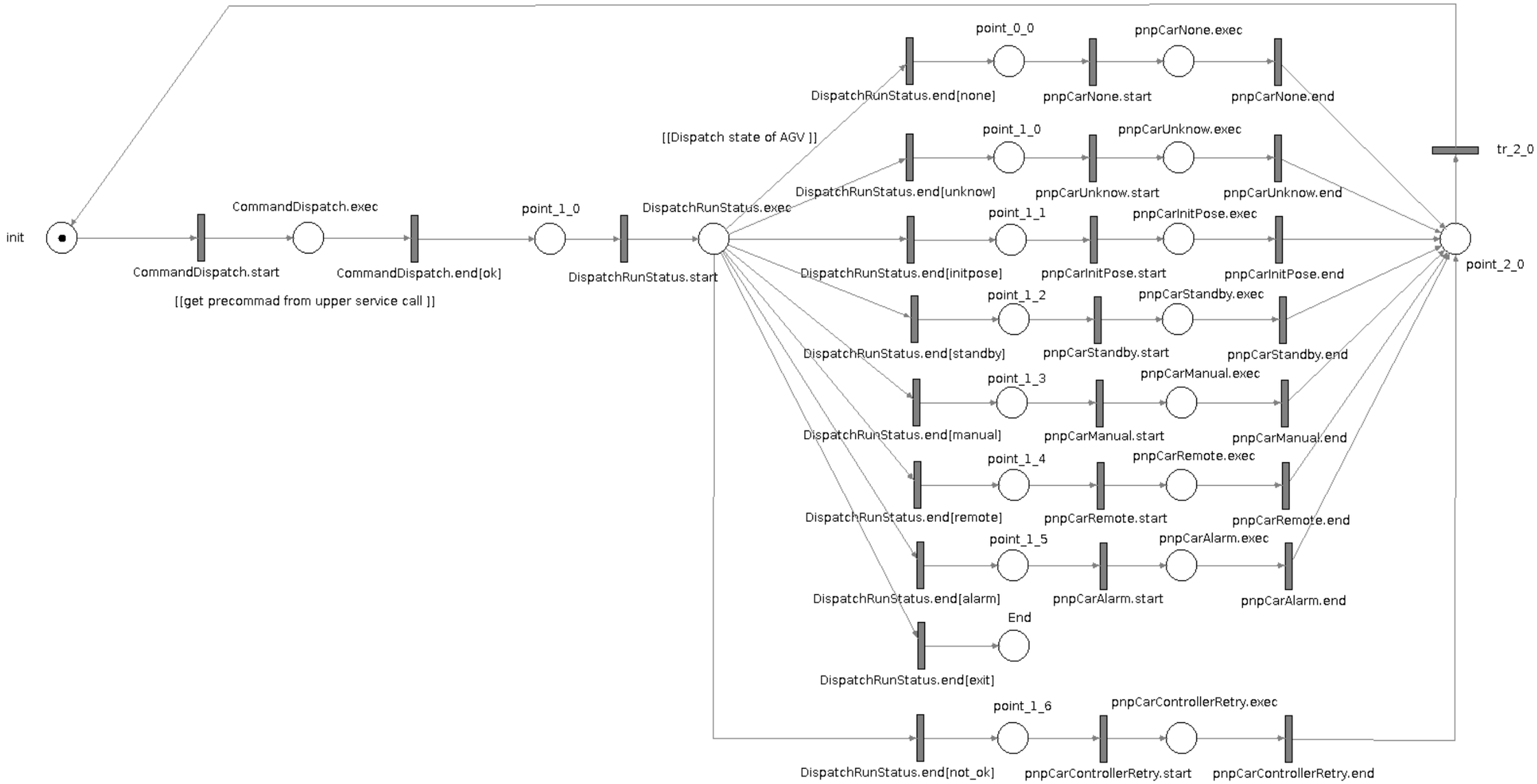
[[Main operation]]

[[File name ==> pnpActionMainDispatch.pnml]]

[[==========]]



[[retry : call service to controller] [[status code: hold status / 9_001]] [[File name ==> pnpCarControllerRetry.pnml]]
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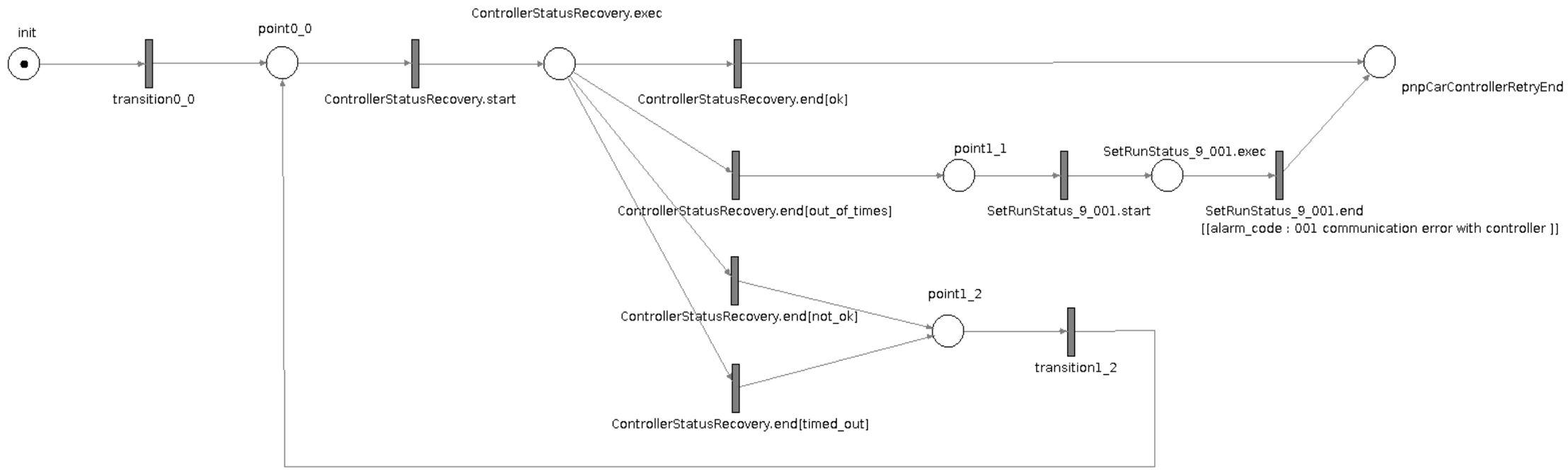
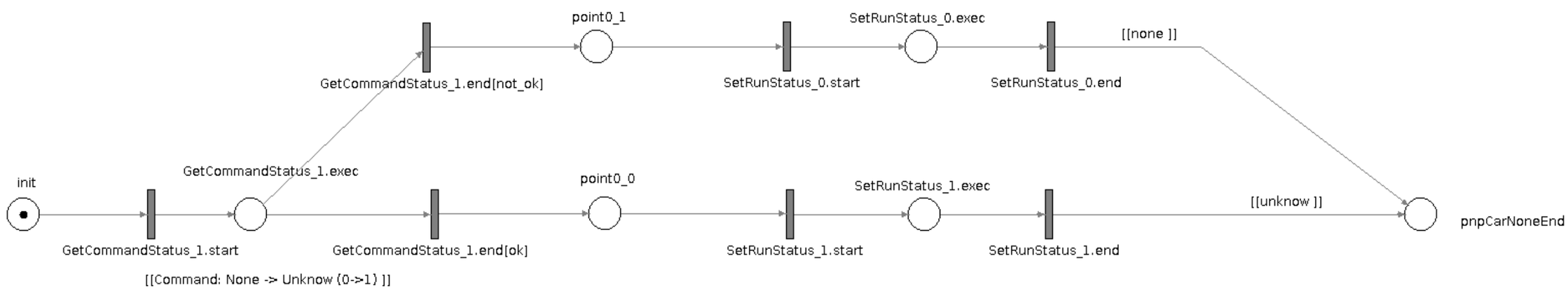
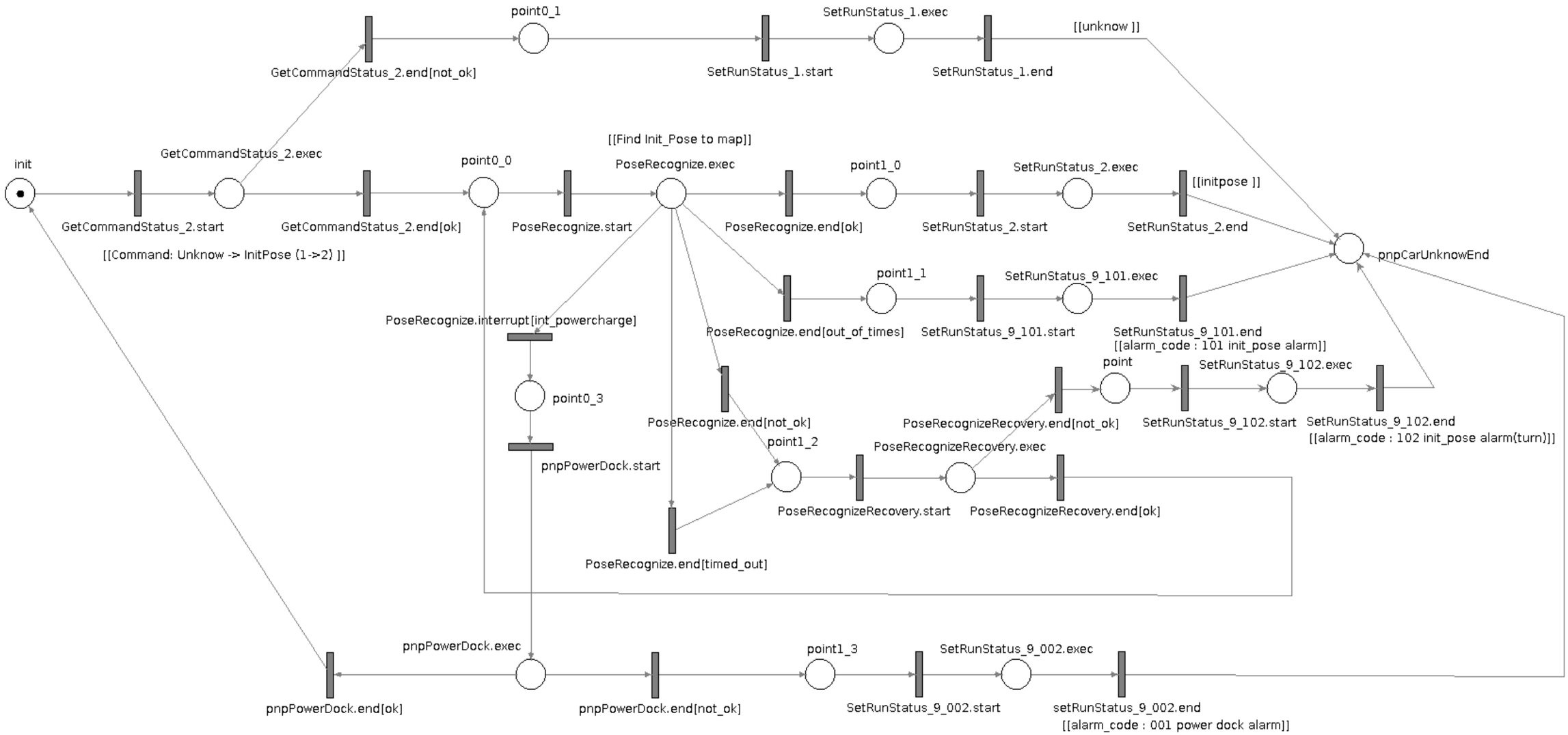


[[none / unknow operation] [[status code: 0 / 1]] [[File name ==> pnpCarNone.pnml]]
[[==========]]



[[unknow / initpose operation]] [[status code: 0 / 1 / 9_001 / 9_101]] [[File name ==> pnpCarUnknow.pnml]]

[[==========]]



[[initpose/Standby operation]] [[status code: 2 / 3 / 9_002 / 9_201]] [[File name ==> pnpCarInitPose.pnml]]
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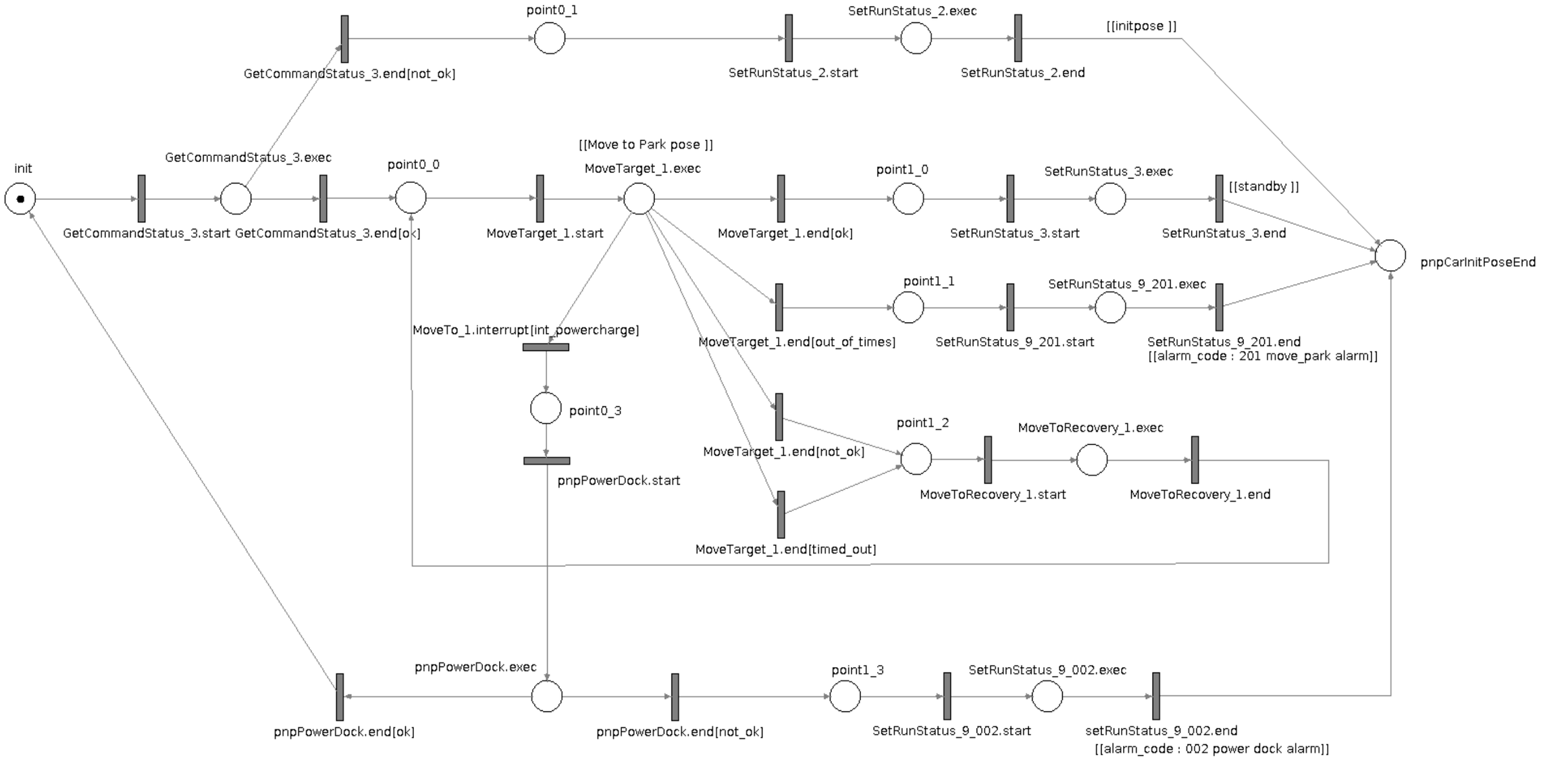

[[Standby / Manual , Remote operation]] [[status code: 3 / 4 / 5 / ---]] [[File name ==> pnpCarStandby.pnml]]
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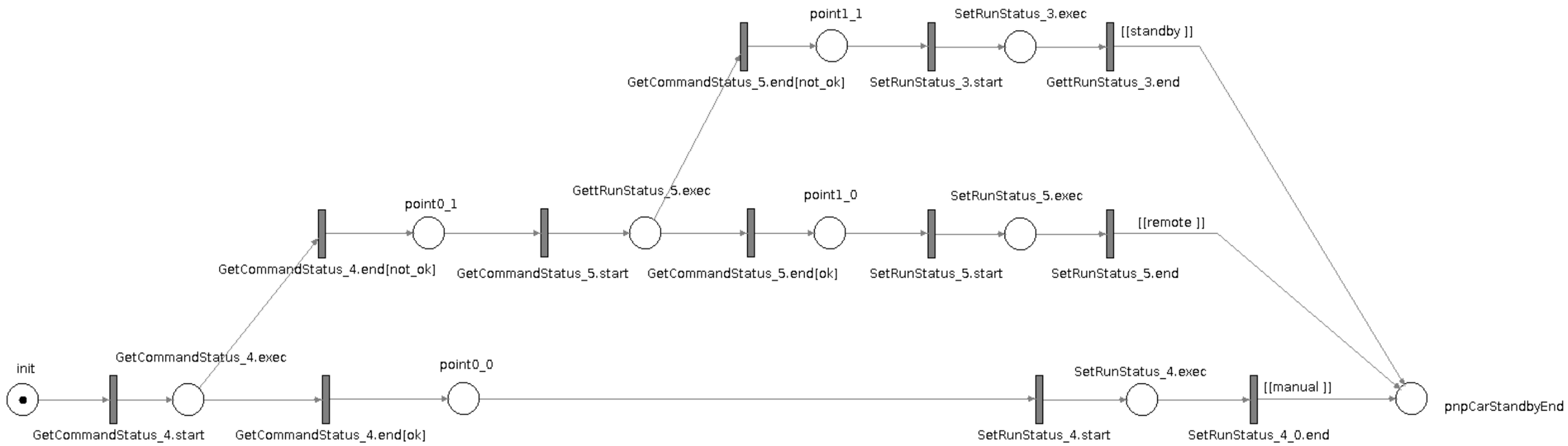

[[Manual / Standby,Remote operation] [[status code: 3 / 4 / 5 / ---]] [[File name ==> pnpCarManual.pnml]]
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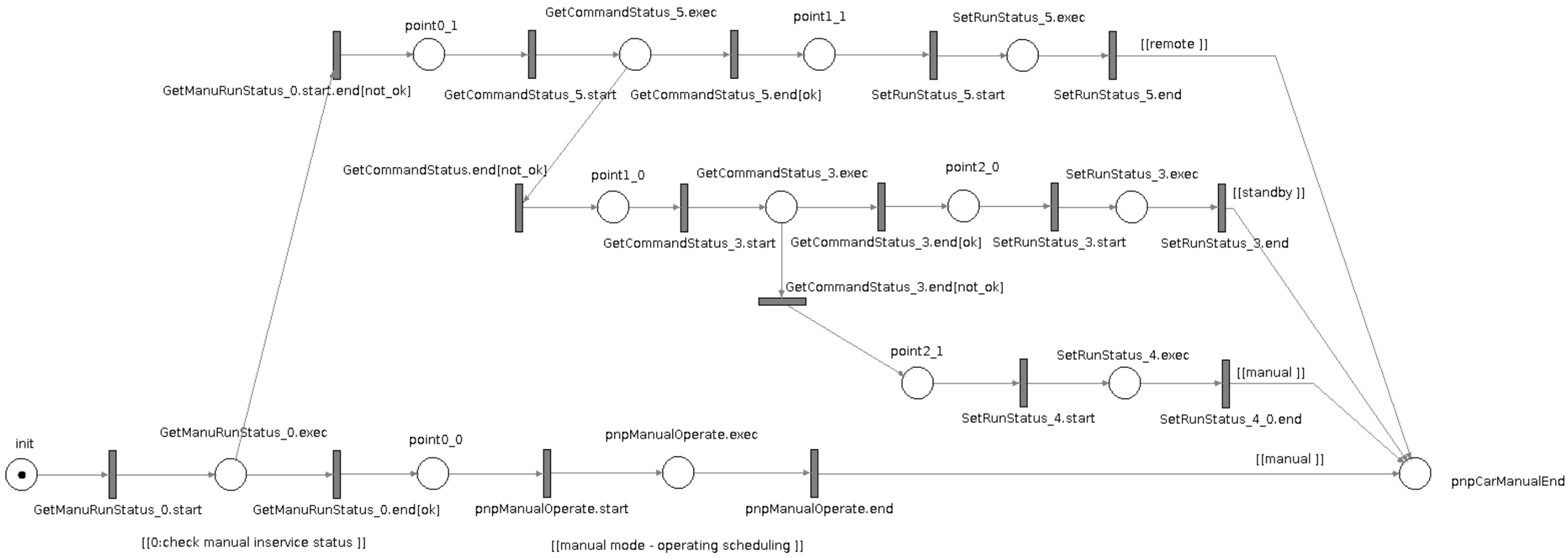

[[Manual / Standby,Auto operation] [[status code: 3 / 4 / 5 / ---]] [[File name ==> pnpCarRemote.pnml]]
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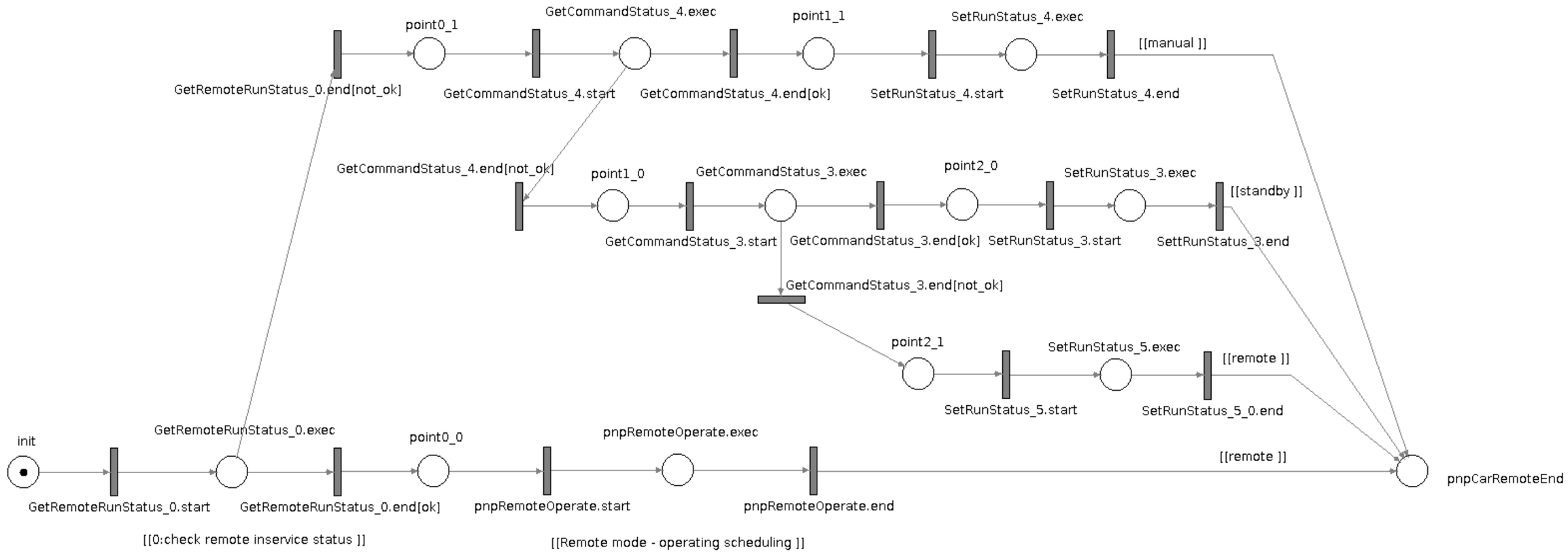
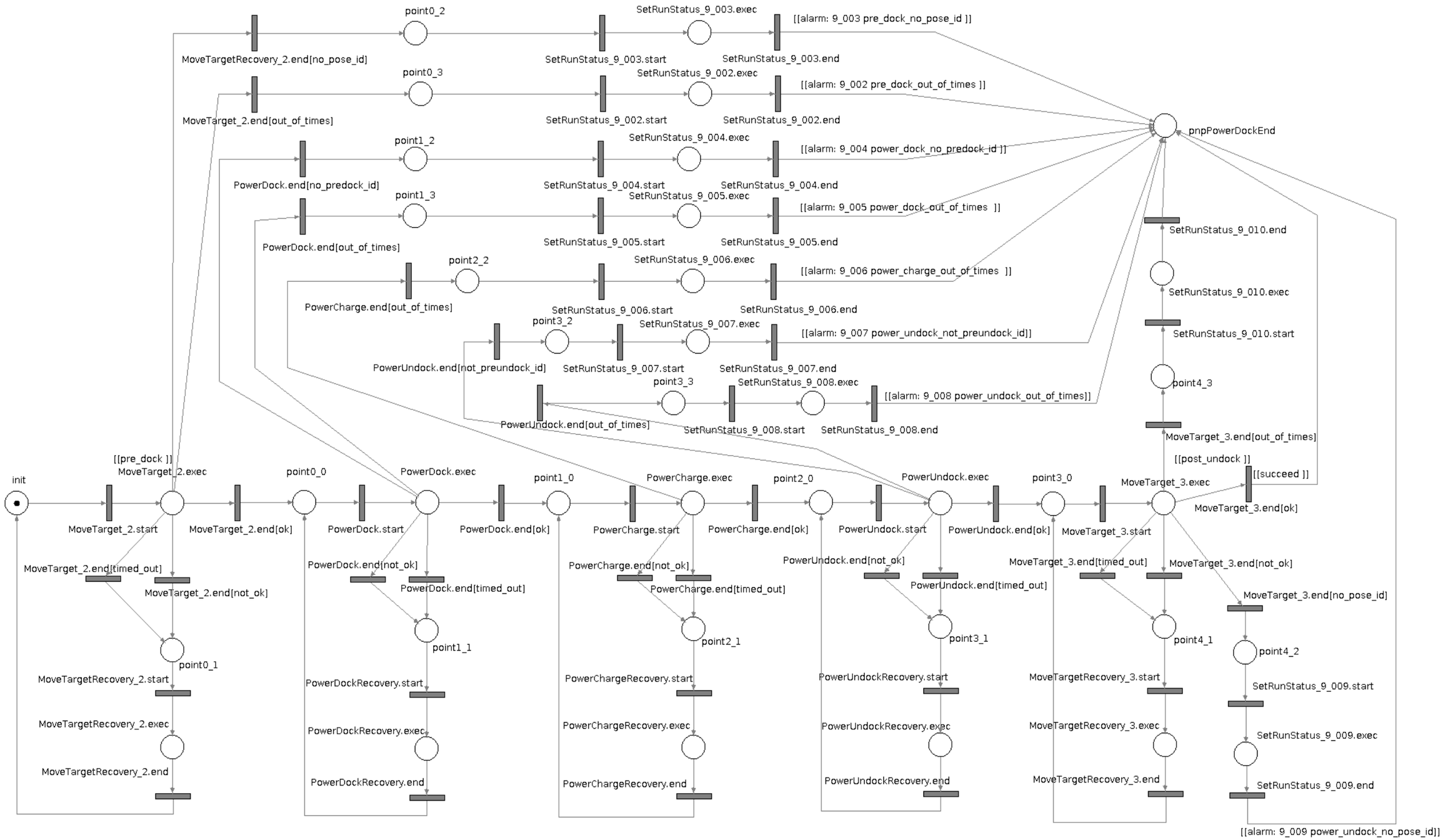
[[PowerDock] [[status code: - / - / 9_002 ~ 9_009]] [[File name ==> pnpPowerDock.pnml]]
[[==========]]