

```
import torch
from torchvision import datasets, transforms, models # datasets , transforms
from torch.utils.data.sampler import SubsetRandomSampler
import torch.nn as nn
import torch.nn.functional as F
from datetime import datetime
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
```

```
import shutil
```

```
transform = transforms.Compose([transforms.Resize(255), transforms.CenterCrop(224), transforms.ToTensor()])
```

```
dataset = datasets.ImageFolder("/content/drive/MyDrive/plant/Plant_leave_diseases_dataset_with_augmentation", transform=tr
```

```
dataset
```

```
Dataset ImageFolder
  Number of datapoints: 61486
  Root location: /content/drive/MyDrive/plant/Plant_leave_diseases_dataset_with_augmentation
  StandardTransform
  Transform: Compose(
    Resize(size=255, interpolation=bilinear, max_size=None, antialias=warn)
    CenterCrop(size=(224, 224))
    ToTensor()
  )
```

```
indices = list(range(len(dataset)))
```

```
split = int(np.floor(0.85 * len(dataset)))
```

```
validation = int(np.floor(0.70 * split))
```

```
print(0, validation, split, len(dataset))
```

```
0 36584 52263 61486
```

```
print(f"length of train size :{validation}")
print(f"length of validation size :{split - validation}")
print(f"length of test size :{len(dataset)-validation}")
```

```
length of train size :36584
length of validation size :15679
length of test size :24902
```

```
np.random.shuffle(indices)
```

```
train_indices, validation_indices, test_indices = (
    indices[:validation],
    indices[validation:split],
    indices[split:],
)
```

```
train_sampler = SubsetRandomSampler(train_indices)
validation_sampler = SubsetRandomSampler(validation_indices)
test_sampler = SubsetRandomSampler(test_indices)
```

```
targets_size = len(dataset.class_to_idx)
```

Convolution Aithmetic Equation : $(W - F + 2P) / S + 1$

W = Input Size

F = Filter Size

P = Padding Size

S = Stride

```

class CNN(nn.Module):
    def __init__(self, K):
        super(CNN, self).__init__()
        self.conv_layers = nn.Sequential(
            # conv1
            nn.Conv2d(in_channels=3, out_channels=32, kernel_size=3, padding=1),
            nn.ReLU(),
            nn.BatchNorm2d(32),
            nn.Conv2d(in_channels=32, out_channels=32, kernel_size=3, padding=1),
            nn.ReLU(),
            nn.BatchNorm2d(32),
            nn.MaxPool2d(2),
            # conv2
            nn.Conv2d(in_channels=32, out_channels=64, kernel_size=3, padding=1),
            nn.ReLU(),
            nn.BatchNorm2d(64),
            nn.Conv2d(in_channels=64, out_channels=64, kernel_size=3, padding=1),
            nn.ReLU(),
            nn.BatchNorm2d(64),
            nn.MaxPool2d(2),
            # conv3
            nn.Conv2d(in_channels=64, out_channels=128, kernel_size=3, padding=1),
            nn.ReLU(),
            nn.BatchNorm2d(128),
            nn.Conv2d(in_channels=128, out_channels=128, kernel_size=3, padding=1),
            nn.ReLU(),
            nn.BatchNorm2d(128),
            nn.MaxPool2d(2),
            # conv4
            nn.Conv2d(in_channels=128, out_channels=256, kernel_size=3, padding=1),
            nn.ReLU(),
            nn.BatchNorm2d(256),
            nn.Conv2d(in_channels=256, out_channels=256, kernel_size=3, padding=1),
            nn.ReLU(),
            nn.BatchNorm2d(256),
            nn.MaxPool2d(2),
        )

        self.dense_layers = nn.Sequential(
            nn.Dropout(0.4),
            nn.Linear(50176, 1024),
            nn.ReLU(),
            nn.Dropout(0.4),
            nn.Linear(1024, K),
        )

    def forward(self, X):
        out = self.conv_layers(X)

        # Flatten
        out = out.view(-1, 50176)

        # Fully connected
        out = self.dense_layers(out)

        return out

```

```

device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
print(device)

```

```

cuda

```

```

device = "cuda"
model = CNN(targets_size)

```

```

model.to(device)

```

```

CNN(
  (conv_layers): Sequential(
    (0): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU()
    (2): BatchNorm2d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (3): Conv2d(32, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (4): ReLU()
    (5): BatchNorm2d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (6): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (7): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (8): ReLU()
    (9): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (10): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (11): ReLU()
    (12): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  )
)

```

```

(13): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
(14): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
(15): ReLU()
(16): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(17): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
(18): ReLU()
(19): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(20): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
(21): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
(22): ReLU()
(23): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(24): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
(25): ReLU()
(26): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(27): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
)
(dense_layers): Sequential(
  (0): Dropout(p=0.4, inplace=False)
  (1): Linear(in_features=50176, out_features=1024, bias=True)
  (2): ReLU()
  (3): Dropout(p=0.4, inplace=False)
  (4): Linear(in_features=1024, out_features=39, bias=True)
)
)

```

```
from torchsummary import summary
```

```
summary(model, (3, 224, 224))
```

```

-----
Layer (type)          Output Shape          Param #
-----
Conv2d-1              [-1, 32, 224, 224]    896
ReLU-2                [-1, 32, 224, 224]    0
BatchNorm2d-3         [-1, 32, 224, 224]    64
Conv2d-4              [-1, 32, 224, 224]    9,248
ReLU-5               [-1, 32, 224, 224]    0
BatchNorm2d-6         [-1, 32, 224, 224]    64
MaxPool2d-7           [-1, 32, 112, 112]    0
Conv2d-8              [-1, 64, 112, 112]    18,496
ReLU-9               [-1, 64, 112, 112]    0
BatchNorm2d-10        [-1, 64, 112, 112]    128
Conv2d-11             [-1, 64, 112, 112]    36,928
ReLU-12              [-1, 64, 112, 112]    0
BatchNorm2d-13        [-1, 64, 112, 112]    128
MaxPool2d-14          [-1, 64, 56, 56]      0
Conv2d-15             [-1, 128, 56, 56]     73,856
ReLU-16              [-1, 128, 56, 56]     0
BatchNorm2d-17        [-1, 128, 56, 56]     256
Conv2d-18             [-1, 128, 56, 56]    147,584
ReLU-19              [-1, 128, 56, 56]     0
BatchNorm2d-20        [-1, 128, 56, 56]     256
MaxPool2d-21          [-1, 128, 28, 28]     0
Conv2d-22             [-1, 256, 28, 28]    295,168
ReLU-23              [-1, 256, 28, 28]     0
BatchNorm2d-24        [-1, 256, 28, 28]     512
Conv2d-25             [-1, 256, 28, 28]    590,080
ReLU-26              [-1, 256, 28, 28]     0
BatchNorm2d-27        [-1, 256, 28, 28]     512
MaxPool2d-28          [-1, 256, 14, 14]     0
Dropout-29            [-1, 50176]           0
Linear-30             [-1, 1024]            51,381,248
ReLU-31              [-1, 1024]            0
Dropout-32            [-1, 1024]            0
Linear-33             [-1, 39]              39,975
=====
Total params: 52,595,399
Trainable params: 52,595,399
Non-trainable params: 0
-----
Input size (MB): 0.57
Forward/backward pass size (MB): 143.96
Params size (MB): 200.64
Estimated Total Size (MB): 345.17
-----

```

```

criterion = nn.CrossEntropyLoss() # this include softmax + cross entropy loss
optimizer = torch.optim.Adam(model.parameters())

```

```

import numpy as np
from datetime import datetime # Import datetime module for time tracking

def batch_gd(model, criterion, train_loader, validation_loader, epochs, optimizer, device):
    train_losses = np.zeros(epochs)
    validation_losses = np.zeros(epochs) # Corrected variable name to match usage

```

```

for e in range(epochs):
    t0 = datetime.now()
    train_loss = []

    for inputs, targets in train_loader:
        inputs, targets = inputs.to(device), targets.to(device)

        optimizer.zero_grad()

        output = model(inputs)

        loss = criterion(output, targets)

        train_loss.append(loss.item())

    loss.backward()
    optimizer.step()

    train_loss = np.mean(train_loss)

    validation_loss = []

    for inputs, targets in validation_loader:
        inputs, targets = inputs.to(device), targets.to(device)

        output = model(inputs)

        loss = criterion(output, targets)

        validation_loss.append(loss.item())

    validation_loss = np.mean(validation_loss)

    train_losses[e] = train_loss
    validation_losses[e] = validation_loss # Corrected variable name to match usage

    dt = datetime.now() - t0

    print(
        f"Epoch : {e+1}/{epochs} Train_loss:{train_loss:.3f} Validation_loss:{validation_loss:.3f} Duration:{dt}"
    )

return train_losses, validation_losses # Corrected variable name to match usage

```

```
device = "cuda"
```

```

batch_size = 32
train_loader = torch.utils.data.DataLoader(
    dataset, batch_size=batch_size, sampler=train_sampler
)
test_loader = torch.utils.data.DataLoader(
    dataset, batch_size=batch_size, sampler=test_sampler
)
validation_loader = torch.utils.data.DataLoader(
    dataset, batch_size=batch_size, sampler=validation_sampler
)

```

```
torch.cuda.empty_cache()
```

```

train_losses, validation_losses = batch_gd(
    model, criterion, train_loader, validation_loader, 5, optimizer, device
)

```

```

Epoch : 1/5 Train_loss:1.570 Validation_loss:1.543 Duration:0:05:05.075720
Epoch : 2/5 Train_loss:1.321 Validation_loss:1.238 Duration:0:05:05.512447
Epoch : 3/5 Train_loss:1.103 Validation_loss:1.048 Duration:0:05:05.808788
Epoch : 4/5 Train_loss:0.921 Validation_loss:0.870 Duration:0:05:04.819274
Epoch : 5/5 Train_loss:0.731 Validation_loss:0.794 Duration:0:05:04.904237

```

```
torch.save(model.state_dict(), 'plant_disease_model_1.pt')
```

```

targets_size = 39
model = CNN(targets_size)
model.load_state_dict(torch.load("plant_disease_model_1.pt"))
model.eval()

```

```

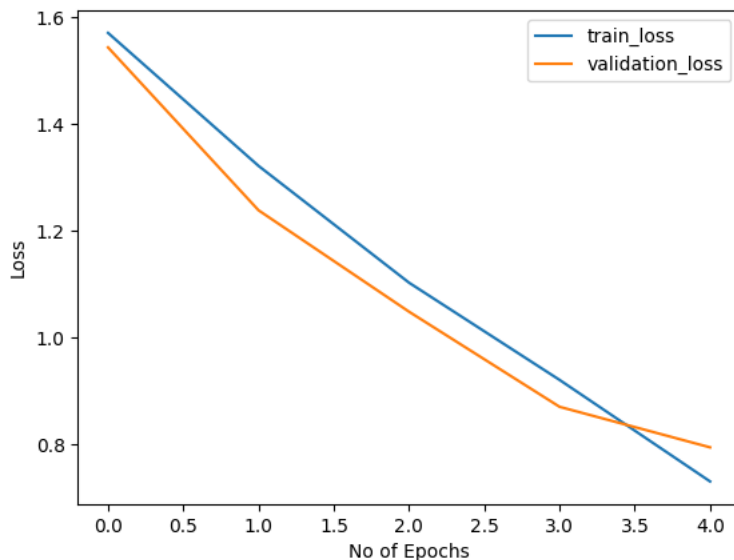
CNN(
  (conv_layers): Sequential(
    (0): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU()
    (2): BatchNorm2d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (3): Conv2d(32, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
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    (7): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (8): ReLU()
    (9): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (10): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
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    (13): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
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    (24): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (25): ReLU()
    (26): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (27): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  )
  (dense_layers): Sequential(
    (0): Dropout(p=0.4, inplace=False)
    (1): Linear(in_features=50176, out_features=1024, bias=True)
    (2): ReLU()
    (3): Dropout(p=0.4, inplace=False)
    (4): Linear(in_features=1024, out_features=39, bias=True)
  )
)

```

```

plt.plot(train_losses , label = 'train_loss')
plt.plot(validation_losses , label = 'validation_loss')
plt.xlabel('No of Epochs')
plt.ylabel('Loss')
plt.legend()
plt.show()

```



```

# Move the model to the GPU (if not already on the GPU)
model.to(device)

def accuracy(loader):
    n_correct = 0
    n_total = 0

    model.eval() # Set the model to evaluation mode

    with torch.no_grad(): # Disable gradient computation for inference
        for inputs, targets in loader:
            inputs, targets = inputs.to(device), targets.to(device)

```

```

        outputs = model(inputs)

        _, predictions = torch.max(outputs, 1)

        n_correct += (predictions == targets).sum().item()
        n_total += targets.shape[0]

    model.train() # Set the model back to training mode

    acc = n_correct / n_total
    return acc

# Now calculate accuracies for train, test, and validation loaders
train_acc = accuracy(train_loader)
test_acc = accuracy(test_loader)
validation_acc = accuracy(validation_loader)

print(
    f"Train Accuracy : {train_acc}\nTest Accuracy : {test_acc}\nValidation Accuracy : {validation_acc}"
)

Train Accuracy : 0.9075278810408922
Test Accuracy : 0.881491922367993
Validation Accuracy : 0.8718030486638179

```

```
transform_index_to_disease = dataset.class_to_idx
```

```

transform_index_to_disease = dict(
    [(value, key) for key, value in transform_index_to_disease.items()]
)

```

```

transform_index_to_disease
{0: 'Apple___Apple_scab',
 1: 'Apple___Black_rot',
 2: 'Apple___Cedar_apple_rust',
 3: 'Apple___healthy',
 4: 'Background_without_leaves',
 5: 'Blueberry___healthy',
 6: 'Cherry___Powdery_mildew',
 7: 'Cherry___healthy',
 8: 'Corn___Cercospora_leaf_spot Gray_leaf_spot',
 9: 'Corn___Common_rust',
10: 'Corn___Northern_Leaf_Blight',
11: 'Corn___healthy',
12: 'Grape___Black_rot',
13: 'Grape___Esca_(Black_Measles)',
14: 'Grape___Leaf_blight_(Isariopsis_Leaf_Spot)',
15: 'Grape___healthy',
16: 'Orange___Haunglongbing_(Citrus_greening)',
17: 'Peach___Bacterial_spot',
18: 'Peach___healthy',
19: 'Pepper,_bell___Bacterial_spot',
20: 'Pepper,_bell___healthy',
21: 'Potato___Early_blight',
22: 'Potato___Late_blight',
23: 'Potato___healthy',
24: 'Raspberry___healthy',
25: 'Soybean___healthy',
26: 'Squash___Powdery_mildew',
27: 'Strawberry___Leaf_scorch',
28: 'Strawberry___healthy',
29: 'Tomato___Bacterial_spot',
30: 'Tomato___Early_blight',
31: 'Tomato___Late_blight',
32: 'Tomato___Leaf_Mold',
33: 'Tomato___Septoria_leaf_spot',
34: 'Tomato___Spider_mites Two-spotted_spider_mite',
35: 'Tomato___Target_Spot',
36: 'Tomato___Tomato_Yellow_Leaf_Curl_Virus',
37: 'Tomato___Tomato_mosaic_virus',
38: 'Tomato___healthy'}

```

```

from PIL import Image
import torchvision.transforms as transforms
import matplotlib.pyplot as plt

def single_prediction(image_path, model, transform_index_to_disease, device):
    image = Image.open(image_path)
    image = image.resize((224, 224))

    # Use torchvision.transforms.ToTensor() to convert the image to a tensor

```

```

transform = transforms.Compose([transforms.ToTensor()])
input_data = transform(image)
input_data = input_data.view((-1, 3, 224, 224))

# Move the input data to the same device as the model
input_data = input_data.to(device)

output = model(input_data)
output = output.detach().cpu().numpy() # Move output to CPU for further processing
index = np.argmax(output)

print("Original : ", image_path[12:-4])
pred = transform_index_to_disease[index]

plt.imshow(image)
plt.title("Disease Prediction: " + pred)
plt.show()

# Example usage:
single_prediction("/content/drive/MyDrive/Plant_leave_diseases_dataset_with_augmentation/Apple___healthy/image_(1004).JPG")

```

Original : ve/MyDrive/Plant_leave_diseases_dataset_with_augmentation/Apple___healthy/image (1004)

Disease Prediction: Tomato___Tomato_Yellow_Leaf_Curl_Virus

