1 Proposal scratch notes

- \mathcal{D} , \mathcal{I} : (unknown) disjoint sets of indices that describe the groups of transformations that are relevant and irrelevant to the output, respectively. $\mathcal{D} \cup \mathcal{I} = \{1, \dots, m\}$.
- U_Y , $U_{\mathcal{I}}$, $U_{\mathcal{D}}$, $\widetilde{U}_{\mathcal{I}}$: independent latent variables that influence the value of the variable(s) that they point to.
- $X^{\text{(hid)}}$: some unknown canonical form of the observed input X. It is assumed that given $U_{\mathcal{D}}$ and $U_{\mathcal{I}}$, X was obtained from an ordered sequence of transformations on the canonical form, i.e.,

$$X = T_{U_{\mathcal{D}}, U_{\mathcal{I}}} \circ X^{\text{(hid)}}$$

where transformations

$$T_{U_{\mathcal{D}},U_{\mathcal{I}}} = T_{\mathcal{I}}^{(1)} \circ T_{\mathcal{D}}^{(1)} \circ T_{\mathcal{I}}^{(2)} \circ \dots$$

make up the overgroup $\mathcal{G}_{\mathcal{D}\cup\mathcal{I}}$, $T_{\mathcal{D}}^{(j)}$ is a transformation in group \mathcal{G}_j from the overgroup $\mathcal{G}_{\mathcal{D}} = \langle \cup_{j\in\mathcal{D}} \mathcal{G}_j \rangle$, and $T_{\mathcal{I}}^{(i)} \in \mathcal{G}_i \subset \mathcal{G}_{\mathcal{I}} = \langle \cup_{i\in\mathcal{I}} \mathcal{G}_i \rangle$. Note that $\mathcal{G}_{\mathcal{I}}$ is also assumed to be a normal subgroup of $\mathcal{G}_{\mathcal{D}\cup\mathcal{I}}$.

• Y: observed output assumed to be generated by

$$Y = h(X^{\text{(hid)}}, U_{\mathcal{D}}, U_{Y})$$

where h is a deterministic function.

• $X_{U_{\mathcal{I}} \leftarrow \widetilde{U}_{\mathcal{I}}}$: counterfactual variable to X where $U_{\mathcal{I}}$ has been replaced by $\widetilde{U}_{\mathcal{I}}$, i.e.,

$$X_{U_{\mathcal{I}} \leftarrow \widetilde{U}_{\mathcal{I}}} = T_{U_{\mathcal{D}}, \widetilde{U}_{\mathcal{I}}} \circ X^{(\mathrm{hid})}$$

• Want CG-invariant representation

$$\Gamma(X) = \Gamma(T_{U_{\mathcal{D}},U_{\mathcal{I}}} \circ X^{(\mathrm{hid})}) = \Gamma(T_{U_{\mathcal{D}},\widetilde{U}_{\mathcal{I}}} \circ X^{(\mathrm{hid})}) = \Gamma(X_{U_{\mathcal{I}} \leftarrow \widetilde{U}_{\mathcal{I}}})$$

When $\mathcal{G}_{\mathcal{I}}$ is a normal subgroup of $\mathcal{G}_{\mathcal{D}\cup\mathcal{I}}$, G-invariant representation

$$\Gamma(X) = \Gamma(T_{\mathcal{I}} \circ X)$$

for all $T_{\mathcal{I}} \in \mathcal{G}_{\mathcal{I}}$ is sufficient.

 \bullet Because groups are finite linear automorphisms, each transformation T is just a linear function and so Reynolds operator can be applied directly to the group actions

$$\bar{T} = \frac{1}{|\mathcal{G}|} \sum_{T \in \mathcal{G}} T$$

For continuous linear groups, orbit-average over a Haar measure λ

$$\bar{T} = \int_{\mathcal{G}} T\lambda(T)$$

TODO: need to estimate the operator. Assume uniform Haar and sample?

2 Kernel hypothesis test notes

- Kernel methods work on inner products of feature maps $(\phi: X \to \mathcal{H})$ of observations in the RKHS associated with kernel. Inner products may be computed without explicitly computing the high-dimensional feature map ("kernel trick").
- Main challenge of designing kernel-based hypothesis tests is deriving large-sample distribution of test statistic under null.
- Gram matrix should be positive semidefinite. Satisfised if kernel is symmetric and positive semidefinite.
- Let X be a r.v. with distribution \mathbb{P} . Mean element $\mu_{\mathbb{P}}$ associated with X is unique element of RKHS \mathcal{H} s.t. for all $f \in \mathcal{H}$,

$$\langle \mu_{\mathbb{P}}, f \rangle = \mathbb{E}_{\mathbb{P}}[f(X)]$$

Covariance operator $\Sigma_{\mathbb{P}}: \mathcal{H} \times \mathcal{H} \to \mathbb{R}$ associated with X is unique operator s.t. for all $f, g \in \mathcal{H}$,

$$\langle f, \Sigma_{\mathbb{P}} g \rangle = \operatorname{Cov}(f(X), g(X)) = \mathbb{E}_{\mathbb{P}}[f(X), g(X)] - \langle \mu_{\mathbb{P}}, f \rangle \langle \mu_{\mathbb{P}}, g \rangle$$

Empirical estimates of inner products that lead to estimates of element/operator are available.

- If $\dim(\mathcal{H} = \infty, \mu_{\mathbb{P}})$ has more significance than in classical statistics.
- Detecting (conditional?) invariances in single training environment via hypothesis testing. Explicitly testing for invariances? Invariant testing