

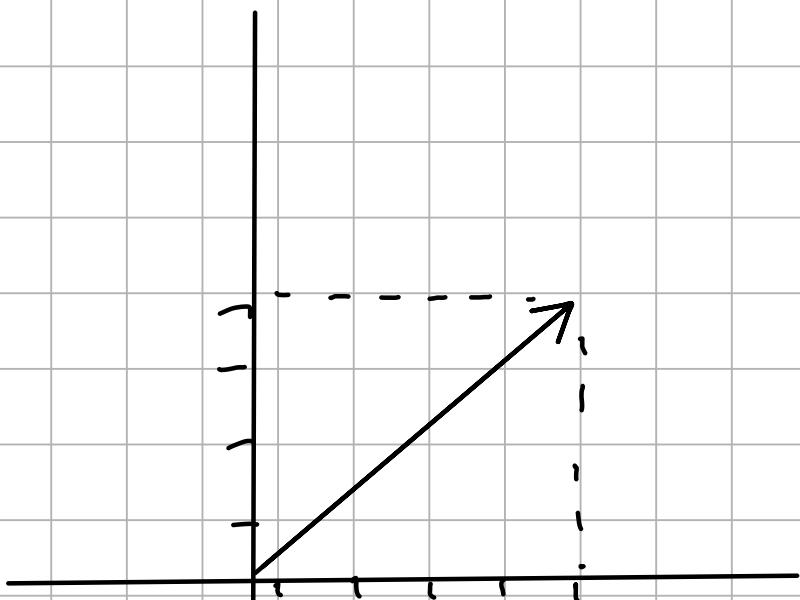
Week - 1

## Vectors

T magnitude and direction

Ex:

$$u = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$



$$u = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}$$

n-component  
vector

$n \times 1$

for real life example

we may refer to a patient and

$u_1, u_2, \dots, u_n$  may be parameters  
of the patient

Field  $\bar{F}$

$\langle \bar{F}, +, \times \rangle$  is a field

when

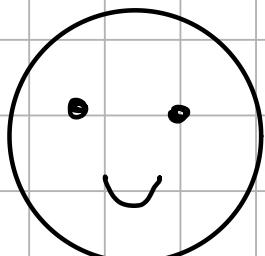
$\langle F, + \rangle$  is a group

and

$\langle F - \{0\}, \times \rangle$  is a group

$\overbrace{\text{additive identity}}$

Prove  $\mathbb{Z}_5$  is a Field



note

$\oplus_2$  ← xor gate

$\otimes_2$  ← and operator

# Vector space $V$

Let  $F$  be any field. Let  $V$  be a non empty collection of objects called 'vectors'.

$V$  is a vector space over  $F$  if rules for adding two vectors and scalar multiplication exists such that

$V$  is closed under vector addition

and scalar multiplication

This means the result must come under the same set

(Example:  $\mathbb{Z}_5$  is closed under  $\mathbb{Z}_5$ )

So basically

i) for  $u, v \in V$ ,  $u+v \in V$

- ii) for  $\alpha \in \mathbb{F}$ ,  $u \in V$ ,  $\alpha u \in V$

and few properties

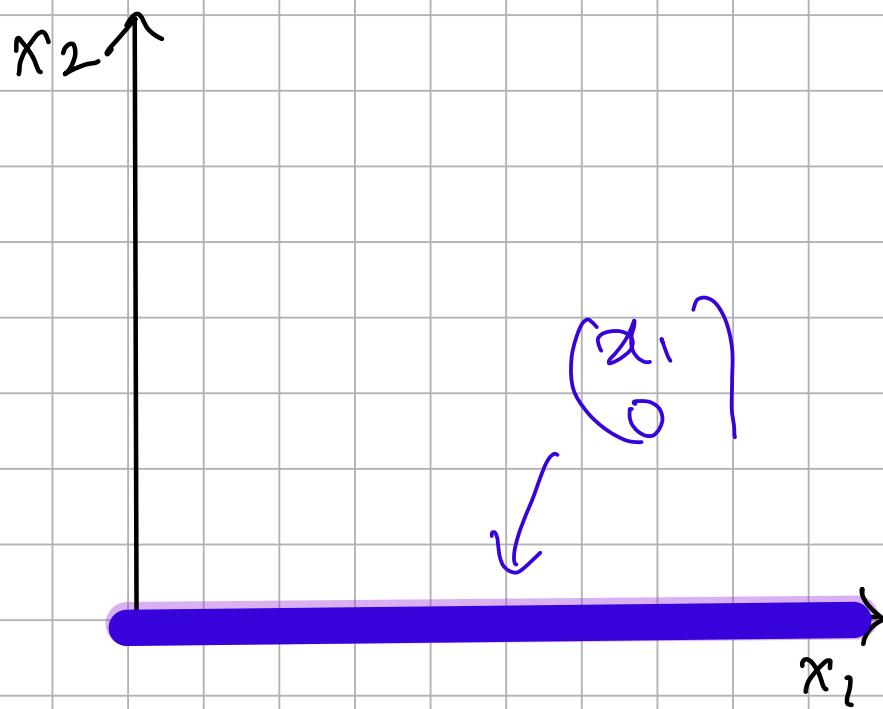
- Commutativity :  $u+v = v+u$
- associativity :  $(u+v)+w = u+(v+w)$
- Distributivity :  $\alpha(u+v) = \alpha u + \alpha v$
- additive identity exists :  $0 \in V$  s.t.  $0+u=u=0+u$
- additive inverse exists : for every  $u \in V$  there exists  $-u$  s.t.  $u+(-u)=0$
- multiplicative identity exists :  $1 u = u$   
where  $u \in V$

If all this hold good,  $V$  is a vector space

## Examples of vector spaces

- i) The field  $\mathbb{F}$  itself is a vector space
- ii)  $\mathbb{R}^n$  for any finite  $n$  is a vector space over  $\mathbb{R}$
- iii) Set of all polynomials of degree  $\leq n$  and with coefficients real is a vector space over  $\mathbb{R}$
- iv) Set of all square matrices  $(n \times n)$  over  $\mathbb{R}$
- v) Set of all real symmetric matrices over  $\mathbb{R}$
- vi) Set of all continuous functions of time  $t$  for  $t$  in  $(-\infty, \infty)$  defined over  $\mathbb{R}$

Consider  $\mathbb{R}^2$



Subset of  $\mathbb{R}^2$        $S_k = \left\{ \begin{pmatrix} x_1 \\ kx_1 \end{pmatrix} \mid x_1 \in \mathbb{R}, k \in \mathbb{R} \right\}$

$$k=0 : S_0 = \left\{ \begin{pmatrix} x_1 \\ 0 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\}$$

Let  $u, v \in S_0$

$$u = \begin{pmatrix} u_1 \\ 0 \end{pmatrix}, \quad v = \begin{pmatrix} v_1 \\ 0 \end{pmatrix}$$

$$U + V = \begin{pmatrix} U_1 + V_1 \\ 0 \end{pmatrix} \in S_0$$

So  $S_0$  is closed under vector add<sup>u</sup>

$$\lambda \in \mathbb{R}$$

$$\lambda U = \lambda \begin{pmatrix} U_1 \\ 0 \end{pmatrix} = \begin{pmatrix} \lambda U_1 \\ 0 \end{pmatrix} \in S_0$$

So  $S_0$  is closed under scalar Mulp<sup>u</sup>

and

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} \in S_0$$

Hence

$S_0$  is a vector space over  $\mathbb{R}$

Similarly  $S_1 = \left\{ \begin{pmatrix} \alpha_1 \\ \alpha_1 \end{pmatrix} \right\}$  is VS (vector space)

$$S_2 = \begin{pmatrix} x_1 \\ -x_1 \end{pmatrix} \text{ is VS}$$

:

So any line passing through  
the origin is a vector space over  $\mathbb{R}$

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Any subset of a vector space  $V$ , which  
by itself is a vector space with  
operations as defined in  $V$  is  
called a vector subspace of  $V$

Remember:

i) Every set is a subset of itself

∴ any  $\mathbb{R}^n$  is a trivial subspace of  $\mathbb{R}^n$

ii) Consider the set  $S_0 = \{(0)\}$

This is also a subspace of  $\mathbb{R}^2$

Hence, Set containing only the zero vector is a vector subspace

iii) In any  $\mathbb{R}^n$ , a plane passing through the origin is a vector Subspace.

Some Questions:

1) What happens if we add multiple vectors in a vectorspace  
Meaning what is it say about combining vectors?

2) Suppose we want to transform an entire vectorspace, what is the effect

of the transformation on the vector space?

## Combining vectors and

## Linear Independence

Linear combination of vectors

Suppose  $u_1, u_2, \dots, u_k$  are  $k$  vectors  
of  $n$  components each

$$u_i = \begin{pmatrix} u_{i1} \\ u_{i2} \\ u_{i3} \\ \vdots \\ u_{in} \end{pmatrix} \quad \text{for } i = \{1, 2, \dots, k\}$$

Let  $\alpha_1, \alpha_2, \dots, \alpha_k$  be scalars

$u_i$  for  $i = 1, \dots, k$ . are real vectors

and let  $\alpha_1, \alpha_2, \dots, \alpha_k$  be real as well

The vectors

$$v = \alpha_1 u_1 + \alpha_2 u_2 + \alpha_3 u_3 + \dots + \alpha_k u_k$$

is called linear combinations of the  
k-vectors  $u_1, u_2, \dots, u_k$

Example:

Suppose  $u_1, u_2, u_3, \dots, u_k$  are standard  
unit vectors

$$u_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ \vdots \end{pmatrix} \quad u_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ \vdots \end{pmatrix} \quad \dots \quad u_k = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix}$$

↑  
k-th component

Suppose  $u_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $u_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$\begin{aligned} v &= \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = v_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + v_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ &= v_1 u_1 + v_2 u_2 \end{aligned}$$

So vector  $v$  is linear combination of  $u$

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Suppose we have  $u_1, u_2 \dots u_n$  all  $n$  component vectors

Let  $\alpha_1, \alpha_2 \dots \alpha_n$  be scalars such that

$$\alpha_1 + \alpha_2 + \alpha_3 + \dots + \alpha_n = \frac{1}{n}$$

$$v = \alpha_1 u_1 + \alpha_2 u_2 + \alpha_3 u_3 + \dots + \alpha_n u_n$$

$$= \frac{1}{n} (u_1 + u_2 + u_3 + \dots + u_n)$$

$\Rightarrow$  Average of the vectors

If the coefficient of the scalars add

up to 1, we call them as affine combination

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Suppose the coefficients in an affine

combination are all non negative, we

call this combination as

i) Convex Combination

ii) Weighted Average

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Suppose we want to study the effect  
of a 'transformation' on a vector space

What strategy do we adopt to do this?

Consider  $u_1, u_2, u_3 \dots u_n$  to be  $n$  component  
vectors

Look at that linear combination of  
the  $v$  vectors that result in  $n$ -comp  
zero vectors.

Vector A is independent

if  $x$  if not zero vector

in  $Ax = 0$  [null space is non zero]

Keep in mind that if A contains

a column full of zeroes, then  $x$  is

always not zero vector

$$\begin{bmatrix} 1 & | & | & \dots & 0 \\ & | & & & | \end{bmatrix} \quad x_1, x_2, \dots, x_k$$

$$x_1 \begin{bmatrix} 1 \end{bmatrix} + x_2 \begin{bmatrix} 1 \end{bmatrix} + \dots + x_k \begin{bmatrix} 0 \\ \vdots \\ 1 \end{bmatrix}$$

$$\text{so } x_1 = x_2 = \dots = x_{k-1} = 0$$

and  $x_k$  can be anything

Linearly independent

if null space of A is zero.

then A is Linearly independent

Some conclusions :

- 1) A linearly independent set cannot contain zero vector
- 2) A single vector is always linearly independent unless it is the zero vector
- 3) Any subset of a linearly independent set of vectors is always linearly independent
- 4) Any superset of dependent vectors are linearly dependent

5) Two vectors are linearly indep if one  
is not a multiple of another

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### Span of set of vectors

Let  $u_1, u_2, \dots, u_k$  be  $k$  vectors

Span := set of all possible Linear combinations

of  $u_1, u_2, u_3, \dots, u_k$

Span is a vector space

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Span of a set of linearly indep vectors

Let  $v_1, v_2, \dots, v_n$  be linearly indep set of vectors

Span:  $\{ \alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n, \alpha_i \in \mathbb{R} \}$   
for  $i = 1, 2, \dots, n$





Smallest subspace that contains the set of linearly indep vectors

for example :  $v_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and  $v_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

$$\left\{ \alpha_1 v_1 + \alpha_2 v_2, \alpha_1, \alpha_2 \in \mathbb{R} \right\}$$

$$\left\{ \alpha_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} + \alpha_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \alpha_1, \alpha_2 \in \mathbb{R} \right\}$$

i)  $\begin{pmatrix} 0 \\ 0 \end{pmatrix} \in \text{Span of } \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}$   $\alpha_1 = \alpha_2 = 0$

ii)  $\text{Span} \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} \& \begin{pmatrix} 1 \\ 2 \end{pmatrix} \right)$  is closed under vector addition

iii)  $\text{Span} \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} \& \begin{pmatrix} 1 \\ 2 \end{pmatrix} \right)$  is closed under scalar multiplication

$\text{Span} \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} \text{ & } \begin{pmatrix} 1 \\ 2 \end{pmatrix} \right)$  is vector space

Basis: A set of  $n$  linearly indep  $n$  component vectors called Basis for the vector space that contains these  $n$ -linearly indep  $n$ -comp vectors

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note

any vector in a vector space can be uniquely represented as basis of that vector space.