view_frames Result

Recorded at time: 31.605

odom

Broadcaster: /gazebo
Average rate: 100.340 Hz
Most recent transform: 31.595 (0.010 sec old)
Buffer length: 2.352 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

torso_lift_link

estop_link

laser_link

torso_fixed_link

l_wheel_link

r_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

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Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

bellows_link2

head_pan_link

bellows_link

shoulder_pan_link

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

head_tilt_link

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

shoulder_lift_link

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

head_camera_link

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

upperarm_roll_link

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

head_camera_depth_frame

head_camera_rgb_frame

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

elbow_flex_link

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

head_camera_depth_optical_frame

head_camera_rgb_optical_frame

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

forearm_roll_link

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

wrist_flex_link

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

wrist_roll_link

Broadcaster: /robot_state_publisher
Average rate: 100.339 Hz
Most recent transform: 32.101 (-0.496 sec old)
Buffer length: 2.362 sec

gripper_link

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

Broadcaster: /robot_state_publisher
Average rate: 100.424 Hz
Most recent transform: 31.593 (0.012 sec old)
Buffer length: 2.360 sec

l_gripper_finger_link

r_gripper_finger_link