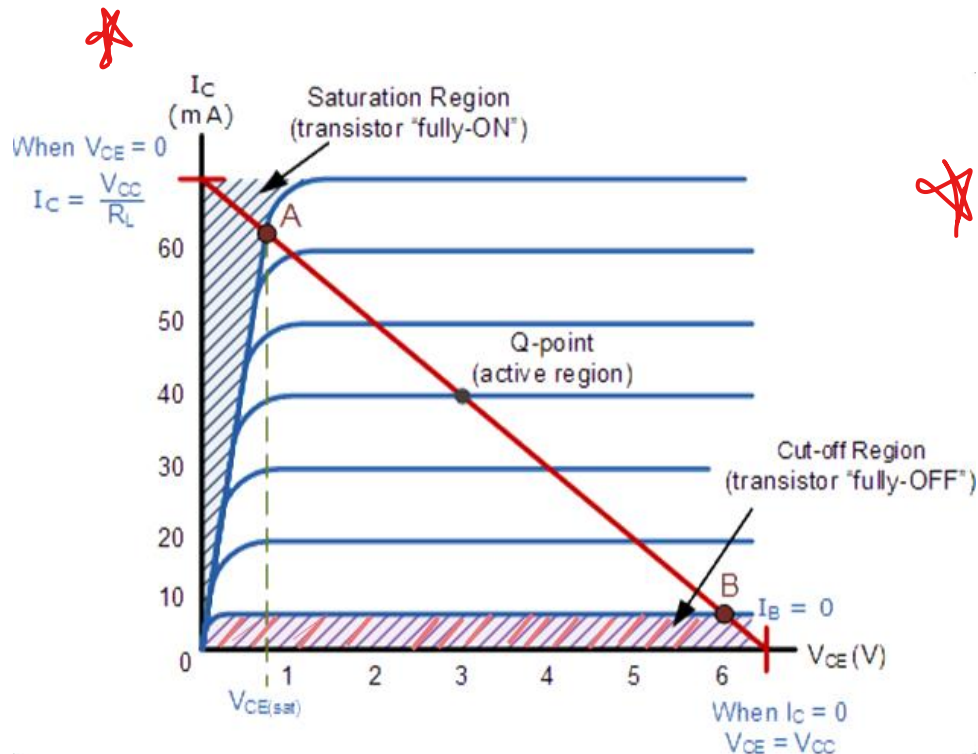
Dissipative realization

The transistor is controlled to absorb the voltage difference between V_g and V , thus providing a regulated output. The transistor operates in its active region as an adjustable output.

- Transistor operates in active region



ripples possible.

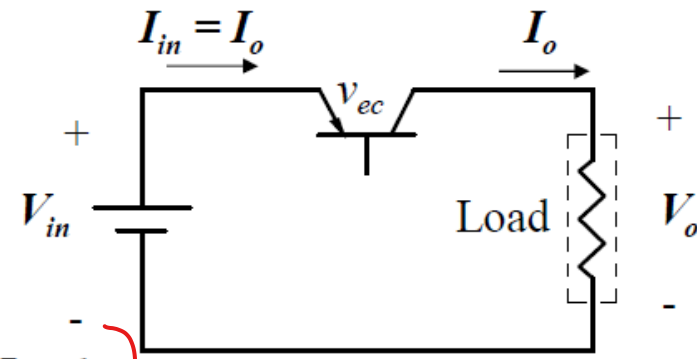


- ✓ Excellent regulation, control
- ✓ Low noise, ripple at the output

Problems with linear electronics approach

** Power density*

Input voltage : 10V to 14V DC
Output voltage : 5V DC +/- 0.1%
Output current : 1A max.

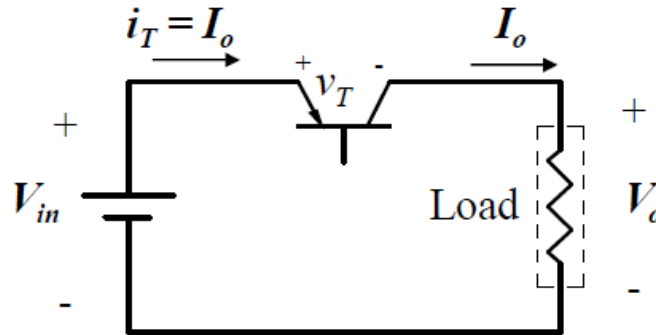


$$\left\{ \text{Efficiency} = \frac{P_o}{P_{in}} = \frac{V_o I_o}{V_{in} I_{in}} = \frac{5 \times 1}{14 \times 1} \right\} \text{diff. example}$$

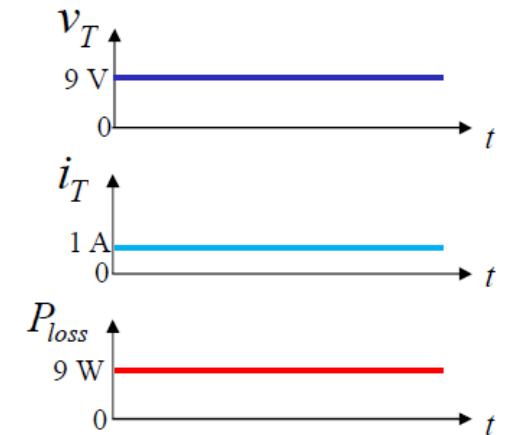
$$= 35.7\%$$

Power lost in transistor = $v_T I_o$

$$= (14 - 5) \times 1 = 9W$$

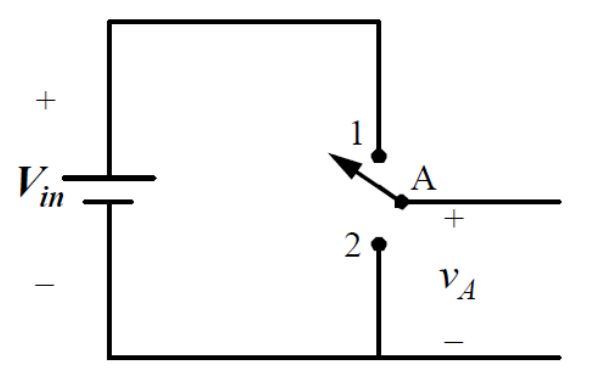


- ↓ Need for large heatsinks / thermal management
- ↓ Impact on power density

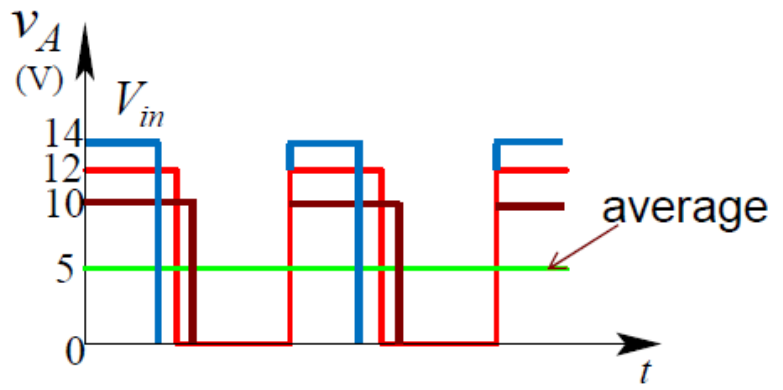


Use of a SPDT switch

Switch mode approach
Uses a bi-positional switch

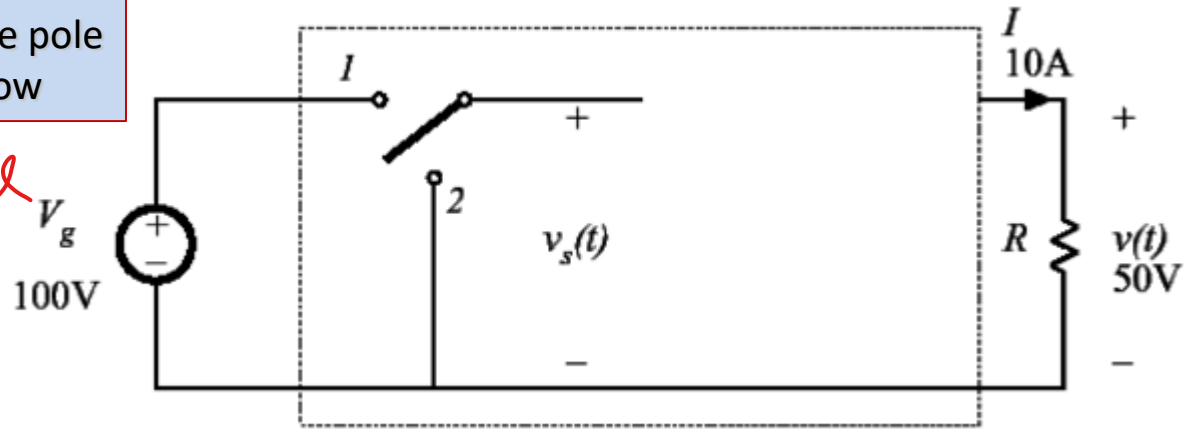


Switch in position 1 $\Rightarrow v_A = V_{in}$
Switch in position 2 $\Rightarrow v_A = 0$



SPDT: Single pole double throw

SPDT: Single Pole Double Throw



✓ By controlling the duration of ON interval (time when switch is in Position 1), the **average** output can be continuously controlled.

$v_s(t)$

V_g

0

$V_s = DV_g$

DT_s

$(1-D)T_s$

t

switch position: 1 2 1

$D = \text{switch duty cycle}$
 $0 \leq D \leq 1$

$T_s = \text{switching period}$

$f_s = \text{switching frequency}$
 $= 1 / T_s$

DC component of $v_s(t)$ = average value:

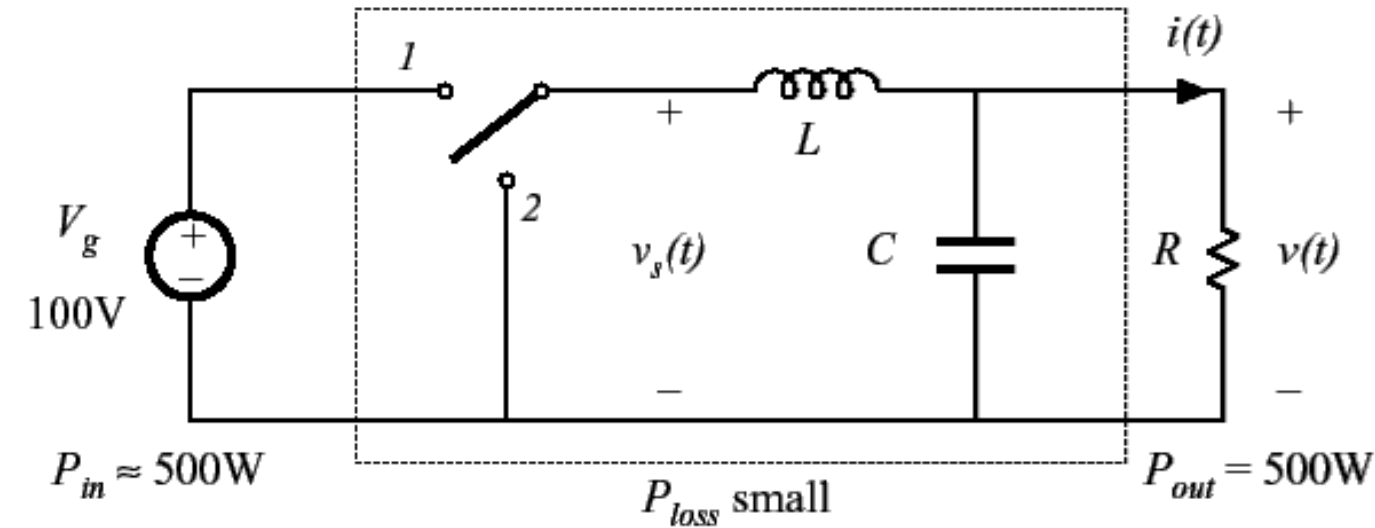
$V_s = \frac{1}{T_s} \int_0^{T_s} v_s(t) dt = DV_g$

The switch changes the dc voltage level

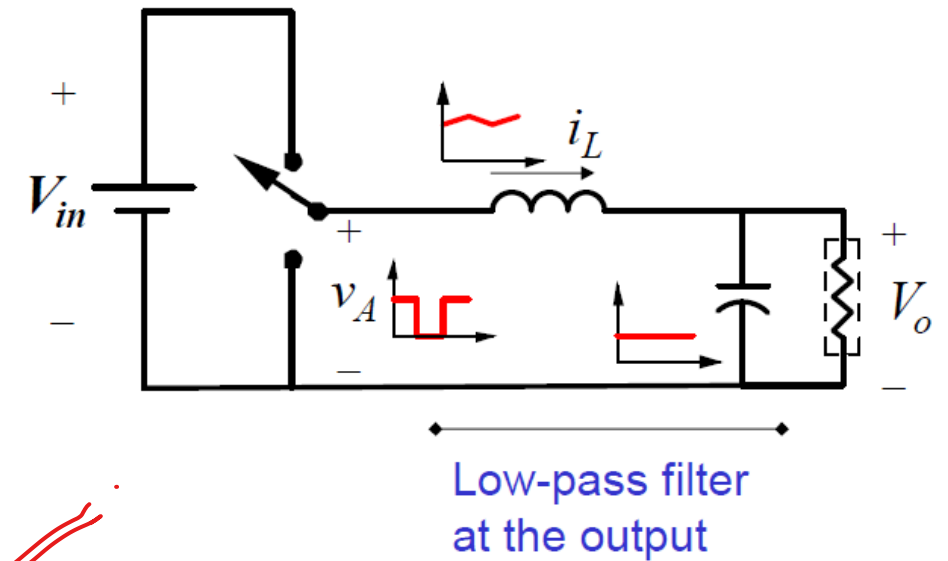
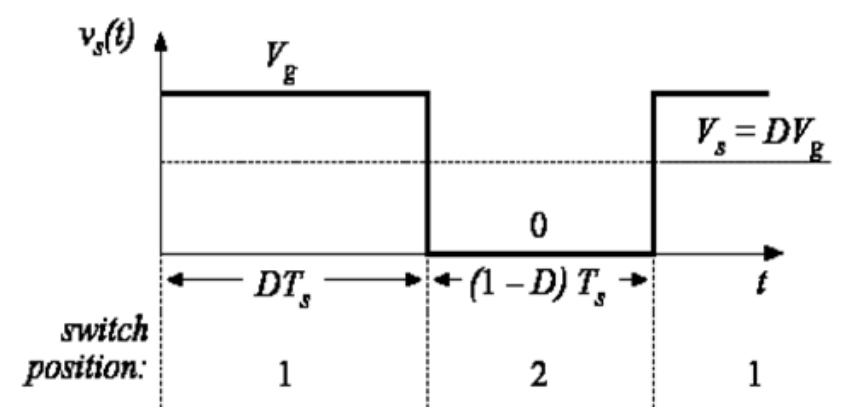
Simple step-down converter

Addition of low pass filter

Addition of (ideally lossless) L-C low-pass filter, for removal of switching harmonics:



- Choose filter cutoff frequency f_0 much smaller than switching frequency f_s
- This circuit is known as the “buck converter”



- High frequency content in v_A filtered using LC filter
- Filter size and cost very small with high frequency