CHIRAG MALHOTRA

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Education

Northeastern University

Boston, MA

Masters of Science in Computer Science, GPA: 3.92

{Expected} May 2025

• Relevant Courses: Machine Learning, Database Management Systems, Object Oriented Design, Data Structures and Algorithms, Foundations of software Engineering, Large Scale Parallel Data Processing

Technical Skills

Languages: Java, Python, C, C++, SQL, JavaScript, HTML/CSS, DLang, Scala, ROS1

Frameworks/Architectures: Pytorch, Tensorflow, DWSA, GLoVe, ResNet, Unet, YOLO, AWS, Hadoop, Apache Spark **Concepts**: PPO, prototype learning, feature extraction, Q-learning, LLMs, fine tuning, model evaluations **Libraries**: pandas, NumPy, Matplotlib, seaborn, spacy, stablebaseline 3, ML agents, QLora, Lora

Experience

CivicAI Lab Boston,MA

Research Assistant | Python, Poetry, React, Node js, Pandas, Numpy

January 2025 – present

- Working towards a ICCV paper banchmarking VLMs instruction following abilities.
- Utilizing GCP's Vertex AI and Lambda labs to generate responses on Nvidia A100 in parallel using multi-threadding.

International Panel on the Information Environment (IPIE)

Remote

Gen AI engineer | Python, Poetry, React, Redux, JS, Django, kmeans, Dashboard

January 2025 – present

- Building GenAI based dashboard to cluster and analyze affiliate data at IPIE to help guide talent acquisition.
- Developing and deploying the **containerized** dashboard with **React and Redux** on frontend and **Django** for the backend.

Northeastern University Boston, MA

Graduate Teaching Assistant | Reinforcement Learning & OOD | Python, Q-learning, Java, OOPs

Jan 2023 - present

• Improved student performance in Object-Oriented Design and reinforcement learning by organizing tutoring sessions, grading assignments, leading to a combined 12% improvement in course outcomes.

Graduate Research Assistant | Python, Docker, Spacy, DWSA, GLoVe, ResNet

June 2023 – Nov 2023

May 2024 - August 2024

- Applied temporal for video data and contextual embeddings for text to achieve **over 5** % **improvement** to model accuracy.
- Utilized DWSA architecture with soft-ordered prototype learning and Spacy to map video and text features effectively.

myRide Boston, MA

Machine Learning Engineer Co-op — Advanced RAG, ROS1, AWS, Python, C++, TensorFlow August 2024 – December 2024

- Developed perception and path planning systems for a self-driving car using ROS1, roscco and OpenCV.
- Implemented digital control of vehicle systems, leveraging OSCC (Open Source Car Control) for core functionality
- Designed a cloud-based language model on AWS to serve as the central intelligence system for autonomous decision-making

LightBird AI

Boston,MA

GenAI Engineer Co-op | python, LLMs, spacy, NLP, prompt engineering

- Fine-Tuned BERTopic Model to improve accuracy by 20 % for domains as well as the clients.
- Implemented intent engine powered by domain expert model allowed reduce on-boarding time by 17%.
- Conducted quantitative and qualitative evaluations, ensuring models met enterprise safety and reliability standards.

Projects

2D Unet for semantic segmentation | Ongoing

• Building a **2D Unet from scratch**, implementing all the important components and comparing it with **segmentation_models_2D's Unet** architecture for **microscopy** application.

Diffusion Gif Generator https://github.com/chiragml/Diffusion-Gif-Generator

- Built a diffusion-based image-to-video generator, cutting GIF generation time from **40 to 9 minutes** with **CPU offloading**, memory and attention optimization.
- Achieved 77% runtime reduction using adaptive pruning (30%) with sensitivity analysis, maintaining high-quality output.

6 Degrees of Separation https://github.com/chiragml/6DegreesOfSeperation

- Designed and built a **Spark** application to parse and traverse a **900 Billion** edges graph from twitter indicating social network.
- Applied Dijkstra's algorithm to the graph in parallel and found out the optimal cluster configuration on AWS EMR and S3.
- Used **RDDs** to handle and distribute **2gb csv(stored as .txt)** data over **8, 10 and 12 nodes** for comparative analysis.