

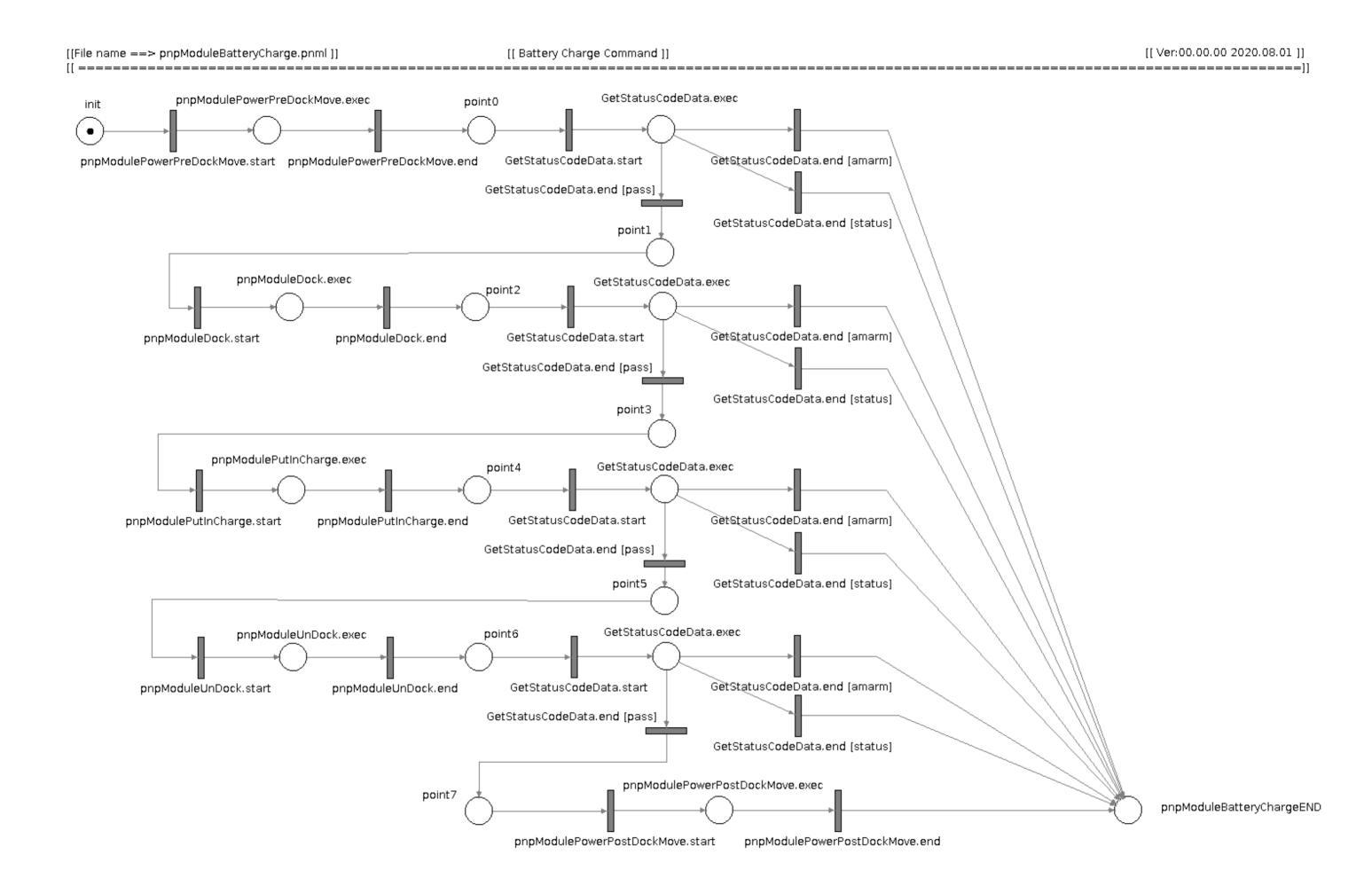
point3

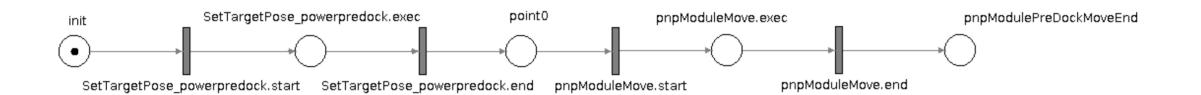
MoveTarget\_m.end[not\_ok]

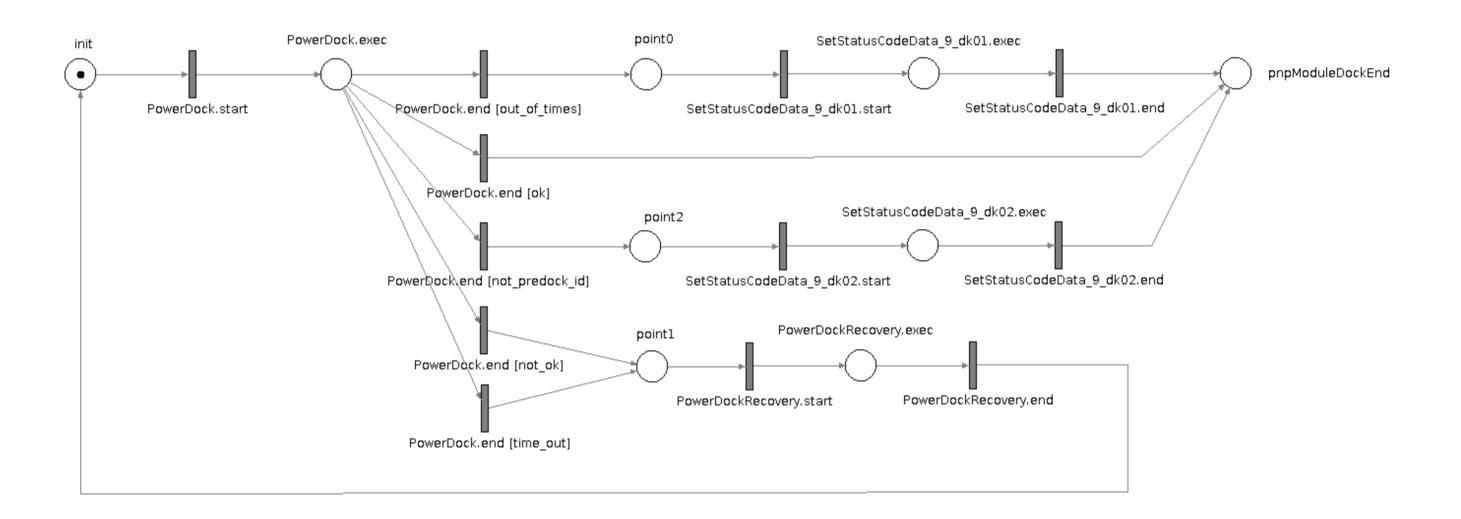
MoveTarget\_m.end[timed\_out]

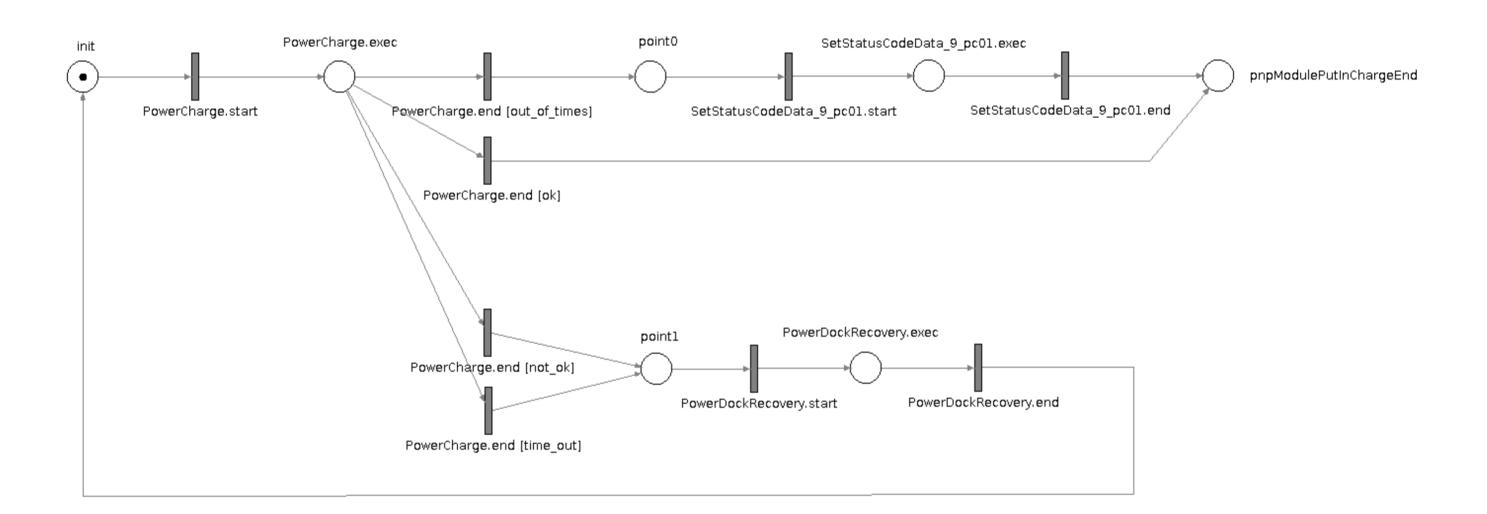
MoveToRecovery\_m.exec

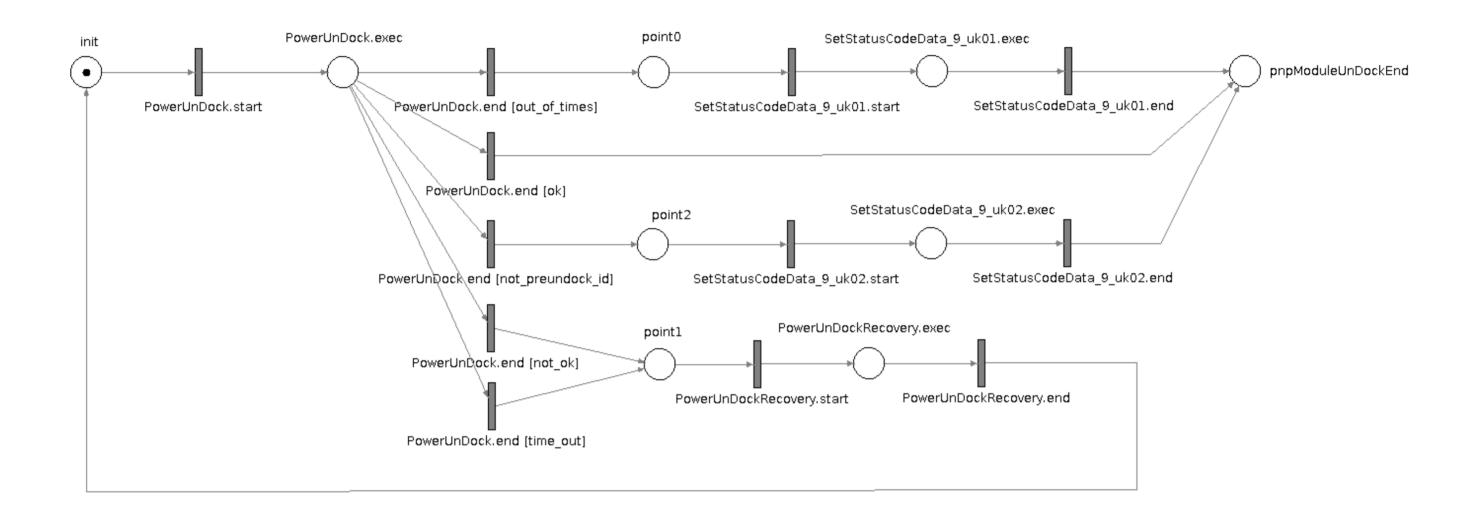
MoveToRecovery\_m.start MoveToRecovery\_m.end

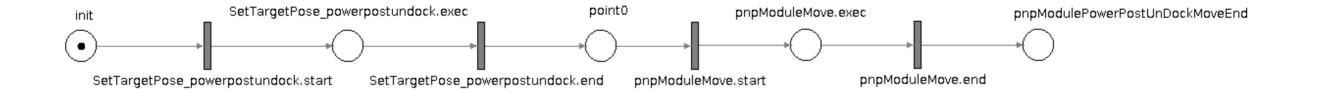


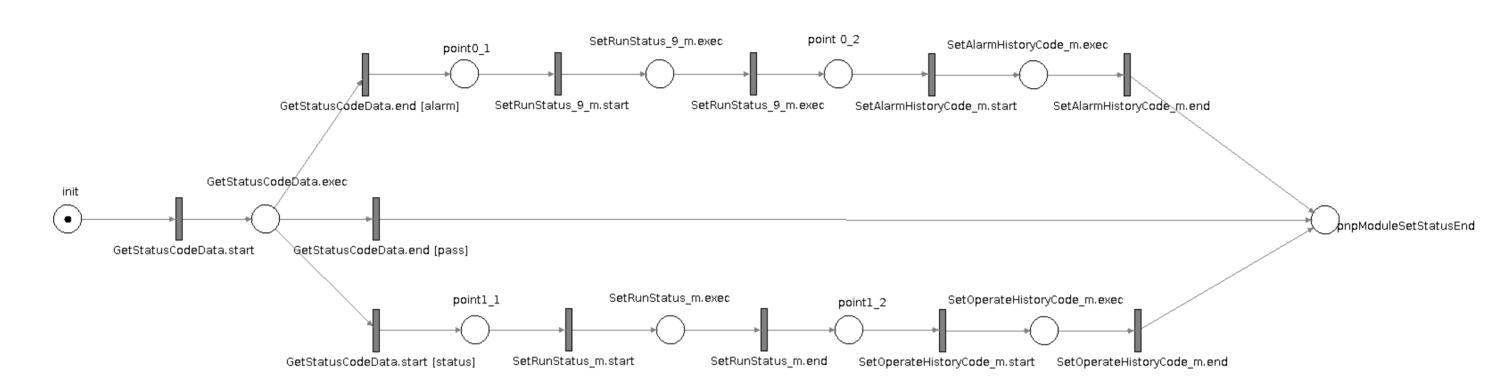


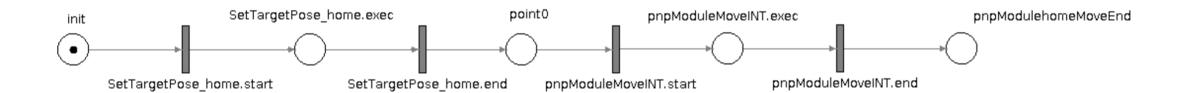












pnpModuleMoveINT.exec

pnpModuleMoveINT.end

pnpModulePostDockMoveEnd

point0

pnpModuleMoveINT.start

SetTargetPose\_postdock.end

SetTargetPose\_postdock.exec

init

SetTargetPose\_postdock.start

DoFunction\_m.end[timed\_out]

